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<tr>
<td>Citation</td>
<td>Physical Review B, 80(23): 235409</td>
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<tr>
<td>Issue Date</td>
<td>2009-12-15</td>
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<tr>
<td>Doc URL</td>
<td><a href="http://hdl.handle.net/2115/42549">http://hdl.handle.net/2115/42549</a></td>
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<td>File Information</td>
<td>PRB80-23_235409.pdf</td>
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Nanoscale mechanical contacts probed with ultrashort acoustic and thermal waves

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Using an ultrafast optical technique we measure coherent phonon-pulse reflection from—and heat flow across—a mechanical contact of nanoscale thickness between a thin metal film and a spherical dielectric indenter. Picosecond phonon wave packets at ~50 GHz returning from this interface probe the pressure distribution, the contact area, and the indentation profile to subnanometer resolution, revealing the film deformation in situ. These measurements and simultaneous thermal-wave imaging at ≥1 MHz are consistent with significant enhancement of phonon transport across the near-contact nanogap.

I. INTRODUCTION

The properties of mechanical contacts between solids depend on how individualasperities mesh on the nanoscale, and a physical understanding is vital in engineering for the study of friction, lubrication, and electrical or heat conduction as well as in biology for the study of cell-membrane adhesion or joints. A generic approach to studying static mechanical contacts that facilitates the separation of elastic and plastic behaviors is the use of microscale or macroscale spherical (Hertz) indenters. This geometry is an apt choice for the lateral imaging of the contact by penetrating wave fields.

The contact area can be imaged by optical interferometry combined with microscopy. Ultrasonic imaging, applicable also to opaque materials, allows one to map in addition the interfacial stiffness or the contact pressure. However, with a spatial resolution on the order of the ~0.1 mm acoustic wavelength at the typical maximum frequencies ~30 MHz used, one cannot effectively probe nanoscale deformations. Neither can one accurately study interfaces with nanoscale roughness. Likewise, probing mechanical contacts using modulated thermoreflectance up to the maximum frequencies ~3 kHz used is limited in spatial resolution by the ~30 μm thermal-diffusion length. One can image nanoindentation processes in a transmission electron microscope with subnanometer resolution, but this technique is not suited to spatially resolved mapping over the contact area.

In this paper we implement much shorter acoustic and thermal wavelengths to map the deformation in or near a Hertz mechanical contact of nanoscale thickness. We introduce an in situ coherent phonon and thermal-profiling technique at frequencies ~100 GHz and ≥1 MHz, respectively, more than 1000 times higher than previously used in contact mechanics.

II. EXPERIMENTAL SETUP

The setup is shown in Fig. 1(a). The sample is a 110-nm polycrystalline Cr film sputtered on a (0001) sapphire substrate of thickness 0.8 mm. The sample lies on a rigid holder pierced with a 1.8-mm radius hole for optical access. A sintered silicon-nitride sphere of diameter 5.96 mm is indented into the pristine Cr film using a high-precision displacement stage. The applied load, stable at each setting to ±5% over several hours, is measured with a load cell. To investigate contacts with nanoscale separations, we use highly polished surfaces. The rms roughnesses of the film, indenter and substrate, determined by atomic force microscopy (AFM) with 40-nm step size [see Fig. 1(b)], are σp=3 nm, σi=13 nm, and σs=1 nm, respectively. Picosecond longitudinal coherent-phonon pulses are thermoelastically generated at the film-substrate (f-s) interface with linearly polarized optical pump pulses of duration 200 fs, repetition frequency 80 MHz, wavelength 810 nm (optical reflectivity 0.23), and pulse energy E=0.5 nJ from a Ti:sapphire mode-locked laser. This light is chopped at 1.1 MHz for thermal-wave excitation and lock-in detection. The reflectivity change δR(t) is measured with frequency-doubled circularly polarized probe pulses of wavelength λpb=405 nm (reflectivity Rb=0.29) and energy 0.06 nJ as a function of the pump-probe time delay t. The coaxial pump and probe beams are circularly polarized at 45° to match the probe reflectivity change.

