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The 28th Sapporo Symposium on Partial Differential Equations
Venues: Department of Mathematics, Faculty of Science, Hokkaido University
July 23, 2003 (Wednesday)
9:30-10:30
Gregory SEREGIN (Steklov Institute/Keio Univ.)
Interior regularity of \( L_3; \infty \)-solutions to the Navier-Stokes equations
11:00-12:00
Takaaki NISHIDA (Kyoto Univ.)
Heat convection problems and computer assisted proof
14:30-15:00
Akihiro SHIMOMURA (Gakushuin Univ.)
Modified wave operators for Maxwell-Schrodinger equations
15:15-15:45
Hideaki SUNAGAWA (Osaka Univ.)
Remarks on the large time asymptotics for nonlinear Klein-Gordon systems
16:00-16:30
Hirokazu NINOMIYA (Ryukoku Univ.)
Curved traveling front of Allen-Cahn equations
July 24, 2003 (Thursday)
9:30-10:30
Masahiro YAMAMOTO (Univ. Tokyo)
Uniqueness in inverse scattering problems with a single incident wave
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Shinya NISHIBATA (Tokyo Inst. Tech.)
Asymptotic behavior of spherically symmetric solutions to the compressible Navier Stokes equation with external forces
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Dening LI (West Virginia Univ.)
Conical shock waves in supersonic flow
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Yasushi TANIUCHI (Shinshu Univ.)
Remarks on global solvability of 2-D Boussinesq equations with nondecaying initial data
July 25, 2003 (Friday)
9:30-10:30
Ryuichi SUZUKI (Kokushikan Univ.)
Blow-up of solutions of quasilinear parabolic equations with localized reactions
11:00-12:00
SAKAGUCHI (Ehime Univ.)
Initial behavior of solutions of diffusion equations and symmetries of domains

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Edited by T. Ozawa, Y. Giga, S. Jimbo,
K. Tsutaya, Y. Tonegawa, G. Nakamura

Sapporo, 2003

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This volume is intended as the proceedings of Sapporo Symposium on Partial Differential Equations, held on July 23 through July 25 in 2003 at Faculty of Science, Hokkaido University.

Sapporo Symposium on PDE has been held annually to present the latest developments on PDE with a broad spectrum of interests not limited to the methods of a particular school. Professor Taira Shirota started the symposium more than 25 years ago. Professor Kōji Kubota and Professor Rentaro Agemi made a large contribution to its organization for many years.

We always thank their significant contribution to the progress of the Sapporo Symposium on PDE.

T. Ozawa, Y. Giga, S. Jimbo, K. Tsutaya, Y. Tonegawa, G. Nakamura
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The 28th Sapporo Symposium on Partial Differential
Equations
(第28回偏微分方程式論札幌シンポジウム)


2. Venues (場所)
Department of Mathematics, Faculty of Science, Hokkaido University
北海道大学大学院 理学研究科 数学教室
理学部8号館309号室 (23日24日午前)
理学部5号館大講義室 (23日24日午後, 25日)
Faculty of Science Building #8 ROOM 309 (Mornings of 23, 24)
Faculty of Science Building #5 Large Lecture Room (Afternoon of 23, 24 and July 25)
“注意：理学部8号館は数学事務室のある理学部3号館から通りをはさんで
南西側80メートルの新しい建物 (3階建)”

3. Programme (プログラム)

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Heat convection problems and computer assisted proof

12:15-13:45 Free discussion time with speakers in the coffee-tea room*

14:00-14:30 Free discussion time with speakers in the coffee-tea room*

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Modified wave operators for Maxwell-Schrödinger equations

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Remarks on the large time asymptotics for nonlinear Klein-Gordon systems

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Uniqueness in inverse scattering problems with a single incident wave
Stability and uniqueness for inverse problems for non-stationary
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16:00-16:30 山口範和 (早大・理工), Norikazu YAMAGUCHI (Waseda Univ.)
$L^q$-$L^r$ estimates of solution to the parabolic Maxwell equations
and their application to the magnetohydrodynamic equations
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Initial behavior of solutions of diffusion equations and symmetries of domains
12:00-13:00 Free discussion time with speakers in the coffee-tea room*

* Lecturers in each session are invited to stay in the coffee-tea room during
discussion time.

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Interior regularity of $L_{3,\infty}$-solutions to the Navier-Stokes equations

G. Seregin

In this talk, we are going to discuss the following result.

**Theorem 0.1** (L. Escauriaza, G. Seregin, V. Šverák) Consider two functions $v$ and $p$ defined in the space-time cylinder $Q = B \times [-1, 0]$, where $B(r) \subset \mathbb{R}^3$ stands for the ball of radius $r$ with the center at the origin and $B = B(1)$. Assume that $v$ and $p$ have the following differentiability properties:

$$v \in L_{2,\infty}(Q) \cap L_{2,\infty}(-1, 0; W^1_2(B)),$$

and satisfy the Navier-Stokes equations

$$\partial_t v + \text{div } v \otimes v - \Delta v = -\nabla p,$$

in $Q$ in the sense of distributions.

Let, in addition,

$$\|v\|_{3,\infty, Q} < +\infty.$$

Then the function $v$ is Hölder continuous in the closure of the set

$$Q(1/2) = B(1/2) \times [-1/2, 0].$$

**Remarks 0.2**

1. The $L_{3,\infty}$-case is the limit case of the so-called Ladyzhenskaya-Prodi-Serrin condition ($v \in L_{s,1}(...)$ with $\frac{3}{s} + \frac{2}{l} \leq 1$) which provides uniqueness and smoothness of solutions to the corresponding initial-boundary value problems. A local version of such kind of results was proved by Serrin for $\frac{3}{s} + \frac{2}{l} < 1$ and Struwe for $\frac{3}{s} + \frac{2}{l} = 1$.

2. The theorem stated above improves Struwe result proved under the condition that $L_{3,\infty}$-norm is sufficiently small.

3. The theorem implies that, under “reasonable” conditions, $L_{3,\infty}$-solutions to the Cauchy problem for the Navier-Stokes system are smooth.
4. Moreover, if, under "reasonable" conditions, $L_{3,\infty}$-solutions to the initial-boundary value problems for the Navier-Stokes equations develop singularities, then the corresponding singular points must be on the boundary.

The main interest of the above result comes from the fact that they seem out to be of reach of "standard methods". By those methods, we mean various conditions on (local) "smallness" of various norms of $v$ which are invariant with respect to the natural scaling

$$u(x, t) \to \lambda u(\lambda x, \lambda^2 t), \quad p(x, t) \to \lambda^2 p(\lambda x, \lambda^2 t)$$

of the equations.

We note that finiteness of a norm $||f||_{s,l}$ with $s, l < \infty$ implies "local smallness" of $f$ in this norm. This is not the case for $L_{3,\infty}$-norm (which is still invariant under the scaling). This possible "concentration effect" was the main obstacle to proving regularity. To rule out concentration, we use a new method based on the reduction of the regularity problem to a backward uniqueness problem, which is then solved by finding suitable Carleman-type inequalities. The backward uniqueness result is new and seems to be of independent interest. It can be formulated as follows.

**Proposition 0.3** Assume that we are given a function $u : (\mathbb{R}^n \setminus \overline{B}) \times ]0, 1[ \to \mathbb{R}$ which meets the conditions:

$$u \in W^{2,1}_{2,1}((B(R) \setminus \overline{B}) \times ]0, 1[), \quad \forall R > 1,$$

$$|u(x, t)| \leq e^{M|x|^2}, \quad \forall (x, t) \in (\mathbb{R}^n \setminus \overline{B}) \times ]0, 1[,$$

$$|\partial_t u - \Delta u| \leq M(|u| + |\nabla u|) \quad \text{in} \quad (\mathbb{R}^n \setminus \overline{B}) \times ]0, 1[,$$

$$u(\cdot, 1) = 0 \quad \text{in} \quad \mathbb{R}^n \setminus \overline{B}. $$

Then,

$$u = 0 \quad \text{in} \quad (\mathbb{R}^n \setminus \overline{B}) \times ]0, 1[. $$

In turn, the proof of this proposition is based on two Carleman-type inequalities. The first of them is of the form

$$\int_{\mathbb{R}^n \times ]0, 2[} h^{-2\alpha}(t) e^{-\frac{|x|^2}{4t}} \left( \frac{1}{t} |u|^2 + |\nabla u|^2 \right) dx dt \leq c_0 \int_{\mathbb{R}^n \times ]0, 2[} h^{-2\alpha}(t) e^{-\frac{|x|^2}{4t}} |\partial_t u + \Delta u|^2 dx dt.$$
It is valid for any function $u \in C_0^\infty(\mathbb{R}^n \times]0, 2[: \mathbb{R})$ and for any positive number $a$. Here, $c_0$ is an absolute positive constant and $h(t) = t e^{\frac{1}{5t^4}}$.

The second inequalities is in a sense anisotropic:

$$
\int_{(\mathbb{R}^n_t + \varepsilon_n) \times [0,1]} t^2 e^{2\phi(x,t)} \left( \frac{|u|^2}{t^2} + \frac{|\nabla u|^2}{t} \right) \, dx \, dt \\
\leq c_\varepsilon \int_{(\mathbb{R}^n_t + \varepsilon_n) \times [0,1]} t^2 e^{2\phi(x,t)} |\partial_t u + \Delta u|^2 \, dx \, dt.
$$

Here

$$\phi = \phi^{(1)} + \phi^{(2)},$$

where $\phi^{(1)}(x,t) = -\frac{|x|^2}{8t}$ and $\phi^{(2)}(x,t) = a(1-t) \frac{|x|^2}{t^2}$, $x' = (x_1, x_2, \ldots, x_{n-1})$ so that $x = (x', x_n)$, and $e_n = (0, 0, \ldots, 0, 1)$, $c_\varepsilon = c_\varepsilon(\alpha)$ is a positive constant and $\alpha \in ]1/2, 1[$ is fixed. This Carleman-type inequality holds for any function $u \in C_0^\infty((\mathbb{R}^n_t + \varepsilon_n) \times [0,1]; \mathbb{R})$ and for any number $a > a_0(\alpha)$.

Our methods can be probably easily adopted to other parabolic problems with critical non-linearities. In fact, one could speculate that the general idea of the approach might be applicable to an even larger class of interesting equations with critical non-linearities, such as non-linear Schrödinger equations or non-linear wave equations. However, the local regularity issues arising in these cases would be slightly harder than in the parabolic case.
Heat Convection Problems and Computer Assisted Proofs

Takaaki NISHIDA
Kyoto University

We consider the Rayleigh-Bénard problem for the heat convection using the Boussinesq equations for the velocity, pressure and temperature in the dimensionless form:

\[
\frac{1}{\mathcal{P}} \left( \frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) + \nabla p = \Delta \mathbf{u} - \rho(T) \nabla z, \quad \nabla \cdot \mathbf{u} = 0, \quad \frac{\partial T}{\partial t} + \mathbf{u} \cdot \nabla T = \Delta T
\]

in the horizontal domain \( \{ x \in \mathbb{R}, \ y \in \mathbb{R}, \ 0 < z < 1 \} \), where \( \rho(T) = G - \mathcal{R}T \) is assumed for the density of the fluid, \( \mathcal{P} \) is the Prandtl number and \( \mathcal{R} \) is the Rayleigh number.

When the temperature \( T = 1 \) is given on the lower boundary and \( T = 0 \) on the upper boundary, the equilibrium state is the purely heat conduction solution, which exists for all parameter values \( \mathcal{P} > 0, \mathcal{R} > 0 \):

\[
\mathbf{u} = 0, \quad T = 1 - z, \quad \rho = G - \mathcal{R}(1 - z), \quad p = G(1 - z) - \mathcal{R}(1 - z - \frac{z^2}{2}) + p_0.
\]

We first assume the stress free boundary condition for the velocity on both boundaries \( (z = 0, 1) \) and the Dirichlet boundary condition for the temperature.

We will consider the bifurcation problems from this equilibrium state under the assumption that all perturbations are periodic in the horizontal direction, especially with the periodicity \( 0 \leq x \leq 2/a, \ 0 \leq y \leq 2/b \). The system for the perturbation to the equilibrium state is given by

\[
\frac{1}{\mathcal{P}} \left( \frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) + \nabla p = \Delta \mathbf{u} + \mathcal{R}\theta \nabla z, \quad \nabla \cdot \mathbf{u} = 0, \quad \frac{\partial \theta}{\partial t} + \mathbf{u} \cdot \nabla \theta = \Delta \theta + w.
\]

Also we assume usual even- or odd-ness for the unknown functions to avoid the multiplicity of the eigenvalue. Then for example the temperature has the representation:

\[
\theta(t,x,y,z) = \sum_{l,m,n} \theta_{lmn}(t) \cos(l \pi x) \cos(m \pi y) \sin(n \pi z).
\]

The other unknowns have similar expressions.
The linearized system is self-adjoint and has real eigenvalues. Therefore when the biggest eigenvalue becomes \( \lambda = 0 \) at a critical Rayleigh number for fixed \( a \) and \( b \) and it is "simple", the usual stationary bifurcation theory can be applied and the stationary bifurcation occurs at the critical Rayleigh number.

However if we choose \( a = 1/2\sqrt{2} \) and the aspect ratio \( b/a = \sqrt{3} \), which is one of the most interesting case, the critical Rayleigh number \( R_c = 6.75 \times \pi^4 \) and the biggest eigenvalue \( \lambda = 0 \) has a two-dimensional eigenspace. One eigenfunction corresponds to the roll type solution, the other eigenfunction does to the rectangle type solution, and a linear combination of them does to the hexagonal type solution. Thus we can not apply the usual bifurcation theory. However if we restrict the function space for solutions to the subspace such that it corresponds to any one type of those eigenfunctions, we can apply the local bifurcation theory for the simple eigenvalue in the corresponding subspace and can obtain each type of solution respectively in a neighbourhood of the same bifurcation point.

Here we will obtain roll type solutions, rectangular cell and hexagonal cell solutions on the extended bifurcation curves numerically to have a better global bifurcation diagram for the full system. Then we consider the stability of them in the original function space as the time evolution problem, and propose an approach to prove the existence of those solutions and secondary bifurcation points as a computer assisted proof.

Then we consider similar problems with another boundary condition that the upper surface is stress free and the bottom surface is non-slip for the velocity.

T. Ikeda, H. Yoshihara and T. Nishida
"Pattern formation of heat convection problems",

Y. Watanabe, N. Yamamoto, M. T. Nakao and T. Nishida
"A numerical verification of bifurcated solutions for the heat convection problems",
MODIFIED WAVE OPERATORS FOR MAXWELL-SCHRÖDINGER EQUATIONS

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1. Introduction

We study the scattering theory for the Maxwell-Schrödinger equations in three space dimensions ([7]). We consider those equations under two gauge conditions, that is, the Coulomb gauge and the Lorentz one. In this talk, we construct modified wave operators to the Maxwell-Schrödinger equations with above two gauge conditions for small scattered states without any restrictions on the support of the Fourier transform of them.

The Maxwell-Schrödinger equation in the Coulomb gauge is as follows:

\[ \begin{cases}
  i \partial_t u = -\frac{1}{2} (\nabla - iA)^2 u + g(|u|^2)u, \\
  \Box A = \mathcal{P}(\text{Im}(\nabla - iA)\nu)), \\
  \nabla \cdot A = 0,
\end{cases} \tag{MS-C} \]

where

\[ g(|u|^2) = \frac{1}{4\pi} \left( \frac{1}{|x|} \ast |u|^2 \right) u = (-\Delta)^{-1/2} |u|^2, \]

\[ \Box \equiv \partial_t^2 - \Delta, \]

\[ \mathcal{P} \equiv 1 - \nabla \Delta^{-1} \nabla \cdot. \]

Here \( u \) and \( A \) are complex and \( \mathbb{R}^3 \)-valued unknown functions of \((t,x) \in \mathbb{R} \times \mathbb{R}^3\), respectively. The last equation in the system (MS-C) is called the Coulomb gauge condition.

The Maxwell-Schrödinger equation in the Lorentz gauge is as follows:

\[ \begin{cases}
  i \partial_t u = -\frac{1}{2} (\nabla - iA)^2 u + \phi u, \\
  \Box \phi = |u|^2, \\
  \Box A = \text{Im}(\bar{u}(\nabla - iA)u), \\
  \partial_t \phi + \nabla \cdot A = 0.
\end{cases} \tag{MS-L} \]

Here \( u, \phi \) and \( A \) are complex, real and \( \mathbb{R}^3 \)-valued unknown functions of \((t,x) \in \mathbb{R} \times \mathbb{R}^3\), respectively. The last equation in the system (MS-L) is called the Lorentz gauge condition.

