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Author(s)	Panteleev, G.G.; Stabeno, P.; Luchin, V.A.; Nechaev, D.A.; Ikeda, M.
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2 Summer transport estimates of the Kamchatka Current derived as a 3 variational inverse of hydrophysical and surface drifter data

4 G. G. Pantelev,^{1,2} P. Stabeno,³ V. A. Luchin,⁴ D. A. Nechaev,⁵ and M. Ikeda⁶

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6 [1] The quasistationary summer Bering Sea circulation is
7 reconstructed as a variational inverse of the hydrographic
8 and atmospheric climatologies, transport estimates through
9 the Bering Strait, and surface drifter data. Our results
10 indicate the splitting of the Kamchatka Current in the
11 vicinity of the Shirshov Ridge. This branching is in
12 agreement with independent ARGO drifter observations. It
13 was also found, that transport of the Kamchatka Current
14 gradually increases downstream from 14 Sv in the
15 Olyutorsky Gulf to 24 Sv in the Kamchatka Strait, which
16 is twice higher than previous estimates. **Citation:** Pantelev,
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20 drifter data, *Geophys. Res. Lett.*, 33, LXXXXX, doi:10.1029/
21 2005GL024974.
22

23 fortunately, the results of both these methods depend on a
24 number unknown parameters, such as the level of no motion
25 or poorly known boundary conditions and tidal rectification
26 through many of the passes that are often not resolved in
27 models [Stabeno *et al.*, 2005].
28

29 [3] The goal of this study is to quantify the summer
30 circulation in the central BS and to derive reliable estimates
31 of the KC transport by combining the information from all
32 available data sources with the dynamical constraints of the
33 primitive equation numerical model. We solve this problem
34 through the variational assimilation of temperature/salinity,
35 drifter and meteorological data into the ocean general
36 circulation model [Nechaev *et al.*, 2005; Pantelev *et al.*,
37 2006]. The summer period was chosen as the period with
38 the best data coverage.
39

24 1. Introduction

25 [2] The circulation and distributions of the hydrophysical
26 properties in the Bering Sea (BS) determine the heat and
27 fresh water exchange between the North Pacific and Arctic
28 Oceans. The circulation in the BS basin is driven by the
29 atmospheric forcing and the inflow/outflow transports
30 through four primary passes: Kamchatka Strait, Near Strait,
31 Amchitka Pass and Amukta Pass [Stabeno *et al.*, 2005]. The
32 currents in the Bering Strait are relatively well monitored by
33 velocity moorings [Woodgate *et al.*, 2005], while the water
34 transports through the straits and passages of the Aleutian
35 Arc have been mainly explored through the estimates of the
36 baroclinic currents by dynamical method [Verkhunov and
37 Tkachenko, 1992; Stabeno and Reed, 1992]. The transport
38 through the Kamchatka Strait is the major outflow from the
39 BS. This region is one of the least studied in the BS because
40 of known difficulties in accessing the Russian historical
41 data. The estimates of the Kamchatka Current (KC) trans-
42 port are based mainly on the hydrophysical data and range
43 from 5 Sv [Verkhunov and Tkachenko, 1992] to 15 Sv
44 [Ohtani, 1970] in dynamical calculations and 8–13 Sv in
45 numerical modelling studies [Overland *et al.*, 1994]. Un-

61 2. Data

62 [4] In the presented research we utilize data sets as
63 follows.

64 2.1. 41,911 Temperature/Salinity Profiles Collected in 65 the Chukcha and Bering Seas (Between 55°N and 69°N) 66 During the Summer (July–September)

67 [5] This database includes bottle data, mechanical bathy-
68 thermograph data, high resolution CTD, expendable bathy-
69 thermograph and PALACE ARGO drifter data. The data
70 were collected by US, Japanese and Russian organizations
71 during the period 1932–2004. The major part of the data
72 was obtained from historical databases in RIHMI-WDC
73 (<http://www.meteo.ru/nodc/>), JODC (<http://jdoss1.jodc.go.jp>), University of Alaska (<http://www.ims.uaf.edu>), data-
74 bases of Levitus [Levitus *et al.*, 2001], and Argo Global
75 Data Assembly Centre (<http://www.coriolis.eu.org/ccdc/argo.htm>). Some of Russian data are classified and not
76 available to the public at present. Figure 1 shows the spatial
77 distribution of salinity profiles. These climatological data
78 and estimates of their standard deviation (STD) were used
79 in data assimilation. Temperature/salinity STD varied within
80 the ranges 0.5°C–1.5°C and 0.1–2.0 near the surface and
81 decreased down to 0.1°C and 0.03 respectively on deeper
82 levels (1000 m).
83
84

