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Timelike Sabban curves in de Sitter space
(ド・ジッター空間内の時間的サバン曲線)

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2017.09
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1 Introduction

It is well known that Lorentzian space forms are classified into three types depending on the value of the scalar curvature. One of them is Lorentz-Minkowski space which has zero curvature. The Lorentz space form with negative curvature is Anti-de Sitter space. De Sitter space is a Lorentzian space form with positive curvature which has rich geometric properties. De sitter space is named after Willem de Sitter (1872-1934). In general relativity, a vacuum solution according to the Einstein field equation is a Lorentzian manifold whose Einstein tensor vanishes identically, and de Sitter space is one of the vacuum solutions of the Einstein field equation. In cosmology, the very early models of inflation are converging on a consistent model where our universe was best described as a de Sitter space, which is called de Sitter universe. In Mathematics, de Sitter space is defined to be the Lorentzian sphere in Minkowski space-time with a positive curvature, which is a good model for studying Lorentzian spherical geometry. This is the motivation for the investigation of submanifolds in de Sitter space from a mathematical viewpoint.

On the other hand, in physics, the locus of a moving particle is called a world line. In special relativity, world lines are timelike curves. World lines of particles/objects with constant speed are called geodesics which are straight lines in Minkowski space. The use of world lines in general relativity is basically the same as in special relativity, with the difference that space-time can be curved. Since the speed of a moving particle never exceed the speed of rays, in general relativity, world lines are timelike curves in space-time, where the tangent vectors of timelike curves fall within the lightcone.

In this thesis we consider timelike Sabban curves in de Sitter space. The original notion of Sabban curves belongs to spherical geometry in the Euclidean space. Let $\gamma : I \rightarrow S^2 \subset \mathbb{R}^3$ be a unit speed regular curve, then we have an orthonormal frame $\{\gamma, t, n\}$ along $\gamma$, where $t(s)$ is the unit tangent vector of $\gamma$ at $s$ and $n(s) = \gamma(s) \times t(s)$. Then we have the Frenet-Serret type
was introduced in §S: the Sabban frame for regular curves in always have the Sabban frame. However, we need some assumptions to define the Sabban type where \( \kappa \) is the Sabban (cf. [10]) and it is called a Sabban frame. For a unit speed curve \( \gamma \) in \( S^2 \), we always have the Sabban frame. However, we need some assumptions to define the Sabban type frame for regular curves in \( S^n \), where \( n \geq 3 \). In [9], the notion of the generalized Sabban curve was introduced in \( S^n \). In this thesis, we consider de Sitter space \( S^n_1 \) in the Minkowski space \( \mathbb{R}^{n+1}_1 \). For detailed notions about Minkowski sapce, see §2. We say that a non-lightlike curve \( \gamma : I \to S^n_1 \subset \mathbb{R}^{n+1}_1 \) is a Sabban curve if \( \| t'(s) + \delta(t(s))\gamma(s) \| \neq 0 \) at any point \( s \in I \), where \( \delta(x) \) is the sign function. Then we have an orthonormal frame \( \{ \gamma(s), t(s), n_1(s), n_2(s) \} \) of \( \mathbb{R}^4 \) along \( \gamma \), where \( n_1(s) = (t'(s) + \delta(t(s))\gamma(s))/\| t'(s) + \delta(t(s))\gamma(s) \| \) and \( n_2(s) = \gamma(s) \wedge t(s) \wedge n_1(s) \). Here, \( x_1 \wedge x_2 \wedge x_3 \) is the pseudo vector product in \( \mathbb{R}^4 \). We have the following formulae (cf. §3):

\[
\begin{align*}
\gamma'(s) &= t(s), \\
t'(s) &= -\delta(t(s))\gamma(s) + \kappa_1(s)n(s), \\
n_1'(s) &= -\delta(t(s))\delta(n_1(s))\kappa_1(s)t(s) + \kappa_2(s)n_2(s), \\
n_2'(s) &= -\delta(n_1(s))\delta(n_2(s))\kappa_2(s)n_1(s),
\end{align*}
\]

where \( \kappa_1(s) = \| t'(s) + \delta(t(s))\gamma(s) \| \neq 0 \) and \( \kappa_2(s) = \delta(n_2(s))(n'_1(s), n_2(s)) \). We call \( \{ \gamma(s), t(s), n_1(s), n_2(s) \} \) a Sabban frame along the Sabban curve \( \gamma \). In §3, we construct a frame \( \{ \gamma(s), t(s), n_1(s), \ldots, n_{n-1}(s) \} \) along the non-lightlike curve \( \gamma : I \to S^n_1 \subset \mathbb{R}^{n+1}_1 \) under some conditions on \( \gamma \). We call the above frame a generalized Lorentzian Sabban frame. In this case, \( \gamma \) is called a generalized Lorentzian Sabban curve. We prove that the generalized Lorentzian Sabban frame is a pseudo-orthonormal frame (cf. Lemma 3.1.1). If the non-lightlike curve \( \gamma \) is timelike curve, then we call it a timelike Sabban curve. For a timelike Sabban curve in \( S^n_1 \), we define the curvature functions \( \kappa_i(s) \) \( i = 1, \ldots, n-1 \), where the curvature function \( \kappa_i(s) \neq 0 \) \( i = 1, \ldots, n-2 \), while \( \kappa_{n-1}(s) \) may be equal to zero. If \( \kappa_{n-1}(s) \equiv 0 \), the timelike Sabban curve \( \gamma \) is always lying on a great de Sitter subspace \( S^n_{n-1}(n, 0) \) in \( S^n_1 \) (cf. Proposition 3.1.2).
On other hand, Izumiya and Liang [4, 7] introduced the mandala of Legendrian dualities between pseudo-spheres in Minkowski space-time. There are three kinds of pseudo-spheres in Minkowski space-time (i.e., the hyperbolic space, the de Sitter space and the lightcone). In particular, if we investigate spacelike submanifolds or timelike submanifolds in the de Sitter space, the theorem of Legendrian dualities is a fundamental tool for the study of extrinsic differential geometry on submanifolds from the viewpoint of singularity theory. Therefore, we discuss the dual hypersurfaces in the de Sitter space as an application of the duality theorem. We consider de Sitter dual hypersurfaces of timelike Sabban curves in $S^n_1$ which are defined by

$$\gamma^* = \{\xi_1 n_1 + \cdots + \xi_{n-1} n_{n-1} | s \in I, \xi_1^2 + \cdots + \xi_{n-1}^2 = 1\}.$$ 

We give classifications and characterizations of the singularities of $\gamma^*$ by using singularity theory and the geometric properties of the generalized Lorentzian Sabban frame. The main results in §3 are Theorems 3.4.2 and 3.5.2 which are analogous to the results in [9].

In §§4.1, we consider timelike Sabban curves in $S^2_1$. As we know, the spherical evolute of a Euclidean spherical curve $\gamma$ is naturally obtained as the envelope of the family of normal geodesics to $\gamma$. The evolute in Euclidean plane is naturally interpreted as a caustic [6]. The spherical evolute is also a caustic [11]. We define the notion of de Sitter evolute of a timelike Sabban curve in $S^2_1$ and study the geometric properties of those singularities from a contact viewpoint. These de Sitter evolutes are associated to timelike Sabban curves in de Sitter 2-space. The geometry of these timelike Sabban curves determine the behavior of the corresponding de Sitter evolutes. We define the *de Sitter height function* of a timelike Sabban curve, and show the bifurcation set of de Sitter height function is the de Sitter evolute. By using the techniques of the unfolding theory on such a function, we show that the singularity of the de Sitter evolute depends on the derivative of the geodesic curvature function (cf. Proposition 4.1.2). We show that the de Sitter evolute is constant if and only if the derivative of the geodesic curvature function is always equal to zero. In this case, the curve $\gamma$ is a special curve on $S^2_1$, which is called a D-slice. Moreover, we give the equivalence condition that $\gamma$ has third order contact with D-slice (cf. Proposition 4.1.3). The main result in §§4.1 is Theorem 4.1.5, which gives a
generic classification of singularities of de Sitter evolutes, and characterizes the contact between timelike Sabban curves and model curves (D-slices).

In the Euclidean space, focal sets are useful for the study of certain optical phenomena (namely, scattering, in fact a rainbow is caused by caustics), expressing some geometrical results within fluid mechanics as well as describing many medical anomalies. Focal surfaces are formed by taking the centers of the curvature spheres, which are the tangential spheres whose radii are the reciprocals of one of the principal curvatures at the point of tangency. Equivalently, they are the surfaces formed by the centers of the circles which osculate the curvature lines. In §§4.2, we consider timelike Sabban curves in $S^3_1$. We define the de Sitter evolute and the de Sitter focal surface of a timelike Sabban curve in $S^3_1$ and study geometric properties of these objects. We show that the de Sitter evolutes are the singularities of the de Sitter focal surfaces. We define the de Sitter height function $H$ on the timelike Sabban curve $\gamma(s)$ in $S^3_1$. By differentiating the de Sitter height function, we obtain a new invariant $\sigma_2(s)$ which characterizes the conditions on the derivatives of de Sitter height functions. For instance, $\frac{\partial H}{\partial s} = \frac{\partial^2 H}{\partial s^2} = \frac{\partial^3 H}{\partial s^3} = \frac{\partial^4 H}{\partial s^4} = 0$ if and only if $\sigma_2(s) = 0$ with some other conditions. We also show that the de Sitter evolute $E_s$ is singular at $s_0$ if and only if $\sigma_2(s_0) = 0$ (cf. Proposition 4.2.2). If $\sigma_2(s) \equiv 0$, then $\gamma$ is a curve not only in $S^3_1$, but also in a special kind of hyperplanes in $\mathbb{R}^4$. As an application of the theory of unfoldings of functions, we give a classification of singularities of both the de Sitter evolutes and de Sitter focal surfaces (cf. Theorem 4.2.7), which are also interpreted by the contact of timelike Sabban curves with tangent de Sitter subspaces.

Since the de Sitter 4-space is a cosmological model for the physical universe, the timelike curve in $S^4_1$ is a quite interesting subject from the view point of relativity theory. In §§4.3, we consider timelike Sabban curves in $S^4_1$. We study the contact between timelike Sabban curves and de Sitter subspaces as an application of singularity theory of smooth functions. One of the basic tools that we use is the notion of the de Sitter height function in $S^4_1$. By using the techniques of singularity theory on such a function, we define tangent de Sitter subspaces and osculating de Sitter subspaces along timelike Sabban curves. We remark that there are infinitely many tangent de Sitter subspaces of $\gamma(s)$ at $s_0$, while there is only one osculating
de Sitter subspace of $\gamma(s)$ at $s_0$. We define de Sitter focal hypersurfaces of timelike Sabban curves as the bifurcation sets of the de Sitter height functions on the curves and define the de Sitter evolute of the timelike Sabban curve under a certain generic assumption, which are different from the case in $S^3_1$. Under the above assumption, de Sitter evolutes are the second order singularities of de Sitter focal hypersurfaces (for the definition, see §§2.3). We study the geometric meanings of singularities of de Sitter focal hypersurfaces and introduce a new invariant $\sigma_3(s)$. We show that $\sigma_3(s) = 0$ for all $s$ if and only if the timelike Sabban curve is located on a special kind of hyperplanes. The main result in this subsection is Theorem 4.3.8, which gives a generic classification of singularities of de Sitter focal hypersurfaces and characterizes the contact between timelike Sabban curves and osculating de Sitter subspaces (or, tangent de Sitter subspaces). We can also consider the de Sitter evolute and the de Sitter focal surface of a timelike Sabban curve in $S^n_1$ ($n \geq 5$) similar to the case for $S^n_1$ ($n \leq 4$). However the calculations in this case is too hard to obtain meaningful results. In §§4.4, we study focal sets of timelike Sabban curves from the view point of Legendrian dualities. In [7], Izumiya investigated Legendrian dualities between pseudo-spheres in Minkowski space-time. It is a fundamental tool for the study of spacelike submanifolds from the view point of singularity theory. The unit tangent vector field of a timelike curve is a curve in the hyperbolic space and the regular part of the focal set of a timelike Sabban curve is a spacelike hypersurface. We show that the dual relationship between the tangent vector field of a timelike Sabban curve and the focal set.

We shall assume throughout the whole thesis that all the maps and manifolds are $C^\infty$ unless the contrary is explicitly stated.


2 Preliminary knowledge

2.1 The basic concepts

In this section we introduce the basic concepts in this thesis. Let $\mathbb{R}^{n+1}$ be an $(n+1)$-dimensional vector space. For any two vectors $\mathbf{x} = (x_1, \ldots, x_{n+1})$, $\mathbf{y} = (y_1, \ldots, y_{n+1})$ in $\mathbb{R}^{n+1}$, their pseudo scalar product is defined to be $\langle \mathbf{x}, \mathbf{y} \rangle = -x_1y_1 + \ldots + x_{n+1}y_{n+1}$. Here, $(\mathbb{R}^{n+1}, \langle \cdot, \cdot \rangle)$ is called Lorentz-Minkowski $(n+1)$-space (simply, Minkowski $(n+1)$-space), which is denoted by $\mathbb{R}_1^{n+1}$.

For any $n$ vectors $\mathbf{x}_1, \mathbf{x}_2, \ldots, \mathbf{x}_n \in \mathbb{R}_1^{n+1}$, their pseudo vector product is defined to be

$$\mathbf{x}_1 \wedge \mathbf{x}_2 \wedge \ldots \wedge \mathbf{x}_n = \begin{vmatrix} -e_1 & e_2 & \cdots & e_{n+1} \\ x_1^1 & x_2^1 & \cdots & x_{n+1}^1 \\ x_1^2 & x_2^2 & \cdots & x_{n+1}^2 \\ \vdots & \vdots & \cdots & \vdots \\ x_1^n & x_2^n & \cdots & x_{n+1}^n \end{vmatrix},$$

where $\{e_1, e_2, \ldots, e_{n+1}\}$ is the canonical basis of $\mathbb{R}_1^{n+1}$ and $\mathbf{x}_i = (x_{i1}^1, x_{i1}^2, \ldots, x_{i1}^{n+1})$. A non-zero vector $\mathbf{x} \in \mathbb{R}_1^{n+1}$ is called spacelike, lightlike or timelike if $\langle \mathbf{x}, \mathbf{x} \rangle > 0$, $\langle \mathbf{x}, \mathbf{x} \rangle = 0$ or $\langle \mathbf{x}, \mathbf{x} \rangle < 0$ respectively. We define the signature of $\mathbf{x}$ by

$$\text{sign}(\mathbf{x}) = \begin{cases} 1 & \mathbf{x} \text{ is spacelike}, \\ 0 & \mathbf{x} \text{ is lightlike}, \\ -1 & \mathbf{x} \text{ is timelike}. \end{cases}$$

The norm of $\mathbf{x} \in \mathbb{R}_1^{n+1}$ is defined to be $\| \mathbf{x} \| = \sqrt{\text{sign}(\mathbf{x}) \langle \mathbf{x}, \mathbf{x} \rangle}$.

Let $\gamma : I \to \mathbb{R}_1^{n+1}$ be a regular curve in $\mathbb{R}_1^{n+1}$ (i.e., $\dot{\gamma}(t) \neq 0$ for any $t \in I$ ), where $I$ is an open interval. For any $t \in I$, the curve $\gamma$ is called spacelike, lightlike or timelike if $\langle \dot{\gamma}(t), \dot{\gamma}(t) \rangle > 0$, $\langle \dot{\gamma}(t), \dot{\gamma}(t) \rangle = 0$ or $\langle \dot{\gamma}(t), \dot{\gamma}(t) \rangle < 0$ respectively. We call $\gamma$ a non-lightlike curve if $\gamma$ is a spacelike or timelike curve. The arc-length of a non-lightlike curve $\gamma$ measured from $\gamma(t_0) (t_0 \in I)$ is $s(t) = \int_{t_0}^{t} \| \dot{\gamma}(t) \| \, dt$.

The parameter $s$ is determined such that $\| \gamma'(s) \| = 1$ for the non-lightlike curve, where $\gamma'(s) = d\gamma/ds(s)$ is the derivative of $\gamma$ by $s$.  

We define the de Sitter n-space by
\[ S^n_1 = \{ x \in \mathbb{R}^{n+1}_1 \mid \langle x, x \rangle = 1 \}. \]

We define the hyperbolic n-space by
\[ H^n(-1) = \{ x \in \mathbb{R}^{n+1}_1 \mid \langle x, x \rangle = -1 \}. \]

We define the closed lightcone with the vertex \( a \) by
\[ LC_a = \{ x \in \mathbb{R}^{n+1}_1 \mid \langle x - a, x - a \rangle = 0 \}. \]

Moreover the open lightcone at the origin is defined to be
\[ LC^* = \{ x \in \mathbb{R}^{n+1}_1 \setminus \{ 0 \} \mid \langle x, x \rangle = 0 \}. \]

2.2 The Legendrian duality theorem

We now review some properties of contact manifolds and Legendrian submanifolds. Let \( N \) be a \((2n+1)\)-dimensional smooth manifold and \( K \) be a tangent hyperplane field on \( N \). Locally, such a field is defined as the field of zeros of a 1-form \( \alpha \). The tangent hyperplane field on \( K \) is non-degenerate if \( \alpha \wedge (d\alpha)^n \neq 0 \) at any point of \( N \). We say that \((N, K)\) is a contact manifold if \( K \) is a non-degenerate hyperplane field. In this case, \( K \) is called a contact structure and \( \alpha \) is a contact form. Let \( \phi : N \rightarrow N' \) be a diffeomorphism between contact manifolds \((N, K)\) and \((N', K')\). We say that \( \phi \) is a contact diffeomorphism if \( d\phi(K) = K' \). Two contact manifolds \((N, K)\) and \((N', K')\) are contact diffeomorphic if there exists a contact diffeomorphism \( \phi : N \rightarrow N' \). A submanifold \( i : L \subset N \) of a contact manifold \((N, K)\) is said to be Legendrian if \( \dim L = n \) and \( di_x(T_x L) \subset K_{i(x)} \) at any \( x \in L \). We say that a smooth fiber bundle \( \pi : E \rightarrow M \) is called a Legendrian fibration if its total space \( E \) is furnished with a contact structure and its fibers are Legendrian submanifolds. Let \( \pi : E \rightarrow M \) be a Legendrian fibration. For a Legendrian submanifold \( i : L \subset E \), \( \pi \circ i : L \rightarrow M \) is called a Legendrian map. The image of the Legendrian map \( \pi \circ i \) is called a wavefront set of \( i \) which is denoted by \( W(i) \). For any
p \in E$, it is known that there is a local coordinate system $(x_1, \ldots, x_m, p_1, \ldots, p_m, z)$ around $p$ such that $\pi(x_1, \ldots, x_m, p_1, \ldots, p_m, z) = (x_1, \ldots, x_m, z)$ and the contact structure is given by the 1-form
\[ \alpha = dz - \sum_{i=1}^{m} p_idx_i \]
(cf. [1], 20.3). One of the examples of Legendrian fibrations is given by the unit spherical tangent bundle of a Riemannian manifold. Let $M$ be a Riemannian manifold and $TM$ is its tangent bundle. Let $(x_1, \ldots, x_n)$ be local coordinates on a neighbourhood $U$ of $M$ and $(v_1, \ldots, v_n)$ be coordinates on the fiber over $U$. Let $g_{ij}$ be the components of the metric $\langle \cdot, \cdot \rangle$ with respect to the above coordinates. Then the canonical 1-form can be locally given by $\theta = \sum_{i,j} g_{ij} v_idq_i$ where $q_i = x_i \circ \pi$ for the projection $\pi : TM \to M$. Let $\tilde{\pi} : S(TM) \to M$ be the unit spherical tangent bundle with respect to the metric $\langle \cdot, \cdot \rangle$. Then the restriction of $\theta$ onto $S(TM)$ gives a contact structure and $\tilde{\pi} : S(TM) \to M$ is a Legendrian fibration (cf., [2]).

We now formulate the basic theorem in this thesis which is the fundamental tool for the study of spacelike submanifolds in pseudo-spheres in Minkowski space. We define 1-forms $\langle dv, w \rangle = -v_0dv_0 + \sum_{i=1}^{n} w_idv_i$, $\langle v, dw \rangle = -v_0dw_0 + \sum_{i=1}^{n} v_idw_i$ on $\mathbb{R}^{n+1}_1 \times \mathbb{R}^{n+1}_1$ and consider the following four double fibrations with 1-forms:

1. $(a)$ $H^n(-1) \times S^n_1 \supset \Delta_1 = \{(v, w) \mid \langle v, w \rangle = 0\}$,
   
   (b) $\pi_{11} : \Delta_1 \to H^n(-1), \pi_{12} : \Delta_1 \to S^n_1$,
   
   (c) $\theta_{11} = \langle dv, w \rangle|_{\Delta_1}, \theta_{12} = \langle v, dw \rangle|_{\Delta_1}$.

2. $(a)$ $H^n(-1) \times LC^*_1 \supset \Delta_2 = \{(v, w) \mid \langle v, w \rangle = -1\}$,
   
   (b) $\pi_{21} : \Delta_4 \to H^n(-1), \pi_{22} : \Delta_4 \to LC^*_1$,
   
   (c) $\theta_{21} = \langle dv, w \rangle|_{\Delta_2}, \theta_{22} = \langle v, dw \rangle|_{\Delta_2}$.

3. $(a)$ $LC^*_1 \times S^n_1 \supset \Delta_3 = \{(v, w) \mid \langle v, w \rangle = 1\}$,
   
   (b) $\pi_{31} : \Delta_3 \to LC^*_1, \pi_{32} : \Delta_3 \to S^n_1$,
   
   (c) $\theta_{31} = \langle dv, w \rangle|_{\Delta_3}, \theta_{32} = \langle v, dw \rangle|_{\Delta_3}$.

4. $(a)$ $LC^*_1 \times LC^*_1 \supset \Delta_4 = \{(v, w) \mid \langle v, w \rangle = -2\}$,
   
   (b) $\pi_{41} : \Delta_4 \to LC^*_1, \pi_{42} : \Delta_4 \to LC^*_1$,
   
   (c) $\theta_{41} = \langle dv, w \rangle|_{\Delta_4}, \theta_{42} = \langle v, dw \rangle|_{\Delta_4}$.
Here, $\pi_{i1}(v, w) = v$, $\pi_{i2}(v, w) = w$ are the canonical projections. Moreover, $\theta_{i1} = \langle dv, w \rangle |_{\Delta_i}$ and $\theta_{i2} = \langle v, dw \rangle |_{\Delta_i}$ are the restrictions of the 1-forms $\langle dv, w \rangle$ and $\langle v, dw \rangle$ on $\Delta_i$. We remark that $\theta_{i1}^{-1}(0)$ and $\theta_{i2}^{-1}(0)$ define the same tangent hyperplane field over $\Delta_i$ which is denoted by $K_i$. In [7], the following theorem was shown:

**Theorem 2.2.1.** Under the same notations as the previous paragraph, each $(\Delta_i; K_i)(i = 1, 2, 3, 4)$ is a contact manifold and both of $\pi_{ij}(j = 1, 2)$ are Legendrian fibrations. Moreover those contact manifolds are contact diffeomorphic each other. In this thesis, we only consider $(\Delta_1, K_1)$ and $(\Delta_5, K_5)$.