FIG. 1. (Color online) (a) Setup. (b) AFM traces. (c) δR(t)/Rb at F=4.2 N. The theory out of contact is shown displaced. Inset: normalized experimental echoes.
and probe beams are focused at the f-s interface by a laterally scanned ×50 objective lens to spots of radii \(w_1=1.9\ \mu m\) and \(w_2=1.1\ \mu m\) (intensity at 1/e²), respectively [effective radius \(w=\left(w_1^2+w_2^2\right)^{1/2}=2.2\ \mu m\)]. Pertinent physical properties are the longitudinal sound velocity \(v_n\), density \(\rho_n\), Poisson’s ratio \(\nu_n\), Young’s modulus \(E_n\), thermal conductivity \(\kappa_n\), and heat capacity \(C_n\), with \(n=i, f, s\) for the indenter, film, and substrate.\(^{15}\)

### III. RESULTS FOR THE ACOUSTIC EXPERIMENTS

#### A. Shape of the acoustic echoes

Figure 1(c) shows the amplitude \(|\delta R(r)/R_0|\) (where \(\delta R<0\)) for the load \(F=4.2\ \text{N}\) in and out of contact.\(^{16}\) \(\delta R \approx E\) was checked up to pump-pulse energy \(E=0.5\ \text{nJ}\). For \(t<0\), \(|\delta R|\) is lower in contact due to thermal-wave effects, as discussed later. At \(t=0\) we observe a peak followed by a dip and then a rise in \(|\delta R/R_0|\) at \(t=10–20\ \text{ps}\). This is due to the cumulative effects of a transient-temperature rise\(^{17}\) \(\Delta T \approx 500\ \text{K}\) \((\Delta T<0)\) and strain generation.\(^{12,18}\)

Initially a hydrostatic compressive stress field is generated in Cr over a depth \(z_{ac} \approx 35\ \text{nm}\) determined by the optical skin depth \(\approx 30\ \text{nm}\) (Ref. 19) and the electron diffusion depth \(\approx 15\ \text{nm}\).\(^{14}\) The acoustic impedances \(Z_n=\rho_n v_n\) of Cr and Al₂O₃ imply a low film-substrate reflection coefficient \(r_f=(Z_f-Z_i)/(Z_f+Z_i)=-0.04\), so two unipolar compressive coherent-phonon pulses (of strain amplitude \(\approx 10^{-3}\)) are launched perpendicular to the f-s interface in both materials.\(^{20}\) In Al₂O₃ these pulses create oscillations in \(\delta R\) (visible after 40 ps) at the Brillouin frequency \(2n_i v_i/\lambda_{dB}=100\ \text{GHz}\), with \(n_i=1.76\) the Al₂O₃ refractive index.\(^{20,22}\) In Cr a broadband picosecond strain pulse of frequency \(0<f\leq 100\ \text{GHz}\) (Ref. 23) and wavelength \(\lambda \approx 70\ \text{nm}\) is reflected from the film-indenter (f-i) interface with a reflection coefficient \(r_f\) (determined later). This pulse is detected at the f-s interface as an echo at \(30\ \text{ps}\). Because of the low value of \(r_f\), only one echo is resolved. Echoes normalized using \(r_f\) in and out of contact are shown in Fig. 1(c). When in contact the echo arrives earlier, is reduced in height, and is asymmetrically distorted, although the echo spectrum is not significantly changed. The echo shape depends on the longitudinal strain \(\eta\) that in the near-surface region can be written in the approximate form\(^{12,14}\)

\[
\eta(z,t) \approx G(z-v_f t) \exp\left((v_f t-z)/z_{ac}\right),
\]

where \(G\) is the half unit step function and \(z\) is the depth. We combine this equation with an ultrasonic attenuation that rises quadratically with the frequency for Cr in the GHz range.\(^{14}\) The resulting \(\eta(z,t)\) allows one to derive the expected reflectivity variation that arises through the photoelastic effect.\(^{12,24}\)