According to linear scattering theory, it seems that the equations (MS-C) and (MS-L) in three space dimensions belongs to the borderline between the short range case and the long range one, because the solution of the three dimensional free wave equation decays like \( t^{-1} \) in \( L^\infty \) as \( t \to \infty \). (The two dimensional Klein-Gordon-Schrödinger equation and the three dimensional Wave-Schrödinger equation also belong to the same case). There are some results of the long range scattering for the coupled systems of the Schrödinger equations and the second order hyperbolic
ones, that is, the Klein-Gordon-Schrödinger equation in two space dimensions in [4, 6], to the Wave-Schrödinger equation in three space dimensions in [1, 3, 5] and to the Maxwell-Schrödinger equation under the Coulomb gauge condition in three space dimensions in [2, 9]. In [1, 4, 9], the restriction on the support of the Fourier transform of the scattered state $\phi$ of the Schrödinger part is assumed, and in [2], the vanishing scattered states for the Maxwell part are considered. (Note that in Ginibre and Velo [1, 2], no size restriction on for data is assumed).

Recently, the existence of wave operators for the two dimensional Klein-Gordon-Schrödinger equation and the three dimensional Wave-Schrödinger equation with the Yukawa type interaction have been proved in [6] and [5], respectively, for small scattered states without any restrictions on the support of the Fourier transform of them. Furthermore combining idea of [1] with that of [5], Ginibre and Velo [3] have proved the existence of modified wave operators for the three dimensional Wave-Schrödinger equation with restrictions on neither size of the scattered states nor the support of the Fourier transform of them.

In this talk, we construct modified wave operators to the equations (MS-C) and (MS-L) in three space dimensions for small scattered states with no restriction on the support of the Fourier transform of them. This talk is mainly based on [7].

Notations. For $s, m \in \mathbb{R}$, we introduce the weighted Sobolev spaces $H^{s, m}$ corresponding to the Lebesgue space $L^2$:

$$H^{s, m} = \{ \psi \in \mathcal{S}': \| \psi \|_{H^{s, m}} = \|(1 + |x|^2)^{m/2}(1 - \Delta)^{s/2}\psi\|_{L^2} < \infty \}.$$

We also denote $H^{s, 0}$ by $H^s$. For $1 \leq p \leq \infty$ and a positive integer $k$, we define the Sobolev space $W^k_p$ corresponding to the Lebesgue space $L^p$ by

$$W^k_p = \left\{ \psi \in L^p : \| \psi \|_{W^k_p} = \sum_{|\alpha| \leq k} \| \partial^\alpha \psi \|_{L^p} < \infty \right\}.$$

Note that for a positive integer $k$, $H^k = W^k_2$ and the norms $\| \cdot \|_{H^k}$ and $\| \cdot \|_{W^k_2}$ are equivalent. For $s > 0$, we define the homogeneous Sobolev spaces $H^s$ by the completion of $\mathcal{S}$ with respect to the norm $\| w \|_{H^s} = \| (-\Delta)^{s/2} w \|_{L^2}$.

We set for $t \in \mathbb{R}$,

$$U(t) \equiv e^{it\Delta}, \quad \omega \equiv (-\Delta)^{1/2}.$$

2. Main Results

We state our result for the case of the Coulomb gauge.

Let $(u^C_+, A^C_+, \tilde{A}^C_+)$ be given scattered states, where $u^C_+$ is complex valued, and $A^C_+$ and $\tilde{A}^C_+$ are $\mathbb{R}^3$-valued. Hereafter we assume that $A^C_+$ and $\tilde{A}^C_+$ satisfy the divergence free condition, that is,

$$\nabla \cdot A^C_+ = \nabla \cdot \tilde{A}^C_+ = 0.$$

Our result for the Coulomb gauge case is as follows.

**Theorem 2.1.** Let $u^C_+ \in H^{6, 7}$, $A^C_+ \in H^{5, 3}$, $\tilde{A}^C_+ \in H^{1, 3}$ and

$$\delta \equiv \| u^C_+ \|_{H^{6, 7}} + \| A^C_+ \|_{H^{5, 3}} + \| \tilde{A}^C_+ \|_{H^{1, 3}}$$

(2.1)
be sufficiently small. Assume that \( A^C_0 \) and \( \hat{A}^C_0 \) satisfy the condition (2). Then there exists a unique solution \((u, A)\) of the equation (MS-C) satisfying

\[
  u \in \bigcap_{k=0}^{1} C^k([0, \infty); H^{3-2k}),
\]

\[
  A \in C([0, \infty); H^1 \cap H^3), \quad \partial_t A \in \bigcap_{k=0}^{2} C^k([0, \infty); H^{2-k}),
\]

\[
  \sup_{t \geq 2} \left[ \frac{t}{(\log t)^2} \left\{ \sum_{j=0}^{1} \| \partial_t^j u(t) - \partial_t^j u^C_0(t) \|_{H^{3-2j}} + \left( \int_{t}^{\infty} \| u(s) - u^C_0(s) \|_{W_{3/2}^{3/2}} \, ds \right)^{3/8} \right\} \right] < \infty,
\]

\[
  \sup_{t \geq 2} \left[ \frac{t^{3/2}}{(\log t)^2} \left( \| A(t) - A^C_0(t) - A^C_1(t) \|_{H^1 \cap H^3} \right)^3 \right] < \infty.
\]

Here

\[
  A^C_0(t, x) \equiv ((\cos \omega t) A^C_0)(x) + ((\omega^{-1} \sin \omega t) \hat{A}^C_0)(x),
\]

\( A^C_1 \) is the solution of the following linear equation:

\[
  \partial_t^2 A^C_1 - \Delta A^C_1 = \frac{1}{t^3} P \left[ \frac{x}{t} \hat{u}^C_0 \left( \frac{x}{t} \right) \right] z(t)^2,
\]

\[
  \| A^C_1(t) \|_{H^1 \cap H^3} + \| \partial_t A^C_1(t) \|_{H^3} \to 0,
\]

as \( t \to +\infty \), where \( z \in C^\infty(\mathbb{R}_t; \mathbb{R}) \) such that \( z(t) = 0 \) for \( |t| \leq 1/2 \), \( z(t) = 1 \) for \( |t| \geq 1 \), and we define

\[
  u^C_0(t, x) = (U(t)e^{-\frac{3z}{2t}e^{-tS^C(t,-1)x}u^C_0}(x))
\]

\[
  = \left( \frac{1}{(it)^{3/2}} \hat{u}^C_0 \left( \frac{x}{t} \right) e^{i|x|^2/2 - tS^C(t, \xi)} \right),
\]

where

\[
  S^C(t, x) \equiv ((g(|\hat{u}^C|_2^2))(x) \log t - x \cdot \int_1^t \hat{A}^C_1(s, sx) \, ds,
\]

for \( t \geq 1 \) and \( x \in \mathbb{R}^3 \).

A similar result holds for negative time.

Let

\[
  \mathcal{V}^C = \{(u^C_0, A^C_0, \hat{A}^C_0), \| u^C_0 \|_{H^{3.7}} + \| A^C_0 \|_{H^{3.3}} + \| \hat{A}^C_0 \|_{H^{3.3}} \leq \delta, \quad \nabla \cdot A^C_0 = \nabla \cdot \hat{A}^C_0 = 0\},
\]

where \( \delta \) is defined by (2.1).

The following corollary is an immediate consequence of Theorem 2.1.

**Corollary 2.1.** For the equation (MS-C), the modified wave operator \( W^C_+ : (u^C_+, A^C_+, \hat{A}^C_+) \mapsto (u(0), A(0), \partial_t A(0)) \) is well-defined on \( \mathcal{V}^C \), where \((u, A)\) is the solution to the equation (MS-C) obtained in Theorem 2.1. Similarly the modified wave operator \( W^C_- \) for negative time is also well-defined on \( \mathcal{V}^C \).
Next we state our result for the case of the Lorentz gauge.

Let \((u^L_+, \phi^L_+, \phi^L_-, A^L_+, A^L_-)\) be given scattered states, where \(u^L_+\) is complex valued, \(\phi^L_+\) and \(\phi^L_-\) are real valued, and \(A^L_+\) and \(A^L_-\) are \(\mathbb{R}^3\)-valued. Hereafter we assume that \(\phi^L_+, \phi^L_-, A^L_+\) and \(A^L_-\) satisfy the condition
\[
\begin{cases}
\phi^L_+ + \nabla \cdot A^L_+ = 0, \\
\Delta \phi^L_- + \nabla \cdot A^L_- = 0.
\end{cases}
\]

Our result for the Lorentz gauge case is as follows.

**Theorem 2.2.** Let \(u^L_+ \in H^{6,4}, \phi^L_+ \in H^{5,2}, \phi^L_- \in H^{4,2}, A^L_+ \in H^{3,3}, \hat{A}^L_+ \in H^{4,3}, \omega^{-1} A^L_- \in H^{0,2}, \omega^{-1} \hat{A}^L_- \in H^{0,2}\) and
\[
\eta = \|u^L_+\|_{H^{6,4}} + \|\phi^L_+\|_{H^{5,2}} + \|\phi^L_-\|_{H^{4,2}} + \|A^L_+\|_{H^{3,3}} + \|\hat{A}^L_+\|_{H^{4,3}} + \|\omega^{-1} A^L_-\|_{H^{0,2}} + \|\omega^{-1} \hat{A}^L_-\|_{H^{0,2}}
\]
be sufficiently small. Assume that \(\phi^L_+, \phi^L_-, A^L_+\) and \(A^L_-\) satisfy the condition (2). Then there exists a unique solution \((u, \phi, A)\) of the equation (MS-L) satisfying
\[
u \in \bigcap_{k=0}^{1} C^k([0, \infty); H^{3-2k}),
\]
\[
\phi \in C([0, \infty); \hat{H}^1 \cap \hat{H}^3), \quad \partial_t \phi \in \bigcap_{k=0}^{2} C^k([0, \infty); H^{2-k}),
\]
\[
A \in C([0, \infty); \hat{H}^1 \cap \hat{H}^3), \quad \partial_t A \in \bigcap_{k=0}^{2} C^k([0, \infty); H^{2-k}),
\]
\[
\sup_{t \geq 2} \left[ \frac{t}{(\log t)^2} \left\{ \sum_{j=0}^{1} \|\partial_t^j u(t) - \partial_t^j u^L_+(t)\|_{H^{3-2j}} + \left( \int_{t}^{\infty} \|u(s) - u^L_+(s)\|^3_{W^{3/2}_4} ds \right)^{3/8} \right\} \right] < \infty,
\]
\[
\sup_{t \geq 2} \left[ \frac{t^{3/2}}{(\log t)^2} \left( \|\phi(t) - \phi^L_+(t)\|_{H^{1} \cap H^{2}} + \sum_{j=1}^{2} \|\partial_t^j \phi(t) - \partial_t^j \phi^L_+(t) - \partial_t^j \phi^L_-(t)\|_{H^{3-j}} \right) + \frac{t}{(\log t)^2} \left( \|\phi(t) - \phi^L_+(t) - \phi^L_-(t)\|_{H^{3}} + \sum_{j=1}^{3} \|\partial_t^j \phi(t) - \partial_t^j \phi^L_+(t) - \partial_t^j \phi^L_-(t)\|_{H^{3-j}} \right) \right] < \infty.
\]
\[
\sup_{t \geq 2} \left[ \frac{t^{3/2}}{(\log t)^2} \left( \|A(t) - A^L_+(t)\|_{H^{1} \cap H^{2}} + \sum_{j=1}^{2} \|\partial_t^j A(t) - \partial_t^j A^L_+(t) - \partial_t^j A^L_-(t)\|_{H^{2-j}} \right) + \frac{t}{(\log t)^2} \left( \|A(t) - A^L_+(t) - A^L_-(t)\|_{H^{3}} + \sum_{j=1}^{3} \|\partial_t^j A(t) - \partial_t^j A^L_+(t) - \partial_t^j A^L_-(t)\|_{H^{3-j}} \right) \right] < \infty.
\]
Here
\[ \phi_0^L(t, x) = ((\cos \omega t) \phi_{+}^L(x) + (\omega^{-1} \sin \omega t) \phi_{-}^L(x)), \]
\[ A_0^L(t, x) = ((\cos \omega t) A_{+}^L(x) + (\omega^{-1} \sin \omega t) A_{-}^L(x)). \]
\( \phi_{+}^L \) and \( A_{+}^L \) are the solutions of the following final value problems of the linear equations:
\[
\partial_t^2 \phi_{+}^L - \Delta \phi_{+}^L = \frac{1}{c^2} \frac{1}{t} u_+^L \left( \frac{x}{t} \right) z(t)^2,
\]
\[
\| \phi_{+}^L(t) \|_{H^{1.5} \cap H^3} + \| \partial_t \phi_{+}^L(t) \|_{H^2} \to 0, \quad t \to +\infty,
\]
and
\[
\partial_t^2 A_{+}^L - \Delta A_{+}^L = \frac{x}{c^2} \frac{1}{t} u_+^L \left( \frac{x}{t} \right) z(t)^2,
\]
\[
\| A_{+}^L(t) \|_{H^{1.5} \cap H^3} + \| \partial_t A_{+}^L(t) \|_{H^2} \to 0, \quad t \to +\infty,
\]
respectively, where \( z \in C^\infty(\mathbb{R}_{t} \times \mathbb{R}) \) such that \( z(t) = 0 \) for \( |t| \leq 1/2 \), \( z(t) = 1 \) for \( |t| \geq 1 \), and we define
\[
u^L_B(t, x) = (U(t) e^{-\frac{|u|^2}{2}} e^{-iS^L(t, -i\nabla)} u^L_+)(x),
\]
where
\[
S^L(t, x) = \int_0^t (\phi_{+}^L(s, sx) - x \cdot A_{+}^L(s, sx)) ds,
\]
for \( t \geq 1 \) and \( x \in \mathbb{R}^3 \).
A similar result holds for negative time.

Let \( \mathcal{V}^L \equiv \{ (u_+, \phi_{+}^L, \phi_{-}^L, A_{+}^L, A_{-}^L) \}; \)
\[
\| u_+^L \|_{H^{1.5} \cap H^3} + \| \phi_{+}^L \|_{H^{1.5} \cap H^3} + \| \phi_{+}^L \|_{H^{1.5} \cap H^3} + \| \phi_{+}^L \|_{H^{1.5} \cap H^3} + \| \phi_{+}^L \|_{H^{1.5} \cap H^3} + \| \phi_{+}^L \|_{H^{1.5} \cap H^3} + \| \phi_{+}^L \|_{H^{1.5} \cap H^3} \leq \eta,
\]
\[
\phi_{+}^L + \nabla \cdot A_{+}^L = 0, \quad \Delta \phi_{+}^L + \nabla \cdot A_{+}^L = 0,
\]
where \( \eta \) is defined by (2.2).

The following corollary is an immediate consequence of Theorem 2.2.

**Corollary 2.2.** For the equation (MS-L), the modified wave operator
\[ W^L_B : (u_+, \phi_{+}^L, \phi_{-}^L, A_{+}^L, A_{-}^L) \mapsto (u(0,0), \phi(0,0), A(0,0), \partial_t A(0)) \] is well-defined on \( \mathcal{V}^L \), where \( (u, \phi, A) \) is the solution to the equation (MS-C) obtained in Theorem 2.2. Similarly the modified wave operator \( W^L_B \) for negative time is also well-defined on \( \mathcal{V}^L \).

### 3. Idea of Proof

Our main idea of proof is as follows. We begin with the equation (MS-C), that is, the Coulomb gauge case. First we determine an asymptotic profile for the Maxwell part \( A_{+}^C + A_{-}^C \), where \( A_{+}^C \) is the free wave solution and \( A_{-}^C \) is a suitable second correction term of the asymptotic profile. Secondly, we determine the asymptotic profile \( u^C_{+} \) for the Schrödinger component. Since the time decay estimate of \( A_{+}^C \) is not sufficient to prove the existence of ordinary wave operators, that is, the long range effect \((A_{+}^C \cdot (x/t) - g(|u^C_{+}|^2)) u^C_{+} \) appears, we introduce the modified free dynamics \( u^C_{+} \) of the Dollard type for the Schrödinger equation such that \( \int (i\partial_t + \frac{3}{2} \Delta) u^C_{+} + (A_{+}^C \cdot (x/t) - g(|u^C_{+}|^2)) u^C_{+} \) decays faster than \((A_{+}^C \cdot (x/t) - g(|u^C_{+}|^2)) u^C_{+} \) by
using the method of phase correction. On the other hand, another effect \( A_0^C \cdot (x/t)u_0^C \) appears. In general, this decays slowly as \( t \to \infty \) and brings difficulty. Furthermore, since all the derivatives with respect to \( x \) of the function \((x/t) \cdot A_0^C\) decay as fast as itself, we can not apply the method of phase correction to \((x/t) \cdot A_0^C u_0^C\). Fortunately in the Coulomb gauge case \( A_0^C \cdot (x/t)u_0^C \) decays faster than in general case, since \( \Box A_0^C = 0 \) and \( \nabla \cdot A_0^C = 0 \) imply \( \Box (x \cdot A_0^C) = 0 \), that is, \( x \cdot A_0^C \) is also a solution for the free wave equation under the Coulomb gauge condition.