85 2.2. 500 Satellite-Tracked Drifters Trajectories From 86 Fisheries Oceanography Coordinated Investigations 87 (NOAA) Database (http://www.pmel.noaa.gov/foci/FOCI_data.html) 88

89 [6] All surface drifters utilized in this paper had drogues
90 at approximately 40 m [e.g., Stabeno and Reed, 1994]. The
91 preliminary analysis of these data included: (i) extraction of
92 summer drifter trajectories; (ii) temporal low-pass filtering
93 with a 7 days cutoff period; (iii) spatial interpolation and
94 smoothing of the filtered drifter velocity components onto

¹International Arctic Research Center, University of Alaska Fairbanks, Fairbanks, Alaska, USA.

²Also at Shirshov Institute of Oceanology, Russian Academy of Sciences, Moscow, Russia.

³Pacific Marine Environmental Laboratory, Seattle, Washington, USA.

⁴Il'ichev Pacific Oceanological Institute, Far Eastern Branch, Russian Academy of Science, Vladivostok, Russia.

⁵Department of Marine Science, University of Southern Mississippi, Stennis Space Center, Mississippi, USA.

⁶Graduate School of Environmental Earth Science, Hokkaido University, Sapporo, Japan.



Figure 1. Spatial distribution of the summer historical salinity data in the Bering Sea. The model domain is shown by thick line. Dashed lines mark the 1000 m and 3000 m isobaths.

95 the model grid with correlation radius of 40 km; (iv)
96 estimation of the error variance of gridded velocity compo-
97 nents. We assimilated only “reliable” velocities obtained
98 from the averaging of at least three different surface drifters
99 (Figure 2).

100 2.3. Estimates of the Total Summer Transports 101 Through the Bering Strait

102 [7] Transport estimates of 1.1 ± 0.2 Sv were taken from
103 [Woodgate *et al.*, 2005].

104 2.4. NCEP/NCAR Wind Stress and Surface 105 Heat/Salt Flux Climatology

106 [8] These climatologies (<http://www.cdc.noaa.gov/cdc/data.ncep.reanalysis.derived.html>) were found to be ex-
108 tremely smooth. To allow for the adjustment of the spatial
109 details in the model forcing we used wind stress and heat/
110 salt flux data with relatively high error variance equal to
111 40% of their spatial and temporal variability in the BS.
112 Significant errors in the NCEP/NCAR forcing were also
113 noticed by Ladd and Bond [2002].
114

115 3. Data Assimilation Technique

116 [9] To find the optimal solution of the model we perform
117 strong constraints minimization of the cost function mea-
118 suring the distance between the model solution and data on
119 the space of the control variables [Le Dimet and Talagrand,
120 1986]. Control variables include the initial conditions, the
121 model field values required to specify the open boundary
122 conditions, and the surface fluxes of momentum, heat and
123 salt [Nechaev *et al.*, 2005].

124 [10] The primitive equation model utilized in this study
125 was successfully used for the reconstruction of the clima-
126 tological circulation in the Barents Sea [Pantelev *et al.*,
127 2006] and for the nowcast of the circulation in the Tsushima
128 Strait [Nechaev *et al.*, 2005]. The model is a modification of
129 the C-grid, z -coordinate OGCM designed by Madec *et al.*
130 [1999]. The model is implicit both for barotropic and
131 baroclinic modes permitting model runs with relatively
132 large time steps [Nechaev *et al.*, 2005]. The model is
133 configured in the domain shown in Figure 1 and is used
134 in “climatological”, “quasistationary” [Tziperman and
135 Thacker, 1989] non-eddy-resolving mode on a relatively

coarse regular z -coordinate grid. The meridional resolution 136
of the grid is 0.2° , zonal resolution – 0.4° , and the time step 137
is 4 hours. Vertically the grid has 34 levels with unequal 138
spacing ranging from 5 m at the surface to 500 m in the 139
deeper levels. The smaller passes in the Aleutian Arc are not 140
resolved, but the primary ones are. 141

[11] Statistical interpretation of the variational data as- 142
similation technique [Thacker, 1989] considers the cost 143
function as an argument of the Gaussian probability distri- 144
bution with the cost function weights being the inverse 145
covariances of the corresponding data errors. In the present 146
study we use the cost function \mathcal{J} containing “data”, 147
“smoothness” and “stationarity” terms: 148

$$\mathcal{J} = \mathcal{J}_{data} + \mathcal{J}_{smoth} + \mathcal{J}_{stat}, \quad \text{where}$$

$$\mathcal{J}_{data} = W_y^{-1}(y - y^*)^2 + W_Y^{-1}(Ly - Y^*)^2,$$

$$\mathcal{J}_{smoth} = \int_{\Omega, t} W_{y,s}^{-1}(\nabla^2 y)^2 d\Omega dt, \quad (1)$$

$$\mathcal{J}_{stat} = \int_{\Omega, t} W_{y,t_1}^{-1}(\partial y / \partial t)^2 + W_{y,t_2}^{-1}(\partial^2 y / \partial t^2)^2 d\Omega dt.$$