The central curve in Fig. 1(c) shows the predicted \(|\delta R(r)/R_0|\) out of contact using the photoelastic constant \(p_{12}^{\text{PE}}=-0.03\) for Al₂O₃ (Ref. 21) and the fit \(p_{12}^{\text{fit}}=0.28+0.001v_1\) for Cr. For the Cr film in this study, ultrasonic attenuation \(\beta=600\ \text{m}^{-1}\) (in GHz) gives the best fit to the echo with a film thickness \(h=110\ \text{nm}\).\(^{14,25}\)

#### B. Profiles of the acoustic reflection coefficient

A left-right average of the base of the echo determines the echo height. Setting \(r_f=-1\) outside the contact determines the in-contact value. We plot \(|r_f|\) vs radial coordinate \(r\) in Fig. 2(a) for load \(F=2.1\ \text{N}\) in 4-μm steps. The fluctuations, showing some correlation with scans at different \(F\), are caused by surface roughness. Over the contact, \(|r_f|\) decreases to 0.8. For a perfect contact, \(r_f=r_{f0}=(Z_f-Z_i)/(Z_f+Z_i)=-0.17\). Intermittial air gaps, shown in Fig. 1(b), result in a larger \(|r_f|\). As \(F\) increases, the total asperity (i.e., real) contact area increases, and \(|r_f(r=0)|\) decreases. We can empirically fit our data with \(|r_f(r=0)|=1-\left(F/F_{\text{1/10}}\right)^{0.4}\), with \(F\) in N. To obtain further insight into the local variations within the contact, we must calibrate our results in terms of pressure.

We first estimate the contact radius \(a\) from Hertz theory\(^{1}\) for a sphere indenting a frictionless half space

\[
a^3 = 3FD/8E^*,
\]

where \(E^*=[(1-v_f^2)/E_1+(1-v_i^2)/E_3]^{-1}=200\ \text{GPa}\) is the effective modulus. We derive \(a\) from \(|r_f(r)|\) and compare it to theory in Fig. 2(b). The data lie above the predictions, consistent with theories for elastically indented thin films for \(E_i/E_f<1.36\). To apply Hertz theory, the combined surface roughness \(\sigma=\left(\sigma_f^2+\sigma_i^2\right)^{1/2} \approx 13\ \text{nm}\) should also be considered. In our case the roughness parameter \(\alpha=\sigma D/2a^2\)< 0.07 is 1 for \(F>1.1\ \text{N}\), so Hertz theory is valid.\(^1\) We thus use the Hertz pressure

\[
p(r)=p_0(1-(r/a)^2)^{3/2},
\]

with maximum value \(p_0=3F/2\pi a^2\), to derive \(|r_f(p_0)|\) from the measured \(|r_f(F)|\) at \(r=0\). We see a linear decrease \(|r_f(p_0)|=1-p_0/p_1\) in Fig. 2(c) with \(p_1=6.1\ \text{GPa}\). This pro-
vides a calibration to obtain \( p(r) = p_f [1 - |r_f(r)|] \), showing good agreement with theory in Fig. 2(d). Before discussing these results in detail we first present the results for film indentation.

C. Profiles of the indentation

Uniquely, with picosecond ultrasonics we can directly extract the film indentation \( \Delta h = \frac{v_i}{2} \Delta t / 2 \) from the echo arrival-time variation \( \Delta t \) during loading.\(^{27}\) \( \Delta h(r) \), plotted in Fig. 2(e), varies over regions slightly larger than the contact radii \( a \), as expected. Striking correlation at each load \( F \) between the fluctuations in \( \Delta h(r) \) and \( p(r) \) [see dashed line in Fig. 2(e)] confirms that these are indeed induced by roughness. Finer scale data at \( r = 0 \) is shown in Fig. 2(f) for a first-load-unload cycle in steps of 0.5 N lasting 10 min per point. The overall shape of \( F \) vs \( \Delta h \) is evidently governed by elasticity. The application of linear elasticity theory for a thin Cr film on a rigid substrate indented by a rigid sphere leads to the following equation:\(^{28}\)

\[
F = \pi D \rho r_0^2 \Delta h^2 / 2h. \tag{4}
\]