We next explain idea of the proof for the equation (MS-L), that is, the Lorentz gauge case. As in the case of the Coulomb gauge, we first determine an asymptotic profile for the Maxwell part \((\phi_0^L + \phi_1^L, A_0^L + A_1^L)\), where \((\phi_0^L, A_0^L)\) are the free wave solution and \((\phi_1^L, A_1^L)\) is a suitable second correction term of the asymptotic profile. We construct a modified free profile \( u_p^L \) of the Dollard type by the method of phase correction in order to overcome difficulty from the long range effect \( u_p^L(A_1^L \cdot (x/t) - \phi_1^L) \), which appears later, as in the case of Coulomb gauge. \( u_p^L \) is a principal term of the asymptotic profile for the Schrödinger component. Finally, we note that since all the derivatives with respect to \( x \) of the function \( \nabla \cdot A_0^C \) decay as fast as itself, we can not apply the method of phase correction to the slowly decaying term \((i/2)\nabla \cdot A_0^C u_p^L\) which appears later. To overcome this difficulty, we construct a suitable second correction term \( u_p^L \) of the asymptotic profile for the Schrödinger part such that \((i\hbar + \frac{1}{2}\Delta)u_p^L - (i/2)\nabla \cdot A_0^C u_p^L \) decays faster than \((i/2)\nabla \cdot A_0^C u_p^L \) so that the Cook-Kuroda method is applicable. This method is also used in [3, 5, 6, 8].

REFERENCES

Remarks on the large time asymptotics for nonlinear Klein-Gordon systems

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We consider the Cauchy problem for

\[
(\Box + m^2)u = F(v), \quad t > 0, \ x \in \mathbb{R}
\]
\[
(\Box + \mu^2)v = G(u), \quad t > 0, \ x \in \mathbb{R}
\]

with sufficiently small, smooth, compactly-supported initial data. Here \(\Box = \partial_t^2 - \partial_x^2\), \(m, \mu\) are positive constants, \(F, G\) are smooth functions of unknowns and they are cubic nonlinear terms in the sense that

\[
|F(w)| + |G(w)| \leq C|w|^3 \quad \text{if} \quad |w| \leq \varsigma
\]

for some constants \(C\) and \(\varsigma > 0\). Though it is possible to consider much more general situations (including derivative nonlinear or quasi-linear cases), we do not go into such directions for the sake of simplicity.

Recently, much efforts are made for study of the large time behavior of solutions to the Cauchy problem for the systems of critical nonlinear Klein-Gordon equations with possibly different masses (see e.g. [14], [11], [12], [3], [4]). It is known that if \((m - \mu)(m - 3\mu)(3m - \mu) \neq 0\), the Cauchy problem (1) admits a unique global classical solution which tends to a free solution as \(t \to \infty\). On the other hand, the case \((m - \mu)(m - 3\mu)(3m - \mu) = 0\) turns out to be more delicate and the previous works leave the problem open except a few partial results. (The scalar case has been extensively studied by Delort [2], after partial results [9], [7], [10], [5], [1] etc. See also the remark after Theorem 1.)

In this talk, we concentrate our attention to the following example:

\[
\begin{align*}
(\Box + m^2)u &= \alpha v^4, & t > 0, \ x \in \mathbb{R}, \\
(\Box + \mu^2)v &= \beta u^3, \\
(u, \partial_t u, v, \partial_t v) \big|_{t=0} &= (\varepsilon u_0, \varepsilon u_1, \varepsilon v_0, \varepsilon v_1), & x \in \mathbb{R},
\end{align*}
\]

where \(\alpha, \beta \in \mathbb{R}, \varepsilon > 0\) is a small parameter, and \(u_0, u_1, v_0, v_1 \in C_0^\infty(\mathbb{R})\). Our purpose is to show that the amplitude of \(v\) in (2) is modulated in the logarithmic
order when \( \mu = m \) or \( \mu = 3m \), whereas, when \( \mu \neq m, \mu \neq 3m \), the influence of nonlinearity disappears eventually and \( v \) behaves like a free solution as \( t \to \infty \). More precisely,

**Theorem 1** For any \( u_0, u_1, v_0, v_1 \in C_0^\infty(\mathbb{R}) \), there exists \( \varepsilon_0 > 0 \) such that (2) admits a unique global classical solution if \( \varepsilon \in ]0, \varepsilon_0] \). Moreover, the following asymptotics is valid as \( t \to \infty \), uniformly with respect to \( x \in \mathbb{R} \):

\[
\begin{align*}
  u(t, x) &= \Re \left[ \frac{e^{im(t^2 - |x|^2)^{1/2}}}{m \sqrt{t}} a(x/t) \right] + O(t^{-1+\delta}), \\
  v(t, x) &= \Re \left[ \frac{e^{im(t^2 - |x|^2)^{1/2}}}{\mu \sqrt{t}} \left\{ A(x/t) \log t + b(x/t) \right\} \right] + O(t^{-1+\delta}).
\end{align*}
\]

Here \((\cdot)_+\) stands for \( \max\{\cdot, 0\} \), \( i = \sqrt{-1} \), \( \delta \) is an arbitrary small positive number, \( a(y), b(y) \) are \( \mathbb{C} \)-valued smooth functions which vanish when \( |y| \geq 1 \), and \( A(y) \) is given by

\[
A(y) = \begin{cases} 
\frac{\beta}{i8m^3} (1 - |y|^2)^{1/2} a(y)^3 & \text{if } \mu = 3m, \\
\frac{3\beta}{i8m^3} (1 - |y|^2)^{1/2} |a(y)|^2 a(y) & \text{if } \mu = m, \\
0 & \text{if } \mu \neq 3m, \mu \neq m.
\end{cases}
\]

**Remark** It is interesting to compare this result with the corresponding one to the scalar case

\[(\Box + 1)w = \beta w^3, \quad t > 0, \ x \in \mathbb{R}. \quad (3)\]

According to [2], \( w \) has the following asymptotics:

\[
w(t, x) = \Re \left[ \frac{1}{\sqrt{t}} e^{i[(t^2 - |x|^2)^{1/2} + \psi(x/t) \log t]} a(x/t) \right] + O(t^{-1+\delta}), \ t \to \infty
\]

with

\[
\psi(y) = -\frac{3\beta}{8} (1 - |y|^2)^{1/2} |a(y)|^2.
\]

Roughly speaking, this shows that the long range character of nonlinearity appears at the level of the phase of oscillation of the solution for the scalar equation (3), while our main result claims that the long range character appears at the level of the amplitude of the solution for the system (2).
The same proof is available for a bit more general systems, such as
\[
\begin{align*}
(\Box + m_1^2)u_1 &= F_1(u, \partial u), \\
(\Box + m_2^2)u_2 &= F_2(u, \partial u), \\
(\Box + m_3^2)u_3 &= F_3(u, \partial u), \\
(\Box + m_4^2)u_4 &= \gamma u_1 u_2 u_3 + F_4(u, \partial u),
\end{align*}
\tag{4}
\]
with the initial data
\[
(u_j, \partial_t u_j) \big|_{t=0} = (\varepsilon u_{0j}, \varepsilon u_{1j}), \quad j = 1, 2, 3, 4.
\tag{5}
\]
Here \( u = (u_j)_{1 \leq j \leq 4}, \partial = (\partial_\nu, \partial_\kappa), \gamma \in \mathbb{R} \) and \( F_j(u, \partial u) = O(|u|^4 + |\partial u|^4) \) \((1 \leq j \leq 4)\). When we put
\[
\Lambda := \left\{ (\lambda_1, \lambda_2, \lambda_3) \in \{ \pm 1 \}^3 \right\}, \quad m_4 = \lambda_1 m_1 + \lambda_2 m_2 + \lambda_3 m_3,
\]
the corresponding result to Theorem 1 is stated as follows:

**Theorem 2** For any \( u_{0j}, u_{1j} \in C_0^\infty(\mathbb{R}) \), there exists \( \varepsilon_0 > 0 \) such that (4)–(5) admits a unique global classical solution if \( \varepsilon \in [0, \varepsilon_0) \). Moreover, the following asymptotics is valid as \( t \to \infty \), uniformly with respect to \( x \in \mathbb{R} \):
\[
\begin{align*}
 u_j(t, x) &= \text{Re} \left[ \frac{e^{im_j(t^2 - |x|^2)^{1/2} i\gamma}}{m_j \sqrt{t}} a_j(x/t) \right] + \mathcal{O} \left( t^{-1+\delta} \right), \quad j = 1, 2, 3, \\
u_4(t, x) &= \text{Re} \left[ \frac{e^{im_4(t^2 - |x|^2)^{1/2} i\gamma}}{m_4 \sqrt{t}} \left\{ A(x/t) \log t + a_4(x/t) \right\} \right] + \mathcal{O} \left( t^{-1+\delta} \right).
\end{align*}
\]
Here, \( \delta \) is an arbitrary small positive number, \( a_j \ (j = 1, 2, 3) \) are \( \mathbb{C} \)-valued smooth functions which vanish when \( |y| \geq 1 \), and \( A(y) \) is given by
\[
A(y) = \begin{cases}
\gamma \sum_{(\lambda_1, \lambda_2, \lambda_3) \in \Lambda} a_1^{(\lambda_1)}(y) a_2^{(\lambda_2)}(y) a_3^{(\lambda_3)}(y) & \text{if } \Lambda \neq \emptyset, \\
0 & \text{if } \Lambda = \emptyset,
\end{cases}
\]
where \( a_j^{(+1)}(y) = a_j(y), \quad a_j^{(-1)}(y) = a_j(y) \).

**Remark** We can also show the analogous result for two-dimensional case, such as
\[
\begin{align*}
(\Box + m^2)v_1 &= \alpha v_2^3, \\
(\Box + \mu^2)v_2 &= \beta v_1^2,
\end{align*}
\tag{6}
\]

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where $\alpha, \beta \in \mathbb{R}$, or

\[
\begin{cases}
(\Box + m_1^2)u_1 = F_1(u, \partial u), \\
(\Box + m_2^2)u_2 = F_2(u, \partial u), \\
(\Box + m_3^2)u_3 = \gamma u_1 u_2 + F_3(u, \partial u),
\end{cases} \quad t > 0, \ x \in \mathbb{R}^2, \tag{7}
\]

where $u = (u_1, u_2, u_3)$, $\partial = (\partial_t, \partial_{x_1}, \partial_{x_2})$, $\gamma \in \mathbb{R}$ and $F_j(u, \partial u) = O(|u|^3 + |\partial u|^3)$. For the solution $v_2$ of (6) (resp. $u_3$ of (7)), the long range effect as in Theorem 1 (resp. Theorem 2) is observed if and only if $\mu = 2m$ (resp. $m_3 = \lambda_1 m_1 + \lambda_2 m_2$ for some $\lambda_1, \lambda_2 \in \{\pm 1\}$).

References


The curved traveling front of the Allen-Cahn equation

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In this talk we consider the Allen-Cahn equation:

\[ u_t = \Delta u + f(u) \quad (x, y, t) \in \mathbb{R}^2 \times \mathbb{R}_+ \]  

(1)

where \( f \) is of “bistable type”. The typical example of the nonlinear term \( f \) is

\[ f(u) = u(1-u)(u-a), \quad 0 < a < \frac{1}{2}. \]  

(2)

The constant states 0 and 1 are stable under the diffusion-free system. By the assumption of \( a \), the region of the state 1 is getting larger and larger and finally it covers the whole space. When the state 1 propagates, we can observe the characteristic profiles. In the one-dimensional space, one of the typical solutions is a traveling wave solution which never changes its shape without translation. Substituting \( u(x,t) = \Phi(x - ct) \), we have

\[ \Phi_{\xi\xi} - c\Phi_\xi + f(\Phi) = 0. \]

Actually for the nonlinearity (2), we have

\[ \Phi(\xi) = \frac{1}{2} \left( 1 - \tanh \frac{\xi}{2\sqrt{2}} \right), \quad c = \sqrt{2} \left( \frac{1}{2} - a \right). \]

As the appropriate singular limit, the interface between two states 1 and 0 becomes sharp and we can get the interface equation (see e.g. [4]):

\[ V = H + k \]  

(3)

where \( V \) is a normal velocity, \( H \) is the curvature, and \( k \) is a given constant. This equation is also observed in the filamentary vortex of the Ginzburg–Landau equation confined in a plane [3] and the BZ reaction [6].
The typical solutions of (3) are the circles and lines. In the case \( k \neq 0 \), unfortunately, some interfaces may possess some self-intersection points eventually, even if the initial interface has none. If the interface is represented by the graph \( y = v(x, t) \), the equation (3) is reduced to

\[
v_t = \frac{v_{xx}}{1 + v_x^2} + k\sqrt{1 + v_x^2} \quad x \in \mathbb{R}, \ t > 0, \tag{4}
\]

Deckelnick et al in [3] proved the existence of the traveling curved front and studied the stability of the front under some restricted assumptions for \( u_0 \). The authors relaxed the assumption for the initial data and classified all the traveling fronts in [7, 8]. They proved the following (see [7, Proposition 1.1, Theorem 1.2]).

**Theorem 1** Any traveling front of (3) with velocity \( t'(0, c) \) is one of the three, after appropriate translations,

(i) lines \( y = m_* x \), and \( y = -m_* x \)

(ii) a traveling curved front \( \Gamma_c(t) \) which possesses two asymptotes \( y = \pm m_* x \),

(iii) stationary circles with radius \( 1/|k| \) only in the case \( c = 0 \),

where \( m_* := \sqrt{c^2 - k^2}/k \). Moreover the explicit form of the traveling curved front \( \Gamma_c(t) = \{ y = \varphi(x) + ct \} \) with speed \( c(\geq k) \) is given in

\[
x(\theta; c) := \frac{\theta}{c} + \frac{k}{c\sqrt{c^2 - k^2}} \log \left| \frac{1 + \frac{c + k}{\tan \frac{\theta}{2}}}{1 - \frac{c + k}{\tan \frac{\theta}{2}}} \right|
\]

\[
y(\theta; c) := -\frac{1}{c} \log \left( \frac{c \cos \theta - k}{c - k} \right),
\]

for \( \theta \in (-\arctan m_*, \arctan m_*) \).

The traveling curved front \( \Gamma_c(t) \) is "V-shaped", which connects two asymptotes. The existence of this traveling front is also reported in [2, 3] and in a liquid BZ reaction [6].

The asymptotic stability of the curved traveling front in (4) is discussed in [3, 8]. It is proved that the traveling curved front is asymptotically stable, if the initial perturbation is restricted to

\[
BC_0 := \{ v \in C^1(\mathbb{R}) \mid \sup_{-\infty < x < \infty} (|v(x)| + |v_x(x)|) < \infty, \lim_{|x| \to \infty} v(x) = 0 \}.
\]
and that if you take the perturbation space

$$BC'_0 := \{ u \in C^1(\mathbb{R}) \mid \sup_{-\infty < x < \infty} (|v(x)| + |v_x(x)|) < \infty \},$$

instead of $BC'_0,$ the traveling curved front is not asymptotically stable (see [8, Theorem 1.1 and Theorem 4.1]).

By the above observation, we can expect that a "V-shaped" traveling wave solution of (1) exists. Actually we have the following theorem.

**Theorem 2** There exists a traveling wave solution $u(x, y, t) = U(x, y - ct)$ of (1) such that

$$\lim_{R \to \infty} \sup_{(x,y) \in D_R} \left| U(x, y) - \Phi \left( \frac{k}{c}(y - m_*|x|) \right) \right| = 0$$

where

$$D_R := \{(x, y) \mid x^2 + y^2 \geq R^2\}.$$ 

Bonnet and Hamel [1] showed the existence of the "V-shaped" traveling wave solutions, if $f$ is of the "ignition temperature" type (mono-stable type) instead of (2). Hamel and Monneau [5] shows the uniqueness of the traveling front of the corresponding singular limit problem.

References


UNIQUENESS IN INVERSE SCATTERING PROBLEMS WITH A SINGLE INCIDENT WAVE

J. CHENG AND M. YAMAMOTO

1. INTRODUCTION

Let \( D \subset \mathbb{R}^2 \) be a bounded domain and \( k \in \mathbb{R} \). For \( x \in \mathbb{R}^2 \), we set \( r = |x| \). We consider a scattering problem with sound-soft obstacle:

\[
\Delta u + k^2 u = 0 \quad \text{in} \quad \mathbb{R}^2 \setminus \text{cl}(D)
\]

(1.1)

\[
u = 0 \quad \text{on} \quad \partial D
\]

(1.2)

\[
\lim_{r \to \infty} \sqrt{r} \left( \frac{\partial}{\partial r} u^S(x) - iku^S(x) \right) = 0.
\]

(1.3)

Henceforth \( \text{cl}(D) \) denotes the closure of a domain \( D \), and we set \( i = \sqrt{-1} \), \( d \in S^1 \equiv \{ x \in \mathbb{R}^2 ; |x| = 1 \} \) and

\[
u^S(x) = u(x) - e^{ikx} d.
\]

Under suitable conditions on \( D \), for \( k \in \mathbb{R} \) and \( d \in S^1 \), there exists a unique \( H^1 \)-solution \( u(x) = u(D)(x) \) to (1.1) - (1.3), and we can define the far field pattern \( u_\infty(D)(x) \):

\[
u^S(D)(x) = \frac{e^{ikr}}{\sqrt{r}} \left\{ u_\infty(D) \left( \frac{x}{r} \right) + O \left( \frac{1}{r} \right) \right\} \quad \text{as} \quad r \to \infty.
\]

(1.4)

**Inverse scattering problem:** Determine \( D \) from the far field pattern \( u_\infty(D) \) for given \( k \) and \( d \) (possibly by changing them).