In §3 we consider the following double fibrations:

$$S^n_1 \times S^n_1 \supset \Delta_5 = \{(v, w) | \langle v, w \rangle = 0\},$$

$$\pi_{51}: \Delta_5 \to S^n_1, \pi_{52}: \Delta_5 \to S^n_1,$$

$$\theta_{51} = \langle dv, w \rangle |_{\Delta_5}, \theta_{52} = \langle v, dw \rangle |_{\Delta_5}.$$

Here, $\pi_{51}(v, w) = v$, $\pi_{52}(v, w) = w$ (see, [4]). In §4 we also consider the following double fibrations in $S^n_1$ for $n = 2, 3, 4$:

$$H^n(-1) \times S^n_1 \supset \Delta_1 = \{(v, w) | \langle v, w \rangle = 0\},$$

$$\pi_{11}: \Delta_5 \to H^n(-1), \pi_{12}: \Delta_1 \to S^n_1,$$

$$\theta_{11} = \langle dv, w \rangle |_{\Delta_1}, \theta_{12} = \langle v, dw \rangle |_{\Delta_1}.$$

If we have an isotropic mapping $i: L \to \Delta_i$ (i.e., $i^*\theta_{ij} = 0$), we say that $\pi_{i1}(i(L))$ and $\pi_{i2}(i(L))$ are $\Delta_i$-dual to each other ($i = 1, 5$). For detailed properties of Legendrian fibrations, see [1].

### 2.3 Unfolding of function germs

We review some results of function germs as an application of the unfolding theory of functions. Let $F: (\mathbb{R} \times \mathbb{R}^r,(s_0, x_0)) \to \mathbb{R}$ be a function germ, $f(s) = F(s, x_0)$. We call $F$ an $r$-parameter unfolding of $f$. If $f^{(p)}(s_0) = 0$ for all $1 \leq p \leq k$ and $f^{(k+1)}(s_0) \neq 0$, we say $f$ has $A_k$-singularity at $s_0$. We also say $f$ has $A_{\geq k}$-singularity at $s_0$ if $f^{(p)}(s_0) = 0$ for all $1 \leq p \leq k$. 

10
Let $F$ be a $r$-parameter unfolding of $f$ and $f$ has $A_k$-singularity ($k \geq 1$) at $s_0$, we define the $(k - 1)$-jet of the partial derivative $\partial F/\partial x_i$ at $s_0$ as

$$J^{(k-1)}\left(\frac{\partial F}{\partial x_i}(s, x_0)\right)(s_0) = \sum_{j=1}^{k+1} \alpha_{ji}(s - s_0)^j, \ (i = 1, \ldots, r).$$

If the rank of $k \times r$ matrix $(\alpha_{0i}, \alpha_{ji})$ is $k$ ($k \leq r$), then $F$ is called a versal unfolding of $f$, where $\alpha_{0i} = \partial F/\partial x_i(s_0, x_0)$. Under the same condition as the above, $F$ is called a $p$-versal unfolding if the $(k - 1) \times r$ matrix of coefficients $(\alpha_{ji})$ has rank $k - 1$ ($k - 1 \leq r$). The discriminant set of $F$ is defined by

$$D_F = \{ x \in \mathbb{R}^r \mid \exists s \in \mathbb{R}, F(s, x) = \frac{\partial F}{\partial s}(s, x) = 0 \}.$$

The bifurcation set of $F$ is

$$B_F = \{ x \in \mathbb{R}^r \mid \exists s, \frac{\partial F}{\partial s}(s, x) = \frac{\partial^2 F}{\partial s^2}(s, x) = 0 \}.$$

We also define

$$D_i^j = \{ x \in \mathbb{R}^r \mid \exists s \in \mathbb{R}, F(s, x) = \frac{\partial F}{\partial s}(s, x) = \cdots = \frac{\partial^i F}{\partial s^i}(s, x) = 0 \},$$

which is called an $ith$-order discriminant set of $F$. We are interested in classification of $D_i^j$ by diffeomorphisms. We say that two function germs $f, g : (\mathbb{R}, 0) \rightarrow \mathbb{R}$ are $R$-equivalent if there exist a diffeomorphism germ $\phi : (\mathbb{R}, 0) \rightarrow (\mathbb{R}, 0)$ such that $f \circ \phi(s) = g(s) + (f(0) - g(0))$ for any $s \in (\mathbb{R}, 0)$. If $f : (\mathbb{R}, 0) \rightarrow \mathbb{R}$ has an $A_k$-singularity at 0, then $f$ is $R$-equivalent to $g(s) = \pm s^{k+1}$.

We can also show that the following proposition [3].

**Proposition 2.3.1.** The unfolding $G : (\mathbb{R} \times \mathbb{R}^r, (0, 0)) \rightarrow (\mathbb{R}, 0)$ given by

$$G(s, x) = \pm s^{k+1} + x_1 + x_2 s + \cdots + x_k s^{k-1}$$

is a versal unfolding of $g(s) = \pm s^{k+1}$ at 0.

Let $F, G : (\mathbb{R} \times \mathbb{R}^r, (0, 0)) \rightarrow (\mathbb{R}, 0)$ be unfolding of $f, g : (\mathbb{R}, 0) \rightarrow (\mathbb{R}, 0)$, respectively. We say that $F, G$ are $P$-$R$-equivalent if there exists a diffeomorphism germ $\Phi : (\mathbb{R} \times \mathbb{R}^r, (0, 0)) \rightarrow$
(\mathbb{R} \times \mathbb{R}^r, (0, 0)) of the form \( \Phi(s, x) = (\phi_1(s, x), \phi_2(x)) \) such that \( F \circ \Phi = G \). So, if \( F, G \) are P-\( \mathcal{R} \)-equivalent, then \( f, g \) are \( \mathcal{R} \)-equivalent. We also say \( F, G \) are \( P-\mathcal{R}^+ \)-equivalent if there exist a germ of a diffeomorphism \( \Phi : (\mathbb{R} \times \mathbb{R}^r, (0, 0)) \to (\mathbb{R} \times \mathbb{R}^r, (0, 0)) \) and a germ of a function \( c : (\mathbb{R}^r, 0) \to \mathbb{R} \) such that \( G(s, x) = F(\Phi(s, x)) + c(x) \). By the uniqueness of versal unfolding [5], we have the following theorem.

**Theorem 2.3.2.** Let \( F, G : (\mathbb{R} \times \mathbb{R}^r, (0, 0)) \to (\mathbb{R}, 0) \) be unfolding of \( f, g : (\mathbb{R}, 0) \to (\mathbb{R}, 0) \), respectively. Suppose that \( F, G \) are versal unfolding of \( f, g \) respectively. If \( f, g \) are \( \mathcal{R} \)-equivalent, then \( F, G \) are P-\( \mathcal{R} \)-equivalent.

By an induction, we show the following proposition.

**Proposition 2.3.3.** Let \( F, G : (\mathbb{R} \times \mathbb{R}^r, (0, 0)) \to (\mathbb{R}, 0) \) be unfolding of \( f, g : (\mathbb{R}, 0) \to (\mathbb{R}, 0) \), respectively. If \( F, G \) are P-\( \mathcal{R} \)-equivalent, then there exists a diffeomorphism germ \( \phi : (\mathbb{R}^r, 0) \to (\mathbb{R}^r, 0) \) such that \( \phi(D^i_G) = D^i_F \) as set germs for any \( i \).

For the unfolding \( G : (\mathbb{R} \times \mathbb{R}^r, (0, 0)) \to (\mathbb{R}, 0) \) given by

\[
G(s, x) = \pm s^{k+1} + x_1 + x_2 s + \cdots + x_k s^{k-1},
\]

we show that \( x = (x_1, x_2, \ldots, x_k) \in D^i_G \) (1 \( \leq i \leq k - 1 \)) if and only if

\[
\begin{align*}
x_1 &= \mp s^{k+1} - x_2 s - \cdots - x_k s^{k-1}, \\
x_2 &= \mp (k + 1) s^k - 2x_3 s - \cdots - (k - 1)x_k s^{k-2}, \\
x_3 &= \mp \frac{(k+1)}{2} s^k - 3x_4 s - \cdots - \frac{(k-1)(k-2)}{2} s^{k-3}, \\
&\quad \vdots \\
x_{i+1} &= \mp \frac{(k+1)(k-1)(k-3)(k-5)\cdots s^{k+1-i} - (i + 1)x_{i+2} s - \cdots - \frac{(k-1)(k-2)(k-3)(k-5)\cdots}{(i-1)!} x_k s^{k-i}}{(i-1)!}. 
\end{align*}
\]  

We now consider a map-germ \( DA_k^+: (\mathbb{R}^{k-1}, 0) \to (\mathbb{R}^k, 0) \) defined by

\[
DA_k^+(u_1, \ldots, u_{k-1}) = (\pm u_1^{k+1} + \sum_{i=2}^{k-1} (i - 1) u_i^i u_i, \mp (k + 1) u_1^k - \sum_{i=2}^{k-1} i u_i^{i-1} u_i, u_2, \ldots, u_{k-1}).
\]

We remark that (Im\( DA_k^+, 0 \)) is diffeomorphic to the cusp \( C = \{(t^2, t^3) | t \in (\mathbb{R}, 0)\} \) and (Im\( DA_k^+, 0 \)) is diffeomorphic to the swallowtail \( SW = \{(3u^4 + u^2 v, 4u^3 + 2uv, v) | (u, v) \in (\mathbb{R}^2, 0)\} \) as set-germs. we show the following proposition [8].
Proposition 2.3.4. Let $F, G : (\mathbb{R} \times \mathbb{R}^r, (0, 0)) \to (\mathbb{R}, 0)$ be unfolding of $f, g : (\mathbb{R}, 0) \to (\mathbb{R}, 0)$, respectively. If $F, G$ are $P\mathcal{R}^+$-equivalent, then there exists a diffeomorphism germ $\phi : (\mathbb{R}^r, 0) \to (\mathbb{R}^r, 0)$ such that $\phi(B_F) = B_G$.

By Theorem 2.3.2 and Proposition 2.3.3, we have the assertion. This completes the proof.

This means that $(D_\lambda^s_{r, 0})$ for some $\lambda$. If we put $s = 3$, then $\lambda^s_{r, 0}$ is $P\mathcal{R}$-equivalent to $(\text{Im} D_{\lambda^s_{r, 0}}^\pm \times \mathbb{R}^{r-k}, 0)$ as set-germs. Moreover, $(D_{\lambda^s_{r, 0}}^{k-1}, x_0)$ is $P\mathcal{R}$-equivalent to $(\text{Im} \sigma_1[2, 3, \ldots, k, k + 1] \times \mathbb{R}^{r-k}, 0)$ as set-germs, where $\sigma_1[2, 3, \ldots, k, k + 1] : (\mathbb{R}, 0) \to (\mathbb{R}^k, 0)$ is a curve defined by

$$\sigma_1[2, 3, \ldots, k, k + 1](t) = (t^2, t^3, \ldots, t^k, t^{k+1}).$$

Proof. By the equation 1 for $i = 1$, we have

$$\begin{align*}
x_1 &= \mp s^{k+1} - x_2 s - \cdots - x_k s^{k-1}, \\
x_2 &= \mp (k + 1)s^k - 2x_3 s - \cdots - (k-1)x_k s^{k-2}.
\end{align*}$$

Then

$$\begin{align*}
x_1 &= \mp s^{k+1} - \mp s^2 + \cdots + (k-2)x_k s^{k-1}, \\
x_2 &= \mp (k + 1)s^k - 2x_3 s - \cdots - (k-1)x_k s^{k-2}.
\end{align*}$$

If we put $s = u_1, x_3 = u_2, \ldots, x_k = u_{k-1}$, the above equations means that $(D_{\lambda^s_{r, 0}}^{k+1}, 0) = (\text{Im} D_{\lambda^s_{r, 0}}^\pm \times \mathbb{R}^{r-k}, 0)$. Since $f(s)$ has an $A_k$ singularity at $s = s_0$, $f$ is $\mathcal{R}$-equivalent to $\pm t^{k+1}$. By Theorem 2.3.2, $F$ and $G$ are $P\mathcal{R}$-equivalent, so $(D_{\lambda^s_{r, 0}}^{k+1}, 0)$ and $(D_{\lambda^s_{r, 0}}^{k+1}, 0)$ are diffeomorphic as set-germs.

On the other hand, if we continue the above calculation until $i = k - 1$, we can show that

$$x_1 = \lambda_1(k)s^{k+1}, \quad x_2 = \lambda_2(k)s^k, \quad x_3 = \lambda_3(k)s^{k-1}, \ldots, \quad x_k = \lambda_k(k)s^2,$$

for some $\lambda_i(k) \in \mathbb{Q}$. By an coordinate change on $\mathbb{R}^r$, we have

$$x_1 = s^2, \quad x_2 = s^3, \quad x_3 = s^4, \ldots, \quad x_k = s^{k+1}.$$

This means that $(D_{\lambda^s_{r, 0}}^{k-1}, 0)$ is diffeomorphic to $(\text{Im} \sigma_1[2, 3, \ldots, k, k + 1] \times \mathbb{R}^{r-k}, 0)$ as set germs. By Theorem 2.3.2 and Proposition 2.3.3, we have the assertion. This completes the proof. \qed
Theorem 2.3.6. Let $F : (\mathbb{R} \times \mathbb{R}^r, (s_0, x_0)) \to \mathbb{R}$ be an $r$-parameter unfolding of $f$ which has the type $A_k$ at $s_0$. If $F$ is a $p$-versal unfolding of $f$, then we have the following:

1. If $k = 3$, then $B_F$ is locally diffeomorphic to $C \times \mathbb{R}^{r-2}$.
2. If $k = 4$, then $B_F$ is locally diffeomorphic to $SW \times \mathbb{R}^{r-3}$.
3. If $k = 5$, then $B_F$ is locally diffeomorphic to $BF \times \mathbb{R}^{r-4}$.

Here $C = \{(x_1, x_2) | x_1^2 = x_2^3\}$ is the cusp, $SW = \{(x_1, x_2, x_3) | x_1 = 3u^4 + u^2v, x_2 = 4u^3 + 2uv, x_3 = v\}$ is the swallowtail and $BF = \{(x_1, x_2, x_3, x_4) | x_1 = 4u^5 + 2u^3v + uv^2 + v, x_2 = -5u^4 - 3u^2v - 2uv, x_3 = v, x_4 = w\}$ is the butterfly.
3 Lorentzian Sabban curves in de Sitter n-space

3.1 Differential geometry of curves in de Sitter space

Let \( \gamma : I \rightarrow \mathbb{R}^{n+1} \) be a regular curve (i.e., \( \gamma(t) = \frac{dt}{dt} \neq 0 \)), where \( I \) is an open interval. Let \( S^n_1 = \{ x \in \mathbb{R}^{n+1} | \langle x, x \rangle = 1 \} \) be the n-dimensional de Sitter space. Given a vector \( n \in \mathbb{R}^{n+1}\setminus\{0\} \) and a real number \( c \), the hyperplane with a normal vector \( n \) is defined to be \( HP(n, c) = \{ x \in \mathbb{R}^{n+1} | \langle x, n \rangle = c \} \). A subspace in \( S^n_1 \) is given by

\[
S^n_q^{-1}(n, c) = S^n_1 \cap HP(n, c) = \{ x \in S^n_1 | \langle x, n \rangle = c \},
\]

where \( q = 0 \) if \( n \) is a timelike vector or a lightlike vector, \( q = 1 \) if \( n \) is a spacelike vector. We say that \( S^n_q^{-1}(n, c) \) is a great de Sitter subspace if \( q = 1 \) and a small de Sitter subspace if \( q = 0 \), respectively.

We now define generalized Lorentzian Sabban frame of a non-lightlike curve in \( S^n_1 \). Let \( \gamma : I \rightarrow S^n_1 \) be a regular non-lightlike curve. We can reparametrize \( \gamma \) by the arc-length \( s \), so that we have the unit tangent vector \( t(s) = \gamma'(s) \). When \( \| t'(s) + \delta(t(s)) \gamma(s) \| \neq 0 \), where \( \delta(x) = \text{sign}(x) \), we define a unit vector \( n_1(s) = (t'(s) + \delta(t(s)) \gamma(s))/\|t'(s) + \delta(t(s)) \gamma(s)\| \). We write \( \kappa_1(s) = \| t'(s) + \delta(t(s)) \gamma(s) \| \), we consider \( \kappa_2(s) = \| n_1'(s) + \delta(n_1(s)) \kappa_1(s) t(s) \| \). In the case when \( \kappa_2(s) \neq 0 \), we have another unit vector \( n_2(s) = (n_1'(s) + \delta(n_1(s)) \kappa_1(s) t(s))/\| n_1'(s) + \delta(t(s)) \delta(n_1(s)) \kappa_1(s) t(s) \| \). By the same way, we have the following functions and unit vectors.

\[
\kappa_i(s) = \| n_{i-1}'(s) + \delta(n_{i-1}(s)) \delta(n_{i-2}(s)) \kappa_{i-1}(s) n_{i-2}(s) \|, \\
n_i(s) = \frac{n_{i-1}'(s) + \delta(n_{i-1}(s)) \delta(n_{i-2}(s)) \kappa_{i-1}(s) n_{i-2}(s)}{\kappa_i(s)},
\]

for \( i = 1, \ldots, n-2 \). We assume that \( \kappa_i(s) \neq 0 \) for all \( i \). At last, we define

\[
n_{n-1}(s) = \frac{\gamma(s) \wedge t(s) \wedge n_1(s) \wedge \cdots n_{n-2}(s)}{\| \gamma(s) \wedge t(s) \wedge n_1(s) \wedge \cdots n_{n-2}(s) \|}, \\
\kappa_{n-1}(s) = \langle n_{n-1}(s), n'_{n-2}(s) \rangle.
\]

We call \( \gamma \) a generalized Lorentzian Sabban curve in \( S^n_1 \), \( \kappa_i(s) \) a \( i \)th-curvature of \( \gamma(s) \).
With the above notation, by a straightforward calculation, we can prove the set of vectors
\[ \{ \gamma(s), t(s), n_1(s), \ldots, n_{n-1}(s) \} \]
is a frame of \( \mathbb{R}^{n+1}_1 \) along \( \gamma \). We call this frame a *generalized Lorentzian Sabban frame* along \( \gamma \).

We remark that \( \kappa_i(s) \neq 0 \) for \( i = 1, \ldots, n-2 \), while \( \kappa_{n-1}(s) \) might be equal to 0.

**Lemma 3.1.1.** With the above notation, vectors \( \gamma(s), t(s), n_1(s), \ldots, n_{n-1}(s) \) are orthogonal to each other.

**Proof.** By definition, \( n_{n-1}(s) \) is orthogonal to \( \gamma(s), t(s), n_1(s), \ldots, n_{n-2}(s) \). For other vectors, we can prove by calculation. For example,
\[
\langle \gamma(s), n_1(s) \rangle = \frac{1}{\kappa_1} \langle \langle \gamma(s), t'(s) \rangle + \delta(t(s)) \langle \gamma(s), \gamma(s) \rangle \rangle.
\]
Since \( \langle \gamma(s), \gamma(s) \rangle = 1 \), so we have \( \langle \gamma(s), t(s) \rangle = 0 \). Then \( \langle \gamma(s), t(s) \rangle' = \langle \gamma'(s), t(s) \rangle + \langle \gamma(s), t'(s) \rangle = 0 \), so
\[
\langle \gamma(s), t'(s) \rangle = -\langle \gamma'(s), t(s) \rangle = -\delta(t(s)).
\]
Then
\[
\langle \gamma(s), n_1(s) \rangle = \frac{1}{\kappa_1} (-\langle \gamma'(s), t(s) \rangle + \delta(t(s)))
= \frac{1}{\kappa_1} (-\delta(t(s)) + \delta(t(s))) = 0.
\]
Therefore \( \gamma(s) \) and \( n_1(s) \) are orthogonal. We can prove all vectors are orthogonal to each other by the same way.

We have the following *Frenet-Serret type formulae* of non-lightlike curves in de Sitter n-
We denote that Sitter subspace which have the following Frenet-Serret type formulae in de Sitter n-space.

**Proof.**

Proposition 3.1.2. \( \kappa \) is constantly equal to 0, \( \kappa(s) \) is a timelike Sabban curve if \( \kappa(s) = 0 \), then a generalized Lorentzian Sabban curve is called a timelike Sabban curve which have the following Frenet-Serret type formulae in de Sitter n-space.

\[
\begin{align*}
\gamma'(s) &= t(s), \\
t'(s) &= -\delta(t(s))\gamma(s) + \kappa_1(s)n_1(s), \\
n'_1(s) &= -\delta(t(s))\delta(n_1(s))\kappa_1(s)t(s) + \kappa_2(s)n_2(s), \\
\cdots &= \cdots \\
n'_i(s) &= -\delta(n_{i-1}(s))\delta(n_i(s))\kappa_i(s)n_{i-1}(s) + \kappa_{i+1}(s)n_{i+1}(s), \\
\cdots &= \cdots \\
n'_{n-2}(s) &= -\delta(n_{n-3}(s))\delta(n_{n-2}(s))\kappa_{n-2}(s)n_{n-3}(s) + \kappa_{n-1}(s)n_{n-1}(s), \\
n'_{n-1}(s) &= -\delta(n_{n-2}(s))\delta(n_{n-1}(s))\kappa_{n-1}(s)n_{n-2}(s).
\end{align*}
\]

If \( \gamma \) is timelike, then a generalized Lorentzian Sabban curve is called a timelike Sabban curve which have the following Frenet-Serret type formulae in de Sitter n-space.

\[
\begin{align*}
\gamma'(s) &= t(s), \\
t'(s) &= \gamma(s) + \kappa_1(s)n_1(s), \\
n'_1(s) &= \kappa_1(s)t(s) + \kappa_2(s)n_2(s), \\
n'_2(s) &= -\kappa_2(s)n_1(s) + \kappa_3(s)n_3(s), \\
\cdots &= \cdots \\
n'_i(s) &= -\kappa_i(s)n_{i-1}(s) + \kappa_{i+1}(s)n_{i+1}(s), \\
\cdots &= \cdots \\
n'_{n-2}(s) &= -\kappa_{n-2}(s)n_{n-3}(s) + \kappa_{n-1}(s)n_{n-1}(s), \\
n'_{n-1}(s) &= -\kappa_{n-1}(s)n_{n-2}(s).
\end{align*}
\]

We have the geometric meaning of the curvature \( \kappa_{n-1}(s) \) of timelike Sabban curve \( \gamma(s) \) as follows.

**Proposition 3.1.2.** Let \( \gamma : I \to S^n_1 \) be a timelike Sabban curve. Then there exists a great de Sitter subspace \( S^n_{1-1}(n,0) \) such that \( \gamma(I) \subset S^n_{1-1}(n,0) \) if and only if \( \kappa_{n-1}(s) \equiv 0 \).

