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Phase transition to a two-peak phase in an information-cascade voting experiment

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Observational learning is an important information aggregation mechanism. However, it occasionally leads to a state in which an entire population chooses a suboptimal option. When this occurs and whether it is a phase transition remain unanswered. To address these questions we perform a voting experiment in which subjects answer a two-choice quiz sequentially with and without information about the prior subjects' choices. The subjects who could copy others are called herders. We obtain a microscopic rule regarding how herders copy others. Varying the ratio of herders leads to qualitative changes in the macroscopic behavior of about 50 subjects in the experiment. If the ratio is small, the sequence of choices rapidly converges to the correct one. As the ratio approaches 100%, convergence becomes extremely slow and information aggregation almost terminates. A simulation study of a stochastic model for 10^6 subjects based on the herder's microscopic rule shows a phase transition to the two-peak phase, where the convergence completely terminates as the ratio exceeds some critical value.

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I. INTRODUCTION

The tendency to imitate others is one of the basic instincts of humans. People effectively and inadvertently act as filters to provide the information that is most useful for an observer. Imitation and copying is a highly adaptive means of gaining knowledge [1]. It presumably results from an evolutionary adaptation that promoted survival over thousands of generations. It allows individuals to exploit the hard-won information of others [1,2]. However, imitating or copying others has disadvantages. The acquired information might be outdated or misleading [2,3]. Copying wrong information might lead to herding, where an entire population makes a wrong decision. This is referred to as an information cascade or rational herding [4–7]. Unfortunately, because imitation is a basic instinct and because it is economically rational to copy others, humans might not be able to evade such a catastrophic situation [4]. Social influences have many forms, including imitation, conformity, and obedience [8]. Recent studies in cognitive neuroscience suggest that some type of imitation occurs automatically via the actions of “mirror neuron” systems [9].

In the field of social psychology, many studies have focused on how humans use social information at the microscopic level [2,10]. In the field of finance and economics, it is now widely believed that investors are influenced by the decisions of others and that this influence is a first-order effect [4,5]. We now have a number of interesting models of rational herding based on simple, straightforward, and convincing intuition [4,5,11–17]. Empirical financial research has focused on macroscopic data primarily because such data are easily available. Microscopic

and macroscopic aspects of the information cascade have been studied in Ref. [18]. It was concluded that the information cascade is fragile and self-correcting. Even if the population makes a wrong decision at a point in the choice sequence, it will eventually turn to a correct choice. The analysis was based on a stochastic model and the asymptotic behavior of the empirical choice sequences was not studied in detail. In order to study the nature of the information cascade and furthermore the possibility of a phase transition, it is necessary to connect the microscopic and macroscopic aspects while depending on a model assumption as little as possible. However, thus far, no empirical work has directly connected the microscopic and macroscopic aspects of the information cascade and herding.

Two types of phase transitions have been predicted in a two-choice voting model depending on the strength of conformity of the people [19,20]. We set two types of individuals: herders and independents. The voting of independents is based on their fundamental values, while the voting of herders is based on the number of previous votes. If the herders are analog herders and they vote for each choice with probabilities that are proportional to the choices' votes, a transition occurs between the superdiffusion and normal diffusion phases [19]. If the independents are the majority of voters, the voting rate converges at the same rate as in a binomial distribution, which is called the normal diffusion phase. As the proportion of herders is over 50%, the voting rate converges more slowly than in a binomial distribution: This is called the superdiffusion phase. However, the presence of herders does not affect the accuracy of the majority's choice. If the independents vote for the correct choice rather than for the wrong one, the majority of voters always choose the correct choice. The probability distribution of the voting rate has only one peak and these two phases are collectively referred to as the one-peak phase. In the

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digital herder case, where herders always choose the choice with the majority of previous votes, the majority's choice does not necessarily coincide with the correct choice, even if the independents vote for the correct choice rather than for the wrong one. When the fraction of herders increases, a phase transition occurs, beyond which a state where most voters choose the correct choice coexists with one where most of them choose the wrong one [20]. If the fraction of herders is below the threshold value, most voters choose the correct choice and the system is in the one-peak phase. If the fraction is above the threshold value, the distribution of the voting rate has two peaks corresponding to the two coexisting states: This phase is called the two-peak phase. We call the phase transition between the one-peak and two-peak phases the information cascade transition.

In this paper we have adopted an experimental and a theoretical approach to the study of the phase transitions in the information cascade. The organization of the paper is as follows. We explain the experiment's design and procedure in Sec. II. Section III is devoted to the analysis of the data of the experiment. We show that varying the ratio of herders leads to qualitative changes in the asymptotic behavior of the convergence of the voting rate. In Sec. IV we introduce a stochastic model that simulates the system. We obtain a microscopic rule regarding how herders copy others. We perform a simulation study of a stochastic model for 10^6 subjects based on the herder's microscopic rule. The model shows the information cascade transition to the two-peak phase, where the convergence completely terminates as the ratio exceeds some critical value. Section V is devoted to the conclusions. In the Appendixes we explain the experimental setup in detail.

II. EXPERIMENT'S DESIGN AND PROCEDURE

The experiments reported here were conducted at the Information Science Laboratory at Kitasato University (KU) and at the Group Experiment Laboratory of the Center for Experimental Research in Social Sciences at Hokkaido University (HU). The subjects included students from the two universities. We call the former experiment KUE and the latter HUE. In KUE (HUE), the number of individuals T was 31 (52). We prepared two groups of subjects, group A and group B. In total, 62 (104) subjects participated in KUE (HUE). There were two sequences of subjects and we denote the order of each subject by $t \in \{1, 2, \dots, T\}$. The number of questions M in the two-choice quiz is 100 (120) in KUE (HUE). Interaction between subjects in each group was permitted only through the social information given by the experimenter (face-to-face) in KUE or by the experiment server (Web) in HUE. Table I summarizes the design.

TABLE I. Experiment's design.

Experiment	T	$\{r\}$	M	Subject pool	System
KUE-A	31	$\{0, 1, 2, 3, 5, 7, 9, \infty\}$	100	KU	face-to-face
KUE-B	31	$\{0, 1, 2, 3, 5, 7, 9, \infty\}$	100	KU	face-to-face
HUE-A	52	$\{0, 1, 5, 11, 21, \infty\}$	120	HU	Web
HUE-B	52	$\{0, 1, 5, 11, 21, \infty\}$	120	HU	Web

The subjects answered the quiz individually with and without information about the previous subjects' choices. This information, called social information, is given as the summary statistics of the previous r subjects $\{C_0(r, t), C_1(r, t)\}$. We denote the $(t + 1)$ th subject's answer for case r by $X(r, t + 1)$, which takes the value 1 (0) if the choice is true (false). $\{C_0(r, t), C_1(r, t)\}$ are the numbers of subjects who choose each choice among the prior r subjects as $C_1(r, t) = \sum_{t'=t-r+1}^t X(r, t')$ and $C_0(r, t) = r - C_1(r, t)$. The choice of r is $r \in \{r\} = \{0, 1, 2, 3, 5, 7, 9, \infty\}$ ($\{0, 1, 5, 11, 21, \infty\}$) in KUE (HUE). Here $r = 0$ means that the subjects receive no information and must answer with their knowledge only. In the case $r = \infty$, the summary statistic is calculated from all previous subjects' choices. The subjects answered the quiz with their knowledge only ($r = 0$) initially. Next, they answered with $\{C_0(r, t), C_1(r, t)\}$ from $r = 1$ to ∞ in increasing order of r in the set $\{r\}$. Any differences between the choices in $r = 0$ and $r \geq 1$ can be attributed to the social information.

