Finite Element Beam Propagation Method with Perfectly Matched Layer Boundary Conditions

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Abstract — The perfectly matched layer boundary condition is incorporated into the beam propagation method based on a finite element scheme. To show the validity and usefulness of this approach, numerical results are shown for a double U-bend and linear tapers with different index contrast and opening angle.

Index terms — beam propagation method, finite element method, perfectly matched layer, wide-angle beam propagation, optical waveguide analysis

I. INTRODUCTION

The beam propagation method (BPM) is at the present the most widely used for the study of light propagation in longitudinally varying waveguides. Especially a recently developed finite element BPM (FE-BPM) using the Padé approximation [1], [2] can give very accurate results without increasing computational effort even if the wide-angle propagation is treated.

One of the key issues in implementing FE-BPM to study light propagation in finite spatial domain is the boundary condition at the computational window (CW) edges. Berenger [3] has recently introduced the concept of a perfectly matched layer (PML) for reflectionless absorption of electromagnetic waves which is successfully applied to the finite difference BPM (FD-BPM) [4]. Unfortunately, since Berenger’s PML technique involves a modification of Maxwell’s equations based on the splitting of the fields components into two subcomponents, these non-Maxwellian equations do not have a desirable form for finite element (FE) formulations. More recently, Pekel and Mittra [5] have presented a new version of PML which does not involve the field splitting and is suitable for FE formulations.

In this paper the revised PML is, for the first time, incorporated into FE-BPM. To show the validity and usefulness of this approach, numerical results are shown for a double U-bend and linear tapers with different index contrast and opening angle.

II. BASIC EQUATION

We consider a planar (two-dimensional) optical waveguide, where \( y \) and \( z \) are the transverse and propagation directions, respectively, and there is no variation in the \( x \) direction \( (\partial / \partial x \equiv 0) \). With these assumptions and the transversely-scaled version of PML [5] we get the following basic equation:

\[
\frac{\partial}{\partial y} \left( \frac{p}{s} \frac{\partial \Phi}{\partial y} \right) + s \frac{\partial}{\partial z} \left( \frac{p}{s} \frac{\partial \Phi}{\partial z} \right) + k_0 \sigma_q \Phi = 0
\]

where

\[
\Phi = E_x, \quad p = 1, \quad q = n^2 \quad \text{for TE modes (2)}
\]

\[
\Phi = H_z, \quad p = 1/n^2, \quad q = 1 \quad \text{for TM modes (3)}
\]

\[
s = 1 - \frac{\sigma_e}{\omega \varepsilon_0 n^2} = 1 - j \frac{\sigma_m}{\omega \mu_0}
\]

which means that the wave impedance of a PML medium exactly equals that of the adjacent medium with refractive index \( n \) in the CW, \( \sqrt{\mu_0 / (\varepsilon_0 n^2)} \), regardless of the angle of propagation or frequency. In the PML medium, a parabolic profile is usually assumed for the conductivities, and thus, the parameter \( s \) is written as

\[
s = \begin{cases} 
1 - j \frac{3\lambda}{4\pi n d} \left( \frac{\rho}{d} \right)^2 \ln \frac{1}{R_t} & \text{in PML region} \\
1 & \text{in non-PML region}
\end{cases}
\]

where \( \lambda \) is the free-space wavelength, \( d \) is the PML thickness, \( \rho \) is the distance from the beginning of PML, and \( R_t \) is called the theoretical reflection coefficient [3].
III. Finite Element Discretization

Substituting a solution of the form
\[ \Phi(y, z) = \phi(y, z) \exp(-j k_0 n_0 z) \]  
into (1), we obtain the following equation for the slowly varying complex amplitude \( \phi \):
\[ p \frac{\partial^2 \phi}{\partial z^2} - 2 j k_0 n_0 p s \frac{\partial \phi}{\partial y} + \frac{\partial}{\partial y} \left( \frac{p \partial \phi}{s \partial y} \right) + k_0^2 s (q - n_0^2 p) \phi = 0 \]  
where \( n_0 \) is the reference refractive index, and the term \( \partial p/\partial z \) is neglected for TM modes.

Dividing the waveguide cross-section into quadratic (second-order) line elements and applying the standard FE technique to (8), we obtain
\[ [M] \frac{d^2 \phi}{dz^2} - 2 j k_0 n_0 [M] \frac{d \phi}{dz} + \{(K) - k_0^2 n_0^2 [M]\} \{\phi\} = \{0\} \]  
where \( \{\phi\} \) is the global electric or magnetic field vector, \( \{0\} \) is a null vector, and the FE matrices \([K]\) and \([M]\) are given by
\[ [K] = \sum_e \int_\Omega \left[ k_0^2 s \{N\} \{N\}^T - \frac{p \{N\} d^2 \{N\}^T}{dy} \right] dy \]
\[ [M] = \sum_e \int_\Omega p s \{N\} \{N\}^T dy. \]

Here, \( \{N\} \) is the shape function vector, \( T \) denotes a transpose, and \( \sum_e \) extends over all different elements.