**Proof.** Suppose that \( \kappa_{n-1}(s) \equiv 0 \). By the Frenet-Serret type formula (2), \( n_{n-1}(s) \) is a constant vector. We denote that \( n_{n-1}(s) = n \). We consider a function \( f : I \to \mathbb{R} \) defined by \( f(s) = \langle \gamma(s), n \rangle \), then we have \( f(s) = \langle \gamma(s), n \rangle = \langle \gamma(s), n_{n-1}(s) \rangle = 0 \) and \( f'(s) = \langle t(s), n \rangle = \langle t(s), n_{n-1}(s) \rangle = 0 \). Therefore \( f(s) \) is constantly equal to 0, so \( \gamma(s) \in S^n_{1-1}(n,0) \).
For the converse, suppose that there exists \( S_{1}^{n-1}(\mathbf{n}, 0) \) such that \( \gamma(I) \subset S_{1}^{n-1}(\mathbf{n}, 0) \). Then the function \( f \) as above is constantly equal to 0. It follows that \( f'(s) = \langle t(s), \mathbf{n} \rangle = 0 \). Thus \( f''(s) = \langle t'(s), \mathbf{n} \rangle = \langle \gamma(s) + \kappa_{1}(s)\mathbf{n}_{1}(s), \mathbf{n} \rangle = \kappa_{1}(\mathbf{n}_{1}(s), \mathbf{n}) = 0 \). Since \( \kappa_{1}(s) \neq 0 \), we have \( \langle \mathbf{n}_{1}(s), \mathbf{n} \rangle = 0 \). It follows that

\[
\langle \mathbf{n}_{1}'(s), \mathbf{n} \rangle = \langle \kappa_{1}(s)t(s) + \kappa_{2}(s)\mathbf{n}_{2}(s), \mathbf{n} \rangle = \kappa_{2}(\mathbf{n}_{2}(s), \mathbf{n}) = 0.
\]

Since \( \kappa_{2}(s) \neq 0 \), we have \( \langle \mathbf{n}_{2}(s), \mathbf{n} \rangle = 0 \). It follows that

\[
\langle \mathbf{n}_{2}'(s), \mathbf{n} \rangle = \langle -\kappa_{2}(s)\mathbf{n}_{1}(s) + \kappa_{3}(s)\mathbf{n}_{3}(s), \mathbf{n} \rangle = \kappa_{3}(\mathbf{n}_{3}(s), \mathbf{n}) = 0.
\]

Since \( \kappa_{3}(s) \neq 0 \), we have \( \langle \mathbf{n}_{3}(s), \mathbf{n} \rangle = 0 \). We continue this procedure. Finally, we have \( \kappa_{n-1}(s)\langle \mathbf{n}_{n-1}(s), \mathbf{n} \rangle = 0 \). If \( \langle \mathbf{n}_{n-1}(s), \mathbf{n} \rangle = 0 \), then \( \mathbf{n} \) is orthogonal to all vectors of the generalized Sabban frame \( \{ \gamma(s), t(s), \mathbf{n}_{1}(s), \ldots, \mathbf{n}_{n-1}(s) \} \) which contradicts to the fact that the generalized Sabban frame is a basis of \( \mathbb{R}_{1}^{n+1} \) and \( \mathbf{n} \neq 0 \). Thus \( \kappa_{n-1}(s) = 0 \) for any \( s \in I \). \( \square \)

### 3.2 De Sitter height function

In this section we introduce a family of functions which is useful for the study of invariants of timelike curves in the \( S_{1}^{n} \). We consider \( \gamma^{(k)}(s) \), by the Frenet-Serret type formulae, we have the following lemma.

**Lemma 3.2.1.** Let \( \gamma : I \rightarrow S_{1}^{n} \) be a timelike Sabban curve. Then \( \gamma^{(k)}(s) \) has the following form:

1. \( \gamma'(s) = t(s) \).
2. \( \gamma''(s) = \gamma(s) + \kappa_{1}\mathbf{n}_{1}(s) \).
3. For \( 3 \leq k \leq n \), there exist functions \( x(s), y(s), a_{1}(s), \ldots, a_{k-2}(s) \) such that

\[
\gamma^{(k)}(s) = x(s)\gamma(s) + y(s)t(s) + a_{1}(s)\mathbf{n}_{1}(s) + \cdots + a_{k-2}(s) + \kappa_{1}(s)\kappa_{2}(s)\cdots\kappa_{k-1}(s)\mathbf{n}_{k-1}(s).
\]

(3)
Proof. By the Frenet-Serret type formulae, (1),(2) hold.

Now we prove (3). Let \( k = 3 \), we have

\[
\gamma^{(3)}(s) = \{ \gamma(s) + \kappa_1(s)n_1(s) \}'
= t(s) + \kappa'_1(s)n_1(s) + \kappa_1(s)n'_1(s)
= t(s) + \kappa'_1(s)n_1(s) + \kappa_1(s)(\kappa_1(s)t(s) + \kappa_2(s)n_2(s))
= (1 + \kappa_1(s))^2 t(s) + \kappa'_1(s)n_1(s) + \kappa_1(s)\kappa_2(s)n_2(s).
\]

So (3) holds for \( k = 3 \).

We assume that (3) holds for \( k - 1 \), there exist \( x(s), y(s), a_1(s), \ldots, a_{k-3}(s) \) such that

\[
\gamma^{(k-1)}(s) = x(s)\gamma(s) + y(s)t(s) + a_1(s)n_1(s) + \cdots + a_{k-3}(s)n_{k-3}(s)
+ \kappa_1(s)\kappa_2(s)\cdots\kappa_{k-2}(s)n_{k-2}(s).
\]

We can calculate \( \gamma^{(k)}(s) \) by using the Frenet-Serret type formulae,

\[
\gamma^{(k)}(s) = \{ \gamma^{(k-1)} \}'(s)
= \{ x(s)\gamma(s) + y(s)t(s) + a_1(s)n_1(s) + \cdots + a_{k-3}(s)n_{k-3}(s)
+ \kappa_1(s)\kappa_2(s)\cdots\kappa_{k-2}(s)n_{k-2}(s) \}'
= (x'(s) + y(s))\gamma(s) + (x(s) + y'(s) + a_1(s)\kappa_1(s))t(s) + \cdots
+ (a_{k-3}(s)\kappa_{k-2}(s) + (\kappa_1(s)\kappa_2(s)\cdots\kappa_{k-2}(s))'n_{k-2}(s)
+ \kappa_1(s)\kappa_2(s)\cdots\kappa_{k-2}(s)\kappa_{k-1}(s)n_{k-1}(s).
\]

The coefficient of \( n_{k-1}(s) \) is \( \kappa_1(s)\kappa_2(s)\cdots\kappa_{k-2}(s)\kappa_{k-1}(s) \), then (3) holds for all \( k = 3, 4, \ldots, n \).

\( \square \)

For a timelike curve \( \gamma : I \rightarrow S^n_1 \), we define a family of de Sitter height function \( H^* : I \times S^n_1 \rightarrow \mathbb{R} \) by \( H^*(s, v) = \langle \gamma(s), v \rangle \). We write \( h^*_v(s) = H^*(s, v) \). Then we have the following proposition.

Proposition 3.2.2. Let \( \gamma : I \rightarrow S^n_1 \) be a timelike Sabban curve. Then we have the following:
(1) \( h^*_v(s) = 0 \) if and only if there exist \( y, a_1, \ldots, a_{n-2}, a_{n-1} \in \mathbb{R} \) such that \( v = yt(s) + a_1n_1(s) + \cdots + a_{n-2}n_{n-2}(s) + a_{n-1}n_{n-1}(s) \).
\[ \cdots + a_{n-1}n_{n-1}(s) + y^2 + a_1^2 + \cdots + a_{n-1}^2 = 1. \]

(2) For \( k < n \), \( h^k_v(s) = (h^k_v)'(s) = \cdots = (h^k_v)^{(k)}(s) = 0 \) if and only if there exist \( a_k, \cdots, a_{n-2}, a_{n-1} \in \mathbb{R} \) such that \( v = a_kn_k(s) + \cdots + a_{n-1}n_{n-1}(s) \) and \( a_k^2 + \cdots + a_{n-1}^2 = 1 \).

(3) \( h^k_v(s) = (h^k_v)'(s) = \cdots = (h^k_v)^{(n)}(s) = 0 \) if and only if \( v = \pm n_{n-1}(s) \) and \( \kappa_{n-1}(s) = 0 \).

(4) For \( k > n \), \( h^k_v(s) = (h^k_v)'(s) = \cdots = (h^k_v)^{(k)}(s) = 0 \) if and only if \( v = \pm n_{n-1}(s) \) and \( \kappa_{n-1}(s) = \kappa'_{n-1}(s) = \cdots = \kappa^{(k-n)}_{n-1}(s) = 0 \).

**Proof.** (1) By using the Frenet-Serret type formulae of timelike curve, there exist \( x, y, a_1, \cdots, a_{n-1} \in \mathbb{R} \) such that

\[ v = x\gamma(s) + yt(s) + a_1n_1(s) + \cdots + a_{n-1}n_{n-1}(s). \]

Then

\[ h^k_v(s) = \langle \gamma(s), v \rangle = \langle \gamma(s), x\gamma(s) + yt(s) + a_1n_1(s) + \cdots + a_{n-1}n_{n-1}(s) \rangle = x, \]

we have \( x = 0 \). Since \( v \in S^o_1 \), then \( -y^2 + a_1^2 + \cdots + a_{n-1}^2 = 1 \).

(2) Let \( k = 1 \), we have

\[ (h^1_v)'(s) = \langle t(s), v \rangle = -y. \]

Thus \( h^1_v(s) = (h^1_v)'(s) = 0 \) means \( x = y = 0 \) and \( a_1^2 + \cdots + a_{n-1}^2 = 1 \). Then (2) holds for \( k = 1 \).

We now assume that (2) for \( k - 1 \), it means that \( h^k_v(s) = (h^k_v)'(s) = \cdots = (h^k_v)^{(k-1)}(s) = 0 \) if and only if there exist \( a_{k-1}, \cdots, a_{n-1} \in \mathbb{R} \) such that \( v = a_{k-1}n_{k-1}(s) + \cdots + a_{n-1}n_{n-1}(s) \) and \( a_{k-1}^2 + \cdots + a_{n-1}^2 = 1 \). By assertion 3.1, we have

\[ \gamma^{(k)}(s) = (x'(s) + y(s))\gamma(s) + \cdots + \kappa_1(s)\kappa_2(s) \cdots \kappa_{k-2}(s)\kappa_{k-1}(s)n_{k-1}(s). \]

Therefore, \( h^k_v(s) = (h^k_v)'(s) = \cdots = (h^k_v)^{(k)}(s) = 0 \) if and only if

\[ \langle \gamma^{(k)}(s), a_{k-1}n_{k-1}(s) + \cdots + a_{n-1}n_{n-1}(s) \rangle = a_{k-1}\kappa_1(s)\kappa_2(s) \cdots \kappa_{k-2}(s)\kappa_{k-1}(s) = 0. \]

Since \( k-1 < n-1 \), we have \( \kappa_1(s)\kappa_2(s) \cdots \kappa_{k-2}(s)\kappa_{k-1}(s) \neq 0 \), so \( a_{k-1} = 0 \) and \( a_k^2 + \cdots + a_{n-1}^2 = 1 \).

This completes the induction step.
When \( k = n \), by the calculation as above, \( h^*_v(s) = (h^*_v)'(s) = \cdots = (h^*_v)^{(n)}(s) = 0 \) if and only if

\[
(h^*_v)^{(n)}(s) = \langle \gamma^{(n)}(s) , \pm n_{n-1}(s) \rangle = \pm \kappa_1(s) \kappa_2(s) \cdots \kappa_{k-2}(s) \kappa_{n-1}(s),
\]

it means that \( \kappa_{n-1}(s) = 0 \). This completes the proof of (3).

By assertion (3), \( h^*_v(s) = (h^*_v)'(s) = \cdots = (h^*_v)^{(n+1)}(s) = 0 \) if and only if \( \mathbf{v} = \pm n_{n-1}(s) \).

\( \kappa_{n-1}(s) = 0 \) and \( (h^*_v)^{(n+1)}(s) = 0 \). By Lemma 3.1, we have

\[
\gamma^{(n)}(s) = \overline{\mathbf{r}}(s) \gamma(s) + \overline{\mathbf{g}}(s) \mathbf{t}(s) + \overline{\mathbf{a}}_1(s) \mathbf{n}_1(s) + \cdots + \overline{a}_{n-2}(s) \mathbf{n}_{n-2}(s) + \kappa_1(s) \kappa_2(s) \cdots \kappa_{k-2}(s) \kappa_{n-1}(s) \mathbf{n}_{n-1}(s).
\]

We put \( K(s) = \kappa_1(s) \kappa_2(s) \cdots \kappa_{k-2}(s) \kappa_{n-1}(s) \), then we have

\[
\gamma^{(n+1)}(s) = \overline{\mathbf{r}}(s) \gamma(s) + \overline{\mathbf{g}}(s) \mathbf{t}(s) + \overline{\mathbf{a}}_1(s) (\kappa_1(s) \mathbf{t}(s) + \kappa_2(s) \mathbf{n}_2(s)) + \cdots \\
\overline{a}_{n-2}(s) \mathbf{n}_{n-2}(s) + \overline{a}_{n-2}(s) (-\kappa_{n-2}(s) \mathbf{n}_{n-3}(s) + \kappa_{n-1}(s) \mathbf{n}_{n-1}(s)) + (K'(s) \kappa_{n-1}(s) + K(s) \kappa'_{n-1}(s)) \mathbf{n}_{n-1}(s) - K(s) \kappa^2_{n-1}(s) \mathbf{n}_{n-2}(s)
\]

\[
= \mathbf{V}(s) + \mathbf{W}(s),
\]

for some \( \mathbf{V}(s) \in \{ \gamma(s), \mathbf{t}(s), \mathbf{n}_1(s), \ldots, \mathbf{n}_{n-2}(s) \} \) and

\[
\mathbf{W}(s) = (\overline{a}_{n-2}(s) \kappa_{n-1}(s) + K'(s) \kappa_{n-1}(s) + K(s) \kappa'_{n-1}(s)) \mathbf{n}_{n-1}(s).
\]

Since \( \langle \mathbf{V}(s), \mathbf{n}_{n-1}(s) \rangle = 0 \) and \( \kappa_1(s) \kappa_2(s) \cdots \kappa_{k-2}(s) \kappa_{n-2}(s) \neq 0 \), \( \mathbf{v}(s) = \pm n_{n-1}(s) \), \( \kappa_{n-1}(s) = 0 \) and \( (h^*_v)^{(n+1)}(s) = 0 \) if and only if \( \mathbf{v}(s) = \pm n_{n-1}(s) \), \( \kappa_{n-1}(s) = 0 \) and \( \kappa'_{n-1}(s) = 0 \). Thus assertion (4) for \( k = n + 1 \) holds. We now assume that the following conditions hold for \( k = n + (r - 1) : h^*_v(s) = (h^*_v)'(s) = \cdots = (h^*_v)^{(k)}(s) = 0 \) if and only if \( \mathbf{v}(s) = \pm n_{n-1}(s) \)

and \( \kappa_{n-1}(s) = \kappa'_{n-1}(s) = \cdots = \kappa^{(r-1)}_{n-1} = 0 \) and \( \gamma^{(k)}(s) = \mathbf{V}(s) + \mathbf{W}(s) \), where \( \mathbf{V}(s) \in \{ \gamma(s), \mathbf{t}(s), \mathbf{n}_1(s), \ldots, \mathbf{n}_{n-2}(s) \} \) and there exist functions \( \eta_0(s), \eta_1(s), \ldots, \eta_{r-2}(s) \) such that

\[
\mathbf{W}(s) = \left( \sum_{i=0}^{r-2} \eta_i(s) \kappa^{(i)}_{n-1}(s) + K(s) \kappa^{(r-1)}_{n-1}(s) \right) \mathbf{n}_{n-1}(s).
\]
Therefore, we have $V(s) = \nabla(s) + \zeta(s)n_{-2}(s)$ for some $\nabla(s) \in \{\gamma(s), t(s), n_1(s), \ldots, n_{-3}(s)\}$.

It means that
\[
V'(s) = \nabla'(s) + \zeta'(s)n_{-2}(s) + \zeta(s)(-\kappa_{-2}(s)n_{-3}(s) + \kappa_{-1}(s)n_{-1}(s))
\]
and
\[
W'(s) = \left(\sum_{i=0}^{r-2} (\eta_i(s)\kappa_{n-1}^{(i)}(s) + \eta_i(s)\kappa_{n-1}^{(i+1)}(s)) + K'(s)\kappa_{n-1}^{(r-1)}(s) + K(s)\kappa_{n-1}^{(r)}(s)\right)n_{-1}(s)
\]
\[- \left(\sum_{i=0}^{r-2} (\eta_i(s)\kappa_{n-1}^{(i)}(s) + K(s)\kappa_{n-1}^{(r-1)}(s))\kappa_{n-2}(s)n_{-2}(s)\right).
\]
It follows that there exist $\tilde{V}(s) \in \{\gamma(s), t(s), n_1(s), \ldots, n_{-2}(s)\}$ and functions $\eta_0(s), \eta_1(s), \ldots, \eta_{r-1}(s)$ such that
\[
\gamma^{(k+1)}(s) = \tilde{V}(s) + \left(\sum_{i=0}^{r-1} \eta_i(s)\kappa_{n-1}^{(i)}(s) + K(s)\kappa_{n-1}^{(r)}(s)\right)n_{-1}(s).
\]
Since $K(s) \neq 0$ and $\langle n_{-1}(s), \tilde{V}(s) \rangle = 0$, $h_v(s) = (h_v')^1(s) = \cdots = (h_v')^{k+1}(s) = 0$ if and only if $v(s) = \pm n_{-1}(s)$ and $\kappa_{-1}(s) = \kappa_{-1}^t(s) = \cdots = \kappa_{n-1}^t(s) = 0$. This completes the proof of (4).

\section*{3.3 De Sitter Legendrian duality}

In [7], Izumiya introduced the Legendrian dualities between pseudo-spheres in Minkowski space which is a basic tool for the study of spacelike submanifolds in pseudo-spheres in Minkowski space. In this section we study the de Sitter Legendrian duality of timelike Sabban curve in the $S^n_1$. We define 1-forms $\langle dv, w \rangle = -w_idv_1 + \sum_{i=2}^{n+1}w_idv_i$, $\langle v, dw \rangle = -v_1dw_1 + \sum_{i=2}^{n+1}v_idw_i$ in $R^{n+1}_1 \times R^{n+1}_1$ and consider the following double fibrations:
\[
S^n_1 \times S^n_1 \supset \Delta_5 = \{(v, w)|\langle v, w \rangle = 0\},
\]
\[
\pi_{51} : \Delta_5 \to S^n_1, \quad \pi_{52} : \Delta_5 \to S^n_1,
\]
\[
\theta_{51} = \langle dv, w \rangle|_{\Delta_5}, \quad \theta_{52} = \langle v, dw \rangle|_{\Delta_5}.
\]
Here, $\pi_{51}(v, w) = v$, $\pi_{52}(v, w) = w$. We remark that $\theta_{51}^{-1}(0)$ and $\theta_{52}^{-1}(0)$ define the same tangent hyperplane field over $\Delta_5$ which is denoted by $K$. In [4], the following theorem was shown:
Theorem 3.3.1. Under the above notation, both of \( \pi_{5i} \) \((i = 1, 2)\) are Legendrian fibrations and \((\Delta_5, K)\) is a contact manifold.

If we have a Legendrian submanifold \( L \subset \Delta_5 \), then we say that \( \pi_{51}(L) \subset S^1_{i} \) and \( \pi_{52}(L) \subset S^1_{i} \) are de Sitter Legendrian dual to each other. Since both of \( \pi_{51}^{-1}(v) = v \times S^1_{i-1}(v, 0) \) and \( \pi_{52}^{-1}(v) = S^1_{i-1}(v, 0) \times v \) are Legendrian submanifolds of \( \Delta_5 \), \( v \in S^1_{i} \) and \( S^1_{i-1}(v, 0) \in S^1_{i} \) are de Sitter Legendrian dual to each other.

We now define a mapping \( D_\gamma : I \times S^{n-2} \to S^{n-1}_{1} \) by
\[
D_\gamma(s, \xi) = \xi_1 n_1 + \cdots + \xi_{n-1} n_{n-1},
\]
where \( \xi = (\xi_1, \ldots, \xi_{n-1}) \in S^{n-2} \). We denote that \( \gamma^* = D_\gamma(s, \xi) \), which is called a de Sitter dual hypersurface of \( \gamma \). We have the following theorem:

Theorem 3.3.2. Let \( \gamma : I \to S^1_{i} \) be a timelike Sabban curve. Then \( \gamma \) and \( \gamma^* \) are de Sitter Legendrian dual to each other.

Proof. We define a mapping \( L : I \times S^1_{i} \to \Delta_5 \) by \( L(s, \xi) = (\gamma(s), D_\gamma(s, \xi)) \). By definition, we have
\[
\frac{\partial L}{\partial s} = (t(s), \frac{\partial D_\gamma}{\partial s}), \quad \frac{\partial L}{\partial \xi_i} = (0, n_i(s)).
\]
Therefore, \( \{\partial L/\partial s, \partial L/\partial \xi_1, \ldots, \partial L/\partial \xi_{n-1}\} \) are linearly independent. This means that \( L : I \times \mathbb{R}^{n+1} \to \Delta_5 \) is an immersion, so that \( L|_{I \times S^1_{i}} \) is an immersion. Moreover, we have \( L^* \theta_{51} = \langle d\gamma(s), D_\gamma(s, \xi) \rangle \) = 0, so that \( L(s, \xi) \) is a Legendrian submanifold of \( \Delta_5 \). This completes the proof.

Corollary 3.3.3. Let \( \gamma : I \to S^1_{i} \) be a regular timelike curve. Then \( \gamma^* \) is a wave front of \( L(s, \xi) \) respect to the Legendrian fibration \( \pi_{52} \).

3.4 An application of the theory of unfoldings of function germs

In this section we classify the families of function germs as an application of the unfolding theory of functions. We consider the family of de Sitter height functions on timelike Sabban curve. Then we have the following proposition.
**Proposition 3.4.1.** Let $\gamma : I \to S_n^a$ be a timelike Sabban curve and $h^a_{v_0}$ has $A_k$-singularity at $s_0$ for any $k \leq n$. Then $H^s$ is an R-versal unfolding of $h^a_{v_0}$.