This inverse problem is also physically significant and has been studied by many authors. We refer for example to Colton and Kress [1].

The first basic topic for this inverse problem is the uniqueness: Does

\[
u_\infty(D_1)(x) = u_\infty(D_2)(x), \quad |x| = 1
\]

(1.5)

(for possible several \( d \) and \( k \)) imply \( D_1 = D_2 \)?

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There is a classical uniqueness result within smooth $D_1, D_2$ if (1.5) holds for an infinite number of $d \in S^1$, which is proved based on Schiffer's idea (see Theorem 5.1 in [1]). For the uniqueness by means of a finite number of $d \in S^1$, see Colton and Sleeman [2], Theorem 5.2 in [1]. Moreover the uniqueness is known with a single $d$, provided that $D_1, D_2$ are contained in a ball of radius $\rho$ such that $k\rho < \pi$. See Corollary 5.3 in [1], [2].

An important open problem is the uniqueness in the inverse scattering problem with a single $(d,k)$. This problem is interesting from the theoretical point of view, because the far field patterns with many $d$ are over-determining data for determination of $D$ and we can expect the uniqueness with a single far field pattern. Moreover the formulation with a single $(d,k)$ is helpful for justification of numerical reconstruction of $D$, because one can usually use far field patterns observed by taking a single or a finite number of $d$.

2. MAIN RESULT

Let $k \in \mathbb{R}$ and $d \in S^1$ be arbitrarily fixed. Henceforth, for $P, Q \in \mathbb{R}^2$, we understand that $\overline{PQ}$ is an open segment (not including the end points $P$ and $Q$). Moreover for a polygonal domain $D$ and $P, Q \in \partial D$, $Q \notin \text{cl}(D)$ such that $\overline{PQ} \subseteq \mathbb{R}^2 \setminus \text{cl}(D)$, by $\angle(\overline{PQ}, \partial D)$ we denote the least angle among the two angles in $\mathbb{R}^2 \setminus \text{cl}(D)$ formed by $\overline{PQ}$ and $\partial D$. By a polygonal domain $D$, we mean that $\partial D$ is composed of a finite number of segments.

**Definition 2.1.** Let $D \subset \mathbb{R}^2$ be a bounded polygonal domain. Let $\ell$-points $P_1, ..., P_\ell$, $\ell \geq 2$, satisfy the following conditions (i) - (iv):

(i) \( P_1, ..., P_\ell \in \partial D \).

For $1 \leq j \leq \ell$, we set

\[ \theta_j = \begin{cases} 
\text{the exterior angle of } D \text{ at } P_j, & \text{if } P_j \text{ is a vertex of a polygon } D, \\
\pi, & \text{otherwise.} 
\end{cases} \]

(ii) $\overline{P_j P_{j+1}} \subseteq \mathbb{R}^2 \setminus \text{cl}(D)$ for $1 \leq j \leq \ell$.

(iii) $\angle(\overline{P_{j-1}P_j}, \partial D) = \angle(\overline{P_j P_{j+1}}, \partial D)$, $1 \leq j \leq \ell$, if $\overline{P_{j-1}P_j}$ does not bisect $\theta_j$ at $P_j$.

(iv) For $1 \leq j \leq \ell$, we have $\frac{\theta_j}{\angle(\overline{P_{j-1}P_j}, \partial D)} \in \mathbb{Q}$. 

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Here we set \( P_0 = P_t \) and \( P_{t+1} = P_1 \) and

\[
TR(D : P_1, ..., P_t) = \begin{cases} 
\text{a closed broken line } P_1 \rightarrow P_2 \rightarrow \cdots \rightarrow P_t \rightarrow P_1 \\
\text{if } P_t P_1 \text{ does not bisect } \theta_1 \text{ at } P_1, \\
\text{an non-closed broken line } P_1 \rightarrow P_2 \rightarrow \cdots \rightarrow P_t, \text{ otherwise.}
\end{cases}
\]

We call \( TR(D : P_1, ..., P_t) \) a trapped ray of \( D \) with rational angles.

By \( TR(D) \), we denote the sum of all the trapped rays of \( D \) with rational angles.

If \( TR(D) \neq \emptyset \), then we call \( D \) trapping with rational angles.

In other words, if \( TR(D) = \emptyset \), then there are no rays in \( \mathbb{R}^2 \setminus cl(D) \) which go out to \( \infty \) after finite times reflecting on \( \partial D \) subject to physical law (iii) with stricter constraint (iv) for angles of incidence.

We can state our main result:

**Theorem 2.2.** Let \( k \in \mathbb{R} \) and \( d \in S^1 \) be arbitrarily fixed and let

\[
(2.1) \quad \partial D_1 \cap TR(D_2) = \emptyset \quad \text{and} \quad \partial D_2 \cap TR(D_1) = \emptyset.
\]

Then \( u_\infty(D_1)(x) = u_\infty(D_2)(x), \quad |x| = 1, \text{ implies } D_1 = D_2. \)

**Corollary 2.3.** Let \( D_1 \) and \( D_2 \) be star-shaped polygons. Then \( u_\infty(D_1)(x) = u_\infty(D_2)(x), \quad |x| = 1, \text{ implies } D_1 = D_2. \)

By the definition, the break of condition (2.1) happens rarely. However we do not know the uniqueness if (2.1) does not hold. In fact, we have the following trapping \( D_1, D_2 \) where our proof does not work.

**Example 1.** Let us form \( D_1, D_2 \) as follows.

1. We take a square \( A_1A_2A_3A_4 \). For convenience, we set \( A_1 = (0,0), A_2 = (1,0), A_3 = (1,1), A_4 = (0,1) \).

2. In the interior of the square \( A_1A_2A_3A_4 \), we take a regular triangle \( B_1B_2B_3 \)
   (i.e., the lengths of the sides are equal). Here we choose vertices \( B_1, B_2, B_3 \) such that \( B_1 \rightarrow B_2 \rightarrow B_3 \) is counterclockwise and that \( B_1B_2 \parallel A_1A_2 \).

3. Take the midpoints \( P_1 \) and \( P_2 \) of the sides \( B_1B_3 \) and \( B_2B_3 \) respectively.

4. Take a point \( Q_1 \) on the segment \( B_3P_2 \) arbitrarily.

5. Take two points \( Q_2, Q_3 \) on the side \( A_2A_3 \) such that \( B_3Q_3 \parallel A_1A_2 \) and \( Q_1Q_2 \parallel A_1A_2 \).
(6) By $D_1$ we denote the interior bounded by the closed broken line $A_1A_2Q_2Q_1B_2B_1B_3Q_3A_3A_4$ (which is a non-convex polygon with those vertices). By $D_2$ we denote the interior bounded by the closed broken line $A_1A_2Q_2Q_1P_2P_1B_3Q_3A_3A_4$ (Figure 1).

Then $D_1$ is trapping with rational angles. In fact, let $P_3$ be the midpoint of the side $B_1B_2$. For $D_1$, we can see that $P_1P_2P_3$ satisfies conditions (i) - (iv), and we have $TR(D_1) \cap \partial D_2 \supset P_1P_2 \neq \emptyset$, that is, condition (2.1) does not hold. In this example, we note that $TR(D_1 : P_1, P_2, P_3)$ is a closed broken line $P_1 \rightarrow P_2 \rightarrow P_3 \rightarrow P_1$. For these $D_1$ and $D_2$, our proof does not work.

Figure 1

REFERENCES


Asymptotic behavior of spherically symmetric solutions to the compressible Navier–Stokes equation with external forces

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We study the large time behavior of an isentropic and spherically symmetric motion of compressible viscous gas in a field of external force over an unbounded exterior domain in \( \mathbb{R}^n \) \((n \geq 2)\). The typical example of this problem appears in the analysis of the behavior of atmosphere around the earth. First, we show that there exists a stationary solution satisfying an adhesion boundary condition and a positive spatial asymptotic condition. Then, it is shown that this stationary solution is a time asymptotic state to the initial boundary value problem with the same boundary and spatial asymptotic conditions. Here, the initial data can be chosen arbitrarily large if it belongs to the suitable Sobolev space. Moreover, if the external force is attractive, it also can be arbitrarily large. This condition includes the most typical external force, i.e., the gravitational force. In the proof of the stability theorem, it is the essential step to obtain the uniform positive lower bound for the density. It is derived through the energy method with the aid of a representation formula for the density.

The Navier-Stokes equation with external force for the isentropic motion of compressible viscous gas in the Eulerian coordinate is the system of equations given by

\[
\begin{align*}
\rho_t + \nabla \cdot (\rho u) &= 0, \quad (1a) \\
\rho (u_t + (u \cdot \nabla) u) &= \mu_1 \Delta u + (\mu_1 + \mu_2) \nabla (\nabla \cdot u) - \nabla p (\rho) + \rho f. \quad (1b)
\end{align*}
\]

We study the asymptotic behavior of a solution \((\rho, u)\) to (1) in an unbounded exterior domain \( \Omega := \{ \xi \in \mathbb{R}^n ; |\xi| > 1 \} \), where \( n \) is a space dimension larger than or equal to 2. Here \( \rho > 0 \)

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is the mass density; \( u = (u_1, \ldots, u_n) \) is the velocity of gas; \( p(\rho) = K\rho^\gamma \) \((K > 0, \gamma \geq 1)\) is the pressure; \( f \) is the external force; \( \mu_1 \) and \( \mu_2 \) are constant viscosity-coefficients satisfying \( \mu_1 > 0 \) and \( 2\mu_1 + n\mu_2 > 0 \).

It is assumed that the external force \( f \) is a spherically symmetric potential force and the initial data is also spherically symmetric. Namely, for \( r := |x| \)

\[
(A1) \quad f := -\nabla U = \frac{\xi}{r} U_r(r), \quad U_r \in C^1[1, \infty), \quad \lim_{r \to \infty} U(r) = \lim_{r \to \infty} \int_1^r U_r(\eta) d\eta,
\]

\[
(A2) \quad \rho_0(x) = \hat{\rho}_0(r), \quad u_0(\xi) = \frac{\xi}{r} \hat{u}_0(r).
\]

Under the assumptions \((A1)\) and \((A2)\), it is shown in [4] that the solution \((\rho, u)\) is spherically symmetric. Here, the spherically symmetric solution is a solution to \((1)\) in the form of

\[
\rho(\xi, t) = \hat{\rho}(r, t), \quad u(\xi, t) = \frac{\xi}{r} \hat{u}(r, t). \tag{2}
\]

Substituting \((2)\) in \((1)\), we reduce the system \((1)\) to the equations for \((\hat{\rho}, \hat{u})(r, t)\). Hereafter, we omit the hat to express a spherically symmetric function without confusion. Then, the spherically symmetric solution \((\rho, u)(r, t)\) satisfies the system of equations

\[
\rho_t + \frac{(r^{n-1} \rho u)_r}{r^{n-1}} = 0, \tag{3a}
\]

\[
\rho(u_t + uu_r) = \mu \left\{ \frac{(r^{n-1} u)_r}{r^{n-1}} \right\} - p(\rho)_r - \rho U_r, \tag{3b}
\]

where \( \mu := 2\mu_1 + \mu_2 \) is supposed to be positive. The initial data to \((3)\) is prescribed to be asymptotically constant in space:

\[
\rho(r, 0) = \rho_0(r) > 0, \quad u(r, 0) = u_0(r), \quad \lim_{r \to \infty} (\rho(r, t), u(r, t)) = (\rho_+, u_+), \quad \rho_+ > 0. \tag{4}
\]

As we interested in the behavior of gas around a solid sphere, an adhesion boundary condition is adopted:

\[
u(1, t) = 0. \tag{5}
\]

In addition, it is assumed that the initial data \((4)\) is compatible with the boundary data \((5)\). Since the characteristic speed of \((3a)\) is zero on the boundary due to \((5)\), one boundary condition is necessary and sufficient for the wellposedness of the initial boundary value problem \((3), (4)\) and \((5)\).

This problem is formulated to study the behavior of compressible viscous gas around the solid sphere in a field of external force. We show that the time asymptotic state of the
solution to the initial boundary value problem (3), (4), (5) is the stationary solution, which is a solution to (3) independent of time $t$, satisfying the same conditions (4) and (5). Hence, the stationary solution $(\bar{\rho}(r), \bar{u}(r))$ satisfies the system of equations

$$\frac{1}{r^{n-1}}(r^{n-1}\bar{\rho})_r = 0,$$

$$\bar{\rho}\bar{\rho}_r = \mu \left\{ \frac{(r^{n-1}\bar{u})_r}{r^{n-1}} \right\} - p(\bar{\rho})_r - \bar{\rho}U_r$$

and the boundary and the spatial asymptotic conditions

$$\bar{u}(1) = 0, \quad \lim_{r \to \infty} (\bar{\rho}(r), \bar{u}(r)) = (\rho_+, u_+).$$

Solving (6), we obtain an explicit formula of the stationary solution $(\bar{\rho}(r), \bar{u}(r))$:

$$\bar{u}(r) \equiv 0,$$

$$\bar{\rho}(r) = \begin{cases} \left\{ \rho_+^{\gamma-1} + \frac{\gamma-1}{K\gamma} (U_+ - U(r)) \right\}^{\frac{1}{\gamma-1}} & \text{for } \gamma > 1, \\ \rho_+ \exp \left\{ \frac{1}{K} (U_+ - U(r)) \right\} & \text{for } \gamma = 1. \end{cases}$$

Due to (8a), the spatial asymptotic data in (7) must satisfy $u_+ = 0$ for the existence of the stationary solution. The stability theorem on the stationary solution in (8) is summarized in the next theorem, which is the main result in the present research.

**Theorem 1.** Suppose the initial data satisfies that for a certain $\sigma \in (0, 1)$

$$\rho_0 \in B^{1+\sigma}_{loc}[1, \infty), \quad u_0 \in B^{2+\sigma}_{loc}[1, \infty),$$

$$r^{n-2} (\rho_0 - \bar{\rho}), \quad r^{n-2} u_0, \quad r^{n-2} (\rho_0 - \bar{\rho})_r, \quad r^{n-2} u_{0r} \in L^2(1, \infty)$$

and the compatibility condition holds. In addition, if there exists a positive constant $\delta$, depending only on the initial data, such that $-\delta \leq \rho(r, t)$, then the initial boundary value problem (3), (4), (5) has a unique solution $(\rho, u)$ globally in time and the solution converges to the corresponding stationary solution. Precisely, it holds that

$$\lim_{t \to \infty} \sup_{r \in [1, \infty)} |(\rho(r, t) - \bar{\rho}(r), u(r, t))| = 0.$$

Notice that any smallness assumptions on the initial data is not necessary for the above stability theorem. Moreover, if $U_+ \geq 0$, then $U_+$ can be arbitrarily large. This is the case that the external force is attractive like the gravitational force. The Hölder continuity of the initial
data (9a) is necessary to ensure the validity of the transformation between the Eulerian and the Lagrangian coordinates. (See (11) below.) Actually, we show the asymptotic stability of the stationary solution in the Lagrangian without the Hölder continuity. In translating this result to that in the Eulerian coordinate, we need the differentiability of solutions. This is the reason we assume (9a), which gives the Hölder continuity of the solution with the aid of the Schauder theory for parabolic equations. The remainder of the present paper is devoted to a brief outline of the proof of Theorem 1. The readers are referred to the paper [11] for the detailed discussions.

In the proof of Theorem 1, we show the uniform a priori estimate by employing the energy method. For this purpose, it is convenient to adopt the Lagrangian coordinate rather than the Eulerian coordinate. The transformation from the Eulerian coordinate \((r, t)\) to the Lagrangian coordinate \((x, t)\) is executed by the relation:

\[
x = \int_{1}^{r} \eta^{n-1} \rho(\eta, t) \, d\eta, \quad r_{t} = u, \quad r_{x} = \frac{v}{r^{n-1}}, \tag{11}
\]

where \(v = 1/\rho\) is the specific volume. Using (11), we deduce the system (3) to

\[
v_{t} = (r^{n-1}u)_{x}, \tag{12a}
\]

\[
u_{t} = \mu r^{n-1} \left( \frac{(r^{n-1}u)_{x}}{v} \right) - r^{n-1}p_{x} - U_{r}. \tag{12b}
\]

The initial and the boundary conditions for \((v, u)\) are derived from (4) and (5) as

\[
v(x, 0) = v_{0}(x) := 1/\rho_{0}(x), \quad u(x, 0) = u_{0}(x), \quad \lim_{x \to \infty} v_{0}(x) = v_{+} := 1/\rho_{+}, \quad \tag{13}
\]

\[
u(0, t) = 0. \tag{14}
\]

The spatial variable \(r\) in the Eulerian coordinate is regarded as a function of \((x, t)\) in the Lagrangian coordinate. Thus, the density \(\bar{\rho}\) in the stationary solution also depends on \((x, t)\), that is, \(\bar{\rho}(x, t) := \bar{\rho}(r(x, t))\). Also, let \(\bar{\rho}_{0}(x) := \bar{\rho}(r(x, 0))\).