[12] Here Ω is the model domain; y stands for the vector 151
of the model solution, and y^* – for the corresponding 152
gridded data; Y^* denotes the data, which are not direct 153
measurement of the model state vector and require some 154

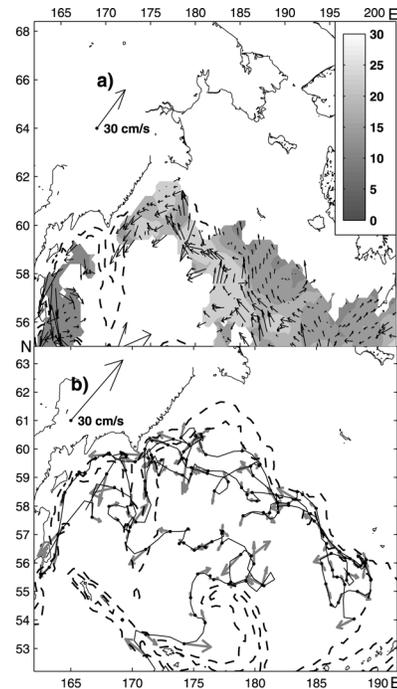


Figure 2. (a) Averaged summer velocities at 40 m derived from drifter data. The shaded areas show the spatial distribution of zonal velocity STD, which ranges from 5 cm/sec to 20 cm/sec. (b) The trajectories and 2-day mean velocities of the four ARGO drifters (<http://www.usgo-dae.org>) parked at 1000 m during 2002–2004. Circles and asterisks designate the initial and final location of the drifter. Dashed lines denote 1000 m and 3000 m isobath.

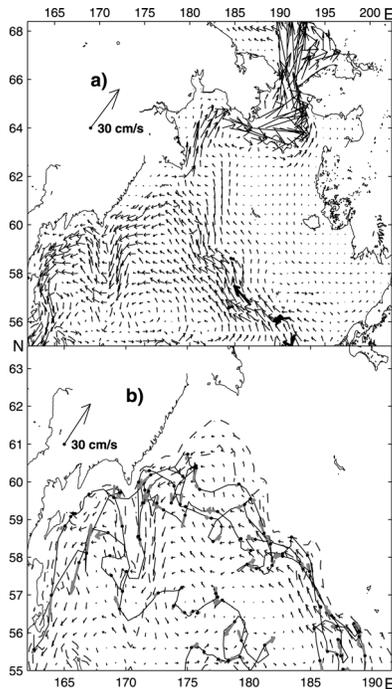


Figure 3. The optimized velocities at (a) 17 m and (b) 1000 m obtained in the experiment A. Thick arrows denote the mean velocities observed at several moorings (Figure 3a) and ARGO velocities at 1000 m (Figure 3b).

operator L acting on the model solution y to compute model-data counterparts (e.g., L can calculate the transports through the open boundaries). The diagonal matrices W_y , $W_{y,s}$ are the variances of the corresponding data and smoothness terms (see Data section).

[13] In the course of \mathcal{J} minimization, the term \mathcal{J}_{data} forces the model solution to be close to the data, the term \mathcal{J}_{smooth} penalizes grid-scale noise. The “stationarity” cost function term \mathcal{J}_{stat} allows us to obtain a quasi-steady state model solution [Tziperman and Thacker, 1989] and to find the estimates of the summer climatological state. The weights W_{y,t_1} and W_{y,t_2} define “degree” of stationarity of model solution. The climatological temperature/salinity distributions and the corresponding geostrophic velocities were used to set up boundary and initial conditions for the first guess solution of the model.

4. Results

[14] The reconstruction of the climatological summer circulation was done using quasistationary variational data assimilation approach proposed by Tziperman and Thacker [1989]. We carried out two numerical experiments:

[15] Experiment A: we assimilated all the observations outlined above, i.e., temperature and salinity climatologies, surface drifter data, the Bering Strait transport, and meteorological data.

[16] Experiment B: we did not assimilate the surface drifter data, but instead, we added to the cost function the transport estimate of 12 ± 4 Sv through the Kamchatka Strait. This outflow estimate is derived from a number of publications implementing the dynamical method calcula-

tions [e.g., Stabeno and Reed, 1992; Verhunov and Tkachenko, 1994].