**Proof.** Let

$$\gamma(s) = (x_1, x_2, x_3, \ldots, x_{n+1})$$

and

$$v_0 = (\lambda, \mu, \xi_1, \ldots, \xi_{n-1})$$

with $\lambda^2 - \mu^2 + \sum_{i=1}^{n-1} \xi_i^2 = 1$. Then we have

$$H^s(s, v_0) = x_1(s)\lambda - x_2(s)\mu + x_3(s)\xi_1 + \cdots + x_{n+1}(s)\xi_{n-1}.$$ 

Suppose that $\xi_{n-1} > 0$ and $\xi_{n-1} = \sqrt{1 - \lambda^2 + \mu^2 - \sum_{i=1}^{n-2} \xi_i^2}$. Then we adopt the local coordinates $(\lambda, \mu, \xi_1, \ldots, \xi_{n-2})$ for $S_1$, it follows that

$$\frac{\partial H^s}{\partial \lambda}(s, v_0) = x_1(s) - \frac{\lambda}{\xi_{n-1}}x_{n+1}(s),$$

$$\frac{\partial H^s}{\partial \mu}(s, v_0) = -x_2(s) + \frac{\mu}{\xi_{n-1}}x_{n+1}(s),$$

$$\frac{\partial H^s}{\partial \xi_1}(s, v_0) = x_3(s) - \frac{\xi_1}{\xi_{n-1}}x_{n+1}(s),$$

$$\vdots$$

$$\frac{\partial H^s}{\partial \xi_{n-2}}(s, v_0) = x_{n}(s) - \frac{\xi_{n-2}}{\xi_{n-1}}x_{n+1}(s).$$

We consider the following matrix:

$$A = \begin{pmatrix}
    x_1(s) - \frac{\lambda}{\xi_{n-1}}x_{n+1}(s) & -x_2(s) + \frac{\mu}{\xi_{n-1}}x_{n+1}(s) & \cdots & x_n(s) - \frac{\xi_{n-2}}{\xi_{n-1}}x_{n+1}(s) \\
    x'_1(s) - \frac{\lambda}{\xi_{n-1}}x'_{n+1}(s) & -x'_2(s) + \frac{\mu}{\xi_{n-1}}x'_{n+1}(s) & \cdots & x'_n(s) - \frac{\xi_{n-2}}{\xi_{n-1}}x'_{n+1}(s) \\
    \vdots & \vdots & \ddots & \vdots \\
    x_{1(n-1)}(s) - \frac{\lambda}{\xi_{n-1}}x_{1(n-1)}(s) & -x_{2(n-1)}(s) + \frac{\mu}{\xi_{n-1}}x_{2(n-1)}(s) & \cdots & x_{n(n-1)}(s) - \frac{\xi_{n-2}}{\xi_{n-1}}x_{n(n-1)}(s)
\end{pmatrix}.$$ 

If we put $a_i = (x_i(s), x'_i(s), \ldots, x_{i(n-1)}(s))$, then we have

$$A = (a_1 - \frac{\lambda}{\xi_{n-1}}a_{n+1}, -a_2 + \frac{\mu}{\xi_{n-1}}a_{n+1}, a_3 - \frac{\xi_1}{\xi_{n-1}}a_{n+1}, \ldots, a_n - \frac{\xi_{n-2}}{\xi_{n-1}}a_{n+1}).$$

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By a straightforward calculation, we have
\[-\det A = \det(a_1, a_2, \ldots, a_n) + \frac{\lambda}{\xi_{n-1}} \det(a_{n+1}, a_2, \ldots, a_n) + \frac{\mu}{\xi_{n-1}} \det(a_1, a_{n+1}, a_3, \ldots, a_n) + \cdots + \frac{\xi_{n-2}}{\xi_{n-1}} \det(a_1, a_2, \ldots, a_{n-1}, a_{n+1})\]
\[= \frac{(-1)^n}{\xi_{n-1}} \langle v_0, \gamma(s) \wedge \gamma'(s) \wedge \cdots \wedge \gamma^{(n-1)}(s) \rangle.\]

Since
\[\gamma(s) \wedge \gamma'(s) \wedge \cdots \wedge \gamma^{(n-1)}(s) = \kappa_1^{n-3}(s) \kappa_2^{n-4}(s) \cdots \kappa_{n-2}(s).\]

As \(h_{v_0}^s\) has \(A_k\)-singularity, so that
\[\det A = (-1)^{n+1} \kappa_1^{n-3}(s) \kappa_2^{n-4}(s) \cdots \kappa_{n-2}(s) \neq 0.\]

It means that rank\(A = n\). Thus the assertion for \(k = n\) holds. It follows that the assertion for \(k < n\) also holds. For other coordinates, we have the arguments similar to above. This completes the proof. \(\square\)

By Proposition 3.2.2, we have \(\gamma^* = D_Hs\) and \(D_{H^s}^{-1} = \{\pm n_{n-1}(s) | s \in I\}\). Proposition 3.2.2 also asserts that \(h_{v_0}^s\) has \(A_k\)-singularity at \(s_0\) for \(k < n\) if and only if exist
\[(0, \ldots, 0, \xi_k, \xi_{k+1}, \ldots, \xi_{n-1}) \in S^{n-2} \text{ and } (\xi_k \neq 0)\]
such that
\[v_0 = \xi_k n_k(s_0) + \cdots + \xi_{n-1} n_{n-1}(s_0).\]

We define a set \(\gamma_k^* \subset S^n\) by
\[\gamma_k^* = \{\xi_k n_k(s) + \cdots + \xi_{n-1} n_{n-1}(s) | \xi_k^2 + \cdots + \xi_{n-1}^2 = 1, s \in I\},\]
so that \(\gamma_k^* = D_{H^s}^k\). By Theorem 2.3.5 and Proposition 3.4.1, we have the following theorem.

**Theorem 3.4.2.** Let \(\gamma : I \to S^n_1\) be a timelike Sabban curve. Then we have the following:

(1) For \(k < n-1\), the germ of de Sitter dual \(\gamma^*\) of \(\gamma\) at \((s_0, \xi) = (s_0, (\xi_1, \ldots, \xi_{n-1})) \in I \times S^{n-1}\) is
diffeomorphic to \((\text{Im} DA_k^\pm \times \mathbb{R}^{n-k}, 0)\) as set-germs if and only if \(\xi_1 = \cdots = \xi_{k-1} = 0\) and \(\xi_k \neq 0\).

In this case the germ of \(\gamma_k^*\) at \((s_0, \xi)\) is diffeomorphic to \((\text{Im} \sigma_1[2, 3, \ldots, k, k+1] \times \mathbb{R}^{n-k}, 0)\) as set-germs.

(2) The germ of de Sitter dual \(\gamma^*\) of \(\gamma\) at \((s_0, \xi)\) \(\in I \times S^{n-1}\) is diffeomorphic to \((\text{Im} DA_k^\pm \times \mathbb{R}, 0)\) as set-germs if and only if \(\xi = (0, \ldots, 0, \pm 1)\) and \(\kappa_{n-1}(s_0) \neq 0\). In this case the germ of the image of \(n_{n-1}(s)\) at \(s_0\) is diffeomorphic to \((\mathbb{R}, 0)\) as set-germs.

(3) The germ of de Sitter dual \(\gamma^*\) of \(\gamma\) at \((s_0, \xi)\) \(\in I \times S^{n-1}\) is diffeomorphic to \((\text{Im} DA_k^\pm \times \mathbb{R}, 0)\) as set-germs if and only if \(\xi = (0, \ldots, 0, \pm 1)\), \(\kappa_{n-1}(s_0) = 0\) and \(\kappa'_{n-1}(s_0) \neq 0\). In this case the germ of the image of \(n_{n-1}(s)\) at \(s_0\) is diffeomorphic to \((\text{Im} \sigma_1[2, 3, \ldots, n-1, n], 0)\) as set-germs.

**Proof.** By Proposition 3.4.1, if \(h_{v_0}^*\) has \(A_k\)-singularity at \(s_0\) for any \(k \leq n\). Then \(H^*\) is an \(R\)-versal unfolding of \(h_{v_0}^*\). Since \(\gamma^* = D_H^*\), the assertions holds by Proposition 3.2.2, Theorem 2.3.5 and Proposition 3.4.1. \(\square\)

### 3.5 Contact with great de Sitter subspaces

In this section, we discuss the contact of \(\gamma\) with a great de Sitter subspace. By Proposition 3.1.2, there exist a spacelike vector \(v \in S^n_1\) such that \(\gamma(I) \subset S^{n-1}_1(v, 0)\) if and only if \(\kappa_{n-1}(s) \equiv 0\).

In this case, \(n_{n-1}(s) \equiv v\) is a constant vector. By definition, \(v \in D_{H^*}\) if and only if there exists \(s_0 \in I\) such that \(h_v^*(s_0) = (h_v^*)'(s_0) = 0\). If we consider a function \(g_v : S^n_1 \to \mathbb{R}\) defined by \(g_v(x) = \langle v, x \rangle\), then \(g_v^{-1}(0) = S^{n-1}_1(v, 0)\) and \(g_v \circ \gamma(s) = h_v^*(s)\), so that \(h_v^*(s_0) = (h_v^*)'(s_0) = 0\) if and only if \(\gamma(s)\) is tangent to \(S^{n-1}_1(v, 0)\) at \(s_0\). We call \(S^{n-1}_1(v, 0)\) a **tangent great de Sitter subspace** of \(\gamma\) at \(s_0\). There are infinite tangent great de Sitter subspaces of \(\gamma\) at \(s_0\). We say that \(S^{n-1}_1(v, 0)\) has at least \(k+1\)-point contact with \(\gamma\) at \(s_0\) if \(h_v^*(s_0) = (h_v^*)'(s_0) = \cdots = (h_v^*)^k(s_0) = 0\), we also say that \(S^{n-1}_1(v, 0)\) has \(k+1\)-point contact with \(\gamma\) at \(s_0\) if \(h_v^*(s_0) = (h_v^*)'(s_0) = \cdots = (h_v^*)^k(s_0) = 0\) and \((h_v^*)^{k+1}(s_0) \neq 0\). By Proposition 3.2.2, we have the following proposition.

**Proposition 3.5.1.** Let \(\gamma : I \to S^n_1\) be a timelike Sabban curve and \(v_0 \in S^n_1\). Then we have the following:

1. \(S^{n-1}_1(v, 0)\) is a tangent great de Sitter subspace of \(\gamma\) at \(s_0\) if and only if there exists
\( \xi = (\xi_1, \ldots, \xi_{n-1}) \in S^{n-2} \) such that \( v_0 = \xi_1 n_1(s_0) + \cdots + \xi_{n-1} n_{n-1}(s_0). \)

(2) For \( k < n \), \( S_{1}^{n-1}(v, 0) \) has at least \( k + 1 \)-point contact with \( \gamma \) at \( s_0 \) if and only if there exists \( \xi = (0, \ldots, 0, \xi_k, \xi_{k+1}, \ldots, \xi_{n-1}) \in S^{n-2} \) such that \( v_0 = \xi_k n_k(s_0) + \cdots + \xi_{n-1} n_{n-1}(s_0). \)

(3) \( S_{1}^{n-1}(v, 0) \) has at least \( n \)-point contact with \( \gamma \) at \( s_0 \) if and only if \( v_0 = \pm n_{n-1}(s_0). \)

(4) For \( k > n \), \( S_{1}^{n-1}(v, 0) \) has at least \( k + 1 \)-point contact with \( \gamma \) at \( s_0 \) if and only if \( v_0 = \pm n_{n-1}(s_0) \) and \( \kappa_{n-1}(s_0) = \cdots = \kappa_{(k-n)}(s_0) = 0. \)

For \( k < n \), \( \gamma^*_k \) is the locus of the vectors \( v \in S_{1}^{n} \) such that \( S_{1}^{n-1}(v, 0) \) has at least \( k + 1 \)-point contact with \( \gamma \). In particular, \( \gamma^*_n = \{\pm n_{n-1}(s)|s \in I\} \) is the locus of the vectors \( v \in S_{1}^{n} \) such that \( S_{1}^{n-1}(v, 0) \) has at least \( n + 1 \)-point contact with \( \gamma \). So if \( v = \pm n_{n-1}(s_0) \), we call \( S_{1}^{n-1}(v, 0) \) an osculating tangent great de Sitter subspace of \( \gamma \) at \( s_0 \). Then, as a corollary of Theorem 3.4.2 and Proposition 3.5.1, we have the following theorem.

**Theorem 3.5.2.** Let \( \gamma : I \to S_{1}^{n} \) be a timelike Sabban curve and \( S_{1}^{n-1}(v_0, 0) \) a tangent great de Sitter subspace of \( \gamma \) at \( s_0 \). Then we have the following:

(1) For \( k < n - 1 \), the germ of de Sitter dual \( \gamma^* \) of \( \gamma \) at \( (s_0, \xi) = (s_0, (\xi_1, \ldots, \xi_{n-1})) \in I \times S^{n-1} \) is diffeomorphic to \((\text{Im} DA_k^\pm \times \mathbb{R}^{n-k}, 0)\) as set-germs if and only if \( S_{1}^{n-1}(v_0, 0) \) has at least \( k + 1 \)-point contact with \( \gamma \) at \( s_0 \). In this case the germ of \( \gamma^*_k \) at \( (s_0, \xi) \) is diffeomorphic to \((\text{Im} \sigma_1[2, 3, \ldots, k, k+1] \times \mathbb{R}^{n-k}, 0)\) as set-germs.

(2) The germ of de Sitter dual \( \gamma^* \) of \( \gamma \) at \( (s_0, \xi) \in I \times S^{n-1} \) is diffeomorphic to \((\text{Im} DA_k^\pm \times \mathbb{R}, 0)\) as set-germs if and only if \( S_{1}^{n-1}(v_0, 0) \) is an osculating tangent great de Sitter subspace of \( \gamma \) at \( s_0 \) and \( \kappa_{n-1}(s_0) \neq 0 \). In this case the germ of the image of \( n_{n-1}(s) \) at \( s_0 \) is diffeomorphic to \((\mathbb{R}, 0)\) as set-germs.

(3) The germ of de Sitter dual \( \gamma^* \) of \( \gamma \) at \( (s_0, \xi) \in I \times S^{n-1} \) is diffeomorphic to \((\text{Im} DA_k^\pm, 0)\) as set-germs if and only if \( S_{1}^{n-1}(v_0, 0) \) is an osculating tangent great de Sitter subspace of \( \gamma \) at \( s_0 \), \( \kappa_{n-1}(s_0) = 0 \) and \( \kappa'_{n-1}(s_0) \neq 0 \). In this case the germ of the image of \( n_{n-1}(s) \) at \( s_0 \) is diffeomorphic to \((\text{Im} \sigma_1[2, 3, \ldots, n-1, n], 0)\) as set-germs.
4 De Sitter evolutes and de Sitter focal surfaces of timelike Sabban curves

4.1 De Sitter evolutes of timelike Sabban curves in $S^2_1$

In this section we consider a timelike Sabban curve in $S^2_1$. Let $\gamma: I \rightarrow S^2_1$ be a timelike Sabban curve, we can reparameterize it by the arc-length $s$. Then we have a orthogonal frame $\{\gamma, t, n\}$ along $\gamma$, where $t(s)$ is the unit tangent vector of $\gamma$ at $s$ and $n(s) = \gamma(s) \wedge t(s)$. We have the Frenet-type formulae:

\[
\begin{align*}
\gamma'(s) &= t(s), \\
t'(s) &= \gamma(s) + \kappa n(s), \\
n'(s) &= \kappa t(s).
\end{align*}
\]

Here, $\kappa = \|\gamma''(s) - \gamma(s)\|$ is the geodesic curvature of $\gamma$.

We define a function $H: I \times S^2_1 \rightarrow \mathbb{R}$ by $H(s, v) = \langle \gamma(s), v \rangle$. We call $H$ a de Sitter height function on $\gamma$ and write $h_{v_0}(s) = H(s, v_0)$ for any fixed vector $v_0 \in S^2_1$.

Here we calculate the derivative of $H$, by Frenet-type formulae, we have

\[
\frac{\partial H}{\partial s} = \langle \gamma'(s), v \rangle = \langle t(s), v \rangle.
\]

Since $v \in S^2_1$, there exists $\theta \in [0, 2\pi)$ such that $v = \cos \theta \gamma(s) + \sin \theta n(s)$ if and only if $\frac{\partial H}{\partial s} = 0$. We also have

\[
\frac{\partial^2 H}{\partial s^2} = \langle t'(s), v \rangle = \langle \gamma(s) + \kappa n(s), v \rangle.
\]

Therefore, $\frac{\partial H}{\partial s} = \frac{\partial^2 H}{\partial s^2} = 0$ if and only if $v = \cos \theta \gamma(s) + \sin \theta n(s)$ and $\cos \theta + \kappa \sin \theta = 0$. Moreover, we have

\[
\frac{\partial^3 H}{\partial s^3} = \langle (1 + \kappa^2) t(s) + \kappa' n(s), v \rangle.
\]

Under the condition $\frac{\partial H}{\partial s} = \frac{\partial^2 H}{\partial s^2} = 0$, $\frac{\partial^3 H}{\partial s^3} = 0$ if and only if $v = \cos \theta \gamma(s) + \sin \theta n(s)$, $\cos \theta + \kappa \sin \theta = 0$ and $\kappa'(s) = 0$. If we calculate the 4th derivative of $H$, we can show that the above
conditions with the extra condition
\[ \frac{\partial^4 H}{\partial s^4} = (1 + \kappa^2)\gamma(s) + 3\kappa\kappa'\mathbf{t}(s) + (\kappa + \kappa^{\prime\prime})\mathbf{n}(s), \cos \theta \gamma(s) + \sin \theta \mathbf{n}(s) = 0 \]
which is equivalent to the \(\kappa''(s) = 0\). As a consequence, we have the following proposition.

**Proposition 4.1.1.** For any \((s, v) \in I \times S^2_t\), we have the followings:

1. \(h'(s) = 0\) if and only if there exists \(\theta \in [0, 2\pi)\) such that \(v = \cos \theta \gamma(s) + \sin \theta \mathbf{n}(s)\).
2. \(h''(s) = 0\) if and only if \(v = \cos \theta \gamma(s) + \sin \theta \mathbf{n}(s)\) and \(\cos \theta + \kappa \sin \theta = 0\).
3. \(h'(s) = 0\) if and only if \(v = \cos \theta \gamma(s) + \sin \theta \mathbf{n}(s)\), \(\cos \theta + \kappa \sin \theta = 0\) and \(\kappa'(s) = 0\).
4. \(h''(s) = 0\) if and only if \(v = \cos \theta \gamma(s) + \sin \theta \mathbf{n}(s)\), \(\cos \theta + \kappa \sin \theta = 0\), \(\kappa'(s) = 0\) and \(\kappa''(s) = 0\).

By the above proposition, we have an invariant \(\kappa'\). \(h''(s) = 0\) if and only if \(v = \cos \theta \gamma(s) + \sin \theta \mathbf{n}(s)\) and \(\cos \theta + \kappa \sin \theta = 0\). Since \(\cos \theta + \kappa \sin \theta = 0\) is equal to \(\sin \theta = \pm \frac{1}{\sqrt{1+\kappa^2}}\) and \(\cos \theta = \mp \frac{\kappa}{\sqrt{1+\kappa^2}}\), then \(h''(s) = 0\) if and only if \(v = \mp \frac{\kappa}{\sqrt{1+\kappa^2}} \gamma(s) \pm \frac{1}{\sqrt{1+\kappa^2}} \mathbf{n}(s)\). We now define curves \(E^\pm_\gamma : I \rightarrow S^2_t\) by

\[ E^\pm_\gamma(s) = \mp \frac{\kappa}{\sqrt{1+\kappa^2}} \gamma(s) \pm \frac{1}{\sqrt{1+\kappa^2}} \mathbf{n}(s). \]

We call \(E^\pm_\gamma\) the *de Sitter evolute* of \(\gamma(s)\). By straightforward calculations, we have the following proposition.

**Proposition 4.1.2.** The evolute \(E^\pm_\gamma(s)\) of \(\gamma(s)\) is singular at \(s_0\) if and only if \(\kappa'(s_0) = 0\).

**Proof.** The evolute \(E^\pm_\gamma(s)\) of \(\gamma(s)\) is given by

\[ E^\pm_\gamma(s) = \mp \frac{\kappa}{\sqrt{1+\kappa^2}} \gamma(s) \pm \frac{1}{\sqrt{1+\kappa^2}} \mathbf{n}(s). \]

We have

\[ (E^\pm_\gamma)'(s) = \mp \frac{\kappa(s)}{\sqrt{1+\kappa^2(s)}} \gamma(s) = \mp \frac{\kappa(s)}{\sqrt{1+\kappa^2(s)}} \mathbf{t}(s) \]

\[ = \mp \frac{\kappa(s)}{(1 + \kappa^2(s)) \sqrt{1 + \kappa^2(s)}} \mathbf{n}(s) \pm \frac{\kappa(s)}{\sqrt{1 + \kappa^2(s)}} \mathbf{t}(s) \]

\[ = \mp \frac{\kappa(s)}{(1 + \kappa^2(s)) \sqrt{1 + \kappa^2(s)}} [(1 + 2\kappa^2(s)) \gamma(s) + \kappa(s) \mathbf{n}(s)]. \]
It follows that \((E^\pm_\gamma)'(s) = 0\) if and only if \(\kappa'(s) = 0\). This completes the proof. \(\Box\)

By the above proposition, \(E^\pm_\gamma(s) = v_0\) is constant if and only if \(\kappa'(s) \equiv 0\). In this case, by Proposition 4.1.1, \(h_{v_0}\) is constant, that is, there is a real number \(c \in \mathbb{R}\) such that \((\gamma(s), v_0) = c\). It means that \(\text{Im} \gamma(s) \in HP(v_0, c) \cap S^2_1\). It suggests that curves of the form \(HP(v_0, c) \cap S^2_1\) for \(v_0 \in S^2_1\) are the candidates of model curves on \(S^2_1\). They might play a similar role to lines in Euclidean plane. We call it \textit{de Sitter slice} (or, a \textit{D-slice}) of \(S^2_1\).

We introduce another family of functions:

\[ H : \mathbb{R}^3 \times S^2_1 \to \mathbb{R}, \quad (x, v) \mapsto \langle x, v \rangle. \]

We denote \(h_v(s) = H(x(s), v)\) for any fixed \(v \in S^2_1\), then we have

\[ h_v(s) = \langle \gamma(s), v_0 \rangle = H(\gamma(s), v_0) = h_{v_0}(\gamma(s)). \]

Moreover, for any \(s_0 \in I\) and \(E^\pm_\gamma(s_0) = v_0\), \((h_{v_0}|_{S^2_1})^{-1}(c)\) is a D-slice of \(S^2_1\). On the other hand, let \(F : \mathbb{R}^3 \to \mathbb{R}\) be a submersion. We say that \(\gamma\) and \(F^{-1}(0)\) have \textit{contact of order} \(k\) at \(s_0\) if the function \(f(s) = F \circ \gamma(s)\) satisfies \(f(s_0) = f'(s_0) = \cdots = f^{(k)}(s_0) = 0\) and \(f^{(k+1)}(s_0) \neq 0\).

Under the above notations and Proposition 4.1.1, we have the following proposition.