Figure 1 shows the experience of the subjects in HUE more concretely. The subjects entered the laboratory and sat in the partitioned spaces. After listening to a brief explanation about the experiment and the reward, they logged into the experiment website using their IDs and started to answer the questions. A question was chosen by the experiment server and displayed on the monitor. First, subjects answered the question using their own knowledge only ($r = 0$). Later, subjects received social information and answered the same question. Figure 1 shows the cases $r = 1$ and ∞ . Subjects could then use or ignore the social information when making decisions.

A. Experiment's procedure

We here explain in detail the procedure and the experience of the subjects in the experiment.¹ A subject answered a question with no public information ($r = 0$) initially. The answer was denoted as $X(0, t)$ for the t th subject in the subjects' sequence. If the subject was first ($t = 1$), the subject answered only in the case $r = 0$. The answer $X(0, 1)$ was copied to $X(r, 1)$ as $X(r, 1) = X(0, 1)$ for $r \geq 1$ for later convenience. If $t > 1$, the experimenter (in KUE) or the server (in HUE) calculated the social information $\{C_0(r, t), C_1(r, t)\}$ and gave it to the subject. If $t = 2$, the subject answered the question in the case $r = \infty$ with $\{C_0(\infty, 1), C_1(\infty, 1)\}$ and the answer was denoted by $X(\infty, 2)$. Here $C_1(\infty, 1)$ is $X(0, 1)$. By the convention $X(r, 1) = X(0, 1)$ for $r \geq 1$, we can write $C_1(\infty, 1) = X(\infty, 1)$. As $C_1(1, 1) = C_1(\infty, 1)$, we copy $X(\infty, 2)$ to $X(1, 2)$ as $X(1, 2) = X(\infty, 2)$. As in $t = 1$, $X(1, 2) = X(\infty, 2)$ is copied to $X(r, 2)$ as $X(r, 2) = X(1, 2)$ for $r > 1$. If $t = 3$, the subject answered the question in the case $r = 1$ with $\{C_0(1, 2), C_1(1, 2)\}$ and the answer was denoted by $X(1, 3)$. The social information $\{C_0(1, 2), C_1(1, 2)\}$ was calculated with the answer $X(1, 2)$ as $C_1(1, 2) = X(1, 2)$ by the copy convention $X(1, 2) = X(\infty, 2)$. Then the subject answered in the case $r = \infty$ and the answer was denoted by $X(\infty, 3)$. The social information $C_1(\infty, 2)$ is $C_1(\infty, 2) = X(0, 1) + X(1, 2)$, which can be written as $C_1(\infty, 2) = X(\infty, 1) + X(\infty, 2)$. For $r > 1$, $X(\infty, 3)$ is copied to $X(r, 3)$. By the copy convention,

¹For more details of the experiments, refer to Appendix A.

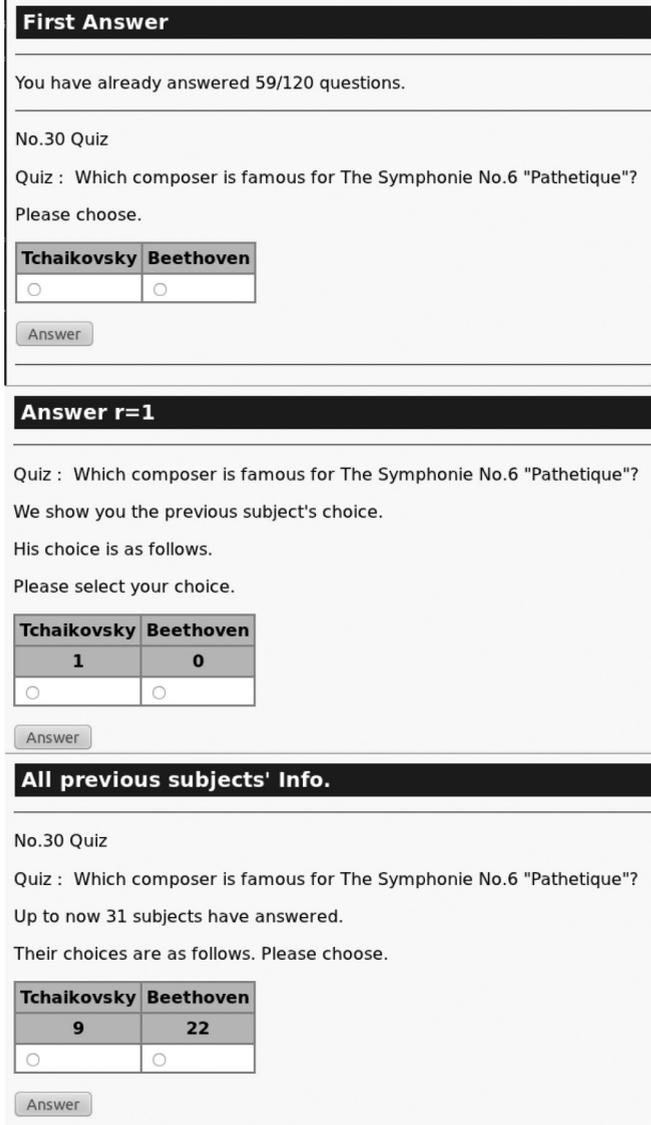


FIG. 1. Snapshot of the screen for $r = 0, 1$, and ∞ in HUE. The summary statistics $\{C_0(\infty, t), C_1(\infty, t)\}$ are given in the second row in the box in cases $r = 1$ and ∞ .

the social information in the case r can be expressed with the answers $\{X(r, t)\}$ in the case r only. If $t = 4$, the subject answered the question in case $r = 0$, which is written as $X(0, 4)$, and then in the case $r = 1$, written as $X(1, 4)$. Next, in HUE, the subject answered in the case $r = \infty$, written as $X(\infty, 4)$. The social information is $C_1(1, 3) = X(1, 3)$ and $C_1(\infty, 3) = X(\infty, 1) + X(\infty, 2) + X(\infty, 3)$. Figure 2 gives the pictorial explanation of the procedure.