4.1. Experiment A

[17] The optimized velocity fields obtained in experiment A are shown in Figure 3. General circulation pattern agrees with conventional scheme of the BS circulation, which includes weak currents on the eastern shelf, the Bering Slope current (BSC), the intensive KC along the Eurasian continent, the intensive Navarin Current in the Gulf of Anadir and the strong northward flow in the Bering Strait. The KC originates as a continuation of the BSC at approximately 175° and then flows clockwise around the Shirshov Ridge. The obtained circulation reveals strong topographic steering of the KC. According to our results, in the vicinity of the point 58°N , 170°E the KC splits into two branches. One of these branches (we will call it “coastal branch”) follows northward along the 1000 m isobath, while, the other branch (“off-shore branch”) flows westward across the Kamchatka Basin and joins the coastal branch of the KC near the Karaginsky Island. This is similar to the flow pattern by Stabeno and Reed [1994]. These branches join northeast of the Karaginsky Island resulting in the gradual increase of the KC transport from approximately 14 Sv in the Olyutorski Gulf to 24 Sv in the Kamchatka Strait. The obtained estimate of the KC transport is almost 1.5–2 times higher than the “traditional” estimates derived by dynamical method.

[18] The mean relative error between modeled surface velocities (Figure 3a) and drifter velocities (Figure 2a) is 0.71. This relatively high error can be explained by the high STD of drifter velocities, which reaches 20 cm/s in the BSC (Figure 2a). Despite the high error, the absolute amplitude of the surface velocities in Bering Slope and Kamchatka Currents (Figure 3a) are close to the amplitude of drifter velocities shown in Figure 2a. A limited amount of available mooring velocities (Figure 3a, thick arrows) reveals very good agreement with optimized velocities. Unfortunately, most of these data are located in the eastern part of the BS and cannot confirm the reliability of the KC reconstruction. Because of that, we compare our results with the trajectories of four ARGO drifters (www.usgodae.org), which were launched at 1000 m depth.

[19] Three of these drifters were released in the southeastern part of the BS and were carried by the BSC up to 58° – 59°N where they deflected from the continental slope and drifted across the Aleutian Basin to the Shirshov Ridge, where they joined KC. One of these drifters entered the KC and sailed clockwise around the Shirshov Ridge up to 60°N ; that is, the trajectory of this drifter follows the “coastal” branch of the KC discussed above (Figures 3a and 3b). The fourth drifter entered the BS through the Near Strait (Figure 2b). The drifter crossed the Bowers and Aleutian Basins and joined the KC near the southern end of the Shirshov Ridge (Figure 3b) and drifted clockwise around the ridge. This drifter deflected westward at 58°N , 170°E following the “off-shore” branch of the KC obtained in our results. The splitting of the KC at this point is probably caused by sharp bottom topography changes in the Shirshov Ridge region. Analysis of bottom relief (Figure 1) allows us to speculate, that off-shore branch initially follows the 3000 m isobath and then deflects

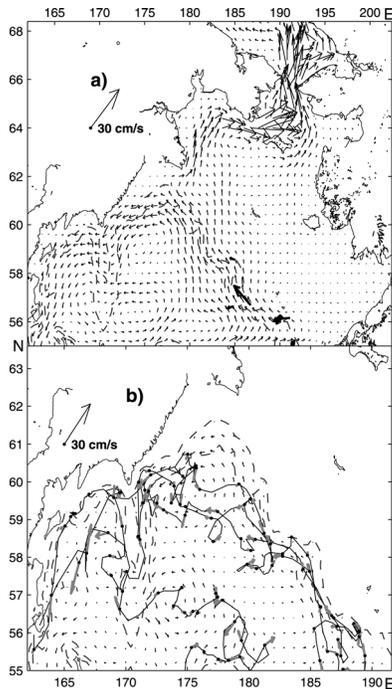


Figure 4. The optimized velocities at (a) 17 m and (b) 1000 m obtained in the experiment B. Thick arrows denote the mean velocities observed at several moorings (Figure 4a) and ARGO velocities at 1000 m (Figure 4b).

246 westward near 58°N , 170°E , while the trajectory of the
247 coastal branch of the KC coincide with the 1000 m isobath.

248 [20] The 2-day mean velocities of the ARGO drifters are
249 shown in Figure 2b. The averaged speed of these four
250 drifters was approximately 4.5 cm/sec. This value is close
251 to the mean 3.5 cm/sec speed of the modeled currents at
252 1000 m (Figure 3b). That seems to be a good agreement
253 with observations, because Lagrangian velocity estimates
254 tend to be larger than Eulerian.