**Proposition 4.1.3.** Let \(\gamma : I \to S^2_1\) be a timelike Sabban curve and \(E^\pm_\gamma(s_0) = v_0\). Then the following conditions are equivalent:

1. \(\gamma\) and \((h_{v_0}|_{S^2_1})^{-1}(c_0)\) have contact of order three,
2. \(\kappa'(s_0) = 0\) and \(\kappa''(s_0) \neq 0\).

In order to investigate the singularities of de Sitter evolutes of timelike Sabban curves, we apply the theory of unfolding of functions. In §2, we defined the bifurcation set \(B_F\) of \(F\) by

\[ B_F = \left\{ x \in \mathbb{R}^r \mid \exists s, \text{with} \frac{\partial F}{\partial s}(s, x) = \frac{\partial^2 F}{\partial s^2}(s, x) = 0 \right\}. \]

Here we have the following proposition.

**Proposition 4.1.4.** Let \(\gamma : I \to S^2_1\) be a timelike Sabban curve. If \(h_v(s)\) has type \(A_3\) at \(s_0\), then \(H\) is a \(p\)-versal unfolding of \(h_v\).
Proof. We denote \( \gamma(s) = (x_0(s), x_1(s), x_2(s)) \), \( \mathbf{v} = (v_0, v_1, \sqrt{v_0^2 - v_1^2 + 1}) \). Then we adopt the local coordinates \((v_0, v_1)\) for \( S_1^2 \). We have

\[
H(s, \mathbf{v}) = -x_0(s)v_0 + x_1(s)v_1 + x_2(s)\sqrt{v_0^2 - v_1^2 + 1}
\]

and

\[
\frac{\partial H}{\partial v_0} = -x_0(s) + \frac{v_0}{\sqrt{v_0^2 - v_1^2 + 1}}x_2(s), \quad \frac{\partial H}{\partial v_1} = x_1(s) - \frac{v_1}{\sqrt{v_0^2 - v_1^2 + 1}}x_2(s),
\]

\[
\frac{\partial^2 H}{\partial s \partial v_0} = -x_0'(s) + \frac{v_0}{\sqrt{v_0^2 - v_1^2 + 1}}x_2'(s), \quad \frac{\partial^2 H}{\partial s \partial v_1} = x_1'(s) - \frac{v_1}{\sqrt{v_0^2 - v_1^2 + 1}}x_2'(s),
\]

\[
\frac{\partial^3 H}{\partial^2 s \partial v_0} = -x_0''(s) + \frac{v_0}{\sqrt{v_0^2 - v_1^2 + 1}}x_2''(s), \quad \frac{\partial^3 H}{\partial^2 s \partial v_1} = x_1''(s) - \frac{v_1}{\sqrt{v_0^2 - v_1^2 + 1}}x_2''(s).
\]

By Proposition 4.1.1, \( h_v(s) \) has type \( A_3 \) at \( s_0 \) if and only if \( \mathbf{v} = \cos \theta \gamma(s_0) + \sin \theta \mathbf{n}(s_0), \cos \theta + \kappa \sin \theta = 0 \) and \( \kappa'(s_0) = 0 \). Since \( \cos \theta + \kappa \sin \theta = 0 \) is equal to \( \sin \theta = \pm \frac{1}{\sqrt{1 + \kappa^2}} \) and \( \cos \theta = \mp \frac{\kappa}{\sqrt{1 + \kappa^2}} \), then \( h_v(s) \) has type \( A_3 \) at \( s_0 \) if and only if

\[
\mathbf{v} = \mp \frac{\kappa}{\sqrt{1 + \kappa^2}} \gamma(s_0) \pm \frac{1}{\sqrt{1 + \kappa^2}} \mathbf{n}(s_0) \quad \text{and} \quad \kappa'(s_0) = 0.
\]

For the purpose, we require the matrix

\[
A = \begin{pmatrix}
-x_0'(s) + \frac{v_0}{\sqrt{v_0^2 - v_1^2 + 1}}x_2'(s) & x_1'(s) - \frac{v_1}{\sqrt{v_0^2 - v_1^2 + 1}}x_2'(s) \\
-x_0''(s) + \frac{v_0}{\sqrt{v_0^2 - v_1^2 + 1}}x_2''(s) & x_1''(s) - \frac{v_1}{\sqrt{v_0^2 - v_1^2 + 1}}x_2''(s)
\end{pmatrix}
\]
to have rank 2. Therefore we calculate the determinant of this matrix as follows:

$$\det A = (-x_1'x_2'' - x_1'x_2', x_1'x_0'' - x_0'x_2', x_0'x_1'' - x_1'x_0') \begin{pmatrix} \frac{v_0}{\sqrt{v_0^2 - v_1^2 + 1}} \\ -\frac{v_1}{\sqrt{v_0^2 - v_1^2 + 1}} \\ 1 \end{pmatrix}$$

$$= ((x_0', x_1', x_2') \land (x_0'', x_1'', x_2'')) \begin{pmatrix} \frac{v_0}{\sqrt{v_0^2 - v_1^2 + 1}} \\ -\frac{v_1}{\sqrt{v_0^2 - v_1^2 + 1}} \\ 1 \end{pmatrix}$$

$$= -\frac{1}{\sqrt{v_0^2 - v_1^2 + 1}}(t \land (\gamma + \kappa n)) \begin{pmatrix} -v_0 \\ v_1 \\ \sqrt{v_0^2 - v_1^2 + 1} \end{pmatrix}$$

$$= -\frac{1}{\sqrt{v_0^2 - v_1^2 + 1}}(-n + \kappa \gamma, \mp \frac{\kappa}{\sqrt{1 + \kappa^2}} \gamma(s) \pm \frac{1}{\sqrt{1 + \kappa^2}} n(s))$$

$$= \pm \frac{\sqrt{1 + \kappa^2}}{\sqrt{v_0^2 - v_1^2 + 1}} \neq 0.$$ 

For other local coordinates, we can apply the arguments similar to above. This completes the proof.

As a consequence, we have the following theorem.

**Theorem 4.1.5.** Let $\gamma : I \to S^2_1$ be a timelike Sabban curve. Then we have the following assertions:

(A1) The evolute $E^\pm_\gamma(s)$ is regular at $s_0$ if and only if $\kappa'(s_0) \neq 0$.

(A2) The following conditions are equivalent:

(i) $\kappa'(s_0) = 0$ and $\kappa''(s_0) \neq 0$,

(ii) $\gamma$ and D-slice $(h_{v_0}|S^2_1)^{-1}(c_0)$ have contact of order three. In this case the germ of $E^\pm_\gamma(s)$ at $s_0$ is diffeomorphic to the ordinary cusp.

**Proof.** (A1) By Proposition 4.1.2, $(E^\pm_\gamma)'(s) = 0$ if and only if $\kappa'(s) = 0$. It means that the evolute $E^\pm_\gamma(s)$ is regular at $s_0$ if and only if $\kappa'(s_0) \neq 0$. 

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(A2) By Proposition 4.1.1, the bifurcation set of $H$ is $E^\pm_\gamma(s)$. By Theorem 2.3.6 and Proposition 4.2.2, the germ of the bifurcation set is diffeomorphic to the cusp if $\kappa'(s_0) = 0$ and $\kappa''(s_0) \neq 0$. By Proposition 4.1.3, (A2),(i) is equivalent to (A2),(ii). This completes the proof.

4.2 De Sitter evolutes and de Sitter focal surfaces of timelike Sabban curves in $S^3_1$

In this section we consider timelike Sabban curves in $S^3_1$. Let $\gamma : I \rightarrow S^3_1$ be a timelike Sabban curve, we can reparameterize it by the arc-length $s$. Then we have the tangent vector $t(s) = \gamma'(s)$, obviously $\|t(s)\| = 1$. When $\langle t'(s), t'(s) \rangle \neq 1$, we define a unit vector

$$n_1(s) = \frac{t'(s) - \gamma(s)}{\|t'(s) - \gamma(s)\|},$$

let $n_2(s) = \gamma(s) \wedge t(s) \wedge n_1(s)$. Then we have the Sabban frame $\{\gamma(s), t(s), n_1(s), n_2(s)\}$ along $\gamma$. As a special case of the Frenet-Serret type formulae in §3, we have the following:

$$\begin{aligned}
\gamma'(s) &= t(s), \\
t'(s) &= \gamma(s) + \kappa_1(s)n_1(s), \\
n'_1(s) &= \kappa_1(s)t(s) + \kappa_2(s)n_2(s), \\
n'_2(s) &= -\kappa_2(s)n_1(s).
\end{aligned}$$

Here, $\kappa_1(s) = \|t'(s) - \gamma(s)\|$ and $\kappa_2(s) = -\kappa_1^{-2}(s)\det(\gamma(s), \gamma'(s), \gamma''(s), \gamma'''(s))$. We remark the condition $\langle t'(s), t'(s) \rangle \neq 1$ is equivalent to $\kappa_1(s) \neq 0$.

Now we define a family of functions on a timelike Sabban curve. Let $\gamma : I \rightarrow S^3_1$ be a timelike Sabban curve. We define a function $H : I \times S^3_1 \rightarrow \mathbb{R}$ by $H(s, \mathbf{v}) = \langle \gamma(s), \mathbf{v} \rangle$, we call $H$ a de Sitter height function on the timelike Sabban curve $\gamma$. We denote $h_{\mathbf{v}}(s) = H(s, \mathbf{v})$ for any fixed $\mathbf{v} \in S^3_1$. Then we have the following proposition.

**Proposition 4.2.1.** Let $\gamma : I \rightarrow S^3_1$ be a timelike Sabban curve. Then we have the following assertions:

1. $h'_{\mathbf{v}}(s) = 0$ if and only if there exist $a, c, d \in \mathbb{R}$ with $a^2 + c^2 + d^2 = 1$ such that $\mathbf{v} =$
\(a \gamma(s) + c n_1(s) + d n_2(s).\)

(2) \(h_v'(s) = h_v''(s) = 0\) if and only if there exists \(\theta \in [0, 2\pi)\) such that
\[
v = \frac{\kappa_1 \cos \theta}{\sqrt{1 + \kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} n_1(s)) + \sin \theta n_2(s).
\]

(3) \(h_v'(s) = h_v''(s) = h_v'''(s) = 0\) if and only if there exists \(\theta \in [0, 2\pi)\) such that
\[
v = \frac{\kappa_1 \cos \theta}{\sqrt{1 + \kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} n_1(s)) + \sin \theta n_2(s)
\]
and \(\frac{\kappa_1'}{\sqrt{1 + \kappa_1^2}} \cos \theta = \kappa_1 \kappa_2 \sin \theta.\)

(4) \(h_v''(s) = h_v'''(s) = h_v''''(s) = 0\) if and only if there exists \(\theta \in [0, 2\pi)\) such that
\[
v = \frac{\kappa_1 \cos \theta}{\sqrt{1 + \kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} n_1(s)) + \sin \theta n_2(s), \quad \frac{\kappa_1'}{\sqrt{1 + \kappa_1^2}} \cos \theta = \kappa_1 \kappa_2 \sin \theta
\]
and
\[2(\kappa_1'(s))^2 \kappa_2(s) + \kappa_1(s) \kappa_1'(s) \kappa_2'(s) + \kappa_1^2(s) \kappa_2^3(s) - \kappa_1(s) \kappa_2(s) \kappa_i'(s) = 0.
\]

(5) \(h_v'(s) = h_v''(s) = h_v'''(s) = h_v''''(s) = 0\) if and only if there exists \(\theta \in [0, 2\pi)\) such that
\[
v = \frac{\kappa_1 \cos \theta}{\sqrt{1 + \kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} n_1(s)) + \sin \theta n_2(s), \quad \frac{\kappa_1'}{\sqrt{1 + \kappa_1^2}} \cos \theta = \kappa_1 \kappa_2 \sin \theta,
\]
\[2(\kappa_1'(s))^2 \kappa_2(s) + \kappa_1(s) \kappa_1'(s) \kappa_2'(s) + \kappa_1^2(s) \kappa_2^3(s) - \kappa_1(s) \kappa_2(s) \kappa_i'(s) = 0,
\]
and
\[
(2(\kappa_1'(s))^2 \kappa_2(s) + \kappa_1(s) \kappa_1'(s) \kappa_2'(s) + \kappa_1^2(s) \kappa_2^3(s) - \kappa_1(s) \kappa_2(s) \kappa_i'(s))'
\]
\[= 3\kappa_1'(s) \kappa_1'(s) \kappa_2'(s) + 3(\kappa_1'(s))^2 \kappa_2'(s) + \kappa_1(s) \kappa_1'(s) \kappa_2''(s) - \kappa_1(s) \kappa_1''(s) \kappa_2'(s)
\]
\[+ 2\kappa_1(s) \kappa_1'(s) \kappa_2'(s) + 3 \kappa_2'(s) \kappa_2'(s) \kappa_2'(s) = 0.
\]

**Proof.** (1) Since \(v \in S^3_1\), there exist \(a, b, c, d \in \mathbb{R}\) such that \(v = a \gamma(s) + b t(s) + c n_1(s) + d n_2(s)\) with \(a^2 + b^2 + c^2 + d^2 = 1\). Because \(h_v'(s) = 0\), we have \(b = 0\), so that \(a^2 + c^2 + d^2 = 1\). The converse direction also holds.
(2) By (1), we show that \( \langle \gamma(s) + \kappa_1 n_1(s), v \rangle = 0 \). Then \( c = -\frac{a}{\kappa_1} \). Since \( a^2 + c^2 + d^2 = 1 \), there exists \( \theta \in [0, 2\pi) \) such that

\[
a = \frac{\kappa_1 \cos \theta}{\sqrt{1 + \kappa_1^2}}, \quad c = -\frac{\cos \theta}{\sqrt{1 + \kappa_1^2}}, \quad d = \sin \theta.
\]

Therefore

\[
v = \frac{\kappa_1 \cos \theta}{\sqrt{1 + \kappa_1^2}}(\gamma(s) - \frac{1}{\kappa_1} n_1(s)) + \sin \theta n_2(s).
\]

(3) Under the assumption that \( h_\nu'(s) = h_\nu''(s) = 0 \), we have

\[
h_\nu'''(s) = \langle (1 + \kappa_1^2) t(s) + \kappa_1' n_1(s) + \kappa_1 \kappa_2 n_2(s), v \rangle = 0.
\]

It follows that \( \frac{\kappa_1'}{\sqrt{1 + \kappa_1^2}} \cos \theta = \kappa_1 \kappa_2 \sin \theta. \)

(4) With the assumption \( h_\nu'(s) = h_\nu''(s) = h_\nu'''(s) = 0 \) and a formula

\[
h_\nu^{(4)}(s) = \langle (1 + \kappa_1^2) \gamma(s) + 3 \kappa_1 \kappa_1' t(s) + (\kappa_1 + \kappa_1^3 + \kappa_1'' - \kappa_1 \kappa_2^2) n_1(s) + (2 \kappa_1' \kappa_2 + \kappa_1 \kappa_2') n_2(s), v \rangle,
\]

\( h_\nu^{(4)}(s) = 0 \) is equivalent to

\[
(\kappa_1 \kappa_2^2 - \kappa_1'') \cos \theta = -\sqrt{1 + \kappa_1^2} (2 \kappa_1' \kappa_2 + \kappa_1 \kappa_2') \sin \theta.
\]

Since we have \( \frac{\kappa_1'}{\sqrt{1 + \kappa_1^2}} \cos \theta = \kappa_1 \kappa_2 \sin \theta, \)

\[
2(\kappa_1'(s))^2 \kappa_2(s) + \kappa_1(s) \kappa_1'(s) \kappa_2'(s) + \kappa_1^2(s) \kappa_2^3(s) - \kappa_1(s) \kappa_2(s) \kappa_1''(s) = 0.
\]

This proves assertion (4).

(5) When \( h_\nu'(s) = h_\nu''(s) = h_\nu'''(s) = 0 \), the fifth derivative is

\[
h_\nu^{(5)}(s) = \langle 5 \kappa_1 \kappa_1' \gamma(s) + (1 + 2 \kappa_1^2 + 3(\kappa_1')^2 + 4 \kappa_1 \kappa_1'' + \kappa_1^4 - \kappa_1^2 \kappa_1^2) t(s) + (6 \kappa_1^2 \kappa_1' + \kappa_1' + \kappa_1'' - 3 \kappa_1' \kappa_2 - 3 \kappa_1 \kappa_2' \kappa_2) n_1(s) + (\kappa_1 \kappa_2 + \kappa_1^3 \kappa_2 + 3 \kappa_1'' \kappa_2 - \kappa_1 \kappa_2^3 + 3 \kappa_1' \kappa_2 + \kappa_1 \kappa_2') n_2(s), v \rangle.
\]

It follows that \( h_\nu^{(5)}(s) = 0 \) is equivalent to

\[
\sqrt{1 + \kappa_1^2} (\kappa_1 \kappa_2^2 + \kappa_1^3 \kappa_2 + 3 \kappa_1'' \kappa_2 - \kappa_1 \kappa_2^3 + 3 \kappa_1' \kappa_2^2 + \kappa_1 \kappa_2') \sin \theta + (-\kappa_1^2 \kappa_1' - \kappa_1' - \kappa_1'' + 3 \kappa_1' \kappa_2 + 3 \kappa_1 \kappa_2' \kappa_2') \cos \theta = 0.
\]
Since \( \frac{\kappa'}{\sqrt{1+\kappa_1^2}} \cos \theta = \kappa_1 \kappa_2 \sin \theta \) and 
\[
2(\kappa'_1(s))^2 \kappa_2(s) + \kappa_1(s)\kappa'_1(s)\kappa'_2(s) + \kappa_1^2(s)\kappa''_2(s) - \kappa_1(s)\kappa_2(s)\kappa''_1(s) = 0,
\]
we have
\[
3\kappa'_1\kappa''_2 + 3(\kappa'_1)^2 \kappa'_2 + \kappa_1 \kappa'_1 \kappa''_2 - \kappa_1 \kappa''_1 \kappa_2 + 2\kappa_1 \kappa'_1 \kappa^3_2 + 3\kappa^2_2 \kappa'_2
\]
\[
= (2(\kappa'_1(s))^2 \kappa_2(s) + \kappa_1(s)\kappa'_1(s)\kappa'_2(s) + \kappa^2_1(s)\kappa^3_2(s) - \kappa_1(s)\kappa_2(s)\kappa''_1(s))' = 0.
\]
This completes the proof. \( \square \)

By the above proposition, we define a new invariant \( \sigma_2(s) \) as follows:
\[
\sigma_2(s) = 2(\kappa'_1(s))^2 \kappa_2(s) + \kappa_1(s)\kappa'_1(s)\kappa'_2(s) + \kappa^2_1(s)\kappa^3_2(s) - \kappa_1(s)\kappa_2(s)\kappa''_1(s).
\]
We now respectively define a curve \( E_\gamma : I \to S^3_1 \) and a surface \( FS : I \times S^1 \to S^3_1 \) by
\[
E_\gamma(s) = \frac{\kappa'_1 \kappa_2}{\sqrt{(\kappa'_2)^2 + \kappa_1^2(1 + \kappa_1^2)}} (\gamma(s) - \frac{1}{\kappa_1} \mathbf{n}_1(s)) + \frac{\kappa'_1}{\sqrt{(\kappa'_1)^2 + \kappa^2_1(1 + \kappa_1^2)}} \mathbf{n}_2(s),
\]
\[
FS(s, u) = u_1 \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} \mathbf{n}_1(s)) + u_2 \mathbf{n}_2(s).
\]
Here \( u = (u_1, u_2) \in S^1 \), we call \( E_\gamma(s) \) the \textit{de Sitter evolute} of \( \gamma \) and \( FS(s, u) \) the \textit{de Sitter focal surface} of \( \gamma \).

We consider some properties of the de Sitter evolutes and de Sitter focal surfaces of timelike Sabban curves in \( S^3_1 \). Moreover we investigate the geometric meanings of the invariant \( \sigma_2(s) \).

We have the following proposition.

**Proposition 4.2.2.** Let \( \gamma : I \to S^3_1 \) be a timelike Sabban curve. Then we have the following assertions:

1. The set \( \left\{ (s, \theta) \left| \frac{\kappa'_1}{\sqrt{1+\kappa_1^2}} \cos \theta = \kappa_1 \kappa_2 \sin \theta \right. \right\} \) is the singularities of \( FS(s, \theta) \).
2. The de Sitter evolute \( E_\gamma(s) \) of \( \gamma \) is singular at \( s_0 \) if and only if \( \sigma_2(s_0) = 0 \).

**Proof.** (1) Since \( FS(s, u) = u_1 \frac{\kappa_1}{\sqrt{1+\kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} \mathbf{n}_1(s)) + u_2 \mathbf{n}_2(s) \) and \( u = (u_1, u_2) \in S^1 \), we denote \( u_1 = \cos \theta \) and \( u_2 = \sin \theta \), where \( \theta \in [0, 2\pi) \). Then the focal surface is parameterized by
\[
FS(s, \theta) = \cos \theta \frac{\kappa_1}{\sqrt{1+\kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} \mathbf{n}_1(s)) + \sin \theta \mathbf{n}_2(s).
\]
By straightforward calculations, we have

\[
\frac{\partial \mathbf{FS}}{\partial \theta} = -\kappa_1 \sin \theta \sqrt{1 + \kappa_1^2} \gamma(s) + \frac{\sin \theta}{\sqrt{1 + \kappa_1^2}} \mathbf{n}_1(s) + \cos \theta \mathbf{n}_2(s),
\]

\[
\frac{\partial \mathbf{FS}}{\partial s} = \left( \frac{\kappa_1' \cos \theta}{\kappa_1 \sqrt{1 + \kappa_1^2}} - \frac{\kappa_1' \cos \theta}{\kappa_1(1 + \kappa_1^2)\sqrt{1 + \kappa_1^2}} - \kappa_2 \sin \theta \right) \mathbf{n}_1(s)
+ \frac{\kappa_1' \cos \theta}{(1 + \kappa_1^2)\sqrt{1 + \kappa_1^2}} \gamma(s) - \frac{\kappa_2 \cos \theta}{\sqrt{1 + \kappa_1^2}} \mathbf{n}_2(s).
\]

Then the above two vectors are linearly dependent if and only if \(\frac{\kappa_1'}{\sqrt{1 + \kappa_1^2}} \cos \theta = \kappa_1 \kappa_2 \sin \theta\). This is the condition for the singularities of \(\mathbf{FS}\).