In general, if the order of the subject is t , there is no public information for $r > t - 1$. There is the maximum value r_{\max} in the set $\{r\}$ that satisfies $r_{\max} < t - 1$. The subject answered from the case $r = 0$ to case r_{\max} in the set $\{r\}$ in increasing order of r . Then the subject was given the social information from all priors ($r = \infty$) and answered in the case $r = \infty$. He did not answer cases $r > r_{\max}$ in the set $\{r\}$ and the answer in the case $r = \infty$ was copied to the unanswered cases as $X(r, t) = X(\infty, t)$ for $r > r_{\max}$ in the set $\{r\}$. The answer in the case r started from the $(r + 2)$ th

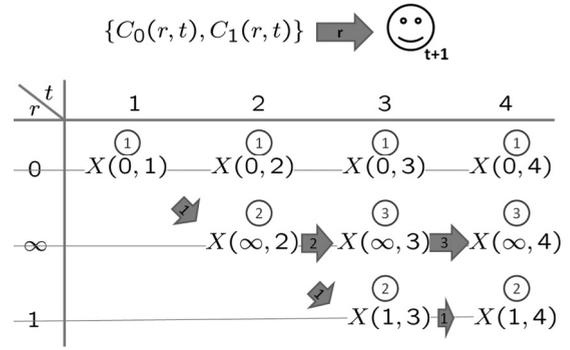


FIG. 2. Pictorial explanation of the experimental procedure. A subject answers the quiz questions in increasing order of r from $r = 0$ to ∞ . The $(t + 1)$ th subject answers in case r with social information $\{C_0(r, t), C_1(r, t)\}$ and the answer is denoted by $X(r, t + 1)$. The first subject ($t = 1$) answers only in the case $r = 0$, which is written as $X(0, 1)$. The second subject ($t = 2$) answers in the cases $r = 0$ and ∞ , which are written as $X(0, 2)$ and $X(\infty, 2)$, respectively. The third subject answers in case $r = 0$, then in case $r = 1$, and finally in case $r = \infty$; these are written as $X(0, 3)$, $X(1, 3)$, and $X(\infty, 3)$, respectively. The number in the circle indicates the order of the answer for each subject. The number in the arrow indicates the memory length of the social information. For $r = 1$, it is one. For $r = \infty$, the t th subject receives $t - 1$ previous subjects' information and the length is $t - 1$.

subject in the sequence. For $t < r + 2$, $X(r, t) = X(\infty, t)$ by the copy convention and $\{C_0(r, t), C_1(r, t)\}$ can be written using only $\{X(r, t)\}$ as $C_1(r, t) = \sum_{t'=t-r+1}^t X(r, t')$ and $C_0(r, t) = r - C_1(r, t)$. We use the same conventions when we prepare a sequence of choices in the case r . All sequences of choices $\{X(r, t)\}$ start from $t = 1$. The percentage of correct answers up to the t th subject is defined as $Z(r, t) = \sum_{t'=1}^t X(r, t')/t$ and the final value is $Z(r, T)$.

B. Quiz selection

We explain the choice of the questions in the quiz. In the experiment it was necessary to control the difficulty of the questions. If a question is too easy, all subjects know the answer. If the question is too difficult, no subjects know the answer. In order to study social influence by varying the ratio of people who do not know the answer, it is necessary to choose moderately difficult questions. In KUE, we selected 100 questions for which only one among the five experimenters knew the answer. This choice means that the ratio is estimated to be around 80% for the subjects. After KUE, we calculated $Z(0, T)$ for each question. In general, $Z(0, T) \geq 0.5$ for two-choice questions. A too-small value of $Z(0, T)$ indicates some bias in the given choices of the question. We excluded questions with too-small values of $Z(0, T)$ and prepared a new quiz with 120 questions in HUE. Table II shows five typical questions from HUE.

III. DATA ANALYSIS

In the analysis the subjects are classified into two categories, independent and herder, for each question. If a subject knows the answer to a question with 100% confidence and the answer is not affected by others' choices, the subject is categorized

TABLE II. Five typical questions from the two-choice quiz in HUE. Here q is the label of the questions in the quiz and $q \in \{0, 1, 2, \dots, 119\}$.

q	Question	Choice 0	Choice 1	Answer
0	Which insect's wings flap more in one minute?	mosquito	honeybee	0
1	During which period did the Tyrannosaurus Rex live?	Jurassic	Cretaceous	1
3	Which animal has a horn at birth?	rhinoceros	giraffe	1
7	Which is forbidden during TV programs in Korea?	commercials	kissing scenes	0
8	Which instrument is in the same group as the marimba?	vibraphone	xylophone	1

as independent. If the subject does not know the answer and may be affected by others' choices, the subject is categorized as herder [15,19,20]. We assume that the probabilities of a correct choice for independent and herder subjects are 100% and 50%, respectively. For a group with p herders and $1 - p$ independent subjects, the expectation value of $Z(0, T)$ is $E(Z(0, T)) = 1 - p/2$. For each question in each group, we estimate p by $p = 2(1 - Z(0, T))$ as the maximal likelihood estimate. The assumption of the random guess (50%) by the herder might be too simple. As $Z(0, T)$ approaches 0.5 and almost all subjects do not know the answer to the question, p approaches 100% and the estimate works well.

The design of our experiment and analysis has three advantages over both theoretical models and observational studies. (i) We control the amount of social information that the subjects receive by the change in r . This enables us to derive a microscopic rule for human decisions under social information [21]. (ii) Based on the answers in the absence of information ($r = 0$), we can estimate the ratio of herders p , which will enable us to extract the herder's decision rule from the results in (i). (iii) Our analysis focuses on the asymptotic behavior of the convergence of $Z(r, t)$ with fixed herder's ratio p . We clearly see the collective behavior of humans and the qualitative change when p is varied. In particular, we can study the possibility of the information cascade transition [7,14,19,20,22].

We include a note about the controllability of p in the experiment. In the experiment, after all T subjects answered, we calculated $Z(0, T)$ and estimated the herder's ratio p as $p = 2(1 - Z(0, T))$. It may seem impossible to control p in the experiment, but this is not so. We think p is an inherent property of two-choice questions. If we can estimate p for a large number of subjects $T \gg 1$, we can apply the same value to the experiments with other groups. We have compared the two values of $Z(0, T)$ of group A and B for the same question in HUE. Pearson's correlation coefficient ρ is 0.82 and there is a strong correlation. The system size T in HUE is very limited ($T \simeq 50$) and some fluctuation in the estimation of p remains, but it will disappear for a large enough T . We can know p in advance and control it in voting experiments.

A. Distribution of $Z(r, T)$

There are 2×120 (100) samples of sequences of choices for each r in HUE (KUE). We divide these samples into 11 (9) bins according to the size of $Z(r, T)$, as shown in Table III(a) [III(b)]. The samples in each bin share almost the same value of p . For example, in the sample in bin 6 [$0.45 < Z(0, T) \leq 0.55$] in HUE, there are almost only herders in the subjects' sequence and $p \simeq 100\%$. In contrast, in the sample in bin

11 [$Z(0, T) > 0.95$], almost all subjects know the answer to the question and are independent ($p \simeq 0\%$). An extremely small value of $Z(0, T)$ indicates some bias in the question. We omit data with $Z(0, T) < 0.45$ (13/31) in the analysis of the system and we are left with 180 (166) samples in HUE (KUE). The samples with $Z(0, T) < 0.5$ in bin 6 in HUE (bin 5 in KUE) have p values larger than 100%. These values are errors of the estimation $p = 2(1 - Z(0, T))$. The standard deviation of $Z(0, T)$ is $p/2\sqrt{T}$ for fixed p . In the estimation of p , there is a fluctuation with the magnitude of order $\simeq p/\sqrt{T}$. If p takes value larger than 100%, we take it to be 100%. Table III shows the number of data samples in each bin for $r = 0, 5$, and ∞ as $N(0)$, $N(5)$, and $N(\infty)$. Social information causes remarkable changes in the subjects' choices. For $r = 0$ ($r = 5$), there is one peak at bin 7 (bin 9) and for $r = \infty$,

TABLE III. Effect of social information on subjects' decisions in (a) HUE and (b) KUE. We divide the samples according to the size of $Z(r, T)$. Here $N(r)$ denotes the number of samples in each bin and p_{avg} is estimated as the average value of $p = 2(1 - Z(0, T))$ in each bin. The suboptimal ratios are shown in the last column.