Define the energy form \(E\) by

\[
E := \frac{1}{2} v^{2} + \Psi(v, \bar{v}),
\]

\[
\Psi(v, \bar{v}) := p(\bar{v})(v - \bar{v}) - \varphi, \quad \varphi := \int_{\bar{v}}^{v} p(\eta) \, d\eta, \quad p(v) := K v^{-\gamma}, \quad \bar{v} := 1/\bar{\rho}.
\]

If \(c \leq v(x, t) \leq C\) for positive constants \(c\) and \(C\), then \(\Psi(v, \bar{v})\) is equivalent to \(|v - \bar{v}|^{2}\). Namely, \(c|v - \bar{v}|^{2} \leq \Psi(v, \bar{v}) \leq C|v - \bar{v}|^{2}\) for positive constants \(c\) and \(C\). Then the energy form \(E\) is equivalent to \(|u|^{2} + |v - \bar{v}|^{2}\).

We state several a priori estimates for the solution \((v, u)\) without detailed proofs.
Proposition 2. (Basic estimate) Suppose that \( v_0 - \tilde{v}_0, u_0 \in L^2(0, \infty) \). Then the solution satisfies
\[
\int_0^\infty \mathcal{E}(x,t) \, dx + \mu \int_0^t \int_0^\infty (n-1) \frac{v^2}{r^2} u^2 + \frac{\gamma^{2n-2}}{v} u_x^2 \, dx \, d\tau \leq \int_0^\infty \mathcal{E}(x,0) \, dx. \tag{15}
\]
Applying the Sobolev inequality on (15), we have

Corollary 3.
\[
\int_0^t \| (r^{n-2} u^2)(r) \|_\infty \, d\tau \leq C, \tag{16}
\]
where \( C \) is a positive constant depending only on the initial data.

In order to obtain the pointwise bound for the specific volume \( v(x,t) \) uniformly in time, we employ a "cut-off-function" defined by
\[
\eta(x) = \begin{cases} 
1, & x \leq k, \\
k + 1 - x, & k \leq x \leq k + 1, \quad \text{for} \quad k = 1, 2, \ldots \\
0, & k + 1 \leq x.
\end{cases}
\]
By using (12) with the cut-off-function \( \eta(x) \), we have a representation formula of the density.

Lemma 4. \( v(x,t) \) is represented by
\[
v(x,t) = \frac{v_0(x) + \frac{K}{\mu} \int_0^t A(x,\tau) B(x,\tau) \, d\tau}{A(x,t) B(x,t)},
\]
for \( x \in [k-1, k) \) and \( t \geq 0 \), where
\[
A(x,t) := \exp \left( \frac{K \gamma}{\mu} \int_0^t \int_k^{k+1} v^{-\gamma} \xi \, d\xi \, d\tau + \frac{\gamma}{\mu} \int_0^t \int_x^\infty \frac{U_r}{r^{n-1} \eta} \, d\xi \, d\tau \right),
\]
\[
B(x,t) := \exp \left( \frac{\gamma}{\mu} \int_x^\infty \left( \frac{u}{r^{n-1}} - \frac{u_0}{r_0^{n-1}} \right) \eta \, d\xi + \frac{\gamma}{\mu} \int_0^t \int_x^\infty (n-1) \frac{u_0^2}{r_0^{n-1}} \eta \, d\xi \, d\tau - \gamma \int_k^{k+1} \log \frac{v}{v_0} \, d\tau \right).
\]

Proposition 2 and Lemma 4 yield the upper and the lower bounds of \( v(x,t) \).

Proposition 5. There exist positive constants \( c \) and \( C \), depending only on the initial data, such that
\[
c \leq v(x,t) \leq C \tag{17}
\]
for \( x \geq 0 \) and \( t \geq 0 \).
The estimate (17) immediately gives the pointwise bounds for the density, \(0 < c \leq \rho \leq C\). To obtain the a priori estimate for the derivatives of the solution, it is convenient to use the function

\[ \varphi(x, t) := \int_0^t p(\eta) \, d\eta. \]

Proposition 6. Suppose that \(v_0 - \tilde{v}_0, u_0, r_0^{n-2}(v_0 - \tilde{v}_0)_x, r_0^{n-2}u_{0x} \in L^2(0, \infty)\). Then we have

\[ \int_0^\infty \left( r^{2n-4} \varphi^2_x \right)(x, t) \, dx + c \int_0^t \int_0^\infty \left( r^{2n-4} \varphi^2_x \right)(x, \tau) \, dx \, d\tau \leq C, \tag{18} \]

\[ \int_0^\infty \left( r^{2n-4} u_x^2 \right)(x, t) \, dx + c \int_0^t \int_0^\infty \left( r^{4n-6} u_{xx}^2 \right)(x, \tau) \, dx \, d\tau \leq C, \tag{19} \]

where \(c\) and \(C\) are positive constants depending only on the initial data.

The estimate for \((v - \tilde{v})_x\) follows from (18);

\[ \int_0^\infty \left( r^{2n-4}(v - \tilde{v})^2 \right)_x(x, t) \, dx \leq C. \tag{20} \]

Using the estimates (15), (18), (19) and (20), we show the global existence of the solution \((v, u)\) in the Lagrangian coordinate. Moreover, these estimates give the asymptotic stability of the solution in (10). In these discussions, the Hölder continuity of the solution is not necessary. It is used to ensure the validity of the translation of these results to those in Eulerian coordinate. Actually, we show that, by applying the Schauder theory for the parabolic equations (see [2]), the solution \((\rho, u)\) is also belonging to the Hölder space if the initial data satisfies (9a). It immediately gives the corresponding stability theorem in the Eulerian coordinate.

Related results. The Navier–Stokes equation has been attracting interests of a lot of researchers in the fields of not only physics but also mathematics for these decays. Thus, we have so many preceding researches and have to restrict ourselves to a certain problem. Here we mainly state several results on the spherically symmetric motion of compressible viscous fluid in an exterior domain.

The first of all, we need to mention the book [1] written by S. N. Antontsev, A. V. Kazhikhov, and V. N. Monakhov, which gives comprehensive introduction to the mathematical theory of the compressible and viscous fluid. The first notable research in the equations on the exterior domain is given by A. Matsumura and T. Nishida in [9], where the stability of the stationary solution is first proved under the smallness assumptions. Note that this research covers more general solutions on more general domain than the present research, studying the spherically symmetric solution on the exterior domain.
Another pioneering work is given by N. Itaya [4], which establishes the existence of the spherically symmetric solution globally in time on a bounded annulus domain without smallness assumptions on the initial data. This paper has drawn attention of the researchers to the spherically symmetric solution. Then, A. Matsumura in [8] shows that the spherically symmetric solution to the isothermal model with external force on the annulus domain exists globally in time and it converges to the corresponding stationary solution as time tends to infinity. Moreover, it shows that the convergence is exponentially fast. The research by K. Higuchi in [3] extends this result to the isentropic model. In addition, it considers the equations of heat-conductive ideal gas on the annulus domain. The present research aims to extend the results in [8] and [3] to those on an unbounded exterior domain.

The study of the spherically symmetric solution over an unbounded exterior domain is started by S. Jiang in [5], where the global existence of the solution is established for the model of heat-conductive ideal gas. Moreover, the partial result on the asymptotic state is obtained. Precisely, it shows that, for the space dimension \( n = 3 \), \( \|u(t)\|_{2j} \to 0 \) as \( t \to \infty \), where \( j \geq 2 \) is an arbitrarily fixed integer.

In the case of one dimensional space \( n = 1 \), the problem on the unbounded exterior domain is coincide with the half-space problem. A. Matsumura and K. Nishihara in [10] start to investigate this problem for the compressible Navier-Stokes equation. In [10], several kinds of boundary conditions are proposed. Namely, inflow, outflow and no flow boundary conditions. Then, it classifies the asymptotic behaviors of the solution into the several cases subject to the relation between the boundary data and the spatial asymptotic data. Moreover, it proves the stability theorem for some cases by using the Lagrangian coordinate. The research [6] by S. Kawashima, S. Nishibata and P. Zhu also studies the same one dimensional half space problem. It obtains the a priori estimates directly in the Eulerian coordinate and proves the stability of the stationary solution. The Hölder continuity of the solution is also discussed in [6].

Notation. For a region \( \Omega \), an integer \( l \) and \( 0 < \sigma < 1 \), \( B^{l+\sigma}_p(\Omega) \) denotes the space of Hölder continuous functions over \( \Omega \) which have the \( l \)-th order derivatives of Hölder continuity with exponent \( \sigma \). \( B^{l+\sigma}_{loc}(\Omega) \) is the space of functions belonging to \( B^{l+\sigma}(\omega) \) for an arbitrarily compact set \( \omega \subset \Omega \). For \( 1 \leq p \leq \infty \), \( L^p(\Omega) \) denotes the standard Lebesgue space over \( \Omega \) equipped with the norm \( \| \cdot \|_p \). \( c \) and \( C \) denote several generic positive constants.

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References


Conical Shock Waves in Supersonic Flow

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Abstract

1 Physical background of shock waves

1. A steady shock front is produced as supersonic flow passes a solid projectile. The most important two typical configurations of the flying projectiles:
   - Long wing: two dimensional object;
   - Conical head: three dimensional object.

2. Depending upon the shape of the leading front of solid object, the shock front will be
   - detached from the projectile if the projectile has a blunt head;
   - attached to the head of the projectile if the projectile has a narrow and sharp pointed head.

3. It is of practical importance because the sharp jump of pressure across shock front produces great resistance to the flying object and therefore is to be avoided.

4. We study the case of steady shock wave attached to sharp pointed front of projectile.
2 Mathematical models

1. Euler system of equations: quasi-linear, hyperbolic,

\[
\begin{align*}
\partial_t \rho + \sum_{j=1}^{3} \partial_{x_j} (\rho v_j) &= 0, \\
\partial_t (\rho v_i) + \sum_{j=1}^{3} \partial_{x_j} (\rho v_i v_j + \delta_{ij} p) &= 0, \quad i = 1, 2, 3 \\
\partial_t (\rho E) + \sum_{j=1}^{3} \partial_{x_j} (\rho v_j E + p v_j) &= 0.
\end{align*}
\]

\( \rho \)- density, \( v \)- velocity, \( E = \frac{1}{2} |\mathbf{v}|^2 \)- total energy, \( p = p(\rho, E) \)- pressure.

2. Various simplified models to (1) can be introduced.

   (a) Linearization: small perturbation.
   (b) Geometrical simplification:
      * One dimensional model: shock transition relations and Lax shock inequality.
      * Geometrically symmetric model: cylindrical and spherical model.
   (c) Steady flow model: time-independent flow.
   (d) Thermodynamical simplification:
      * Polytropic gas model: \( p = A \rho^n \);
      * Isentropic model: \( p = p(\rho) \);
      * Irrotational model: \( \nabla \times \mathbf{v} = 0 \).
3 Conical shock wave for steady irrotational and isentropic flow

1. Irrotational flow: $\nabla \times \mathbf{v} = 0$ implies $\mathbf{v} = \nabla \phi$, $\phi$-velocity potential.

2. Second order scalar equation for $\phi$

\[
\left( \frac{v_1^2}{a^2} - 1 \right) \phi_{x_1 x_1} + \left( \frac{v_2^2}{a^2} - 1 \right) \phi_{x_2 x_2} + \left( \frac{v_3^2}{a^2} - 1 \right) \phi_{x_3 x_3} \\
+ \frac{2v_1 v_2}{a^2} \phi_{x_1 x_2} + \frac{2v_1 v_3}{a^2} \phi_{x_1 x_3} + \frac{2v_2 v_3}{a^2} \phi_{x_2 x_3} = 0. \tag{2}
\]

3. (2) is hyperbolic in the region of supersonic flow ($|\mathbf{v}| > a$), and is elliptic in the region of subsonic flow ($|\mathbf{v}| < a$).

4. Symmetric conical shock wave:
   - shock polar and apple curve;
   - weak and strong shock.

5. Theorems: Linear stability of conical shock wave and existence.


7. Generalized hodograph transformation: to transform the domain with free boundary into a fixed annular region.
4 Stability for oblique shock wave

My current work on the stability of oblique shock waves for isentropic system of Euler equations.

1. Boundary value problem for $m \times m$ hyperbolic system:

$$\begin{cases}
\partial_t u + \sum_{j=1}^{n} A_j \partial_{x_j} u + Cu = f, \text{ in } x_1 > 0; \\
Pu = g \text{ on } x_1 = 0.
\end{cases}$$

(3)

2. Well-posedness of (3): if there is energy estimate

$$\eta\|u\|_\eta^2 + |u|_\eta^2 \leq C_0 \left( \frac{1}{\eta} \|f\|_\eta^2 + |g|_\eta^2 \right)$$

(4)

$$\|u\|_\eta = \left( \int_{\mathbb{R}^1} \int_{\mathbb{R}^{n-1}} \int_{0}^{\infty} e^{2nt} |u(t,x_1,x')|^2 dx_1 \, dx' \, dt \right)^{\frac{1}{2}},$$

$$|u|_\eta = \left( \int_{\mathbb{R}^1} \int_{\mathbb{R}^{n-1}} e^{2nt} |u(t,0,x')|^2 dx' \, dt \right)^{\frac{1}{2}}.$$

3. Kreiss' condition for well-posedness:

- Eigenvectors and generalized eigenvectors with negative eigenvalues: $u_j$.
- Kreiss' condition: $Pu_j$ are uniformly linearly independent.


- Oblique shock front is stable for weak shock.
- Mathematical condition and its physical implication.
Remarks on global solvability of 2-D Boussinesq equations with nondecaying initial data

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1. INTRODUCTION

We consider the natural convection in a viscous incompressible fluid described by the Boussinesq equations:

\[
\begin{aligned}
\partial_t u - \Delta u + u \cdot \nabla u + \nabla p &= g \theta \\
\partial_t \theta - \Delta \theta + u \cdot \nabla \theta &= 0 \\
\text{div } u &= 0 \\
u|_{t=0} &= u_0, \quad \theta|_{t=0} = \theta_0
\end{aligned}
\]  

in \( t > 0 \) and \( x \in \mathbb{R}^n \),

where \( u = (u^1(x,t), u^2(x,t), \ldots, u^n(x,t)) \), \( \theta = \theta(x,t) \) and \( p = p(x,t) \) denote the unknown velocity vector field, the unknown temperature and the unknown pressure of the fluid at the point \( (x,t) \in \mathbb{R}^n \times (0,\infty) \), respectively. \((u_0, \theta_0)\) is a given initial data and \( g \) is the given constant vector which denotes acceleration of gravity.

Many researchers have investigated the Boussinesq equations. See e.g. Cannon–DiBenedetto[1], Fife–Joseph[5], Poias–Mainley–Temam[4], Morimoto[14][15], Oeda[16][17], Hishida[6], Hishida–Yamada[7], Kagei[10], Kagei–von Wahl[11] and papers cited there.

These results, however, are imposed the integrability condition on the initial data \( u_0, \theta_0 \in L^q \) for some \( q < \infty \). This condition implies that \( u_0(x) \) and \( \theta_0(x) \) decay at infinity in some sense.

On the other hand, Giga–Inui–Matsui[8], Cannon–Knightly[2] and Cannone[3] showed the time-local existence of solution to the Navier–Stokes equations:

\[
\text{(N-S)} \quad \begin{cases}
\partial_t u - \Delta u + u \cdot \nabla u + \nabla p = 0, \\
\text{div } u = 0
\end{cases}
\]

in \( t > 0 \) and \( x \in \mathbb{R}^n \),

with nondecaying initial data \( u_0 \in L^\infty \). It is notable that in the two dimensional case Giga-matsui-Sawada[9] proved the unique global solvability of (N-S) with \( u_0 \in L^\infty(\mathbb{R}^2) \).

In [18], we proved the unique local existence theorem for the Boussinesq equations with nondecaying initial data. To be precise, we showed that if \( u_0 \in L^\infty \) with \( \text{div } u = 0 \) in \( \mathcal{D}' \) and \( \theta_0 \in \dot{B}_{\infty,1}^0 \), then there exists the strong solution

\[
(1.1) \quad (u, \theta) \in C_w([0,T); L^\infty(\mathbb{R}^n)) \times C([0,T); \dot{B}_{\infty,1}^0(\mathbb{R}^n))
\]

to the Boussinesq equations with \( \nabla p \in C((0,T); \dot{B}_{\infty,1}^0(\mathbb{R}^n)) \). We note that the space \( \dot{B}_{\infty,1}^0 \) includes some nondecaying functions, for example, \( \sin(a \cdot x) + (1 + |x|^2)^{-1} \). Moreover, in [18] it was shown that there exists a unique global solutions to the 2-D Boussinesq equations when the initial data \( (u_0, \theta_0) \in L^\infty(\mathbb{R}^2) \times L^p(\mathbb{R}^2) \) for some \( p \in (2, \infty) \). Although the initial velocity need not to be decay at infinity, the initial temperature \( \theta_0 \) was restricted to decay at infinity.
The purpose of this paper is to remove this decay condition on $\theta_0$. Now we state our main
Theorem.