(2) Since

\[
E_\gamma(s) = \frac{\kappa_1^2 \kappa_2}{\sqrt{(\kappa_1')^2 + \kappa_1^2 \kappa_2^2(1 + \kappa_1^2)}} \left( \gamma(s) - \frac{1}{\kappa_1} \mathbf{n}_1(s) \right) + \frac{\kappa_1'}{\sqrt{(\kappa_1')^2 + \kappa_1^2 \kappa_2^2(1 + \kappa_1^2)}} \mathbf{n}_2(s),
\]

we have

\[
\frac{dE_\gamma}{ds} = -\frac{\kappa_1' \kappa_1'' + \kappa_1' \kappa_2' + 2 \kappa_1^2 \kappa_2' + \kappa_1^2 \kappa_2 \kappa_2' + \kappa_1^2 \kappa_2 \kappa_2'}{(\kappa_1')^2 + \kappa_1^2 \kappa_2^2 + \kappa_1^2 \kappa_2^2) \sqrt{1}} \left( \kappa_1^2 \kappa_2 \gamma(s) - \kappa_1 \kappa_2 \mathbf{n}_1(s) + \kappa_1' \mathbf{n}_2(s) \right)
+ 1 \left( (\kappa_1')^2 + \kappa_1^2 \kappa_2^2 + \kappa_1^2 \kappa_2^2) \right) \left( (2 \kappa_1 \kappa_2 + \kappa_1^2 \kappa_2) \gamma(s) + (-2 \kappa_1' \kappa_2 + \kappa_1 \kappa_2') \mathbf{n}_1(s) + (-\kappa_1 \kappa_2 + \kappa_1') \mathbf{n}_2(s) \right)
= ((\kappa_1')^2 + \kappa_1^2 \kappa_2^2 + \kappa_1^2 \kappa_2^2) \gamma(s) - \kappa_1 \kappa_2 \mathbf{n}_1(s) + \kappa_1' \mathbf{n}_2(s).
\]

Therefore, \(\frac{dE_\gamma}{ds} = 0\) if and only if \(\sigma_2(s) = 0\). This completes the proof.

In order to investigate the singularities of de Sitter evolutes and de Sitter focal surfaces of timelike Sabban curves, we apply the theory of unfolding of functions. Here we have the following proposition.
Proposition 4.2.3. Let $\gamma : I \to S^3_1$ be a timelike Sabban curve with $\kappa'_1(s) \neq 0$. If $h_v(s)$ has type $A_k$ at $s_0$ ($k = 3, 4$), then $H$ is a $p$-versal unfolding of $h_v$.

Proof. Let $\gamma(s) = (x_0(s), x_1(s), x_2(s), x_3(s))$. Since $v \in S^3_1$, let

$$v = (v_0, v_1, v_2, v_3) = (v_0, v_1, v_2, \sqrt{1 + v_0^2 - v_1^2 - v_2^2}).$$

Then we adopt the local coordinates $(v_0, v_1, v_2)$ for $S^3_1$. We have

$$H(s, v) = -x_0(s)v_0 + x_1(s)v_1 + x_2(s)v_2 + x_3(s)\sqrt{1 + v_0^2 - v_1^2 - v_2^2},$$

so that

$$\frac{\partial H}{\partial v_0} = -x_0(s) + v_0 x_3(s), \quad \frac{\partial H}{\partial v_1} = x_1(s) - \frac{v_1}{v_3} x_3(s), \quad \frac{\partial H}{\partial v_2} = x_2(s) - \frac{v_2}{v_3} x_3(s),$$

$$\frac{\partial^2 H}{\partial s \partial v_0} = -x_0'(s) + \frac{v_0}{v_3} x_3'(s), \quad \frac{\partial^2 H}{\partial s \partial v_1} = x_1'(s) - \frac{v_1}{v_3} x_3'(s), \quad \frac{\partial^2 H}{\partial s \partial v_2} = x_2'(s) - \frac{v_2}{v_3} x_3'(s),$$

$$\frac{\partial^3 H}{\partial s^2 \partial v_0} = -x_0''(s) + \frac{v_0}{v_3} x_3''(s), \quad \frac{\partial^3 H}{\partial s^2 \partial v_1} = x_1''(s) - \frac{v_1}{v_3} x_3''(s), \quad \frac{\partial^3 H}{\partial s^2 \partial v_2} = x_2''(s) - \frac{v_2}{v_3} x_3''(s),$$

$$\frac{\partial^4 H}{\partial s^3 \partial v_0} = -x_0'''(s) + \frac{v_0}{v_3} x_3'''(s), \quad \frac{\partial^4 H}{\partial s^3 \partial v_1} = x_1'''(s) - \frac{v_1}{v_3} x_3'''(s), \quad \frac{\partial^4 H}{\partial s^3 \partial v_2} = x_2'''(s) - \frac{v_2}{v_3} x_3'''(s).$$

By Proposition 4.2.1, $h_v$ has the $A_3$ singularity if and only if

$$v = \frac{\kappa_1 \cos \theta}{\sqrt{1 + \kappa_1^2}} \left( \gamma(s) - \frac{1}{\kappa_1} n_1(s) \right) + \sin \theta n_2(s)$$

and $\frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} \cos \theta = \kappa_1 \kappa_2 \sin \theta$. When $h_v$ has the $A_3$ singularity, we require the $2 \times 3$ matrix

$$\begin{pmatrix}
    x_0'(s) - \frac{v_0}{v_3} x_3'(s) & x_1'(s) - \frac{v_1}{v_3} x_3'(s) & x_2'(s) - \frac{v_2}{v_3} x_3'(s) \\
    x_0''(s) - \frac{v_0}{v_3} x_3''(s) & x_1''(s) - \frac{v_1}{v_3} x_3''(s) & x_2''(s) - \frac{v_2}{v_3} x_3''(s)
\end{pmatrix}$$

to have rank 2, which follows from the proof of the next case.

By Proposition 4.2.1, $h_v$ has the $A_4$ singularity if and only if

$$v = \frac{\kappa_1 \cos \theta}{\sqrt{1 + \kappa_1^2}} \left( \gamma(s) - \frac{1}{\kappa_1} n_1(s) \right) + \sin \theta n_2(s), \quad \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} \cos \theta = \kappa_1 \kappa_2 \sin \theta$$

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and \( \sigma_2(s) = 0 \). In this case, we need the \( 3 \times 3 \) matrix

\[
A = \begin{pmatrix}
  x'_0(s) - \frac{v_1}{v_3} x'_2(s) & x'_1(s) - \frac{v_1}{v_3} x'_3(s) & x'_2(s) - \frac{v_2}{v_3} x'_3(s) \\
  x''_0(s) - \frac{v_1}{v_3} x''_2(s) & x''_1(s) - \frac{v_1}{v_3} x''_3(s) & x''_2(s) - \frac{v_2}{v_3} x''_3(s) \\
  x'''_0(s) - \frac{v_1}{v_3} x'''_2(s) & x'''_1(s) - \frac{v_1}{v_3} x'''_3(s) & x'''_2(s) - \frac{v_2}{v_3} x'''_3(s)
\end{pmatrix}
\]

to have rank 3. Put \( a_i = (x'_i, x''_i, x'''_i)^t \), then we have

\[
A = \left( a_0 - \frac{v_0}{v_3} a_3, a_1 - \frac{v_1}{v_3} a_3, a_2 - \frac{v_2}{v_3} a_3 \right).
\]

\[
-\det A = \det(a_0, a_1, a_2) + \frac{v_0}{v_3} \det(a_3, a_1, a_2) + \frac{v_1}{v_3} \det(a_0, a_3, a_2) + \frac{v_2}{v_3} \det(a_0, a_1, a_3)
\]

\[
= -\left( \frac{v}{v_3}, (\gamma'(s) \wedge \gamma''(s) \wedge \gamma'''(s)) \right)
\]

\[
= \kappa_1 \sin^2 \theta = \frac{\kappa_1^2 (\kappa'_1)^2}{(\kappa_1')^2 + \kappa_1^2 \kappa_2^2 (1 + \kappa_1^2)} \neq 0.
\]

For other local coordinates, we can apply the arguments similar to above. This completes the proof.

By Proposition 4.2.1, Proposition 4.2.3 and Theorem 2.3.6, we have the following theorem.

**Theorem 4.2.4.** Let \( \gamma : I \to S^3_1 \) be a timelike Sabban curve with \( \kappa'_1(s) \neq 0 \). Then we have the following:

(1) If \( h_v \) has \( A_3 \) singularity at \( s_0 \), the germ of de Sitter focal surface \( FS \) at \((s_0, \theta_0)\) is diffeomorphic to \( C \times \mathbb{R} \).

(2) If \( h_v \) has \( A_1 \) singularity at \( s_0 \), the germ of de Sitter focal surface \( FS \) at \((s_0, \theta_0)\) is diffeomorphic to \( SW \) and the germ of de Sitter evolute \( E_\gamma \) at \( s_0 \) is diffeomorphic to \( C \).

We consider the **hyperplane** in \( \mathbb{R}^4_1 \), which is defined by \( HP(v, c) = \{ x \in \mathbb{R}^4_1 | \langle x, v \rangle = c \} \), where \( v \in S^3_1 \) is a fixed vector and \( c \in \mathbb{R} \) is a constant. We define

\[
S^3_1(v, c) = S^3_1 \cap HP(v, c)
\]

and call \( S^3_1(v, c) \) a **2-dimensional de Sitter subspace** in \( S^3_1 \). For any fixed \( s_0 \in I \), we set \( \langle \gamma(s_0), v \rangle = \varepsilon \). If we consider a function \( \eta_v : S^3_1 \to \mathbb{R} \) defined by \( \eta_v(x) = \langle x, v \rangle \), then
$h_v^{-1}(\varepsilon) = S^2_1(v, \varepsilon)$ and $h_v \circ \gamma(s) = h_v(s)$, so that $h_v(s_0) = \varepsilon$ and $h'_v(s_0) = 0$ if and only if $S^2_1(v, \varepsilon)$ is tangent to $\gamma(s)$ at $s_0$. In this case, we call $S^2_1(v, \varepsilon)$ a tangent de Sitter subspace at $s_0$, we remark that there are infinitely many tangent de Sitter subspaces of $\gamma(s)$ at $s_0$. We say that a tangent de Sitter subspace $S^2_1(v, \varepsilon)$ of $\gamma(s)$ at $s_0$ has at least $k + 1$-point contact with $\gamma$ if $h_v(s_0) = \varepsilon$ and $h'_v(s_0) = \cdots = h^{(k)}_v(s_0) = 0$. We also say that tangent de Sitter subspace $S^2_1(v, \varepsilon)$ of $\gamma(s)$ at $s_0$ has $k + 1$-point contact with $\gamma$ if $h_v(s_0) = \varepsilon$, $h'_v(s_0) = \cdots = h^{(k)}_v(s_0) = 0$ and $h^{(k+1)}_v(s_0) \neq 0$. By Propositions 4.2.1, 4.2.2 and arguments similar to the proof of Proposition 3.1.2, we have the following propositions.

**Proposition 4.2.5.** Let $\gamma: I \to S^3_1$ be a timelike Sabban curve. Then the following conditions are equivalent:

1. The de Sitter evolute $E_\gamma(s)$ is a constant vector.
2. There exist $v \in S^3_1$ and $c \in \mathbb{R}$ such that $\gamma(I) \subset S^2_1(v, c)$.
3. $\sigma_2(s) \equiv 0$.

**Proposition 4.2.6.** Let $\gamma: I \to S^3_1$ be a timelike Sabban curve. Then we have the following:

1. $S^2_1(v, \varepsilon)$ is a tangent de Sitter subspace of $\gamma(s)$ at $s_0$ if and only if there exist $a, b, c \in \mathbb{R}$ with $a^2 + b^2 + c^2 = 1$ such that $v = a\gamma(s_0) + bn_1(s_0) + cn_2(s_0)$.
2. The tangent de Sitter subspace $S^2_1(v, \varepsilon)$ has at least 3-point contact with $\gamma(s)$ at $s_0$ if and only if there exists $\theta_0 \in [0, 2\pi)$ such that
   \[ v = \frac{\kappa_1 \cos \theta_0}{\sqrt{1 + \kappa_1^2}} (\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \sin \theta_0 n_2(s_0). \]
3. The tangent de Sitter subspace $S^2_1(v, \varepsilon)$ has at least 4-point contact with $\gamma(s)$ at $s_0$ if and only if there exists $\theta_0 \in [0, 2\pi)$ such that
   \[ v = \frac{\kappa_1 \cos \theta_0}{\sqrt{1 + \kappa_1^2}} (\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \sin \theta_0 n_2(s_0) \]
   and $\frac{\kappa'_1}{\sqrt{1 + \kappa_1^2}} \cos \theta_0 = \kappa_1 \kappa_2 \sin \theta_0$.
4. The tangent de Sitter subspace $S^2_1(v, \varepsilon)$ has at least 5-point contact with $\gamma(s)$ at $s_0$ if and only if there exists $\theta_0 \in [0, 2\pi)$ such that
   \[ v = \frac{\kappa_1 \cos \theta_0}{\sqrt{1 + \kappa_1^2}} (\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \sin \theta_0 n_2(s_0), \quad \frac{\kappa'_1}{\sqrt{1 + \kappa_1^2}} \cos \theta_0 = \kappa_1 \kappa_2 \sin \theta_0. \]
and $\sigma_2(s_0) = 0$.

(5) The tangent de Sitter subspace $S^2_1(v, \varepsilon)$ has at least 6-point contact with $\gamma(s)$ at $s_0$ if and only if there exists $\theta_0 \in [0, 2\pi)$ such that

$$v = \frac{\kappa_1 \cos \theta_0}{\sqrt{1 + \kappa_1^2}}(\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \sin \theta_0 n_2(s_0), \quad \frac{\kappa'_1}{\sqrt{1 + \kappa_1^2}} \cos \theta_0 = \kappa_1 \kappa_2 \sin \theta_0$$

and $\sigma_2(s_0) = \sigma'_2(s_0) = 0$.

As a consequence, $E_\gamma(s)$ is the locus of the polar vector $v \in S^3_1$ such that $S^2_1(v, \varepsilon)$ has at least 4-point contact with $\gamma(s)$ at $s_0$. We call $S^2_1(v, \varepsilon)$ an osculating de Sitter subspace of $\gamma(s)$ at $s_0$ if $v = E_\gamma(s_0)$. As a corollary of Theorem 4.2.4 and Proposition 4.2.6, we have the following theorem.

**Theorem 4.2.7.** Let $\gamma : I \to S^3_1$ be a timelike Sabban curve with $\kappa'_1(s) \neq 0$. Then we have the following:

1. If $v_0 = FS(s_0, \theta_0)$, then the tangent de Sitter subspace $S^2_1(v_0, \varepsilon)$ and $\gamma(s)$ have at least 3-point contact at $s_0$.

2. The osculating de Sitter subspace $S^2_1(v_0, \varepsilon)$ and $\gamma(s)$ have 4-point contact at $s_0$ if and only if there exists $\theta_0 \in [0, 2\pi)$ such that

$$v = \frac{\kappa_1 \cos \theta_0}{\sqrt{1 + \kappa_1^2}}(\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \sin \theta_0 n_2(s_0), \quad \frac{\kappa'_1}{\sqrt{1 + \kappa_1^2}} \cos \theta_0 = \kappa_1 \kappa_2 \sin \theta_0$$

and $\sigma_2(s_0) = \sigma'_2(s_0) \neq 0$. In this case, the germ of $FS$ at $FS(s_0, \theta_0)$ is diffeomorphic to $C \times \mathbb{R}$.

3. The osculating de Sitter subspace $S^2_1(v_0, \varepsilon)$ and $\gamma(s)$ have 5-point contact at $s_0$ if and only if there exists $\theta_0 \in [0, 2\pi)$ such that

$$v = \frac{\kappa_1 \cos \theta_0}{\sqrt{1 + \kappa_1^2}}(\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \sin \theta_0 n_2(s_0), \quad \frac{\kappa'_1}{\sqrt{1 + \kappa_1^2}} \cos \theta_0 = \kappa_1 \kappa_2 \sin \theta_0, \sigma_2(s_0) = 0 \text{ and } \sigma'_2(s_0) \neq 0.$$
4.3 De Sitter evolutes and de Sitter focal hypersurfaces of timelike Sabban curves in $S^4_1$

In this section we consider the timelike Sabban curve in $S^4_1$. Let $\gamma : I \to S^4_1$ be a timelike Sabban curve, we can reparameterize it by the arc-length $s$. Then we have the tangent vector $t(s) = \gamma'(s)$, obviously $\|t(s)\| = 1$. When $\langle t'(s), t'(s) \rangle \neq 1$, we define a unit vector

$$n_1(s) = \frac{t'(s) - \gamma(s)}{\|t'(s) - \gamma(s)\|}.$$

Let $\kappa_1(s) = \|t'(s) - \gamma(s)\|$, $\langle t'(s), t'(s) \rangle \neq 1$ is equal to $\kappa_1(s) \neq 0$. If $\|n'_1(s) - \kappa_1(s)t(s)\| \neq 0$, we define a unit vector

$$n_2(s) = \frac{n'_1(s) - \kappa_1(s)t(s)}{\|n'_1(s) - \kappa_1(s)t(s)\|}$$

and denote $\kappa_2(s) = \|n'_1(s) - \kappa_1(s)t(s)\|$. Let $n_3(s) = \gamma(s) \wedge t(s) \wedge n_1(s) \wedge n_2(s)$, then we have the Sabban frame \{ $\gamma(s), t(s), n_1(s), n_2(s), n_3(s)$ \} along $\gamma$. In §3, we have shown the Frenet-Serret type of timelike Sabban curves, under the assumption that $\kappa_1(s) \neq 0$ and $\kappa_2(s) \neq 0$, the Frenet-Serret type is as follows:

$$\begin{cases}
\gamma'(s) = t(s), \\
t'(s) = \gamma(s) + \kappa_1(s)n_1(s), \\
n'_1(s) = \kappa_1(s)t(s) + \kappa_2(s)n_2(s), \\
n'_2(s) = -\kappa_2(s)n_1(s) + \kappa_3(s)n_3(s), \\
n'_3(s) = -\kappa_3(s)n_2(s).
\end{cases}$$

Here $\kappa_1(s)$ and $\kappa_2(s)$ can’t be zero, $\kappa_3(s)$ may equal to zero.

We define a family of functions on timelike Sabban curve. Let $\gamma : I \to S^4_1$ be a timelike Sabban curve. We define a function $H : I \times S^4_1 \to \mathbb{R}$ by $H(s, v) = \langle \gamma(s), v \rangle$, which is called a de Sitter height function on the timelike Sabban curve $\gamma$. We denote that $h_v(s) = H(s, v)$ for any fixed $v \in S^4_1$. Then we have the following proposition.

**Proposition 4.3.1.** Let $\gamma : I \to S^4_1$ be a timelike Sabban curve. Then we have the following assertions:
(1) \( h_v'(s) = 0 \) if and only if there exist \( a, b, c, d \in \mathbb{R} \) with \( a^2 + b^2 + c^2 + d^2 = 1 \) such that
\[
v = a\gamma(s) + b\mathbf{n}_1(s) + c\mathbf{n}_2(s) + d\mathbf{n}_3(s).
\]
(2) \( h_v'(s) = h_v''(s) = 0 \) if and only if there exist \( \theta \in [0, 2\pi) \) and \( \varphi \in [-\pi, \pi) \) such that
\[
v = \sin \theta \cos \varphi \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} \mathbf{n}_1(s)) + \cos \theta \cos \varphi \mathbf{n}_2(s) + \sin \varphi \mathbf{n}_3(s).
\]
(3) \( h_v'(s) = h_v''(s) = h_v'''(s) = 0 \) if and only if there exist \( \theta \in [0, 2\pi) \) and \( \varphi \in [-\pi, \pi) \) such that
\[
v = \sin \theta \cos \varphi \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} \mathbf{n}_1(s)) + \cos \theta \cos \varphi \mathbf{n}_2(s) + \sin \varphi \mathbf{n}_3(s),
\]
\[
\sin \theta = \frac{\kappa_1 \kappa_2 \sqrt{1 + \kappa_1^2}}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}} \quad \text{and} \quad \cos \theta = \frac{\kappa_1'}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}}.
\]
(4) \( h_v'(s) = h_v''(s) = h_v'''(s) = 0 \) if and only if there exist \( \theta \in [0, 2\pi) \) and \( \varphi \in [-\pi, \pi) \) such that
\[
v = \sin \theta \cos \varphi \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} \mathbf{n}_1(s)) + \cos \theta \cos \varphi \mathbf{n}_2(s) + \sin \varphi \mathbf{n}_3(s),
\]
\[
(\kappa_1^2 \kappa_2^3 - \kappa_1'' \kappa_1 \kappa_2 + 2(\kappa_1')^2 \kappa_2 + \kappa_1 \kappa_1' \kappa_2') \cos \varphi + \kappa_1 \kappa_2 \kappa_3 \sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2} \sin \varphi = 0,
\]
\[
\sin \theta = \frac{\kappa_1 \kappa_2 \sqrt{1 + \kappa_1^2}}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}} \quad \text{and} \quad \cos \theta = \frac{\kappa_1'}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}}.
\]
(5) \( h_v'(s) = h_v''(s) = h_v'''(s) = 0 \) if and only if there exist \( \theta \in [0, 2\pi) \) and \( \varphi \in [-\pi, \pi) \) such that
\[
v = \sin \theta \cos \varphi \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} \mathbf{n}_1(s)) + \cos \theta \cos \varphi \mathbf{n}_2(s) + \sin \varphi \mathbf{n}_3(s),
\]
\[
(\kappa_1^2 \kappa_2 - \kappa_1'' \kappa_1 \kappa_2 + 2(\kappa_1')^2 \kappa_2 + \kappa_1 \kappa_1' \kappa_2') \cos \varphi + \kappa_1 \kappa_2 \kappa_3 \sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2} \sin \varphi = 0,
\]
\[
- \kappa_1^2 \kappa_1' \kappa_2 \kappa_3 - \kappa_1^2 \kappa_1' \kappa_2^3 \kappa_3 + \kappa_1^3 \kappa_2^3 \kappa_2 \kappa_3 + 6 \kappa_1 \kappa_1' \kappa_1' \kappa_2 \kappa_2 \kappa_3 - 4 \kappa_1 (\kappa_1')^2 \kappa_2 \kappa_2 \kappa_3 + \kappa_1' \kappa_1 \kappa_2 \kappa_2' \kappa_3
\]
\[
- \kappa_1^2 \k_1' \k_2 \k_3 - 6 (\kappa_1')^3 \k_2 \k_3 + 2 \kappa_1 \k_1' \k_1' \k_2 \k_2 \k_3 - 2 \kappa_1^2 \k_1' (\kappa_1')^2 \k_3 - \kappa_1^3 \k_1 \k_2 \k_3 + \kappa_1^2 \k_1' \k_2 \k_2' \k_3
\]
\[
- 2 \kappa_1 (\kappa_1')^2 \k_2' \k_3 - \kappa_1^2 \k_1' \k_2 \k_2' \k_3 = 0,
\]
\[
\sin \theta = \frac{\kappa_1 \kappa_2 \sqrt{1 + \kappa_1^2}}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}} \quad \text{and} \quad \cos \theta = \frac{\kappa_1'}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}}.
\]
Proof. (1) Since \( v \in S_1 \), there exist \( a, x, b, c, d \in \mathbb{R} \) such that \( v = a\gamma(s) + xt(s) + bn_1(s) + cn_2(s) + dn_3(s) \) with \( a^2 + x^2 + b^2 + c^2 + d^2 = 1 \). Since \( h_v'(s) = 0 \), \( x = 0 \) so that \( a^2 + b^2 + c^2 + d^2 = 1 \). The converse assertion also holds.