No.	$Z(r, T)$ (%)	$N(0)$	p_{avg} (%)	$N(5)$	$N(\infty)$	Ratio
(a) HUE						
1	<5	0		0	2	
2	5–15	0		4	18	
3	15–25	8		8	22	8:8
4	25–35	16		21	20	13:16
5	35–45	36		24	8	28:36
6	45–55	43	96.7	26	9	16:43
7	55–65	46	79.3	34	10	9:46
8	65–75	45	62.7	40	14	2:45
9	75–85	33	41.9	45	33	0:33
10	85–95	11	21.3	32	67	0:11
11	≥ 95	2	2.0	6	37	0:2
Total		240		240	240	76:240
No.	$Z(r, 31)$	$N(0)$	p_{avg} (%)	$N(5)$	$N(\infty)$	Ratio
(b) KUE						
1	$\leq 1/31$	0		0	3	
2	2/31–5/31	2		7	20	2:2
3	6/31–9/31	6		18	22	6:6
4	10/31–13/31	26		21	14	23:26
5	14/31–17/31	52	97.6	33	6	26:52
6	18/31–21/31	54	74.6	21	7	5:54
7	22/31–25/31	33	49.1	35	29	1:33
8	26/31–29/31	25	26.3	47	67	0:25
9	$\geq 30/31$	2	6.5	18	32	0:2
Total		200		200	200	63:200

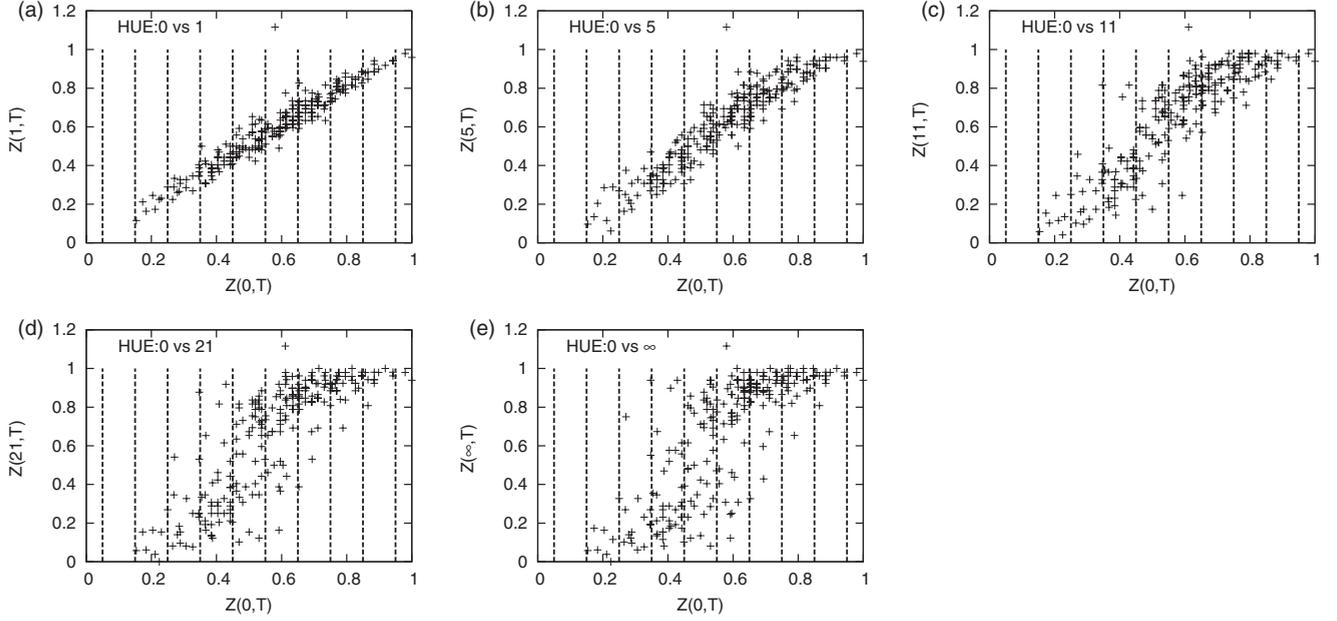


FIG. 3. Scatter plots of $Z(0, T)$ vs $Z(r, T)$ in HUE for (a) $r = 1$, (b) $r = 5$, (c) $r = 11$, (d) $r = 21$, and (e) $r = \infty$. The vertical lines show the border of the bins in Table III(a).

there are peaks at bins 3 and 11 in HUE. Here we compare the densities, not the value $N(r)$ itself. In the last column we show the ratio of suboptimal cases $\{Z(\infty, T) < 1/2\}$ with respect to the $N(0)$ samples in each bin. The crucial problem is whether the suboptimal cases $\{Z(\infty, T) < 1/2\}$ remain so in the thermodynamic limit $T \rightarrow \infty$ [7,20].

In order to see the social influence more pictorially, we show the scatter plots of $Z(0, T)$ vs $Z(r, T)$ for all 240 samples in HUE for each $r \in \{1(a), 5(b), 11(c), 21(d), \infty(e)\}$ in Fig. 3. The x axis shows $Z(0, T)$ and the y axis shows $Z(r, T)$. The vertical lines show the boundary between the bins (from 1 to 11) in Table III(a). As we move from Fig. 3(a) ($r = 1$) to Fig. 3(e) ($r = \infty$), the amount of social information r increases. If the subjects' answers are not affected by the social information, the data should distribute on the diagonal line. However, as the plots clearly indicate, this is not the case. As r increases from $r = 1$ to ∞ , the changes $Z(r, T) - Z(0, T)$ increase and the samples scatter more widely in the plane. For the samples with $Z(0, T) \geq 0.75$ [bins 9–11 in Table III(a)], the changes are almost positive and $Z(\infty, T)$ takes a value of about one. The suboptimal ratios are zero in the bins. The average performance improves by the social information there. In contrast, for the samples with $0.45 \leq Z(0, T) < 0.55$ [bin 6 in Table III(a)], the social information does not necessarily improve the average performance. There are many samples with negative change $Z(\infty, T) - Z(0, T) < 0$. These samples are in the suboptimal state and constitute the lower peak in Table III(a).

B. Order parameters of the phase transition

We have seen drastic changes in the distribution of $Z(\infty, T)$ from the distribution of $Z(0, T)$. Table III shows the two-peak structure in the distribution of $Z(\infty, T)$. In Fig. 3 we see an S-shaped curve in the case $r = \infty$. The natural question is whether these macroscopic changes can be attributed to

the information cascade transition. In our previous work on the voting model with digital herders [20], we showed the possibility of the phase transition from the one-peak phase to the two-peak phase. If p is smaller than some critical value p_c , the system is in the one-peak phase. The distribution of $Z(\infty, T)$ has only one peak at $Z(\infty, T) > 1/2$. If $p > p_c$, the distribution of $Z(\infty, T)$ has two peaks at $Z(\infty, T) < 1/2$ and $Z(\infty, T) > 1/2$. In the thermodynamic limit $T \rightarrow \infty$, the probability that $Z(\infty, T) < 1/2$ becomes a function of p , which is nonanalytic at $p = p_c$ and takes a positive value for $p > p_c$. There are two candidates for the order parameter of the phase transition: One is the suboptimal ratio $Z(\infty, T) < 1/2$; the other is the variance of $Z(\infty, T)$, $\text{Var}(Z(\infty, T))$. Both candidates are zero for $p < p_c$ and positive for $p > p_c$ in the thermodynamic limit $T \rightarrow \infty$.