**Theorem 1 (global existence).** Let the initial data $(u_0, \theta_0) \in L^\infty(\mathbb{R}^2) \times \dot{B}^{0}_{\infty,1}(\mathbb{R}^2)$ with $\text{div} u_0 = 0$. Then there exists a unique solution $(u, \theta) \in C_w([0, \infty); L^\infty(\mathbb{R}^2)) \times C([0, \infty); \dot{B}^{0}_{\infty,1}(\mathbb{R}^2))$ to (B) with $\nabla \theta \in C((0, \infty); \dot{B}^{0}_{\infty,1})$.

**Remark.** $\dot{B}^{0}_{\infty,1}$ contains some nondecaying functions as well as $L^\infty$. For example, $\sin(a \cdot x)$ and $\cos(b \cdot x) \in \dot{B}^{0}_{\infty,1}$, where $a$ and $b$ are constant vectors and $b \neq 0$. Furthermore, periodic functions $f \in W^{1,\infty}(T)$ with $\int_T f \, dx = 0$ belongs to $\dot{B}^{0}_{\infty,1}(\mathbb{R}^n)$. We observe this fact by the Fourier series. We also see that if $f_1(x_1, x_2, \ldots, x_{n-1}) \in W^{1,\infty}(\mathbb{R}^{n-1})$ and $f_2(x_n) \in W^{1,\infty}(\mathbb{R}) \cap L^p(\mathbb{R})$ ($p < \infty$), then $f_1 f_2 \in \dot{B}^{0}_{\infty,1}(\mathbb{R}^n)$.

In two dimension, taking rotation to first equation of (B), we get the rotation equation

$$(\text{Rot}) \quad \omega_t - \Delta \omega + u \cdot \nabla \omega = \text{rot} (g \theta),$$

where $\omega = \text{rot} u$ is a scalar function. If $\theta \equiv 0$, the maximum principle yields $\|\omega(t)\|_{\infty} \leq \|\omega(0)\|_{\infty}$.

In [9], this estimate plays an important role in proving the global solution to the 2-D Navier-Stokes equations. We, however, cannot apply the maximum principle for the rotation equation directly, nevertheless, $\partial \theta$ is bounded. To overcome this difficulty, we establish the following uniformly local $L^p$ estimate for the vorticity equation.

**Lemma 1.1.** Let $u \in L^\infty(0, T; W^{1,\infty}(\mathbb{R}^2))$ with $\nabla \cdot u = 0$ and let $v \in L^\infty(0, T; L^\infty(\mathbb{R}^2))$ be a solution to the 2 dimensional vorticity equation

$$(1.2) \quad \frac{\partial v}{\partial t} - \Delta v + u \cdot \nabla v = f + \partial J g, \quad \text{in} \ R^2 \times (0, T), \quad v|_{t=0} = v_0.$$  

Then there holds for all $t \in [0, T]$ and all $p \geq 2$

$$(1.3) \quad \|v(t)\|_{L^p_v} \leq C \left(1 + t + \int_0^t \|u(\tau)\|_{\infty} \, d\tau \right)^{2/p} \left\{ \|v_0\|_{L^p_v} + \int_0^t \|f\|_{L^p_v} \, d\tau + \|g(\tau)\|_{\dot{B}^{0}_{\infty,1}}^{1/2} \right\}^{1/2}$$

where $C$ is an absolute constant and $\|f\|_{L^p_v} = \sup_{x} \left( \int_{|x-y|<1} |f(y)|^p \, dy \right)^{1/p}$.

2. FUNCTION SPACES

Before proving the main results, we first recall definition of the homogeneous Besov space. For integer $j$, let $\varphi_j$ be the Littlewood–Paley decomposition satisfying $\varphi_j(\xi) = \varphi_0(2^{-j} \xi) \in C^\infty_c(\mathbb{R}^n)$, $\text{supp} \varphi_0 \subset \{1/2 < |\xi| < 2 \}$ and $\sum_{j=-\infty}^{\infty} \varphi_j(\xi) = 1$ excepting $\xi = 0$.

**Definition 1** The homogeneous Besov space $\dot{B}^s_{p,q} = \dot{B}^s_{p,q}(\mathbb{R}^n)$ is introduced by

$$\dot{B}^s_{p,q} \equiv \{ f \in Z; \|f\|_{\dot{B}^s_{p,q}} < \infty \}.$$
for $s \in \mathbb{R}$, $1 \leq p, q \leq \infty$, where
\[ \|f\|_{\dot{B}^{s}_{p,q}} \equiv \left\{ \sum_{j=-\infty}^{\infty} \left(2^{js}\|\varphi_j \ast f\|_p^q\right)^{1/q} \right\}^{1/q} \quad \text{if } q < \infty, \\
\sup_{-\infty < j < \infty} 2^{js}\|\varphi_j \ast f\|_p \quad \text{if } q = \infty. \]

Here $\mathcal{Z} \equiv \{ f \in S; D^\alpha \hat{f}(0) = 0, \forall \alpha \text{ is multi-index} \}$.

If the exponents satisfy the following condition:
\[ s < n/p \quad \text{or} \quad s = n/p \quad \text{and} \quad q = 1, \]
then $\dot{B}^{s}_{p,q}$ can be regarded as subspace of $S'$. To be precise, there holds
\[ \dot{B}^{s}_{p,q} \cong \{ f \in S'; \|f\|_{\dot{B}^{s}_{p,q}} < \infty \text{ and } f = \sum_{j=-\infty}^{\infty} \varphi_j \ast f \text{ in } S' \}, \]
if $s, p$ and $q$ satisfy (2.1). For the details one can see e.g. Kozono-Yamazaki[13, Proposition 2.10].

In what follows, we deal with (2.2) as the definition of $\dot{B}^{s}_{p,q}$, when $s, p$ and $q$ satisfy (2.1). We note that any polynomial excepting 0 no longer belongs to $\dot{B}^{s}_{p,q}$, when $s, p$ and $q$ satisfy (2.1).

Finally, we give some definitions. Let $B(x,r)$ denote the ball centered at $x$ of radius $r$ and let
\[ \|f\|_{p;\Omega} \equiv \left( \int_{y \in \Omega} |f(y)|^p dy \right)^{1/p}, \quad \|f\|_{p;\lambda} \equiv \sup_{x \in \mathbb{R}^n} \left( \int_{|x-y|<\lambda} |f(y)|^p dy \right)^{1/p}, \]
\[ \|f\|_{L^p_{ul}} \equiv \|f\|_{p;1} = \sup_{x} \left( \int_{|x-y|<1} |f(y)|^p dy \right)^{1/p}, \quad L^p_{ul} \equiv \{ f \in L^1_{loc}; \|f\|_{p;1} < \infty \}. \]

3. PRELIMINARY

To prove Theorem 1 and Lemma 1.1, we need the followings.

Lemma 3.1 (Sawada–Taniuchi[18]). Assume that the initial data $(u_0, \theta_0) \in L^\infty(\mathbb{R}^n) \times \dot{B}^0_{\infty,1}(\mathbb{R}^n)$ with $\text{div} u_0 = 0$ in the sense of distribution. Then there exists $T > 0$ and a unique solution $(u, \theta, \nabla p)$ to (B) with
\begin{align*}
(3.1) & \quad u \in C_w([0,T); L^\infty(\mathbb{R}^n)) \cap C^1((0,T); L^\infty(\mathbb{R}^n)) \cap C((0,T); W^{2,\infty}(\mathbb{R}^n)), \\
(3.2) & \quad \theta \in C_w([0,T); \dot{B}^0_{\infty,1}) \cap C^1((0,T); L^\infty(\mathbb{R}^n)) \cap C((0,T); W^{2,\infty}(\mathbb{R}^n)), \\
(3.3) & \quad \nabla p \in C((0,T); \dot{B}^0_{\infty,1}), \\
(3.4) & \quad \partial_t u - \Delta u + P(u \cdot \nabla u) = P(\theta g) \quad \text{in } L^\infty, \\
(3.5) & \quad \partial_t \theta - \Delta \theta + u \cdot \nabla \theta = 0 \quad \text{in } L^\infty, \\
(3.6) & \quad \nabla p = (1 - P)(u \cdot \nabla u + g \theta). 
\end{align*}
Here \( P = \{ P_{kl} \}_{1 \leq l, k \leq n} = \{ \delta_{kl} + R_l R_k \}_{1 \leq l, k \leq n} \). Moreover there exists \( C = C(n) \) such that
\[
(3.7) \quad T > (\| u_0 \|_\infty + \| \theta_0 \|_{\partial \omega_t})^2 + |g| + 1.
\]

**Remark.** To solve (B) we reduce to construct a solution \((u, \theta)\) to the integral equations:

\[
\begin{align*}
(I.E.B)_1 & \quad u(t) = e^{t \Delta} u_0 - \int_0^t e^{(t - \tau) \Delta} P(u \cdot \nabla u)(\tau) d\tau + \int_0^t e^{(t - \tau) \Delta} P(g\theta)(\tau) d\tau \\
(I.E.B)_2 & \quad \theta(t) = e^{t \Delta} \theta_0 - \int_0^t e^{(t - \tau) \Delta} (u \cdot \nabla \theta)(\tau) d\tau.
\end{align*}
\]

**Proposition 3.1.** There holds for all \( f \in L^\infty \)
\[
(3.8) \quad \| e^{t \Delta} f \|_{\dot{H}^{s+1}_\omega} \leq C(n, s) t^{-s/2} \| f \|_\infty \quad \text{for } t > 0 \text{ and } s > 0.
\]

**Proposition 3.2.** If \( m \geq 1 \), then
\[
\| f \|_{q, m, \lambda} \leq (2m^2)^{1/q} \| f \|_{q, \lambda} \quad \text{for all } f \in L^q_{ul}(\mathbb{R}^2), \lambda > 0.
\]

**Proposition 3.3.** Let \( 1 \leq q \leq \infty, \ j = 0, \pm 1, \pm 2, \cdots, \phi \in S \) and let \( f \in L^q_{ul}(\mathbb{R}^2) \). Then there holds
\[
(3.9) \quad \| \phi_j * f \|_{\infty} \leq \begin{cases} C 2^{2j/q} \| f \|_{q, 1} & \text{for all } j \geq 0, \\ C \| f \|_{q, 1} & \text{for all } j \leq 0, \end{cases}
\]
where \( C \) is independent of \( q, j \) and \( f \). Here \( \phi_j(\cdot) = 2^{2j} \phi(2^{2j} \cdot) \).

**Proposition 3.4** (Gronwall’s inequality). Let \( A_1, A_2 \) and \( A_3 \) be nonnegative function on \((0, T)\) with \( \int_0^T A_j(t) dt < \infty \) for \( j = 1, 2, 3 \), and let \( A_0, \gamma_1, \gamma_2 \) be positive constants with \( 0 < \gamma_2 < \gamma_1 < 1 \). Assume that \( z \in C([0, T]) \) and
\[
0 \leq z(t) \leq A_0 + \int_0^t A_1(\tau) z(\tau)^{1-\gamma_1} d\tau + \int_0^t A_2(\tau) z(\tau)^{1-\gamma_2} d\tau + \int_0^t A_3(\tau) z(\tau) d\tau \quad \text{for all } 0 \leq t < T.
\]
Then
\[
z(t) \leq \left( \left( A_0^\gamma + \gamma_1 \int_0^t A_1(\tau) d\tau \right) \right)^{1/\gamma_1} + \gamma_2 \int_0^t A_2(\tau) d\tau \quad \text{for all } 0 \leq t < T.
\]

4. **OUTLINE OF THE PROOF OF \( L^p_{ul} \) ESTIMATE FOR THE VORTICITY EQUATION**

In this section we sketch the proof of Lemma 1.1. We first fix \( x \in \mathbb{R}^2 \) and \( \lambda \geq 1 \). Let \( \rho \in C^\infty_0(\mathbb{R}^2) \) with \( \rho(y) = \begin{cases} 1, & |x| \leq 1, \\ 0, & |x| \geq 2, \end{cases} \) \( \| \nabla \rho \|_\infty \leq 2, \| \Delta \rho \|_\infty \leq 4 \) and let \( \rho_{x, \lambda}(y) = \rho(\frac{y-x}{\lambda}) \). We easily see that
\[
\frac{\partial}{\partial t} (\rho_{x, \lambda} v) - \Delta (\rho_{x, \lambda} v) + u \cdot \nabla (\rho_{x, \lambda} v) = \rho_{x, \lambda} f + \rho_{x, \lambda} \partial_2 g - 2 \nabla \rho_{x, \lambda} \cdot \nabla v - (\Delta \rho_{x, \lambda}) v + u \cdot (\nabla \rho_{x, \lambda}) v.
\]
Taking inner product in \( L^2(\mathbb{R}^2) \) between (4.10) and \( |\rho_{x,\lambda}v|^p \rho_{x,\lambda}v \) and taking supremum of it over \( x \in \mathbb{R}^2 \), we obtain

\[
|v(t)|_{p,\lambda}^p \leq 8 \left\{ |v_0|_{p,\lambda}^p + p \int_0^t \left| f \right|_{p,\lambda} \left| v \right|_{p,\lambda}^{p-1} \left| f \right|_{p,\lambda} + \frac{p(p+1)}{2} \int_0^t \left| g \right|_{p,\lambda}^2 \left| v \right|_{p,\lambda}^{p-2} \right\} \\
+ p \int_0^t \left( \frac{2 \cdot 264}{\lambda^2} + 2 \frac{\|u(\tau)\|_\infty}{\lambda} \right) \left| v(\tau) \right|_{p,\lambda}^p \left| f \right|_{p,\lambda} \left( f \right|_{p,\lambda} \right),
\]

(4.11)

where we used to

\[
|f|_{p,\lambda}^p \leq 8 \left| f \right|_{p,\lambda}^p \quad \text{and} \quad \sup_{x \in \mathbb{R}^2} \left( \int_0^t \int_{B(x,2\lambda)} \left| f \right| dy \right) \leq 8 \sup_{x \in \mathbb{R}^2} \left( \int_0^t \int_{B(x,\lambda)} \left| f \right| dy \right).
\]

Then Proposition 3.4 with \( z(t) = \left| v(t) \right|_{p,\lambda} \) and Proposition 3.2 yield

\[
|v(t)|_{p,1} \leq \left| v(t) \right|_{p,\lambda} \leq (2\lambda^2)^{1/p} \left\{ 8^{1/p} |v_0|_{p,1} + 8^{1/2}(p+1)^{1/2} \left( \int_0^t \left| g \right|_{p,1}^2 \left( f \right|_{p,1} \right) \left( f \right|_{p,1} \right) + \int_0^t 8 \left| f \right|_{p,1} \left( f \right|_{p,1} \right) \left( f \right|_{p,1} \right) \right\} \\
\times \exp \left\{ \frac{8 \cdot 264}{\lambda^2} - t + \frac{16}{\lambda} \int_0^t \left| u(\tau) \right|_\infty \left| f \right|_{p,1} \left( f \right|_{p,1} \right) \left( f \right|_{p,1} \right) \right\}.
\]

(4.12)

Now let \( s \in (0, T] \) and set \( \lambda = 1 + s + \int_0^s \left| u(\tau) \right|_\infty \left| f \right|_{p,1} \left( f \right|_{p,1} \right) \left( f \right|_{p,1} \right) \). Then there holds

\[
|v(t)|_{p,1} \leq C \left( 1 + s + \int_0^s \left| u(\tau) \right|_\infty \left| f \right|_{p,1} \left( f \right|_{p,1} \right) \left( f \right|_{p,1} \right) \right)^{2/p} \left\{ |v_0|_{p,1} + p^{1/2} \left( \int_0^t \left| g \right|_{p,1}^2 \left( f \right|_{p,1} \right) \left( f \right|_{p,1} \right) + \int_0^t \left| f \right|_{p,1} \right\}
\]

for all \( 0 < t \leq s \leq T \). Since \( s \in (0, T] \) is arbitrary, we get the desired estimate (1.3).

5. OUTLINE OF THE PROOF OF THEOREM 1

In this section we shall sketch the proof of Theorem 1. We use the similar method as in [20].