(2) By (1), we can show that \( \langle \gamma(s) + \kappa_1 n_1(s), v \rangle = 0 \). Thus \( b = -\frac{a}{\kappa_1} \). Since \( a^2 + b^2 + c^2 + d^2 = 1 \), there exist \( \theta \in [0, 2\pi) \) and \( \varphi \in [-\pi, \pi) \) such that

\[
a = \sin \theta \cos \varphi \frac{\kappa_1}{\sqrt{1 + \kappa_1'^2}}, \quad b = -\sin \theta \cos \varphi \frac{1}{\sqrt{1 + \kappa_1'^2}}, \quad c = \cos \theta \cos \varphi, \quad d = \sin \varphi.
\]

Therefore

\[
v = \sin \theta \cos \varphi \frac{\kappa_1}{\sqrt{1 + \kappa_1'^2}} (\gamma(s) - \frac{1}{\kappa_1} n_1(s)) + \cos \theta \cos \varphi n_2(s) + \sin \varphi n_3(s).
\]

(3) We assume that \( h_v''(s) = h_v'''(s) = 0 \). Since

\[
h_v'''(s) = ((1 + \kappa_1^2)t(s) + \kappa_1' n_1(s) + \kappa_1 \kappa_2 n_2(s), v) = 0,
\]

\[
\frac{\kappa_1'}{\sqrt{1 + \kappa_1'^2}} \sin \theta = \kappa_1 \kappa_2 \cos \theta. \quad \text{The last condition is equivalent to} \quad \sin \theta = \frac{\kappa_1 \kappa_2 \sqrt{1 + \kappa_1^2}}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}}
\]

\[
\cos \theta = \frac{\kappa_1'}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}}
\]

(4) We assume that \( h_v'(s) = h_v''(s) = h_v'''(s) = 0 \). Then we have

\[
h_v^{(4)}(s) = ((1 + \kappa_1^2)\gamma(s) + 3 \kappa_1 \kappa_2^2 t(s) + (\kappa_1 + \kappa_1^3 + \kappa_1'' - \kappa_1 \kappa_2^2) n_1(s) + (2 \kappa_1' \kappa_2 + \kappa_1 \kappa_2') n_2(s) + \kappa_1 \kappa_2 \kappa_3 n_3(s), v).
\]

Therefore \( h_v^{(4)}(s) = 0 \) if and only if

\[
\sin \theta \cos \varphi \frac{\kappa_1 \kappa_2^2 - \kappa_1''}{\sqrt{1 + \kappa_1^2}} + \cos \theta \cos \varphi (2 \kappa_1' \kappa_2 + \kappa_1 \kappa_2') + \kappa_1 \kappa_2 \kappa_3 \sin \varphi = 0.
\]

Since we have \( \sin \theta = \frac{\kappa_1 \kappa_2 \sqrt{1 + \kappa_1^2}}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}} \) and \( \cos \theta = \frac{\kappa_1'}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}} \), then

\[
(\kappa_1^2 \kappa_2^3 - \kappa_1'' \kappa_1 \kappa_2 + 2(\kappa_1')^2 \kappa_2 + \kappa_1 \kappa_2' \kappa_2') \cos \varphi + \kappa_1 \kappa_2 \kappa_3 \sqrt{\kappa_1^2 \kappa_2^3 (1 + \kappa_1^2) + (\kappa_1')^2} \sin \varphi = 0.
\]

This proves assertion (4).
When \( h_v'(s) = h_v''(s) = h_v'''(s) = 0 \), we have the fifth derivative:

\[
\begin{align*}
    h_v^{(5)}(s) &= (5\kappa_1 \kappa_1' \gamma(s) + (1 + 2\kappa_1' + 3(\kappa_1')^2 + 4\kappa_1 \kappa_1'' + \kappa_1^4 - \kappa_1^2 \kappa_2^2) t(s) \\
    &+ (6\kappa_1^2 \kappa_1' + \kappa_1'' + \kappa_1''' - 3\kappa_1' \kappa_2' - 3\kappa_1 \kappa_2 \kappa_2') n_1(s) \\
    &+ (\kappa_1 \kappa_2 + \kappa_1^3 \kappa_2 + 3\kappa_1' \kappa_2' - \kappa_1 \kappa_2'' + 3\kappa_1' \kappa_2'' + \kappa_1 \kappa_2''') n_2(s) \\
    &+ (3\kappa_1' \kappa_2' \kappa_3 + 2\kappa_1' \kappa_2' \kappa_3 + \kappa_1 \kappa_2' \kappa_3) n_3(s), v).
\end{align*}
\]

It follows that \( h_v^{(5)}(s) = 0 \) if and only if

\[
\sin \varphi \sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2)} + (\kappa_1')^2 (3\kappa_1' \kappa_2' \kappa_3 + 2\kappa_1' \kappa_2' + \kappa_1 \kappa_2') = \cos \varphi (-\kappa_1' \kappa_2' - 2\kappa_1 \kappa_2^3 \kappa_3 + 3\kappa_1^2 \kappa_2' \kappa_3 + 3(\kappa_1')^2 \kappa_2' + \kappa_1 \kappa_2' \kappa_3) - \kappa_1 \kappa_2' \kappa_3.
\]

Since

\[
(\kappa_1^2 \kappa_2^3 - \kappa_1' \kappa_2 + 2(\kappa_1')^2 \kappa_2 + \kappa_1 \kappa_2' \kappa_3) \cos \varphi + \kappa_1 \kappa_2 \kappa_3 \sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2)} + (\kappa_1')^2 \sin \varphi = 0,
\]

we have

\[
\begin{align*}
    &- \kappa_1^2 \kappa_1' \kappa_2' \kappa_3 - \kappa_1^2 \kappa_1' \kappa_2' \kappa_3 + \kappa_1^3 \kappa_1' \kappa_2' \kappa_3 + 6\kappa_1 \kappa_1' \kappa_2' \kappa_3 - 4\kappa_1 (\kappa_1')^2 \kappa_2' \kappa_3 + \kappa_1^2 \kappa_1' \kappa_2' \kappa_3 \\
    &- \kappa_1^2 \kappa_1' \kappa_2 \kappa_3 - 2\kappa_1^2 \kappa_1' \kappa_2' \kappa_3 - 2\kappa_1 \kappa_1' \kappa_2' \kappa_3 - \kappa_1^3 \kappa_1' \kappa_2' \kappa_3 + \kappa_1^2 \kappa_1' \kappa_2' \kappa_3 \\
    &- 2\kappa_1 (\kappa_1')^2 \kappa_2' \kappa_3 - \kappa_1^2 \kappa_1' \kappa_2' \kappa_3 = 0.
\end{align*}
\]

This completes the proof. \( \square \)

We now define a new invariant as follows:

\[
\sigma_3(s) = -\kappa_1^3 \kappa_1'' \kappa_2^3 \kappa_3 - \kappa_1^2 \kappa_1' \kappa_2' \kappa_3 + \kappa_1^3 \kappa_1' \kappa_2' \kappa_3 + 6\kappa_1 \kappa_1'' \kappa_2' \kappa_3 \\
    - 4\kappa_1 (\kappa_1')^2 \kappa_1' \kappa_2' \kappa_3 - \kappa_1^2 \kappa_1' \kappa_2' \kappa_3 - 4\kappa_1 \kappa_1'' \kappa_2' \kappa_3 - 3(\kappa_1')^3 \kappa_2' \kappa_3 \\
    + 2\kappa_1^3 \kappa_1' \kappa_2' \kappa_3 - 2\kappa_1^2 \kappa_1' \kappa_2' \kappa_3 - \kappa_1^3 \kappa_1' \kappa_2' \kappa_3 + \kappa_1^2 \kappa_1' \kappa_2' \kappa_3 \\
    - 2\kappa_1 (\kappa_1')^2 \kappa_2' \kappa_3 - \kappa_1^2 \kappa_1' \kappa_2' \kappa_3.
\]
Conjecture 4.3.2. Let $\gamma : I \to S^4_1$ be a timelike Sabban curve. Then $h'_v(s) = h''_v(s) = h'''_v(s) = h^{(4)}_v(s) = h^{(5)}_v(s) = h^{(6)}_v(s) = 0$ if and only if there exist $\theta \in [0, 2\pi)$ and $\varphi \in [-\pi, \pi)$ such that

$$v = \sin \theta \cos \varphi \frac{\kappa_1}{1 + \kappa_1'}(\gamma(s) - \frac{1}{\kappa_1}n_1(s)) + \cos \theta \cos \varphi n_2(s) + \sin \varphi n_3(s),$$

$$(\kappa_1'^2 - \kappa_1'' \kappa_1' \kappa_2 + 2(\kappa_1')^2 \kappa_2 + \kappa_1 \kappa_2' \kappa_3') \cos \varphi + \kappa_1 \kappa_2 \kappa_3 \sqrt{\kappa_1'^2 \kappa_2^2 (1 + \kappa_1^2)} + (\kappa_1')^2 \sin \varphi = 0,$$

$$\sin \theta = \frac{\kappa_1 \kappa_2 \sqrt{1 + \kappa_1'^2}}{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}, \quad \cos \theta = \frac{\kappa_1'}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}}$$

and $\sigma_3(s) = \sigma_3'(s) = 0$.

By the above proposition, we get a function $\sigma_3(s)$ which is useful in following investigation. We define another function $\rho(s)$ by

$$\rho(s) = (\kappa_1^2 \kappa_2^3 - \kappa_1'' \kappa_1 \kappa_2 + 2(\kappa_1')^2 \kappa_2 + \kappa_1 \kappa_2' \kappa_3')^2 + \kappa_1^2 \kappa_2^2 \kappa_3^2 (1 + \kappa_1^2) + (\kappa_1')^2 \kappa_1^2 \kappa_2^2 \kappa_3^2.$$

Now we define a hypersurface $FHS : I \times S^2 \to S^4_1$ by

$$FHS(s, u) = u_1 \frac{\kappa_1}{1 + \kappa_1'}(\gamma(s) - \frac{1}{\kappa_1}n_1(s)) + u_2 n_2(s) + u_3 n_3(s).$$

Here $u = (u_1, u_2, u_3) \in S^2$, we call $FHS(s, u)$ the de Sitter focal hypersurface of $\gamma$. Since $u = (u_1, u_2, u_3) \in S^2$, there exist $\theta \in [0, 2\pi)$ and $\varphi \in [-\pi, \pi)$ such that

$$FHS(s, \theta, \varphi) = \sin \theta \cos \varphi \frac{\kappa_1}{1 + \kappa_1'}(\gamma(s) - \frac{1}{\kappa_1}n_1(s)) + \cos \theta \cos \varphi n_2(s) + \sin \varphi n_3(s).$$

If $\rho(s) \neq 0$, we define a curve $E_\gamma : I \to S^4_1$ by

$$E_\gamma(s) = \frac{1}{\sqrt{\rho(s)}}[\kappa_1^3 \kappa_2^2 \kappa_3 (\gamma(s) - \frac{1}{\kappa_1}n_1(s)) + \kappa_1 \kappa_1' \kappa_2 \kappa_3 n_2(s) - (\kappa_1^2 \kappa_2^3 - \kappa_1'' \kappa_1 \kappa_2 + 2(\kappa_1')^2 \kappa_2 + \kappa_1 \kappa_2' \kappa_3') n_3(s)].$$

We call $E_\gamma(s)$ the de Sitter evolute of $\gamma$.

We consider some properties of the de Sitter evolute and the de Sitter focal hypersurface of a timelike Sabban curve in $S^4_1$. Moreover we investigate the geometric meaning of the function $\sigma_3(s)$. We have the following proposition.

Proposition 4.3.3. Let $\gamma : I \to S^4_1$ be a timelike Sabban curve. Then we have the following assertions:
(1) The set \( \{(s, \theta, \varphi)|\frac{\kappa'}{\sqrt{1+\kappa_1^2}} \sin \theta = \kappa_1 \kappa_2 \cos \theta \} \) is the singularities of \( \text{FHS}(s, \theta, \varphi) \).

(2) If \( \rho(s) \neq 0 \), the de Sitter evolute \( E_\gamma(s) \) of \( \gamma \) is singular at \( s_0 \) if and only if \( \sigma_3(s_0) = 0 \).

Proof. (1) Since

\[
\text{FHS}(s, \theta, \varphi) = \sin \theta \cos \varphi \frac{\kappa_1}{\sqrt{1+\kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} n_1(s)) + \cos \theta \cos \varphi n_2(s) + \sin \varphi n_3(s).
\]

By straightforward calculations, we have

\[
\frac{\partial \text{FHS}}{\partial \theta} = \frac{\kappa_1 \cos \theta \cos \varphi}{\sqrt{1+\kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} n_1(s)) - \frac{\cos \theta \cos \varphi}{\sqrt{1+\kappa_1^2}} n_1(s) - \sin \theta \cos \varphi n_2(s),
\]

\[
\frac{\partial \text{FHS}}{\partial \varphi} = -\frac{\kappa_1 \sin \theta \sin \varphi}{\sqrt{1+\kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} n_1(s)) - \frac{\sin \theta \sin \varphi}{\sqrt{1+\kappa_1^2}} n_1(s) - \cos \theta \sin \varphi n_2(s) + \cos \varphi n_3(s),
\]

\[
\frac{\partial \text{FHS}}{\partial s} = \frac{\kappa_1' \kappa_1 \sin \theta \cos \varphi}{(1+\kappa_1^2)\sqrt{1+\kappa_1^2}} - \frac{\kappa_2 \cos \theta \cos \varphi}{(1+\kappa_1^2)\sqrt{1+\kappa_1^2}} n_1(s) + \frac{\kappa_1' \sin \theta \cos \varphi}{(1+\kappa_1^2)\sqrt{1+\kappa_1^2}} \gamma(s)
\]

\[
- \frac{\kappa_2 \sin \theta \cos \varphi}{\sqrt{1+\kappa_1^2}} + \sin \theta \kappa_3) n_2(s) + \kappa_1' \kappa_3 \sin \theta \cos \varphi \frac{1}{\kappa_1 \kappa_2 \sqrt{1+\kappa_1^2}} n_3(s).
\]

The above three vectors are linearly dependent if and only if \( \frac{\kappa'}{\sqrt{1+\kappa_1^2}} \sin \theta = \kappa_1 \kappa_2 \cos \theta \), which gives the condition for the singularities of \( \text{FHS} \).

(2) We define a function \( f(s) = \langle t(s), v(s) \rangle \). Under the condition \( f(s) = 0 \), if \( \langle t'(s), v(s) \rangle = 0 \), we have \( \langle t(s), v'(s) \rangle = 0 \). Under the condition \( \langle t'(s), v(s) \rangle = 0 \), if \( \langle t''(s), v(s) \rangle = 0 \), we have \( \langle t'(s), v'(s) \rangle = 0 \). We continue this procedure. Finally, if

\[
\langle t(s), v(s) \rangle = \langle t'(s), v(s) \rangle = \langle t''(s), v(s) \rangle = \langle t'''(s), v(s) \rangle = \langle t^{(4)}(s), v(s) \rangle = 0,
\]

then

\[
\langle t(s), v'(s) \rangle = \langle t'(s), v'(s) \rangle = \langle t''(s), v'(s) \rangle = \langle t'''(s), v'(s) \rangle = 0.
\]

If \( \rho(s) \neq 0 \), by the Proposition 4.3.1, \( v(s) = E_\gamma(s) \) is orthogonal to the following vectors: \( t(s), t'(s), t''(s) \) and \( t'''(s) \). Since \( v(s) \in S_1^1 \), we have \( \langle v(s), v'(s) \rangle = 0 \). Then \( v'(s) \) is orthogonal to \( v(s), t(s), t'(s), t''(s) \) and \( t'''(s) \), this means \( v'(s) = 0 \). By the Proposition 4.3.1, we have that \( \frac{dE_\gamma}{ds} = 0 \) if and only if \( \sigma_3(s) = 0 \). This completes the proof. \( \square \)
In order to investigate the singularities of de Sitter evolutes and de Sitter focal hypersurfaces of timelike Sabban curves, we apply the theory of unfolding of functions. In §2, we defined the bifurcation set \( B_H \) of \( H \) by

\[
B_H = \left\{ \mathbf{x} \in \mathbb{R}^r \mid \exists s, \text{with } \frac{\partial H}{\partial s}(s, \mathbf{x}) = \frac{\partial^2 H}{\partial s^2}(s, \mathbf{x}) = 0 \right\}.
\]

Therefore, the focal hypersurface \( FHS \) is the bifurcation set of the de Sitter height function \( H \). We have the following proposition.

**Proposition 4.3.4.** Let \( \gamma : I \to S^4 \) be a timelike Sabban curve with \( \rho(s) \neq 0 \). If \( h_v(s) \) has type \( A_k \) at \( s_0 \) (\( k = 3, 4, 5 \)), then \( H \) is a \( p \)-versal unfolding of \( h_v \).

**Proof.** We denote \( \gamma(s) = (x_0(s), x_1(s), x_2(s), x_3(s), x_4(s)) \), \( \mathbf{v} = (v_0, v_1, v_2, v_3, \sqrt{v_0^2 - v_1^2 - v_2^2 - v_3^2 + 1}) \).

Then we adopt the local coordinates \((v_0, v_1, v_2, v_3)\) for \( S^4 \). We have

\[
H(s, \mathbf{v}) = -x_0(s)v_0 + x_1(s)v_1 + x_2(s)v_2 + x_3(s)v_3 + x_4(s)\sqrt{v_0^2 - v_1^2 - v_2^2 - v_3^2 + 1},
\]

so that

\[
\begin{align*}
\frac{\partial H}{\partial v_0} &= -x_0(s) + \frac{v_0}{v_4}x_4(s), & \frac{\partial H}{\partial v_1} &= x_1(s) - \frac{v_1}{v_4}x_4(s), \\
\frac{\partial H}{\partial v_2} &= x_2(s) - \frac{v_2}{v_4}x_4(s), & \frac{\partial H}{\partial v_3} &= x_3(s) - \frac{v_3}{v_4}x_4(s), \\
\frac{\partial^2 H}{\partial s \partial v_0} &= -x_0'(s) + \frac{v_0}{v_4}x_4'(s), & \frac{\partial^2 H}{\partial s \partial v_1} &= x_1'(s) - \frac{v_1}{v_4}x_4'(s), \\
\frac{\partial^2 H}{\partial s \partial v_2} &= x_2'(s) - \frac{v_2}{v_4}x_4'(s), & \frac{\partial^2 H}{\partial s \partial v_3} &= x_3'(s) - \frac{v_3}{v_4}x_4'(s), \\
\frac{\partial^3 H}{\partial s^2 \partial v_0} &= -x_0''(s) + \frac{v_0}{v_4}x_4''(s), & \frac{\partial^3 H}{\partial s^2 \partial v_1} &= x_1''(s) - \frac{v_1}{v_4}x_4''(s), \\
\frac{\partial^3 H}{\partial s^2 \partial v_2} &= x_2''(s) - \frac{v_2}{v_4}x_4''(s), & \frac{\partial^3 H}{\partial s^2 \partial v_3} &= x_3''(s) - \frac{v_3}{v_4}x_4''(s), \\
\frac{\partial^4 H}{\partial s^3 \partial v_0} &= -x_0'''(s) + \frac{v_0}{v_4}x_4'''(s), & \frac{\partial^4 H}{\partial s^3 \partial v_1} &= x_1'''(s) - \frac{v_1}{v_4}x_4'''(s), \\
\frac{\partial^4 H}{\partial s^3 \partial v_2} &= x_2'''(s) - \frac{v_2}{v_4}x_4'''(s), & \frac{\partial^4 H}{\partial s^3 \partial v_3} &= x_3'''(s) - \frac{v_3}{v_4}x_4'''(s), \\
\frac{\partial^5 H}{\partial s^4 \partial v_0} &= -x_0^{(4)}(s) + \frac{v_0}{v_4}x_4^{(4)}(s), & \frac{\partial^5 H}{\partial s^4 \partial v_1} &= x_1^{(4)}(s) - \frac{v_1}{v_4}x_4^{(4)}(s), \\
\frac{\partial^5 H}{\partial s^4 \partial v_2} &= x_2^{(4)}(s) - \frac{v_2}{v_4}x_4^{(4)}(s), & \frac{\partial^5 H}{\partial s^4 \partial v_3} &= x_3^{(4)}(s) - \frac{v_3}{v_4}x_4^{(4)}(s).
\end{align*}
\]
Here, \( v_4 = \sqrt{v_0^2 - v_1^2 - v_2^2 - v_3^2 + 1} \neq 0 \). We now consider the following matrix:

\[
A = \begin{pmatrix}
    x_0'(s) - \frac{v_0}{v_4} x_4'(s) & x_1'(s) - \frac{v_0}{v_4} x_4'(s) & x_2'(s) - \frac{v_2}{v_4} x_4'(s) & x_3'(s) - \frac{v_3}{v_4} x_4'(s) \\
    x_0''(s) - \frac{v_0}{v_4} x_4''(s) & x_1''(s) - \frac{v_0}{v_4} x_4''(s) & x_2''(s) - \frac{v_2}{v_4} x_4''(s) & x_3''(s) - \frac{v_3}{v_4} x_4''(s) \\
    x_0'''(s) - \frac{v_0}{v_4} x_4'''(s) & x_1'''(s) - \frac{v_0}{v_4} x_4'''(s) & x_2'''(s) - \frac{v_2}{v_4} x_4'''(s) & x_3'''(s) - \frac{v_3}{v_4} x_4'''(s) \\
    x_0^{(4)}(s) - \frac{v_0}{v_4} x_4^{(4)}(s) & x_1^{(4)}(s) - \frac{v_1}{v_4} x_4^{(4)}(s) & x_2^{(4)}(s) - \frac{v_2}{v_4} x_4^{(4)}(s) & x_3^{(4)}(s) - \frac{v_3}{v_4} x_4^{(4)}(s)
\end{pmatrix}.
\]

If we put \( a_i = (x_i', x_i'', x_i''', x_i^{(4)})^t \), we have

\[
A = (a_0 - \frac{v_0}{v_4} a_4, a_1 - \frac{v_1}{v_4} a_4, a_2 - \frac{v_2}{v_4} a_4, a_3 - \frac{v_3}{v_4} a_4).
\]

Then

\[
\det A = \frac{v_0}{v_4} - \frac{v_1}{v_4} \det(a_0, a_1, a_2, a_3) + \frac{v_2}{v_4} \det(a_0, a_1, a_2, a_3) + \frac{v_3}{v_4} \det(a_0, a_1, a_2, a_4)
\]

\[
= \left( \frac{v}{v_4}, (\gamma'(s) \wedge \gamma''(s) \wedge \gamma'''(s) \wedge \gamma^{(4)}(s)) \right).
\]

Since

\[
v = \sin \theta \cos \varphi \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} n_1(s)) + \cos \theta \cos \varphi n_2(s) + \sin \varphi n_3(s),
\]

by a straightforward calculation, we have \( \gamma'(s) \wedge \gamma''(s) \wedge \gamma'''(s) \wedge \gamma^{(4)}(s) = \sqrt{\rho(s)} v \). Therefore \( \det A = \frac{\sqrt{\rho(s)}}{v_4} \neq 0 \). For other local coordinates, we can apply the arguments similar to above. This completes the proof. \( \square \)

By Proposition 4.3.1, Proposition 4.3.4 and Theorem 2.3.6, we have the following theorem.