Figure 4 shows the plot of the two order parameters vs p . We plot the ratios of the suboptimal [$Z(\infty, T) < 1/2$] cases [Fig. 4(a)] and $\text{Var}(Z(\infty, T))$ [Fig. 4(b)]. The ratios are given in the last column of Table III. As p increases, the order parameters change from zero to some finite value. They are monotonically increasing functions of p . However, in the behaviors, we cannot see any clear evidence of the phase transition. The system size is very small and we cannot see any nonanalytic nature there. We cannot use them to prove the existence of the information cascade transition.

C. Asymptotic behavior of the convergence of $Z(\infty, t)$

We study the convergence of $Z(\infty, t)$ in the limit $t \rightarrow \infty$ to clarify the possibility of the information cascade transition. If information aggregation works under social information, $Z(\infty, t)$ converges to some value larger than half. The distribution of $Z(r, t)$ has only one peak: It is in the one-peak phase. Depending on the convergence behavior, the one-peak phase is classified into two phases. If the variance of $Z(r, t)$ shows

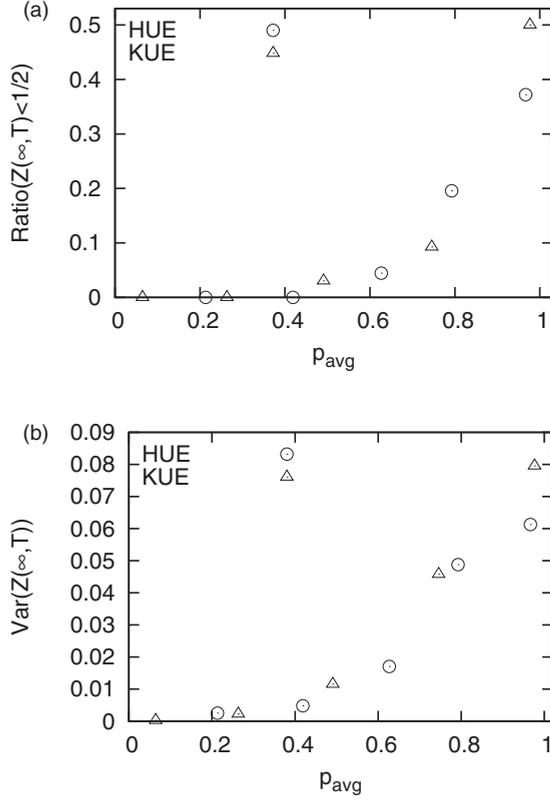


FIG. 4. (a) Ratios of the suboptimal [$Z(\infty, T) < 1/2$] cases, which are given in the last column of Table III, and (b) the variance $\text{Var}(Z(\infty, T))$ are plotted vs p . The symbols \circ and \triangle indicate the results of HUE and KUE, respectively.

normal diffusive behavior as $\text{Var}(Z(r, t)) \propto t^{-1}$, it is called the normal diffusion phase. We note that the variance is estimated for the ratio and the usual behavior t^1 for the sum of t random variables is replaced by one that is proportional to $t/t^2 = t^{-1}$. If the convergence is slow and obeys $\text{Var}(Z(r, t)) \propto t^{-\gamma}$ with $0 < \gamma < 1$, it is called the superdiffusion phase [19,23]. If information aggregation does not work and there is a finite probability that $Z(r, t)$ converges to some value less than half, the distribution of $Z(r, t)$ has two peaks [7,20]. It is in the two-peak phase and $\text{Var}(Z(r, t))$ converges to some finite value in the limit $t \rightarrow \infty$.

Figure 5(a) [5(b)] shows the double logarithmic plots of $\text{Var}(Z(\infty, t))$ as a function of t for HUE (KUE). If the plot of $\text{Var}(Z(\infty, t))$ vs t has a negative slope ($\gamma > 0$) in the limit $t \rightarrow \infty$, the system is in the one-peak phase. If the slope is zero ($\gamma \leq 0$) in the limit $t \rightarrow \infty$, the system is in the two-peak phase. We see that the convergence becomes very slow as p increases. The exponent γ is estimated by fitting with a value proportional to $t^{-\gamma}$ for $t \geq 20$. It decreases from 1.43 (1.53) to 0.09 with the increase in p in HUE (KUE). For the cases with $p = 96.7\%$ (97.6%) in HUE (KUE), the system can be in the two-peak phase.

IV. STOCHASTIC MODEL AND SIMULATION STUDY

The asymptotic analysis of the convergence of $Z(\infty, t)$ shows the possibility of the two-peak phase in the cases $p = 96.7\%$ and 97.6% . The negative slope γ is remarkably

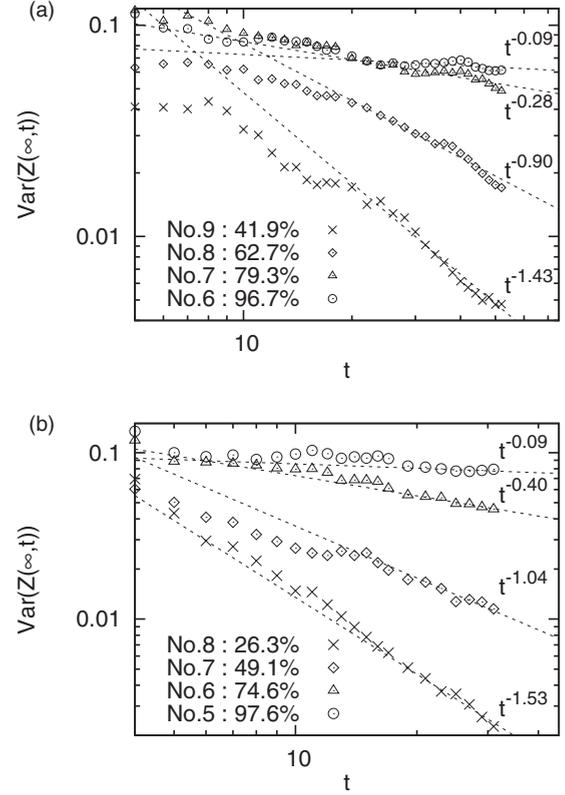


FIG. 5. Convergent behavior for (a) HUE and (b) KUE. The convergence is given by the double logarithmic plot of $\text{Var}(Z(\infty, t))$ vs t using the samples in the four bins for $r = 0$ in Table III(a) (No. 6, \circ ; No. 7, \triangle ; No. 8, \circ ; and No. 9, \times) and in Table III(b) (No. 5, \circ ; No. 6, \triangle ; No. 7, \circ ; and No. 8, \times). The dotted lines are fitted results that are proportional to $t^{-\gamma}$ for $t \geq 20$.

small (~ 0.09) in both experiments. However, the system sizes are limited and far from the thermodynamic limit $T \rightarrow \infty$. In this section we derive a microscopic rule as to how the herders copy others' information. Based on the herder's microscopic rule, we introduce an *ad hoc* stochastic model. A simulation study of the model for 10^6 subjects showed the information cascade transition.