(See also Serfatii[19].) We show that the time-local solution given in Lemma 3.1 can be extended to a global one. Thanks to (3.1) and (3.2), we may assume \( u_0 \in W^{2,\infty}, \theta_0 \in \dot{B}^{0}_{\infty,1} \cap W^{2,\infty} \) and assume \((u, \theta) \in C([0, T]; W^{2,\infty}) \times C([0, T]; \dot{B}^{0}_{\infty,1})\). It suffices to show

\[
\sup_{0 < t < T} \left( \left| u(t) \right|_\infty + \left| \theta(t) \right|_{\dot{B}^{0}_{\infty,1}} \right) < \infty \quad \text{if} \quad T < \infty.
\]

By the equations (3.5) and (I.E.B)2 we have

\[
\left| \theta(t) \right|_\infty \leq \left| \theta_0 \right|_\infty,
\]

\[
\left| \theta(t) \right|_{\dot{B}^{0}_{\infty,1}} \leq \left| \theta_0 \right|_{\dot{B}^{0}_{\infty,1}} + Ct^{1/2} \left( \sup_{0 \leq \tau \leq t} \left| u(\tau) \right|_\infty \right) \left| \theta_0 \right|_\infty.
\]

Therefore, for (5.1) we only need to show

\[
\sup_{0 \leq \tau < T} \left| u(\tau) \right|_\infty < \infty \quad \text{if} \quad T < \infty.
\]

\[-41-\]
Here we recall that the Littlewood-Paley decomposition:

\[ 1 = \psi_N(\xi) + \sum_{j \geq N} \tilde{\phi}_j(\xi) \quad (\xi \in \mathbb{R}^2, \; N = 0, \pm 1, \pm 2, \ldots), \]

where \( \psi_N = 2^{2N} \psi(2^N \cdot) = F^{-1} (1 - \sum_{j = N} \tilde{\phi}_j) \). We easily see that

\[ (5.5) \quad ||u(t)||_\infty \leq ||\psi_N * u(t)||_\infty + \sum_{j = N}^\infty ||\phi_j * u(t)||_\infty = J_1 + J_2 \]

By (I.B.E) and (I.E.B) we have for all \( 0 \leq s \leq t < T \)

\[ J_1 = \left\| \psi_N * e^{(t-s)\Delta} u(s) + \int_s^t P \nabla \cdot \psi_N * e^{(t-\tau)\Delta} (u \otimes u)(\tau) d\tau \right\|_\infty \]

\[ + \int_s^t \psi_N * e^{(t-\tau)\Delta} P \left( g e^{\tau \Delta} \theta_0 + g \int_0^\tau \nabla \cdot e^{(\tau-\tau')\Delta} (u \theta)(\tau')d\tau' \right) d\tau \]

\[ \leq ||u(s)||_\infty + C_1 2^N \left( \sup_{0 \leq \tau \leq t} ||u(\tau)||_\infty \right)^2 (t - s) \]

\[ + C_2 |g| ||\theta_0||_{L^p(t)} (t-s) + C_3 |\nabla (\sup_{0 \leq \tau \leq t} ||u(\tau)||_\infty)||\theta_0||_\infty (t^2 - s^2), \]

since \( \|\nabla P \phi_N\|_{L^1} \leq \|\nabla^2 \psi_N\|_{H^1} \leq C \|\nabla \psi_N\|_{H^1} \leq C N^N \). Here \( H^1 \) denotes Hardy space.

To estimate \( J_2 \), we use the Biot-Savart law \( (\partial_{x_2} \omega, -\partial_{x_1} \omega) = -\Delta u \), which yields \( ||\phi_j * u||_\infty \leq C 2^{-j} ||\phi_j * \omega||_\infty \). Let \( p \geq 4 \). Then by this inequality and Proposition 3.3 we have

\[ (5.6) \quad \sum_{j = N}^\infty ||\phi_j * u(t)||_\infty \leq C \sum_{j = N}^\infty 2^{-j ||\phi_j * \omega(t)||_\infty} \leq C 2^{-N} \max \{2^{2N/p}, 1\} ||\omega(t)||_{L^p} \]

Let \( s \leq t < \min \{T, s + 1\} \), (i.e. \( t - s < 1 \)). Then Lemma 1.1 and (5.7) yield

\[ J_2 \leq C 2^{-N} \max \{2^{2N/p}, 1\} \left( 1 + \sup_{0 \leq \tau \leq t} ||u(\tau)||_\infty \right)^{2/p} \left( ||\omega(s)||_{L^p} + p^{1/2} (t-s)^{1/2} ||\theta_0||_\infty \right) \]

for all \( p \geq 4 \) and \( s \leq t < \min \{T, s + 1\} \).

Let \( h(t) \equiv 1 + t + \sup_{0 \leq \tau \leq t} ||u(\tau)||_\infty \). Then Gathering the estimates (5.6) and (5.8) with (5.5), we obtain

\[ h(t) \leq h(s) + (t-s) + C_1 2^N h(t)^2 (t-s) \]

\[ + C_2 |g| ||\theta_0||_{L^p(t)}^2 (t-s) + 2 C_3 |\nabla (\sup_{0 \leq \tau \leq t} ||u(\tau)||_\infty)||\theta_0||_\infty (t-s) \]

\[ + C_4 2^{-N} \max \{2^{2N/p}, 1\} h(t)^{2/p} ||\omega(s)||_{L^p} + p^{1/2} (t-s)^{1/2} ||\theta_0||_\infty \]

for all \( p \geq 4 \) and all \( 0 \leq s \leq t < \min \{T, s + 1\} \).

Now we fix \( s \in [0, T) \). Since \( h(t) \) is a continuous function, there holds \( h(t) \leq 2h(s) \) for \( t \) sufficiently close to \( s \). Let

\[ T_{1}(s) \equiv \sup \{ \tau \in (0, T-s) \mid h(s + \tau) \leq 2h(s) \} \quad (T_{1}(s) \leq T-s). \]

(Since \( h \) is a nondecreasing function, \( h(t) \leq 2h(s) \) for all \( s \leq t < s + T_{1}(s) \).) Then (5.9) yields

\[ h(t) < h(s) + \frac{1}{2} + C_5 2^N h(s)^2 (t-s) + C_6 2^{-N} \max \{2^{2N/p}, 1\} h(s)^{2/p} (||\omega(s)||_{L^p} + p^{1/2}) \]

\[ \leq h(s) + \frac{1}{2} + C_5 2^N h(s)^2 (t-s) + C_6 2^{-N} \max \{2^{2N/p}, 1\} h(s)^{2/p} (||\omega(s)||_{L^p} + p^{1/2}) \]

\[-42-\]
for all $s \leq t < s + \min\left\{ \frac{1}{4}, \frac{1}{\delta C_3 g \|\theta_0\|_{B_{\infty,1}}}, T_1(s) \right\}$ and $p \geq 4$. Here $C_5 \equiv 4C_1 + 4C_3 g \|\theta_0\|_{\infty}$ and $C_6 = \sqrt{2} C_4 \cdot (1 + g \|\theta_0\|_{\infty})$. Now we choose $N$ suitably as follows.

When \( \frac{h(s)^{1 - \frac{2}{p}}}{8C_6 (\|\omega(s)\|_{L^p_{u,t}} + p^{1/2})} \leq 1 \), we choose $N \geq 0$ such as \( 2^{-(1-2/p)N} \sim \frac{h(s)^{1 - \frac{2}{p}}}{8C_6 (\|\omega(s)\|_{L^p_{u,t}} + p^{1/2})} \). When \( \frac{h(s)^{1 - \frac{2}{p}}}{8C_6 (\|\omega(s)\|_{L^p_{u,t}} + p^{1/2})} > 1 \), we choose $N \leq -1$ such as \( 2^{-N} \sim \frac{h(s)^{1 - \frac{2}{p}}}{8C_6 (\|\omega(s)\|_{L^p_{u,t}} + p^{1/2})} \). Then the last term of (5.10) is smaller than $1/(8h(s))$. Therefore, since $\frac{1}{2} \leq \frac{h(s)}{8}$, we obtain

\[
h(t) < \frac{13}{8}h(s) + C_7 \max \left\{ (\|\omega(s)\|_{L^p_{u,t}} + p^{1/2})^{p/2}, (\|\omega(s)\|_{L^p_{u,t}} + p^{1/2})h(s)^{p/2} \right\} h(s)(t-s)
\]

for all $s \leq t < s + \min\left\{ \frac{1}{4}, \frac{1}{\delta C_3 g \|\theta_0\|_{B_{\infty,1}}}, T_1(s) \right\}$ and $p \geq 4$. Here $C_7 = 2C_5 (2\delta + 1)^2$. Hence we have

\[
(5.11) \quad h(t) < \frac{15}{8}h(s) \quad \text{for all } s \leq t < s + \min\{\delta(s,p), T_1(s)\},
\]

where

\[
\delta(s,p) = \min \left\{ \frac{1}{(4C_7)}, \frac{1}{h(s)^{2/p} \|\omega(s)\|_{L^p_{u,t}} + p^{1/2}} \right\}.
\]

Obviously from the definition of $T_1(s)$ we obtain $T_1(s) \geq \min\{\delta(s,p), T - s\}$ and hence

\[
(5.12) \quad h(t) \leq 2h(s) \quad \text{for all } s \leq t \leq s + \min\{\delta(s,p), T - s\}.
\]

We note that this estimate holds for all $s \in (0, T)$ and $p \geq 4$.

Let $p_k = k + 4$ and $\{t_k\}_{k=0}^{\infty}$ be the increasing sequence defined by

\[
t_0 = 0, \quad t_{k+1} - t_k = \delta(t_k, p_k).
\]

Now we assume that

\[
(5.13) \quad \delta(t_k, p_k) < T - t_k \quad \text{for all } k = 0, 1, 2, \ldots \quad \text{(i.e., } t_{k+1} < T \quad \text{for all } k = 0, 1, 2, \ldots \).
\]

Then by (5.12) we have

\[
(5.14) \quad h(t_k) \leq 2h(t_{k-1}) \leq \cdots \leq 2^k h(0)
\]

and hence

\[
(5.15) \quad h(t_k)^{2/p_k} \leq (2^k h(0))^{2/(k+4)} \leq Ch(0)^{2/(k+4)} \leq Ch(0)^{1/2}.
\]
Since $t_k = \sum_{j=0}^{k-1} \delta(t_j, p_j) \leq \sum_{j=0}^{k-1} \frac{1}{p_j} \leq Ck^{1/2}$ and since $\|\varpi(0)\|_{L_{\text{ul}}^p} \leq \pi^{2/p} \|\varpi_0\|_\infty$, by Lemma 1.1 and (5.15) we see

$$
\|\varpi(t_k)\|_{L_{\text{ul}}^{p_k}} \leq C \left( 1 + t_k \left( 1 + \sup_{0 \leq \tau \leq t_k} \| u(\tau) \|_\infty \right) \right)^{2/p_k} \left( \|\varpi_0\|_{L_{\text{ul}}^{p_k}} + p_k^{1/2} t_k^{1/2} g \|\vartheta_0\|_\infty \right)
$$

$$
\leq C \left[ 2^{k^{1/2}} h(t_k) \right]^{2/p_k} \left( \|\varpi_0\|_{L_{\text{ul}}^{p_k}} + k^{3/4} |g| \|\vartheta_0\|_\infty \right)
$$

$$
\leq C \left( 2^{k^{1/2}} k^{3/4} h(t_k) \right)^{2/p_k} \left( \|\varpi_0\|_{L^\infty} + k^{3/4} |g| \|\vartheta_0\|_\infty \right)
$$

$$
\leq C h(0)^{1/2} k^{3/4} \left( \|\varpi_0\|_{L^\infty} + |g| \|\vartheta_0\|_\infty \right)
$$

Therefore we observe that for all large $k$

$$
\delta(t_k, p_k) \geq C \min \left\{ \left( \frac{1}{k^{3/4}} \right)^{(k+4)/(k+2)}, \frac{1}{k^{3/4}} \right\} \geq C \left( \frac{1}{k^{3/4}} \right)^{3/4}
$$

$$
(t_k = \sum_{j=0}^{k-1} \delta(t_j, p_j) \geq C k^{1/4},
$$

(5.16)

which contradicts the assumption $T < \infty$.

Hence we see that if $T < \infty$, there exists some integer $m$ such that

$$
\delta(t_m, p_m) \geq T - t_m, \quad (i.e., t_{m+1} \geq T),
$$

which and (5.12) yield

$$
(5.17) \quad h(t) \leq 2 h(t_k) \text{ for all } t \in [t_k, T).
$$

This implies the desired estimate (5.4) and proves Theorem 1.

**Remark.** Moreover, letting $T = \infty$, we have by (5.14) and (5.16)

$$
(5.18) \quad h(C k^{1/4}) \leq h(t_k) \leq 2^k h(0) \text{ for all } k = 1, 2, \ldots,
$$

which implies

$$
\| u(t) \|_\infty \leq C (\| u_0 \|_\infty + 1) \exp(C t^4)
$$

for all $t > 0$.

**REFERENCES**


L²-Lⁿ estimates of solution to the parabolic Maxwell equations and their application to the magnetohydrodynamic equations*

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1. Introduction and main results

Let Ω be a simply connected and unbounded domain in the three dimensional Euclidean space R³ whose boundary ∂Ω is a compact and sufficiently smooth hypersurface. Suppose that there is some R₀ > 0 such that ∂Ω ⊂ B₆₀(0) = {x ∈ R³ | |x| < R₀}. In this paper we are concerned with the initial boundary value problem of the magnetohydrodynamic equations in $\Omega \times (0, \infty)$ concerning the velocity vector field $v = (v₁(x,t), v₂(x,t), v₃(x,t))$, the magnetic vector potential $H = (H₁(x,t), H₂(x,t), H₃(x,t))$ and the scalar pressure $p = p(x,t)$:

\[
\begin{align*}
  v_t - \Delta v + (v \cdot \nabla)v + \nabla p + H \times \text{curl} H &= 0 \quad \text{in} \quad \Omega \times (0, \infty), \\
  H_t + \text{curl} \text{curl} H + (v \cdot \nabla)H - (H \cdot \nabla)v &= 0 \quad \text{in} \quad \Omega \times (0, \infty), \\
  \text{div} v &= 0, \quad \text{div} H = 0 \quad \text{in} \quad \Omega \times (0, \infty), \\
  v &= 0, \quad \text{curl} H \times v = 0, \quad \nu \cdot H = 0 \quad \text{on} \quad \partial \Omega \times (0, \infty), \\
  v(x,0) &= a, \quad H(x,0) = b \quad \text{in} \quad \Omega.
\end{align*}
\]

Here $a = (a₁(x), a₂(x), a₃(x))$ and $b = (b₁(x), b₂(x), b₃(x))$ are prescribed initial data and $\nu$ is the unit outward normal on $\partial \Omega$. We impose the perfectly conducting wall condition on the magnetic vector potential on the boundary. The perfectly conducting wall condition means that the obstacle, $R³ \setminus \overline{\Omega}$, is the perfect conductor body. The magnetohydrodynamic equations were proposed by Cowling [3] or Landau and Lifshitz

*This is joint work with Prof. Y. Shibata of Waseda University.
They are known to be one of the mathematical models describing the motion of viscous incompressible resistive fluid.

The main purpose of this paper is to show the global solvability of (MHD). The initial boundary value problem of the magnetohydrodynamic equations was treated in a bounded domain by the Galerkin method. However, in general the Galerkin method does not work well in the unbounded domain case. Thus we shall take another approach. On the other hand, there are some works in exterior domain. Zhao [17] considered (MHD) with nonperfect conductor body, that is the boundary condition of the magnetic vector potential is replaced by the homogeneous Dirichlet condition. However from a physical viewpoint, the case of the perfectly conducting wall is also important. The author knows only the result by Kozono [9] concerning the perfectly conducting wall case, where the weak solution was dealt with. There has been no work on the global strong solvability to the (MHD) in the exterior domain.

Our approach is based on the argument of T. Kato [8]. Kato proved the global solvability of the Cauchy problem of the Navier-Stokes equations in \( \mathbb{R}^N \) \((N \geq 2)\) with small initial velocity with respect to \(L^N\)-norm. The argument of Kato is based on the estimates of various \(L^q\)-norm of the Stokes semigroup. In particular \(L^q\)-type estimates play crucial role in it. The argument of Kato was extended to the case of exterior domain by Iwashita [7]. Our aim of this talk is to show the global solvability of (MHD), by use of the argument of Kato and Iwashita which is known to work well in exterior domain. In order to do this, one of the main points is to study the linearized problems corresponding to (MHD). They are consisted of two systems of equations. First is the system of well known nonstationary Stokes equations and second is the system of the Maxwell equations of parabolic type with perfectly conducting wall condition:

\[
\begin{cases}
  u_t + \text{curl} \text{curl} u = 0 & \text{in} \quad \Omega \times (0, \infty), \\
  \text{div} u = 0 & \text{in} \quad \Omega \times (0, \infty), \\
  \text{curl} u \times \nu = 0 & \text{on} \quad \partial \Omega \times (0, \infty), \\
  \nu \cdot u = 0 & \text{on} \quad \partial \Omega \times (0, \infty), \\
  u(x, 0) = b & \text{in} \quad \Omega.
\end{cases} \tag{PM}
\]

Here \(u = (u_1(x, t), u_2(x, t), u_3(x, t))\) is unknown vector valued function and \(b\) is a prescribed initial function. In order to derive good linear estimates, we have to study the parabolic Maxwell equations (PM). The parabolic Maxwell equations are important not only for (MHD) but also for another equations involving the Maxwell equations. For example, the time dependent Ginzburg-Landau-Maxwell superconductivity model and the magneto-micropolar fluid equations.