**Theorem 4.3.5.** Let \( \gamma : I \to S^4_1 \) be a timelike Sabban curve with \( \rho(s) \neq 0 \). Then we have the following:

1. If \( h_v \) has \( A_3 \) singularity at \( s_0 \), then the germ of focal hypersurface \( FHS \) at \( (s_0, \theta_0, \varphi_0) \) is diffeomorphic to \( C \times \mathbb{R}^2 \).
2. If \( h_v \) has \( A_4 \) singularity at \( s_0 \), then the germ of focal surface \( FHS \) at \( (s_0, \theta_0, \varphi_0) \) is diffeomorphic to \( SW \times \mathbb{R} \).
3. If \( h_v \) has \( A_5 \) singularity at \( s_0 \), then the germ of focal surface \( FHS \) at \( (s_0, \theta_0, \varphi_0) \) is 45

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We consider a hyperplane \( HP(v,c) = \{ x \in \mathbb{R}_s^5 | (x,v) = c \} \), for a fixed vector \( v \in S^4_1 \) and a constant \( c \in \mathbb{R} \). Then
\[
S^3_1(v,c) = S^4_1 \cap HP(v,c)
\]
is called a \textit{3-dimensional de Sitter subspace} in \( S^4_1 \). For any fixed \( s_0 \in I \), put \( (\gamma(s_0), v) = \varepsilon \).

If we consider a function \( h_v : S^4_1 \rightarrow \mathbb{R} \) defined by \( h_v(x) = (x,v) \), then \( h_v^{-1}(\varepsilon) = S^3_1(v,\varepsilon) \) and \( h_v \circ \gamma(s) = h_v(s) \). Therefore, \( h_v(s_0) = \varepsilon \) and \( h'_v(s_0) = 0 \) if and only if \( S^3_1(v,\varepsilon) \) is tangent to \( \gamma(s) \) at \( s_0 \). We call \( S^3_1(v,\varepsilon) \) a \textit{tangent de Sitter subspace} at \( s_0 \). We remark that there are infinitely many tangent de Sitter subspaces of \( \gamma(s) \) at \( s_0 \). We say that a tangent de Sitter subspace \( S^3_1(v,\varepsilon) \) of \( \gamma(s) \) at \( s_0 \) has \textit{at least} \( k+1 \)-point contact with \( \gamma \) if \( h_v(s_0) = \varepsilon \) and \( h'_v(s_0) = \cdots = h^{(k)}_v(s_0) = 0 \).

We also say that tangent de Sitter subspace \( S^3_1(v,\varepsilon) \) of \( \gamma(s) \) at \( s_0 \) has \textit{k+1-point contact} with \( \gamma \) if \( h_v(s_0) = \varepsilon \), \( h'_v(s_0) = \cdots = h^{(k)}_v(s_0) = 0 \) and \( h^{(k+1)}_v(s_0) \neq 0 \). By Propositions 4.3.1, 4.3.3 and arguments similar to the proof of Proposition 3.1.2, we have the following propositions.

**Proposition 4.3.6.** Let \( \gamma : I \rightarrow S^4_1 \) be a timelike Sabban curve with \( \rho(s) \neq 0 \). Then the following conditions are equivalent:

1. The de Sitter evolute \( E_\gamma(s) \) is a constant vector.
2. There exist \( v \in S^4_1 \) and \( \varepsilon \in \mathbb{R} \) such that \( \gamma(I) \subset S^3_1(v,\varepsilon) \).
3. \( \sigma_3(s) \equiv 0 \).

**Proposition 4.3.7.** Let \( \gamma : I \rightarrow S^4_1 \) be a timelike Sabban curve with \( \rho(s) \neq 0 \). Then we have the following:

1. \( S^3_1(v,\varepsilon) \) is a tangent de Sitter subspace of \( \gamma(s) \) at \( s_0 \) if and only if there exist \( a, b, c, d \in \mathbb{R} \) with \( a^2 + b^2 + c^2 + d^2 = 1 \) such that \( v = a\gamma(s_0) + bn_1(s_0) + cn_2(s_0) + dn_3(s_0) \).
2. The tangent de Sitter subspace \( S^3_1(v,\varepsilon) \) has at least 3-point contact with \( \gamma(s) \) at \( s_0 \) if and only if there exist \( \theta_0 \in [0, 2\pi) \) and \( \varphi_0 \in [-\pi, \pi) \) such that
\[
v = \sin \theta_0 \cos \varphi_0 \sqrt{1 + \kappa_1} (\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \cos \theta_0 \cos \varphi_0 n_2(s_0) + \sin \varphi_0 n_3(s_0).
\]
3. The tangent de Sitter subspace \( S^3_1(v,\varepsilon) \) has at least 4-point contact with \( \gamma(s) \) at \( s_0 \) if and
only if there exist \( \theta_0 \in [0, 2\pi) \) and \( \varphi_0 \in [-\pi, \pi) \) such that
\[
v = \sin \theta_0 \cos \varphi_0 \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \cos \theta_0 \cos \varphi_0 n_2(s_0) + \sin \varphi_0 n_3(s_0),
\]
\[
\sin \theta_0 = \frac{\kappa_1 \kappa_2 \sqrt{1 + \kappa_1^2}}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}} \quad \text{and} \quad \cos \theta_0 = \frac{\kappa_1'}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}}.
\]
(4) The tangent de Sitter subspace \( S^3_0(v, \varepsilon) \) has at least 5-point contact with \( \gamma(s) \) at \( s_0 \) if and only if there exist \( \theta_0 \in [0, 2\pi) \) and \( \varphi_0 \in [-\pi, \pi) \) such that
\[
v = \sin \theta_0 \cos \varphi_0 \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \cos \theta_0 \cos \varphi_0 n_2(s_0) + \sin \varphi_0 n_3(s_0),
\]
\[
(\kappa_1'^2 \kappa_2^2 - \kappa_1'' \kappa_1 \kappa_2 + 2(\kappa_1')^2 \kappa_2 + \kappa_1 \kappa_1' \kappa_2') \cos \varphi_0 + \kappa_1 \kappa_2 \kappa_3 \sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2} \sin \varphi_0 = 0,
\]
\[
\sin \theta_0 = \frac{\kappa_1 \kappa_2 \sqrt{1 + \kappa_1^2}}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}} \quad \text{and} \quad \cos \theta_0 = \frac{\kappa_1'}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}}.
\]
(5) The tangent de Sitter subspace \( S^3_0(v, \varepsilon) \) has at least 6-point contact with \( \gamma(s) \) at \( s_0 \) if and only if there exist \( \theta_0 \in [0, 2\pi) \) and \( \varphi_0 \in [-\pi, \pi) \) such that
\[
v = \sin \theta_0 \cos \varphi_0 \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \cos \theta_0 \cos \varphi_0 n_2(s_0) + \sin \varphi_0 n_3(s_0),
\]
\[
(\kappa_1'^2 \kappa_2^2 - \kappa_1'' \kappa_1 \kappa_2 + 2(\kappa_1')^2 \kappa_2 + \kappa_1 \kappa_1' \kappa_2') \cos \varphi_0 + \kappa_1 \kappa_2 \kappa_3 \sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2} \sin \varphi_0 = 0,
\]
\[
\sin \theta_0 = \frac{\kappa_1 \kappa_2 \sqrt{1 + \kappa_1^2}}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}}, \quad \cos \theta_0 = \frac{\kappa_1'}{\sqrt{\kappa_1^2 \kappa_2^2 (1 + \kappa_1^2) + (\kappa_1')^2}} \quad \text{and} \quad \sigma_3(s_0) = 0.
\]
As a consequence, \( E_\gamma(s) \) is the locus of the polar vector \( v \in S^4_1 \) such that \( S^3_0(v, \varepsilon) \) has at least 5-point contact with \( \gamma(s) \) at \( s_0 \). We call \( S^3_0(v, \varepsilon) \) an osculating de Sitter subspace of \( \gamma(s) \) at \( s_0 \) if \( v = E_\gamma(s_0) \). As a corollary of Theorem 4.3.5, Proposition 4.3.3 and 4.3.7, we have the following theorem.

**Theorem 4.3.8.** Let \( \gamma : I \to S^4_1 \) be a timelike Sabban curve with \( \rho(s) \neq 0 \). Then we have the following:

1. If \( v_0 = FHS(s_0, \theta_0, \varphi_0) \), then the tangent de Sitter subspace \( S^3_0(v_0, \varepsilon) \) and \( \gamma(s) \) have at least 3-point contact at \( s_0 \).
2. The tangent de Sitter subspace \( S^3_0(v_0, \varepsilon) \) and \( \gamma(s) \) have 4-point contact at \( s_0 \) if and only if
there exist $\theta_0 \in [0, 2\pi)$ and $\varphi_0 \in [-\pi, \pi)$ such that

$$v = \sin \theta_0 \cos \varphi_0 \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \cos \theta_0 \cos \varphi_0 n_2(s_0) + \sin \varphi_0 n_3(s_0),$$

$$(\kappa_1^2 \kappa_2^3 - \kappa_1'' \kappa_1 \kappa_2 + 2(\kappa_1')^2 \kappa_2 + \kappa_1 \kappa_1' \kappa_2') \cos \varphi_0 + \kappa_1 \kappa_2 \kappa_3 \sqrt{\kappa_1^2 \kappa_2^3 (1 + \kappa_1^2)} + (\kappa_1')^2 \sin \varphi_0 = 0,$$

$$\sin \theta_0 = \frac{\kappa_1 \kappa_2 \sqrt{1 + \kappa_1^2}}{\sqrt{\kappa_1^2 \kappa_2^3 (1 + \kappa_1^2) + (\kappa_1')^2}}, \cos \theta_0 = \frac{\kappa_1'}{\sqrt{\kappa_1^2 \kappa_2^3 (1 + \kappa_1^2) + (\kappa_1')^2}}.$$ In this case, the germ of $FHS$ at $FHS(s_0, \theta_0, \varphi_0)$ is diffeomorphic to $C \times \mathbb{R}^2$.

(3) The osculating de Sitter subspace $S_0^3(v_0, \varepsilon)$ and $\gamma(s)$ have 5-point contact at $s_0$ if and only if there exist $\theta_0 \in [0, 2\pi)$ and $\varphi_0 \in [-\pi, \pi)$ such that

$$v = \sin \theta_0 \cos \varphi_0 \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \cos \theta_0 \cos \varphi_0 n_2(s_0) + \sin \varphi_0 n_3(s_0),$$

$$(\kappa_1^2 \kappa_2^3 - \kappa_1'' \kappa_1 \kappa_2 + 2(\kappa_1')^2 \kappa_2 + \kappa_1 \kappa_1' \kappa_2') \cos \varphi_0 + \kappa_1 \kappa_2 \kappa_3 \sqrt{\kappa_1^2 \kappa_2^3 (1 + \kappa_1^2)} + (\kappa_1')^2 \sin \varphi_0 = 0,$$

$$\sin \theta_0 = \frac{\kappa_1 \kappa_2 \sqrt{1 + \kappa_1^2}}{\sqrt{\kappa_1^2 \kappa_2^3 (1 + \kappa_1^2) + (\kappa_1')^2}}, \cos \theta_0 = \frac{\kappa_1'}{\sqrt{\kappa_1^2 \kappa_2^3 (1 + \kappa_1^2) + (\kappa_1')^2}}, \sigma(s_0) = 0 \text{ and } \sigma'(s_0) \neq 0.$$

(4) If the osculating de Sitter subspace $S_0^3(v_0, \varepsilon)$ and $\gamma(s)$ have 6-point contact at $s_0$, then the germ of $FHS$ at $FHS(s_0, \theta_0, \varphi_0)$ is diffeomorphic to $BF$.

Remark 4.3.9. We have a conjecture as follows:

The osculating de Sitter subspace $S_0^3(v_0, \varepsilon)$ and $\gamma(s)$ have 6-point contact at $s_0$ if and only if there exist $\theta_0 \in [0, 2\pi)$ and $\varphi_0 \in [-\pi, \pi)$ such that

$$v = \sin \theta_0 \cos \varphi_0 \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s_0) - \frac{1}{\kappa_1} n_1(s_0)) + \cos \theta_0 \cos \varphi_0 n_2(s_0) + \sin \varphi_0 n_3(s_0),$$

$$(\kappa_1^2 \kappa_2^3 - \kappa_1'' \kappa_1 \kappa_2 + 2(\kappa_1')^2 \kappa_2 + \kappa_1 \kappa_1' \kappa_2') \cos \varphi_0 + \kappa_1 \kappa_2 \kappa_3 \sqrt{\kappa_1^2 \kappa_2^3 (1 + \kappa_1^2)} + (\kappa_1')^2 \sin \varphi_0 = 0,$$

$$\sin \theta_0 = \frac{\kappa_1 \kappa_2 \sqrt{1 + \kappa_1^2}}{\sqrt{\kappa_1^2 \kappa_2^3 (1 + \kappa_1^2) + (\kappa_1')^2}}, \cos \theta_0 = \frac{\kappa_1'}{\sqrt{\kappa_1^2 \kappa_2^3 (1 + \kappa_1^2) + (\kappa_1')^2}}, \sigma_3(s_0) = 0 \text{ and } \sigma_3'(s_0) \neq 0.$$

4.4 Dualities for focal sets of timelike Sabban curves

Izumiya introduced the Legendrian dualities between pseudo-spheres in Minkowski space in [7]. In this section we study the Legendrian dualities of focal sets of timelike Sabban curves. We
define 1-forms \( \langle dv, w \rangle = -w_1 dv_1 + \sum_{i=2}^{n+1} w_i dv_i \) and \( \langle v, dw \rangle = -v_1 dw_1 + \sum_{i=2}^{n+1} v_i dw_i \) in \( \mathbb{R}^{n+1} \times \mathbb{R}^{n+1} \). and consider the following double fibrations:

\[
H^n(-1) \times S^n_1 \supset \Delta_1 = \{ (v, w) \mid \langle v, w \rangle = 0 \},
\]

\[
\pi_{11} : \Delta_1 \longrightarrow H^n(-1), \quad \pi_{12} : \Delta_1 \longrightarrow S^n_1,
\]

\[
\theta_{11} = \langle dv, w \rangle|_{\Delta_1}, \quad \theta_{12} = \langle v, dw \rangle|_{\Delta_1}.
\]

Here, \( \pi_{11}(v, w) = v \), \( \pi_{12}(v, w) = w \) are the canonical projections. Moreover, \( \theta_{11} = \langle dv, w \rangle|_{\Delta_1} \) and \( \theta_{12} = \langle v, dw \rangle|_{\Delta_1} \) are the restrictions of the 1-form \( \langle dv, w \rangle \) and \( \langle v, dw \rangle \) on \( \Delta_1 \). We remark that \( \theta_{11}^{-1}(0) \) and \( \theta_{12}^{-1}(0) \) define the same tangent hyperplane field over \( \Delta_1 \). In [7], the following theorem was shown:

**Theorem 4.4.1.** Under the above notation, both of \( \pi_{1i} \) (\( i = 1, 2 \)) are Legendrian fibrations and \( (\Delta_1, K) \) is a contact manifold.

If we have a Legendrian submanifold \( L \subset \Delta_1 \), then we say that \( \pi_{11}(L) \subset H^n(-1) \) and \( \pi_{12}(L) \subset S^n_1 \) are \( \Delta_1 \)-dual to each other. Since both of \( \pi_{11}^{-1}(v) = v \times S^n_{1-1}(v, 0) \) and \( \pi_{12}^{-1}(w) = H^n(-1)(0, w) \times w \) are Legendrian submanifolds of \( \Delta_1 \). We consider timelike Sabban curve \( \gamma : I \rightarrow S^n_1 \) (\( n = 2, 3, 4 \)). The de Sitter evolutes \( E^\pm_\gamma(s) \) of a timelike Sabban curve \( \gamma : I \rightarrow S^n_1 \), which is the focal set of \( \gamma(s) \). Since a timelike Sabban curve \( \gamma \) is a unit speed timelike curve, we have the hyperbolic tangent indicatrix \( t : I \rightarrow H^n(-1) \) of \( \gamma \). Then we have the following theorem:

**Theorem 4.4.2.** Let \( \gamma : I \rightarrow S^n_1 \) be a timelike Sabban curve. Then the hyperbolic tangent indicatrix \( t \) and de Sitter evolute \( E^\pm_\gamma \) are \( \Delta_1 \)-dual to each other.

**Proof.** We define a mapping \( L : I \rightarrow \Delta_1 \) by \( L(s) = (t(s), E^\pm_\gamma(s)) \). By definition, we have

\[
\frac{\partial L}{\partial s} = \left( \gamma(s) + \kappa n(s), \frac{\partial E^\pm_\gamma}{\partial s} \right).
\]

Since \( \{ \gamma, n \} \) are linearly independent, \( \partial L/\partial s \) can't be zero. This means that \( L : I \rightarrow \Delta_1 \) is an immersion, so that \( L|_I \) is an immersion. Moreover, we have \( L^*\theta_{11} = \langle dt(s), E^\pm_\gamma(s) \rangle = 0 \), so that \( L(s) \) is a Legendrian submanifold of \( \Delta_1 \). This completes the proof. \( \square \)
If we consider timelike Sabban curves in $S^3_1$ and $S^4_1$, then the focal sets of the curve $\gamma$ are de Sitter focal surfaces $FS(s, \theta)$ and de Sitter focal hypersurfaces $FHS(s, \theta, \varphi)$ respectively. Then we have the following theorems:

**Theorem 4.4.3.** Let $\gamma : I \rightarrow S^3_1$ be a timelike Sabban curve. Then the hyperbolic tangent indicatrix $t$ and de Sitter focal surface $FS(s, \theta)$ are $\Delta_1$-dual to each other.

**Proof.** We define a mapping $\mathcal{L} : I \times [0, 2\pi) \rightarrow \Delta_1$ by $\mathcal{L}(s) = (t(s), FS(s, \theta))$. By definition, we have

$$\frac{\partial \mathcal{L}}{\partial s} = \left(\gamma(s) + \kappa_1 n_1(s), \left(\frac{\kappa_1'}{\kappa_1} \frac{\cos \theta}{\sqrt{1 + \kappa_1^2}} - \frac{\kappa_2}{\kappa_1} \frac{\cos \theta}{\sqrt{1 + \kappa_1^2}}\right) - \kappa_1 n_1(s)\right) + \left(\frac{\kappa_1'}{\kappa_1^2} - \frac{\sin \theta}{\sqrt{1 + \kappa_1^2}}\right) n_2(s),$$

$$\frac{\partial \mathcal{L}}{\partial \theta} = \left(0, -\frac{\kappa_1 \sin \theta}{\sqrt{1 + \kappa_1^2}} \gamma(s) + \frac{\kappa_1' \sin \theta \cos \varphi}{\sqrt{1 + \kappa_1^2}} n_2(s) + \frac{\kappa_1' \kappa_3 \sin \theta \cos \varphi}{\kappa_1 \kappa_2} n_3(s)\right).$$

Since $\{\gamma, n_1\}$ are linearly independent and $\partial \mathcal{L}/\partial \theta \neq 0$, so $\{\partial \mathcal{L}/\partial s, \partial \mathcal{L}/\partial \theta\}$ are linearly independent. This means that $\mathcal{L} : I \times [0, 2\pi) \rightarrow \Delta_1$ is an immersion, so that $\mathcal{L}|_{I \times [0, 2\pi]}$ is an immersion. Moreover, we have

$$\mathcal{L}^* \theta_{11} = (dt(s), FS(s, \theta)) = \langle \gamma(s) + \kappa_1 n_1(s), \cos \theta \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} n_1(s)) + \sin \theta n_2(s)\rangle = 0,$$

so that $\mathcal{L}(s, \theta)$ is a Legendrian submanifold of $\Delta_1$. This completes the proof. □

**Theorem 4.4.4.** Let $\gamma : I \rightarrow S^4_1$ be a timelike Sabban curve. Then the hyperbolic tangent indicatrix $t$ and de Sitter focal hypersurface $FHS(s, \theta, \varphi)$ are $\Delta_1$-dual to each other.

**Proof.** We define a mapping $\mathcal{L} : I \times [0, 2\pi] \times [-\pi, \pi) \rightarrow \Delta_1$ by $\mathcal{L}(s) = (t(s), FHS(s, \theta, \varphi))$. By definition, we have

$$\frac{\partial \mathcal{L}}{\partial s} = \left(\gamma(s) + \kappa_1 n_1(s), \left(\frac{\kappa_1' \sin \theta \cos \varphi}{(1 + \kappa_1^2) \sqrt{1 + \kappa_1^2}} - \frac{\kappa_2 \cos \theta \cos \varphi}{(1 + \kappa_1^2) \sqrt{1 + \kappa_1^2}}\right) n_1(s) + \frac{\kappa_1' \sin \theta \cos \varphi}{(1 + \kappa_1^2) \sqrt{1 + \kappa_1^2}} \gamma(s)\right),$$

$$\frac{\partial \mathcal{L}}{\partial \theta} = \left(0, -\frac{\kappa_1 \cos \theta \cos \varphi}{\sqrt{1 + \kappa_1^2}} \gamma(s) - \frac{\cos \theta \cos \varphi}{\sqrt{1 + \kappa_1^2}} n_1(s) - \sin \theta \cos \varphi n_2(s)\right),$$

$$\frac{\partial \mathcal{L}}{\partial \varphi} = \left(0, -\frac{\kappa_1 \sin \theta \sin \varphi}{\sqrt{1 + \kappa_1^2}} \gamma(s) + \frac{\sin \theta \sin \varphi}{\sqrt{1 + \kappa_1^2}} n_1(s) - \cos \theta \sin \varphi n_2(s) + \cos \varphi n_3(s)\right).$$
Since \( \{ \gamma, n_1 \} \) are linearly independent and \( \{ \partial L / \partial \theta, \partial L / \partial \varphi \} \) are linearly independent, so \( \{ \partial L / \partial s, \partial L / \partial \theta, \partial L / \partial \varphi \} \) are linearly independent. This means that \( L : I \times [0, 2\pi) \times [-\pi, \pi) \rightarrow \Delta_1 \) is an immersion, so that \( L|_{I \times [0,2\pi) \times [-\pi,\pi)} \) is an immersion. Moreover, we have

\[
L^*\theta_{11} = \langle dt(s), FHS(s, \theta, \varphi) \rangle = \langle \gamma(s) + \kappa_1 n_1(s), \sin \theta \cos \varphi \frac{\kappa_1}{\sqrt{1 + \kappa_1^2}} (\gamma(s) - \frac{1}{\kappa_1} n_1(s)) \\
+ \cos \theta \cos \varphi n_2(s) + \sin \varphi n_3(s) \rangle = 0,
\]

so that \( L(s, \theta, \varphi) \) is a Legendrian submanifold of \( \Delta_1 \). This completes the proof. \( \square \)

References