The predicted load-indentation curve is shown by the dashed line in Fig. 2(f). Unsurprisingly, the measured \( \Delta h \) (<6 nm) is smaller because of the indenter and substrate elasticity. In comparison, the deformation of the substrate-indentner system is much larger: \( \delta = 2w^2 / D > 180 \) nm for \( F > 1.1 \) N.\(^1\)

A permanent plastic deformation ~1 nm remains after unloading [see arrows in Fig. 2(f)]. However, the Vickers hardness \( H = 15 \) GPa of thin-film Cr,\(^{29}\) the softer material, indicates that the maximum pressure \( \rho_i = 1.5 \) GPa is not sufficient for bulk-film yielding.\(^1\) This justifies the use of linear elastic theory for the bulk deformation of Cr. In order to understand the origin of the plasticity, one should consider the asperity deformation. For our Gaussian distribution of asperity heights, this is governed by the so-called plasticity index:\(^2,30\)

\[
\psi = (E^*/H) (\sigma r_0)^{1/2}. \tag{5}
\]

Here \( \psi \geq 3 \), where \( r_0 \leq 0.3 \) \( \mu m \) is the AFM-measured average \( \text{Si}_3\text{N}_4 \) asperity radius; \( \psi > 1 \) indicates Cr plastic compression by the harder \( \text{Si}_3\text{N}_4 \). For noninteracting asperities, overall force balance dictates that \( S_z H = S_0 \rho_i \), where \( S_z \) and \( S_0 \) are the real and nominal contact areas, respectively.\(^2,4\) At the maximum load \( F = 4.2 \) N, \( S_z / S_0 = 0.1 \) at \( r = 0 \). Using the measured \( \text{Si}_3\text{N}_4 \) rms roughness \( \sigma_f = 13 \) nm and rms surface slope 0.2 rad, we estimate a corresponding contact clearance \( u \sim 15 \) nm, with an average asperity contact radius \( R_a \sim 60 \) nm at a density \( N_a \sim 10 \) \( \mu m^{-2}.31\) This order of magnitude for \( u \) demonstrates that picosecond ultrasonics is exquisitely sensitive to the closing of nanoscale gaps between solids.

D. Interpretation of the results for acoustic reflection coefficient

Precise modeling of \( |r_f| \) from contacts is complicated by the broadband strain pulse. At very low frequencies, it is common to assume the presence of a thin interlayer of thickness \( l \), density \( \rho \), and longitudinal sound velocity \( v \), or a contact stiffness per unit area \( K = \rho v^2 / l.32-35\) For plastic deformation of asperities, each of Hertz stiffness \( 2E^*R_a l^{-1/2} \), \( K = 2E^*R_a N_a \ll 0.2 \) GPa nm\(^{-1}.3\) This implies a reduced \( |r_f| \) for \( f \leq K/(2\pi Z_f) = 0.7 \) GHz (\( \Lambda \approx 10 \) \( \mu m \)). However, this results in a negligible change in \( |r_f| \), inconsistent with the observed ~25% reduction at \( F = 4.2 \) N. Since wavelengths \( \Lambda \approx 70 \) nm \( \sim R_a \) are present at the \( f \)-i interface, this model should be replaced by a theory of acoustic scattering from nanoscale contacts.

To this end, consider the diffraction of a strain pulse, of radial dependence \( \eta_f \propto \exp(-r^2 / w_i^2) \) governed by the pump spot of radius \( w_i \), generated at the \( f \)-s interface. The \( z \) and \( t \) dependences in \( \eta_f \) are implicit here. This pulse reaches the \( f \)-i interface in the near field without lateral spreading since the Cr thickness satisfies the relation \( h \ll w_i / \Lambda \). Provided \( R_a > \Lambda / 2\pi \), reasonable only at frequencies \( f > 20 \) GHz, each contacting asperity can be approximated to have a reflection coefficient \( |r_f| = 0.17 \), assuming negligible mode conversion.\(^36\) We define a corresponding normalized top-hat function \( T(r - d_i) \), where \( r \) and \( d_i \) are, respectively, the in-plane position vector and that of the \( i \)-th asperity. The reflected field \( \eta_f(r) \) at the \( f \)-i interface is then

\[
\eta_f(r) = \eta_f(r) - (1 - |r_f(r)|) \sum_i T(r - d_i) \eta_f(r_i). \tag{6}
\]