A. Microscopic behavior of herders

We determine how a herder's decision depends on social information. For this purpose we need to subtract the independent subjects' contribution from $X(r, t + 1)$. The probability of being independent is $1 - p$ and such a subject always chooses 1; the herder's decision is then simply estimated as²

$$(X(r, t + 1) - (1 - p) \times 1) / p.$$

The expectation value of this under $C_1(r, t) = n_1$ indicates the probability that a herder chooses an option under the influence

²More precisely, the probability that the t th subject is independent depends on the choice $X(0, t)$. If $X(0, t) = 0$, the subject is not independent and the probability is zero. In contrast, if $X(0, t) = 1$, the probability is $(1 - p)/(1 - 0.5p)$. The subtraction should take into account the value of $X(0, t)$.

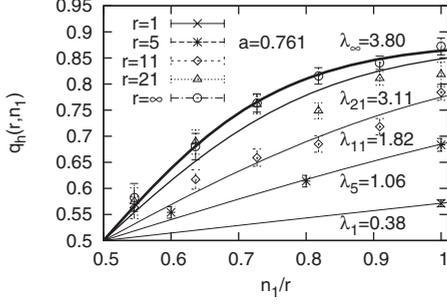


FIG. 6. Microscopic rule of the herder's decision in HUE, which shows the probability $q_h(r, n_1)$ that a herder chooses an option under the influence of the prior n_1 subjects among r choosing it for cases $r = 1$ (\times), 5 ($*$), 11 (\diamond), and 21 (\triangle). For $r = \infty$ (\circ), r is considered to be t . The thin solid curves are fitted results with Eq. (2) for $r = 1, 5, 11$, and 21 from the bottom to the top. The top thick solid line corresponds to $r = \infty$.

of the prior n_1 subjects among r choosing it. We denote it by $q_h(r, n_1)$ and it is defined for $t \geq r$ as

$$q_h(r, n_1) \equiv E([X(r, t+1) - (1-p)]/p | C_1(r, t) = n_1). \quad (1)$$

The conditional expectation value in Eq. (1) is estimated using the samples that satisfy $C_1(r, t) = n_1$ from HUE. From the symmetry $1 \leftrightarrow 0$, we assume $q_h(r, n_1) = 1 - q_h(r, r - n_1)$. For $r = \infty$, the $(t+1)$ th subject obtains information from the previous t subjects and r is considered to be t . The $r = \infty$ case is averaging several values of r . For $r = 21$ and ∞ , we study the dependence of $q_h(r, n_1)$ on n_1/r and round n_1/r to the nearest values in $\{k/11 | k \in \{0, 1, 2, \dots, 11\}\}$. In addition, we estimate $q_h(\infty, n_1)$ for $t \geq 22$ to understand the herder's decision under the largest amount of social information. Another reason is that the subjects receives much information for $t \geq 22$ and we can assume that the dependence of $q_h(\infty, n_1)$ on (t, n_1) is replaced by the dependence on n_1/t .

Figure 6 shows the plot of $q_h(r, n_1)$ vs n_1/r . It is clear that $q_h(r, n_1)$ is an almost monotonically increasing function of n_1 . As r increases, it shows a stronger dependence on n_1/r and the herder's decision is affected more greatly by the prior subjects' choices. We fit the plot by the following functional form:

$$q_h(r, n_1) = \frac{1}{2} [a \tanh[\lambda_r(n_1/r - 1/2)] + 1]. \quad (2)$$

The parameters a and λ_r indicate the strength of the conformity of the subjects. Social psychology studies suggest that people's likelihood to use social information depends on their mood [10]. Here a denotes the net ratio of herders who react positively to the prior subjects' choices and λ_r denotes the strength of the dependence on social information. By a least-squares fit, we obtain $a = 0.761$ and $\lambda_\infty = 3.80$ for $r = \infty$. The fitted result is also shown in Fig. 6. The values of a and λ_∞ depend on the experimental situation and the system size T .³ Using the same a , we fit the data for other r using Eq. (2). The results are also given in Fig. 6. As the amount r of social information increases, the strength of the dependence λ_r increases.

³The microscopic behavior of the herders in KUE is given in Appendix B.

B. Information cascade transition of voting model

To understand the behavior of the system in the thermodynamic limit $T \rightarrow \infty$, we simulate the system for large T by a stochastic model based on Eq. (2). We introduce a stochastic process $\{X(t)\}$, $t \in \{1, 2, 3, \dots, T\}$. Note that $X(t+1) \in \{0, 1\}$ is a Bernoulli random variable and its probabilistic rule depends on all the previous $\{X(t')\}$, $t' \in \{1, \dots, t\}$ through $C_1(t) = \sum_{t'=1}^t X(t')$. The probability that $X(t+1)$ is 1 for $C_1(t) = n_1$, which is denoted by $q(t, n_1)$, is given as

$$q(t, n_1) = (1-p) + p \frac{1}{2} [a \tanh \lambda_t (n_1/t - 1/2) + 1]. \quad (3)$$

We set a as $a = 0.761$ and λ_t for $t \in \{1, 5, 11, 21\}$ as $\lambda_t = \lambda_r$. Here λ_r takes the values given in Fig. 6. For other values of t and $t < 21$, we use the linearly extrapolated value. For $t > 21$, we set $\lambda_t = \lambda_\infty$.

We denote the probability function $\Pr(\sum_{t'=1}^t X(t') = n)$ as $P(t, n)$. The master equation for $P(t, n)$ is

$$P(t+1, n) = q(t, n-1)P(t, n-1) + [1 - q(t, n)]P(t, n). \quad (4)$$

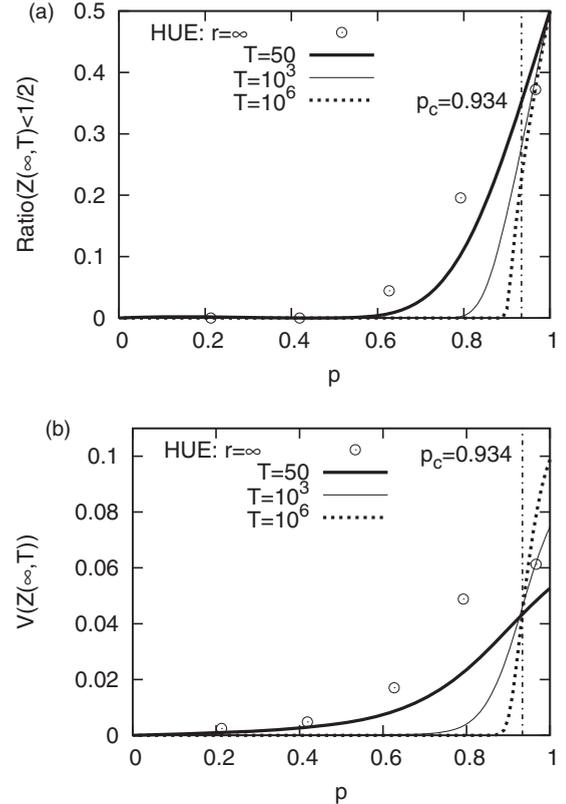


FIG. 7. Plots of order parameters vs p for the voting model and the limit $T \rightarrow \infty$. We plot (a) the suboptimal ratio $Z(\infty, T) < 1/2$ and (b) $\text{Var}(Z(\infty, T))$ vs p ; here T is the length of the sequence. The symbol \circ indicates the experimental data for HUE (with $r = \infty$ and $T \simeq 50$) for five bins, Nos. 6–10 in Table III. The lines show the data from the stochastic model for $r = \infty$. For the stochastic model, we set $T = 50$ (thick solid line), 10^3 (thin solid), and 10^6 (thick dotted). As T increases, the nonzero regions of the order parameters move rightward. In the limit $T \rightarrow \infty$, the region reduces to $p > p_c = 93.4\%$. The vertical chain line at $p = p_c$ shows the critical point of the phase transition between the one-peak phase ($p < p_c$) and the two-peak phase ($p > p_c$).