255 4.2. Experiment B

256 [21] Velocity field obtained in experiment B are shown in
257 Figure 4. The solution without drifter data assimilation
258 retains most of the features of the BS circulation [Stabeno
259 and Reed, 1994] and visually the circulation pattern is
260 similar to the circulation in Figure 3. Meanwhile, the
261 detailed analysis reveals both qualitative and quantitative
262 differences.

263 [22] For example, the BSC in the experiment B does not
264 deflect westward in the vicinity of 59°N and continues to
265 follow the slope up to 62°N . That contradicts to the
266 trajectories of all ARGO drifters in this region (Figures 2b
267 and 4b). Both surface and deep velocities in Figure 4 do not
268 reveal “branching” of the KC on the western slope of the
269 Shirshov Ridge (58°N , 170°E), which is supported by
270 ARGO drifters trajectories.

271 [23] The quantitative analysis of the velocity fields
272 reveals even stronger difference between velocities in Fig-
273 ure 4 and observations. On the level of 1000 m, the
274 averaged speed in the experiment B (Figure 4b) is approx-
275 imately 1.5 cm/s, which is more than two times smaller than
276 the velocities in the experiment A (3.3 cm/s) and three times

smaller than the observations of ARGO floats (4.5 cm/s). 277
Similar differences can be observed in the surface layer: the 278
surface velocities in the experiment B in the vicinity of 279
Kamchatka Strait is only about 5 cm/sec, while the drifters 280
give the averaged estimate of 20–30 cm/s. Overall we can 281
state, that the velocity field obtained in the experiment B 282
only approximately agrees with the available velocity 283
observations. 284

5. Conclusions 286

[24] The performed numerical experiments and compar- 287
ison with surface and ARGO drifters reveal the splitting of 288
the BSC in the vicinity of 58°N 180°E and KC on the 289
western slope of the Shirshov Ridge and indicate that 290
traditional transport estimate of 12 Sv through the Kam- 291
chatka Strait is not a realistic climatological estimate. The 292
most probable climatological summer state (experiment A) 293
derived from the assimilation of all available data 294
[Thacker, 1989] shows that the transport of the KC 295
increases gradually from 14 Sv in the Olyutorsky Gulf to 296
24 Sv in the Kamchatka Strait. Our KC transport estimate 297
is in a good agreement with the 20 Sv summer KC 298
transport obtained by combining the section hydrophysical 299
data and surface floats data by Hughes *et al.* [1974]. Also, 300
higher than traditional transport estimates has been 301
obtained recently by Stabeno *et al.* [2005]. This paper 302
provides the analysis of the direct velocity measurements 303
and derives the inflow estimate into the Bering Sea of 4 Sv 304
through the Amutka Pass, which is five times higher than 305
the previous estimates. 306

[25] We speculate that the difference between the tradi- 307
tional transport estimates and the results of the present study 308
can be explained by some underestimation of the barotropic 309
velocity component in the Bering Sea in the traditional 310
transport estimates. To support this speculation we calculat- 311
ed baroclinic transport through the Kamchatka Strait by 312
dynamical method with zero bottom velocities from hydro- 313
graphic data utilized in the paper. Our estimate of the 314
baroclinic transport of approximately 10 Sv appeared to be 315
very close to the traditional transport estimates cited in 316
the literature [Ohtani, 1970; Verhunov and Tkachenko, 317
1994]. 318

[26] Due to the model limitations the study region does 319
not extend south of 55°N . In the future we plan to apply 320
similar technique for the reconstruction of BS circulation 321
within its natural boundaries (Aleutian Arc and Bering 322
Strait) and to provide comprehensive analysis of the tem- 323
perature/salinity distributions and posterior error analysis. 324

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- M. Ikeda, Graduate School of Environmental Earth Science, Hokkaido 379
 University, Sapporo 060-0810, Japan. 380
- V. A. Luchin, Il'ichev Pacific Oceanological Institute, Far Eastern 381
 Branch, Russian Academy of Science, Vladivostok 690041, Russia. 382
- D. A. Nechaev, Department of Marine Science, University of Southern 383
 Mississippi, Stennis Space Center, MS 39529–9904, USA. 384
- G. G. Panteleev, International Arctic Research Center, University of 385
 Alaska Fairbanks, Fairbanks, AK 99775–7335, USA. (gleb@iarc.uaf.edu) 386
- P. Stabeno, Pacific Marine Environmental Laboratory, Seattle, WA 387
 98115–6349, USA. 388