Applying Babinet’s principle to the diffraction of this discontinuous source—analogous to a holey cheese—over the propagation length \( h \ll w_i / \Lambda \). Provided \( \eta_f \propto \exp(-r^2 / w_i^2) \), each contacting asperity can be approximated to have a reflection coefficient \( |r_f| = 0.17 \), assuming negligible mode conversion.\(^36\) We define a corresponding normalized top-hat function \( T(r - d_i) \), where \( r \) and \( d_i \) are, respectively, the in-plane position vector and that of the \( i \)-th asperity. The reflected field \( \eta_f(r) \) at the \( f \)-i interface is then

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\[
\eta_f(r) = \eta_f(r) - (1 - |r_f(r)|) \sum_i T(r - d_i) \eta_f(r_i). \tag{6}
\]
radial scans of $|\delta R/R_0|$ at $t=-10$ ps to avoid acoustic effects. The probed temperature variation is $A\sin(\omega t + \phi)$, where $\sin \omega t$ is in phase with the chopping at 1.1 MHz and $\phi$ is the phase lead recorded by the lock-in amplifier. $|\delta R/R_0| \propto A [-70 K$ (Ref. 17)], normalized with respect to its out-of-contact value, and phase lead $\phi$ are plotted vs $r$ in Fig. 3(c). The contact radius, determined from the initial rise $a$ or decrease $\phi$ [arrows in Fig. 3(c)], agrees with Hertz theory. At larger $r$, $A$ saturates, whereas $\phi$ shows a sharp minimum. Both remain constant over the contact area for $F \geq 1.1$ N.

Confirmation of these results in two spatial dimensions is shown for $|\delta R/R_0|$ in Fig. 3(a) for a $200 \times 200 \mu m^2$ region scanned in $1-\mu m$ steps.\(^{38}\) We resolve the circular contact area as well as low-contrast Newton’s rings.\(^{3}\) These arise from variations in pump-light absorption on residual transmission to the $f$-$i$ air gap.\(^{19}\) The derived air gap agrees with Hertz theory [see Fig. 3(b)].

B. Interpretation of the thermal profiles

The three-dimensional (3D) thermal-diffusion equation was solved for a sinusoidal spatially Gaussian heat source (of radius $w=2.2 \mu m$) at the $f$-$s$ interface with an air gap $d$ below a flat and parallel (in practice to $<1^\circ$) Si$_3$N$_4$ surface. The effect of the periodic laser-pulse trains when probing at the chopping frequency was also included using a sum arising from harmonics of the 80 MHz repetition rate.\(^{40}\) Harmonics up to order $\approx 2000$ (corresponding to $\approx 160$ GHz thermal waves) give a non-negligible contribution here, but only those with frequencies $\approx 1$ GHz ($\mu_s=\infty$) probe the $f$-$i$ interface.

The predictions for $A(d)$ and $\phi(d)$ are compared to experiment on a normalized scale in Fig. 3(d), assuming literature values of thermal properties.\(^{15,41}\) Thermal-boundary resistances $R_{ts}=1.3 \times 10^{-7}$ and $R_{st}=1.0 \times 10^{-7}$ K m$^2$ W$^{-1}$ at the $f$-$s$ and $f$-$i$ interfaces (the latter for $d=0$ only) are determined by matching the contrast in $A$ and the difference $\Delta \phi$ in $\phi$ in and out of contact.\(^{32}\) Standard models\(^{43}\) based on acoustic mismatch, constricted, and electron-phonon resistances give values of a similar order. However, in experiment $\phi(d)$ shows a minimum.\(^{44}\) $A(d)$ also varies more slowly;\(^{45}\) this points to enhanced heat transport through the gap for $d \leq 50$ nm. At 293 K and 1 atm, the molecular mean-free path and the Knudsen number are $L=60$ nm and $Kn=\frac{L/d}{0.6}$ (for $d<100$ nm).\(^{46}\) For this “near-continuum” regime, ballistic heat transport competes strongly with diffusion. The ratio of the thermal conductances in the diffusive ($K_d=K_s/d$) (Ref. 41) and near-continuum ($K_{nc}$) regimes is