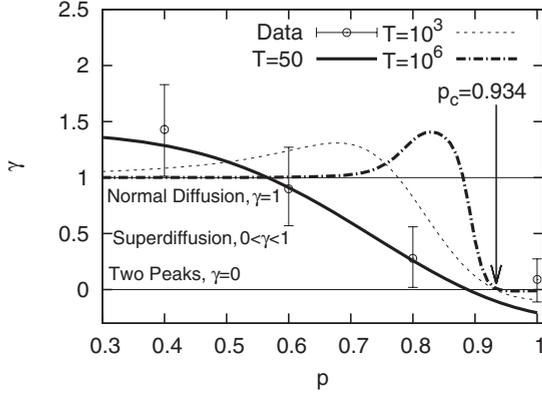


FIG. 8. Thermodynamic limit and phase diagram. The asymptotic behavior of the convergence is given by the plot of γ vs p . The symbols \circ show γ vs p_{avg} in Fig. 5(a). The lines show the results of the stochastic model with system size $T = 50$ (thick solid line), 10^3 (dotted line), and 10^6 (thick chain).

We solved the master equation recursively and obtain $P(t, n)$ for $t \leq 10^6$.

Figure 7 shows the results of the model. We plot the suboptimal ratio $Z(\infty, T) < 1/2$ [Fig. 7(a)] and $\text{Var}(Z(\infty, T))$ vs p [Fig. 7(b)]. For comparison, we plot the experiment's results (HUE) using an open circle. The model with $T = 50$ well describes the experimental results quantitatively. In the figure we also plot the results for $T = 10^3$ and 10^6 . As T increases, the nonzero regions of the order parameters move rightward. In particular, we see that there is a crossing point in the curves of $\text{Var}(Z(\infty, T))$ at $p = 93.4\%$, which we denote by p_c . If $p < p_c$, $\text{Var}(Z(\infty, T))$ goes to zero as T increases. In contrast, if $p > p_c$, the variance seems to remain in the limit $T \rightarrow \infty$. This shows the phase transition between the one-peak and two-peak phases. For $p > p_c$, the system is in the two-peak phase ($\gamma = 0$). For $p < p_c$, the system is in the one-peak phase ($0 < \gamma \leq 1$). In order to see the convergence rate (the exponent γ), it is necessary to study the asymptotic behavior of $\text{Var}(Z(\infty, t))$ for large values of t .

We estimate γ from the slope of $\text{Var}(Z(t))$ as

$$\gamma = \ln \frac{\text{Var}(Z(T - \Delta T))}{\text{Var}(Z(T))} \bigg/ \ln \frac{T}{T - \Delta T} \quad (5)$$

for the time horizons $T = 50, 10^3$, and 10^6 . For $T = 50$, we take $\Delta T = 30$ to match the analysis of the experiment's data in HUE. For $T = 10^3$ and 10^6 , we take $\Delta T = 10^2$. The results are summarized in Fig. 8. For $T = 50$, γ is a monotonically decreasing function of p and describes the experiment's results of HUE well. For the limit $T \rightarrow \infty$, we compare the results with $T = 50, 10^3$, and 10^6 . Here γ shows nonmonotonic behavior as a function of p for the latter two cases; it is an artifact of finite T . In the limit $T \rightarrow \infty$, γ monotonically decreases from 1 to 0 and the threshold value is $p_c = 93.4\%$ [24]. For $p < p_c$ ($p > p_c$), the system is in the one-peak (two-peak) phase.

V. CONCLUSIONS

The instinct to imitate others led to the remarkably slow convergence of information aggregation as the herder's ratio

p approached 100%. A stochastic model based on the herder's microscopic copying rule predicted the information cascade transition between the one-peak ($p < p_c$) and the two-peak ($p > p_c$) phases [24]. In the one-peak phase, information aggregation works and the majority's choice is always correct when the independents choose the correct choice rather than the incorrect one. In the two-peak phase, the majority's choice is not necessarily correct. The coexistence of the optimal [$Z(\infty, T) > 1/2$] and the suboptimal [$Z(\infty, T) < 1/2$] states occurs there.

It has been thought that the information cascade was fragile [5,6] or self-correcting where the suboptimal state disappears and switches to the optimal state [18]. Our study indicates that the system is in the two-peak phase and that the suboptimal state is stable against small perturbations for $p > p_c$ if the subjects are given the summary statistics $\{C_0(\infty, t), C_1(\infty, t)\}$. The conclusion might appear to be contradictory to the previous one, but this is not so. In previous works the subjects each have their own information and it is not necessary to follow the majority if one can trust one's own information [18]. In addition, the social information is the time series of the previous choices $\{X(\infty, t')\}_{1 \leq t' \leq t}$ and it contains much more information than the summary statistics $\{C_0(\infty, t), C_1(\infty, t)\}$. In our experiment the herder does not have information and it is necessary to follow the majority to choose a correct answer. However, the system size in our experiment is very limited and it is difficult to infer the state of the system in the thermodynamic limit based only on experimental data. Our conclusion that an information cascade transition occurs relies heavily on the results of the simulation study of the stochastic model. In addition, the experiments were performed with students at universities and the scope of the subjects is thus very restricted. The robustness of the conclusion should be established by further experiments. For this purpose, a web-based experiment in artificial laboratories is promising [25]. There we can approach the thermodynamic limit $T \rightarrow \infty$ more easily than in physical laboratories and study the microscopic and macroscopic features of the information cascade.

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APPENDIX A: SETUP OF EXPERIMENT

1. KUE

In KUE, the 62 subjects who participated in the experiment were recruited from the School of Science of Kitasato University. The subjects were randomly assigned to either group A or group B; each group had 31 subjects. In each session, one subject from each group entered the laboratory, a total of two subjects. We explained that we were studying how their choices were affected by the choices of others. After explaining the details of the experimental procedure and payment, each subject sat in front of an experimenter and had no contact with the other subject in the laboratory. The experiments on groups

A and B were performed independently. Interaction between subjects in each group was permitted only through the social information given by the experimenter in front of each subject. The subjects were asked to answer the 100 questions in the two-choice quiz. The subjects answered the quiz with at most eight social influence conditions, including the case $r = 0$. Each session lasted about one hour. In order to obtain data from all $T = 31$ subjects in both groups, we performed the session 31 times during three days. Subjects were paid upon being released from the session. There was a 2000-yen (about \$24) participation fee and an additional 1000-yen reward (about \$12) for the top ten subjects. The ranking of the subjects was calculated based on the ratio of correct answers to all questions and r .