Utilizing the Padé approximation \([1],[2],[6]\), (9) is reduced to
\[ -2 j k_0 n_0 [\bar{M}] \frac{d \phi}{dz} + \{(K) - k_0^2 n_0^2 [M]\} \{\phi\} = \{0\} \]
with
\[ [\bar{M}] = [M] + \frac{1}{4 k_0^2 n_0^2} \{(K) - k_0^2 n_0^2 [M]\}. \]

Applying the Crank-Nicholson algorithm for the propagation direction \( z \) to (12) yields
\[ [A] \{\phi_{i+1}\} = [B] \{\phi\}_i \]
with
\[ [A]_i = -2 j k_0 n_0 [\bar{M}]_i + 0.5 \Delta z \{(K)_i - k_0^2 n_0^2 [M]_i\} \]
\[ [B]_i = -2 j k_0 n_0 [\bar{M}]_i - 0.5 \Delta z \{(K)_i - k_0^2 n_0^2 [M]_i\} \]
where \( \Delta z \) is the propagation step size, \( \{\phi\}_i \) and \( \{\phi_{i+1}\} \) are the input and output field vectors at the \( i \)th propagation step, respectively, and the reference refractive index \( n_0,i \) and the FE mesh are adaptively renewed at each propagation step \([2]\).

A temporary input field vector on the next \((i+1)\)th mesh, \( \{\phi\}'_{i+1} \), is easily obtained by quadratic interpolation using the
\[ \sum_e \{\phi_{\Delta z}\}_{i,e} \left[ \int_e p_i \{N\} \{N\}^T dy \right] \{\phi\}'_{i+1,e} \]
with \( \{\phi_{\Delta z}\}_{i,e} \) and \( \{\phi\}'_{i+1,e} \) are the elemental field vectors, \( \dagger \) denote complex conjugate and transpose, and \( \sum_e \) extends over the elements within CW except PML regions.

IV. Numerical Results

First, we consider a double U-bend as shown in Fig. 1, where the core index is \( n_1 = 1.45 \), the relative refractive index
difference is \( \Delta = (n_1 - n_2)/n_1 = 0.25 \% \), the core width is \( w = 5 \mu m \), and the curvature radius is \( R = 3130 \mu m \). Fig. 2 shows the electric field evolution of the fundamental TE wave propagating in the U-bend. A wavelength of 1.55 \( \mu m \) is assumed, the PML thickness is \( d = 1 \mu m \), the theoretical reflection coefficient is \( R_l = 10^{-5} \), and the propagation step size is \( \Delta z = 1 \mu m \). We can see that the waves virtually disappear into the boundaries, irrespective of the CW size \( W \).

Fig. 3 shows the electric field \((E_y)\) pattern at the propagation distance of \( z = 2200 \mu m \). When using the PML, the reflection from the CW edges is not observed. When using the transparent boundary condition (TBC) [7], on the other hand, we can see the field disturbance due to the spurious reflection.

Next, we consider a linear taper for the reciprocity test as shown in Fig. 4 [8] and compare numerical results with those of other propagation schemes in Tables I to III. Univ. Twente (FD-BPM), Univ. Porto (FD-BPM), HHI (FD-BPM), Thomson-CFS (FD-BPM), AAR-UCL (FE-BPM), and Hokkaido Univ. (wide-angle FE-BPM presented here) use beam propagation methods, in other word, unidirectional algorithms, while Univ. Hagen (method of line BPM abbreviated as MoL-BPM), IREE Prague (mode expansion propagation method abbreviated as MEPM), and Univ. Gent (MEPM) use bidirectional algorithms taking account of reflected waves. In these tables \( M \) is the number of discretization points within the CW (the number of modes for MEPM), \( N \) is the number of propagation steps, a wavelength of 1.55 \( \mu m \) is assumed, two opening angles of 0.1° and 1.0° are considered, and ‘forward’ or ‘backward’ propagation is defined in Fig. 4.

The fundamental TE and TM mode power losses in \( \% \) for the semiconductor cover case are listed in Tables I and II, respectively, where \( n_1 = 3.3, n_2 = 3.17, n_3 = 3.17, w_1 = 0.2 \mu m, w_2 = 0.1 \mu m, W = 20 \mu m \), and \( d = 1.0 \mu m \). Also in \%, the fundamental TE mode power losses for the air cover case are listed in Table III, where \( n_1 = 3.3, n_2 = 3.17, n_3 = 1.0, w_1 = 0.8 \mu m, w_2 = 0.4 \mu m, W = 20 \mu m \), and \( d = 1.0 \mu m \). In general, unidirectional algorithms are not able to fulfil the reciprocity criterion exactly [8]. However, our results (Hokkaido Univ.) obtained by the lowest discretization effort among the unidirectional algorithms fulfil fairly well the principle of reciprocity and agree approximately with the results of MEPM from Univ. Gent [8].

V. CONCLUSION

The PML boundary condition was, for the first time, incorporated into the wide-angle FE-BPM based on the Padé approximation and its effectiveness was demonstrated. The FE-BPM with PML for three-dimensional optical waveguides is now under consideration.

REFERENCES


### TABLE I
CALCULATION CONDITIONS AND THE FUNDAMENTAL TE MODE POWER LOSS FOR THE SEMICONDUCTOR COVER CASE ($n_1 = 3.3$, $n_2 = 3.17$, $n_3 = 3.17$, $w_1 = 0.2\mu m$, and $w_2 = 0.1\mu m$)

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### TABLE II
CALCULATION CONDITIONS AND THE FUNDAMENTAL TM MODE POWER LOSS FOR THE SEMICONDUCTOR COVER CASE ($n_1 = 3.3$, $n_2 = 3.17$, $n_3 = 3.17$, $w_1 = 0.2\mu m$, and $w_2 = 0.1\mu m$)

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### TABLE III
CALCULATION CONDITIONS AND THE FUNDAMENTAL TE MODE POWER LOSS FOR THE AIR COVER CASE ($n_1 = 3.3$, $n_2 = 3.17$, $n_3 = 1.0$, $w_1 = 0.2\mu m$, and $w_2 = 0.4\mu m$)

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