$$\frac{K_d}{K_{nc}} = 1 + \frac{4\gamma}{\gamma+1} \frac{\alpha_s}{\alpha_l} \frac{K_l}{Pr},$$

with $\gamma=7/5$ for a diatomic gas and $Pr=0.72$ the Prandtl number in air.\(^{2,46}\) $\alpha_s$ and $\alpha_l$ are the film and indenter accommodation coefficients ($<1$). Gap heat transport should therefore be overestimated ($K_d/K_{nc} \approx 3$) (Ref. 47), so kinetic theory fails to explain the anomaly in $A$. Another possibility is near-field thermal radiation.\(^{38}\) But to account for our results would require a $K_d/4\sigma g T^3 \approx 10^7$ enhancement compared to the blackbody value, where $\sigma g$ is the Stefan-Boltzmann constant, an implausible factor for dissimilar materials. Although Hertz theory explains the acoustically determined contact radius $a$, it may be that surface roughness plays a role in explaining the anomalies. The roughness parameter $a_l \approx 0.05$ implies some contact even at radii $1.3a_l$.\(^{3}\) Compared to the coherent acoustic phonons, the efficient transmission of the much shorter wavelength incoherent thermal phonons through the asperities should therefore broaden the thermal-wave-probed contact area. However, the anomalies in amplitude and phase occur at a gap thickness of $\approx 50$ nm, a value that is seemingly too large to be accounted for by the smaller rms surface roughnesses of the contacting Cr and Si$_3$N$_4$. A theory accounting for the detailed geometry of the asperity penetration into the gap, an intermediate region in which asperities and air coexist, is required. To elucidate the thermal anomalies we observe, measurements with different indenters in evacuated chambers should be carried out to reveal the physics of asperity deformation and thermal transport through the nanowire-like connections that connect the contacting bodies.

V. CONCLUSION

In conclusion, we demonstrate that nanoscale acoustic waves excited with ultrashort optical pulses show enhanced coherent phonon transport between or enhanced scattering from solids in mechanical contact. In addition, we demonstrate that optically excited microscale thermal waves show enhanced incoherent phonon transport across the gap between solids under near-contact conditions. These findings should be investigated in the future by experiments on different contacting materials, on a range of surface roughnesses, and with a variety of gases or a vacuum in the contact region. In addition, further measurements using coated
transparent indenter with the pump and probe light incident on opposite sides of the interface will allow phonon transmission to be monitored. Accessing nanometer indentation with high-frequency phonons also opens the way to mapping deformation or plastic flow in a wide variety of materials—whether metallic, semiconductor, or dielectric—and to direct probing of the effects of wear and friction in nanomechanical systems.

35 Such theories have also been applied in picosecond ultrasonics to ultrathin layers. See, Ref. 13 or G. Tas, J. J. Loomis, H. J. Maris, A. A. Bailes, and L. E. Seiberling, Appl. Phys. Lett. 72, 2235 (1998).
38 Acoustic transmission at ~50 GHz only occurs for air gaps <0.1 mm (see Ref. 7). Intermittent contact at our acoustic displacements ~0.1 nm has negligible influence as does a ~2 nm water layer under our conditions of 35% humidity. See J. Israelachvili, Intermolecular and Surface Forces (Academic, London, 1985).
39 This data was taken at t~4 ps. The contrast at this time is mainly determined by the temperature changes.
41 For air at 300 K, μa=1.01 g m⁻³, μv=0.26 W m⁻¹ K⁻¹, and C=1.02×10⁶ J m⁻³ K⁻¹ (see Ref. 21).
42 Reduction in Rf leads to similar results, consistent with the observed saturation in A and φ for F~1.1 N.
44 The predicted φ in and out of contact are ~14.4° and ~17.9°.
45 Preliminary measurements of (A/df for an h=215 nm and σf ~7 nm film [T. Dehoux, R. Li Voti, and O. B. Wright unpubl.] showed similar trends.