2. HUE

In HUE, the 104 subjects who participated were recruited from the Literature Department of Hokkaido University. The subjects were randomly assigned to either group A or group B; each group had 52 subjects. In each session, between one and six subjects from each group entered the laboratory, for a total of between two and eleven subjects. The experiment was performed in the Group Experiment Laboratory of the Center for Experimental Research in Social Sciences of Hokkaido University. There were fifteen desks furnished with partitions and personal computers. Each subject sat behind a partition and communication among them was prohibited. The experiments on groups A and B were performed independently. In order to study the effect of social information on the choices of the subjects, it was necessary to control the transmission of information from others in the same group. We developed a web-based voting system by which multiple subjects could simultaneously participate in the experiment. The subjects used a web browser to access the web voting server in the intranet. They could obtain information about the others' choices from the summary statistics $\{C_0(r,t), C_1(r,t)\}$ shown on the monitor. Subjects did not know which questions the other subjects were answering or what their choices were.

With slides, we showed subjects how the experiment would proceed. We explained that we were studying how their choices were affected by the choices of others. In particular, we emphasized that the social information was realistic information calculated from the choices of previous subjects. The reason for this is that in contrast to KUE, the social information was given on the monitor and seemed less credible to the subjects. Through the slides, we also explained the payment. After the explanation, the experiment started. The subjects answered the 120-question quiz with at most six social influence conditions within about one hour. A total of 15 sessions were held. Subjects were paid in cash upon being released from the session. There was a 600-yen (about \$7) participation fee and additional rewards that were proportional to the number of correct answers. One correct choice was worth one point and this was worth one yen (about one and one-third cents).

Some subjects could not answer all the questions within the allotted time, so the number T of subjects who answered a question varied. The distribution of T is $\{T = 52\} = 143$, $\{T = 51\} = 5$, $\{T = 50\} = 2$, $\{T = 49\} = 85$, $\{T = 48\} = 4$, and $\{T = 47\} = 1$. The average value of T

was 50.8 and the standard deviation σ_T was 1.48. The average length of the sequence was about 50.

The assignment of quiz questions in HUE was as follows. Each question had a label q in $q \in \{0, 1, 2, \dots, 119\}$ and each subject had an ID number i . If the ID number i of the subject was odd, the subject started with the question with the smallest q in the pool not chosen by the server for another subject in the same group. If i was even, the subject started with the question with the largest q not chosen by the server for another subject. If another subject was answering a question, that question was never chosen by the server. It was strictly prohibited for multiple subjects to answer the same question simultaneously.

APPENDIX B: MICROSCOPIC BEHAVIOR OF HERDERS IN KUE

We determine how a herder's decision depends on social information in KUE. We follow the same procedure written in the main text. Figure 9 plots the results. The fitted results with Eq. (2) are also shown. Compared with Fig. 6, the convergence to Eq. (2) is not so good. The system size $T = 31$ is not enough to derive the microscopic rule.

APPENDIX C: ESTIMATE OF γ AND ITS ERROR BAR

In our study we focus on the asymptotic behavior of $\text{Var}(Z(\infty, t))$. In particular, we are interested in the power law behavior as $\text{Var}(Z(\infty, t)) \propto t^{-\gamma}$. The negative slope $-\gamma$ of the double logarithmic plot of $\text{Var}(Z(\infty, t))$ vs t gives the exponent γ in the limit $t \rightarrow \infty$. In our analysis we estimate γ by the least-squares fit with the functional form $at^{-\gamma}$ in the range $20 \leq t \leq T$. We denote the estimate by γ_{exp} .

For the error bar of the exponent γ_{exp} , we adopted the voting model to simulate the system and apply the parametric bootstrapping method based on it. First, we solved the model

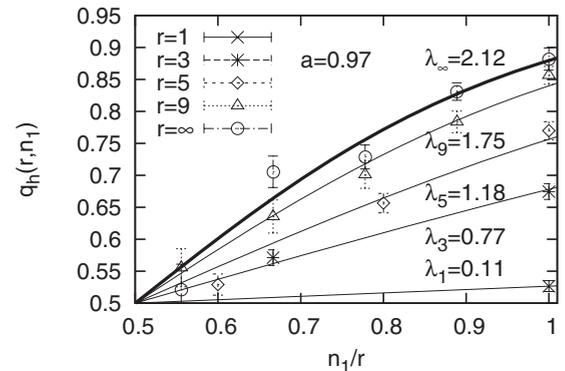


FIG. 9. Microscopic rule of herders' decisions in KUE, which shows the probability $q_h(r, n_1)$ that a herder chooses an option under the influence of the prior n_1 subjects among r choosing it for cases $r = 1$ (\times), 3 ($*$), 5 (\diamond), and 9 (Δ). For $r = \infty$ (\circ), the $(t + 1)$ th subject's decision depends on the previous t subjects' decisions and r is considered to be t . We estimate the dependencies of $q_h(\infty, n_1)$ on n_1/t for $t \geq 10$, where n_1/t is rounded to the nearest value in $\{k/9 | k \in \{0, 1, 2, \dots, 9\}\}$. The solid curves are fitted results with $q_h(r, n_1) = \{a \tanh[\lambda_r(n_1/r - 1/2)] + 1\}/2$. For $r = \infty$ (the thick solid line), we set $r = t$. From bottom to top, the thin solid lines correspond to $r = 1, 3, 5$, and 9.

recursively up to $T = 20$ and 50 and obtained the probability functions $P(T, n)$ for both time horizons T . We defined $Z(T)$ as $Z(T) = \frac{n}{T}$ and estimated γ by the relation

$$\gamma = \ln \frac{\text{Var}(Z(T - \Delta T))}{\text{Var}(Z(T))} \bigg/ \ln \frac{T}{T - \Delta T} \quad (\text{C1})$$

using the probability function $P(T, n)$. Here γ was estimated in the range $T - \Delta T \leq t \leq T$. For $T = 50$, we take $\Delta T = 30$ to match the analysis of the experimental data in HUE. The estimate is exact and we denote it by γ_{exact} . In HUE, the number of samples in each bin ranges from 33 to 46 and is very limited.

We studied the stochastic model using the Monte Carlo method with the same sample size as the experimental data in each bin and estimated γ for the samples. We repeated this 10^4 times to obtain the samples of γ . Using the samples of γ , we estimated the 95% confidence interval, which is denoted by $[\gamma_-, \gamma_+]$. The approximately estimated γ was distributed around γ_{exact} . The upper (lower) deviation was calculated as $\Delta\gamma_+ \equiv \gamma_+ - \gamma_{\text{exact}}$ ($\Delta\gamma_- \equiv \gamma_{\text{exact}} - \gamma_-$). We estimated the 95% confidence interval of γ_{exp} as $[\gamma_{\text{exp}} - \Delta\gamma_-, \gamma_{\text{exp}} + \Delta\gamma_+]$. Using this procedure, we estimated the error bars for each γ in Fig. 8.

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