Before stating our main results we shall introduce some notations. Let \(1 < q < \infty\).
It is well known that the Banach space $L^q(\Omega)^3$ admits the Helmholtz decomposition:

$$L^q(\Omega)^3 = L^2_0(\Omega) \oplus G^q(\Omega), \quad \oplus: \text{direct sum.}$$

Here

$$L^2_0(\Omega) = \{ f \in C_0^\infty(\Omega)^3 \mid \text{div } f = 0 \text{ in } \Omega \},$$

$$G^q(\Omega) = \{ f \in L^q(\Omega)^3 \mid f = \nabla p \text{ for some } p \in L^q_{\text{loc}}(\Omega) \}.$$

By the assumption that $\partial \Omega$ is sufficiently smooth, the space $L^2_0(\Omega)$ is characterized as (see e.g., Galdi [6, Chapter 3])

$$L^2_0(\Omega) = \{ f \in L^q(\Omega)^3 \mid \text{div } f = 0 \text{ in } \Omega, \ \nu \cdot f = 0 \text{ on } \partial \Omega \}.$$

Let $P = P_{q,t}$ be a continuous projection from $L^q(\Omega)^3$ onto $L^2_0(\Omega)$ and let us define the operators $A$ and $B$ as follows:

$$\mathcal{D}(A) = L^2_0(\Omega) \cap W^{2,q}(\Omega)^3 \cap W^{1,q}_0(\Omega)^3,$$

$$Av = -P\Delta v \quad \text{for } v \in \mathcal{D}(A),$$

$$\mathcal{D}(B) = L^2_0(\Omega) \cap \{ H \in W^{2,q}(\Omega)^3 \mid \text{curl } H \times \nu = 0 \text{ on } \partial \Omega \},$$

$$BH = P(\text{curl curl } H) = \text{curl curl } H \quad \text{for } H \in \mathcal{D}(B).$$

From Akiyama, Kasai, Shibata and M. Tsutsumi [1], Borchers and Sohr [2] and Miyakawa [12, 13] both $-A$ and $-B$ generate bounded analytic semigroups $\{e^{-tA}\}$ and $\{e^{-tB}\}$ in $L^2_0(\Omega)$, respectively. By use of operators $A$ and $B$, (MHD) is converted into the following system of integral equations:

$$v(t) = e^{-tA}a - \int_0^t e^{-(t-\tau)A}P[(v(\tau) \cdot \nabla)v(\tau) + H(\tau) \times \text{curl } H(\tau)] \, d\tau,$$

$$H(t) = e^{-tB}b - \int_0^t e^{-(t-\tau)B}P[(v(\tau) \cdot \nabla)H(\tau) - (H(\tau) \cdot \nabla)v(\tau)] \, d\tau. \quad \text{(INT)}$$

In analyzing (INT) we require $L^q$-$L^r$ estimates for the semigroup $\{e^{-tA}\}$ and $\{e^{-tB}\}$. The first was already proved by Iwawita (see also Maremonti and Solonnikov [11] and Enomoto and Shibata [5]). Therefore we have to do is to derive $L^q$-$L^r$ estimates for the semigroup $\{e^{-tB}\}$.

We are now in a position to state our main results. The first result is concerned with the local energy decay property for the semigroup $\{e^{-tB}\}$. 

**Theorem 1.1** (Local energy decay). Let $1 < q < \infty$. For any $R > R_0$ and any integer $m \geq 0$, there exists $C = C(q, R, m) > 0$ such that

$$\| \partial_t^m e^{-tB} f \|_{W^{2,q}(\Omega_R)} \leq Ct^{-(3/2 + m)} \| f \|_{L^q(\Omega)}, \quad t \geq 1,$$

for any $f \in L^q_0(\Omega) \cap L^q_R(\Omega)$, where $\Omega_R = \Omega \cap B_R$ and $L^q_R(\Omega) = \{ u \in L^q(\Omega)^3 \mid u = 0 \text{ for } |x| \geq R \}$.
By use of Theorem 1.1, one can obtain the following $L^q-L^r$ estimates for $\{e^{-tB}\}$.

**Theorem 1.2** ($L^q-L^r$ estimates). 
(i) Let $1 \leq q \leq r \leq \infty$ and $(q,r) \neq (1,1), (\infty,\infty)$. Then there exists $C = C(q,r) > 0$ such that 
\[ \|e^{-tB}f\|_{L^r(\Omega)} \leq Ct^{-\frac{q(r-1)}{2}}\|f\|_{L^q(\Omega)}, \quad t > 0 \]
for any $f \in L^q_0(\Omega)$.
(ii) Let $1 < q \leq r \leq 3$. Then there exists $C = C(q,r) > 0$ such that 
\[ \|\nabla e^{-tB}f\|_{L^r(\Omega)} \leq Ct^{-\frac{q(r-1)}{2}}\|f\|_{L^q(\Omega)}, \quad t > 0 \]
for any $f \in L^q_0(\Omega)$.

The basic idea to prove Theorem 1.1 and Theorem 1.2 is similar to that of Iwashita [7] which deals with the nonstationary Stokes equations. However the boundary condition of (PM), perfectly conducting wall condition, is quite different from the boundary condition of the Stokes equations that is homogeneous Dirichlet condition, nonslip boundary condition. Therefore in constructing the parametrix of the resolvent problem corresponding to (PM) (see (2.1)), we have to introduce a new idea which is based on a theorem due to von Wahl [16, Theorem 3.2].

The following result by Iwashita is concerning the $L^q-L^r$ estimates for the Stokes semigroup, which is refined by Maremonti and Solonnikov and Enomoto and Shibata.

**Theorem 1.3** ([7, 11, 5]). 
(i) Let $1 \leq q \leq r \leq \infty$ and $(q,r) \neq (1,1), (\infty,\infty)$. Then there exists $C = C(q,r) > 0$ such that 
\[ \|e^{-tA}f\|_{L^r(\Omega)} \leq Ct^{-\frac{q(r-1)}{2}}\|f\|_{L^q(\Omega)}, \quad t > 0 \]
for any $f \in L^q_0(\Omega)$.
(ii) Let $1 < q \leq r \leq 3$. Then there exists $C = C(q,r) > 0$ such that 
\[ \|\nabla e^{-tA}f\|_{L^r(\Omega)} \leq Ct^{-\frac{q(r-1)}{2}}\|f\|_{L^q(\Omega)}, \quad t > 0 \]
for any $f \in L^q_0(\Omega)$.

Combining Theorem 1.2 and Theorem 1.3 we obtain the global solvability of (MHD) with small initial data.

**Theorem 1.4.** There exists a constant $\epsilon > 0$ such that if $(a,b) \in L^3_\sigma(\Omega) \times L^3_\sigma(\Omega)$ and $\|(a,b)\|_3 < \epsilon$, then a unique strong solution $(u,H)$ to (MHD) exists and satisfies the following properties:
\[ t^{(1-3/q)/2}(u,H) \in BC([0,\infty); L^q_\sigma(\Omega) \times L^q_\sigma(\Omega)) \quad \text{for any } q, \; 3 \leq q \leq \infty, \quad (1.1) \]
\[ t^{1/2}\nabla(u,H) \in BC([0,\infty); L^3(\Omega) \times L^3(\Omega)), \quad (1.2) \]
where $BC(\cdot)$ denotes the class of bounded continuous functions. All the values in (1.1)-(1.2) vanish at $t = 0$ except for $q = 3$ in (1.1), and in case $q = 3$, $(u(0), H(0)) = (a, b)$.

2. Sketch of the proof of Theorem 1.1

As stated in the previous section, in view of argument of Iwashita we know that once obtaining the local energy decay, by cut-off technique we have $L^q$-$L^{r}$ estimates. Therefore, in this section we will give a sketch of our proof of Theorem 1.1.

To prove Theorem 1.1 we have to study the resolvent problem corresponding to (PM). In view of Miyakawa [12], to do this it is suffices to study the following Laplace resolvent system with perfectly conducting wall condition:

\[
\begin{align*}
\{ & \lambda u - \Delta u = f \quad \text{in} \quad \Omega, \\
& \text{curl} \, u \times v = 0 \quad \text{on} \quad \partial \Omega, \\
& \nu \cdot u = 0 \quad \text{on} \quad \partial \Omega.
\end{align*}
\] (2.1)

Here $\lambda \in \Sigma_\epsilon = \{ \lambda \in C \setminus \{0\} \mid |\arg \lambda| < \pi - \epsilon, \ 0 < \epsilon < \pi/2 \}$ and $f = (f_1(x), f_2(x), f_3(x))$ is given function. Our aim of this section is to prove the following theorem.

Theorem 2.1. Let $1 < q < \infty$ and $m$ be a nonnegative integer. There exists solution operator $R(\lambda) \in B(W^{m,p}_R(\Omega), W^{m+2,p}(\Omega_R))$ such that $R(\lambda)$ depends on $\lambda \in \Sigma_\epsilon$ meromorphically and has the following properties:

(i) The set $\Lambda$ of the poles is discrete.

(ii) $u = R(\lambda)f$ is a solution of (2.1) for $\lambda \in \Sigma_\epsilon \setminus \Lambda$ and $f \in W^{m,p}_R(\Omega)$.

(iii) $R(\lambda) \in B(W^{m,p}_R(\Omega), W^{m+2,p}(\Omega_R))$ for each $\lambda \in \Sigma_\epsilon \setminus \Lambda$.

(iv) Let $\Sigma_\epsilon(\delta) = \{ \lambda \in \Sigma_\epsilon \mid |\lambda| < \delta \}$. There exists $\delta_0 > 0$ such that $\Sigma_\epsilon(\delta_0) \cap \Lambda = \emptyset$ and $R(\lambda)$ has the following expansion of $\lambda \in \Sigma_\epsilon(\delta_0)$ in $B(W^{m,p}_R(\Omega), W^{m+2,p}(\Omega_R))$:

\[
R(\lambda) = \lambda^{1/2}G_1 + G_2(\lambda) + \lambda^{1/2}G_3(\lambda). \tag{2.2}
\]

Here $G_1 \in B(W^{m,p}_R(\Omega), W^{m+2,p}(\Omega_R))$, $G_2(\lambda)$ is $B(W^{m,p}_R(\Omega), W^{m+2,p}(\Omega_R))$-valued holomorphic function of $\lambda \in \Sigma_\epsilon(\delta_0)$ and $G_3(\lambda)$ is bounded.

Here $W^{m,p}_R(\Omega) = \{ f \in W^{m,p}(\Omega) \mid f = 0 \ for \ |x| > R \}$.

In order to prove Theorem 2.1, first of all we construct the parametrix to (2.1). Choose a positive number $R > 0$ such that $R > R_0 + 3$. Here $R_0$ is introduced in the previous
section. Let $\Phi$ be a mapping of $f \in L^q(\Omega_{R+3})$ to unique solution $u \in W^{2,p}(\Omega_{R+3})$ of the following problem:

$$
\begin{aligned}
-\Delta u &= f \quad \text{in } \Omega_{R+3}, \\
\text{curl } u \times \nu &= 0 \quad \text{on } \partial \Omega_{R+3}, \\
\nu \cdot u &= 0 \quad \text{on } \partial \Omega_{R+3}.
\end{aligned}
$$

Then $\Phi \in B(L^q(\Omega_{R+3}), W^{2,q}(\Omega_{R+3}))$. Put $\varphi \in C_0^\infty(\mathbb{R}^3)$ such that $\varphi = 1$ for $|x| \leq R + 1$ and $= 0$ for $|x| \geq R + 2$. For $f \in L^q(\Omega)$, let $f_{R+3}$ be the restriction of $f$ to $\Omega_{R+3}$ and let $f_0$ be the zero extension of $f$ to $\mathbb{R}^3$, that is, $f_0 = f$ in $\Omega$ and $f_0 = 0$ in $\mathbb{R}^3 \setminus \Omega$. Let us define an operator $A(\lambda)$ by

$$
A(\lambda)f = (1 - \varphi)R_0(\lambda)f_0 + \varphi\Phi f_{R+3}.
$$

(2.3)

Here $R_0(\lambda)$ denotes the solution operator to $\lambda u - \Delta u = f$ in $\mathbb{R}^3$ (The properties of $R_0(\lambda)$ is stated in Murata [14]). For $A(\lambda)f$ we have

$$
\begin{aligned}
(\lambda - \Delta)A(\lambda)f &= f + S(\lambda)f \quad \text{in } \Omega, \\
\text{curl } (A(\lambda)f) \times \nu &= 0 \quad \text{on } \partial \Omega, \\
\nu \cdot (A(\lambda)f) &= 0 \quad \text{on } \partial \Omega,
\end{aligned}
$$

where

$$
S(\lambda)f = 2\nabla \varphi \cdot \nabla R_0(\lambda)f_0 + (\Delta \varphi)R_0(\lambda)f_0 + \lambda \varphi \Phi f_{R+3} - 2\nabla \varphi \cdot \nabla \Phi f_{R+3} - (\Delta \varphi)\Phi f_{R+3}
$$

From the definition of the cut-off function $\varphi$, supp $S(\lambda)f \subset \Omega_{R+3}$. If $f \in L^p_{R+2}(\Omega)$, then by the Fourier multiplier theorem and the property of $R_0(\lambda)$, we obtain

$$
\|R_0(\lambda)f_0\|_{W^{2,p}(\mathbb{R}^3)} \leq C\|f\|_{L^p(\Omega)}.
$$

**Lemma 2.2.** The inverse $(I + S(\lambda))^{-1}$ of $I + S(\lambda)$ exists as a $B(L^p_{R+2}(\Omega), L^p_{R+2}(\Omega))$-valued meromorphic function of $\lambda \in \Sigma_e$. The set $\Lambda$ of poles is discrete and has no intersection with $\Sigma_e(\delta_0)$ for some $\delta_0 > 0$. Furthermore, $(I + S(\lambda))^{-1}$ has the same type of expansion as (2.2).

This lemma will follow from the following lemma.

**Lemma 2.3.** $I + S(0)$ has the bounded inverse $(I + S(0))^{-1}$.

Before stating the proof of Lemma 2.3, we introduce the following uniqueness result which will be required in the proof of Lemma 2.3.
Proposition 2.4. Let $1 < q < \infty$. Suppose that $u \in W_{\text{loc}}^{2,q}(\Omega)$ satisfies

\begin{equation}
\begin{cases}
-\Delta u = 0 & \text{in } \Omega, \\
\text{curl } u \times \nu = 0 & \text{on } \partial \Omega, \\
\nu \cdot u = 0 & \text{on } \partial \Omega,
\end{cases}
\tag{2.4}
\end{equation}

and $u(x) = O(|x|^{-1})$, $\nabla u(x) = O(|x|^{-2})$. Then $u = 0$ in $\Omega$.

Remark 2.5. The assumption that $\Omega$ is simply connected is essentially required to prove Proposition 2.4 only.

Proof of Proposition 2.4. By virtue of the local theory for the elliptic equations, one can take $u \in W_{\text{loc}}^{2,r}(\Omega)$ for any $r \in (1,\infty)$. In particular, now we take $u \in W_{\text{loc}}^{2,2}(\Omega)$. We consider a function $\psi \in C^\infty_0(\mathbb{R}^3)$ with the properties $0 \leq \psi(x) \leq 1$, $\psi(x) = 1$ for $|x| \leq 1/2$ and $= 0$ for $|x| \geq 1$ and define $\psi_R(x) := \psi(x/R)$. According to the well known formula $\Delta u = \nabla \text{div } u - \text{curl } \text{curl } u$, the divergence theorem and the assumption we get

\begin{align*}
0 &= \int_{\Omega} -\Delta u \cdot \psi_R u \, dx = \int_{\Omega_R} \text{curl } u \cdot (\nabla \psi_R \times u) \, dx + \int_{\Omega_R} (\text{div } u)(\nabla \psi_R \cdot u) \, dx \\
&\quad + \int_{\Omega_R} \psi_R((\text{div } u)^2 + \text{curl } u \cdot \text{curl } u) \, dx.
\end{align*}

Since $\text{supp } \psi_R \subset \{ x \in \mathbb{R}^3 \mid R/2 < |x| < R \}$, we have

\begin{equation}
\left| \int_{\Omega_R} \text{curl } u \cdot (\nabla \psi_R \times u) \, dx + \int_{\Omega_R} (\text{div } u)(\nabla \psi_R \cdot u) \, dx \right| \leq \frac{C}{R}.
\end{equation}

Therefore letting $R \to \infty$, we have $\| \text{curl } u \|_{L_2(\Omega)}^2 + \| \text{div } u \|_{L_2(\Omega)}^2 = 0$. This implies that $\text{curl } u = 0$ and $\text{div } u = 0$ in $\Omega$ and moreover by virtue of theorem due to von Wahl [16], we obtain $\nabla u = 0$. Hence $u = \text{const}$ in $\Omega$. From the assumption that $u$ satisfies $\nu \cdot u = 0$ on $\partial \Omega$, we have $u = 0$ in $\Omega$ in $\Omega$. This completes the proof.

Now we shall show Lemma 2.3.

Proof of Lemma 2.3. Since the operator $S(0)$ is compact, by the Fredholm alternative theorem it suffices to show injectivity of $I + S(0)$. Let us pick up $f \in L_{R+2}^p(\Omega)$ so that $(I + S(0))f = 0$. Then it follows from (2.3), $A(0)f$ satisfies (2.4) and moreover $A(0)f$ has the properties that $A(0)f = O(|x|^{-1})$ and $\nabla (A(0)f) = O(|x|^{-2})$. Therefore from Proposition 2.4, $A(0)f = 0$. Namely we have

\begin{equation}
(1 - \varphi)R_0(0)f_0 + \varphi \Phi f_{R+3} = 0 \quad \text{in } \Omega.
\end{equation}
By the definition of the cut-off function \( \varphi \) we have \( \Phi f_{R+3} = 0 \) for \( |x| \leq R + 1 \) and \( R_0(0)f_0 = 0 \) for \( |x| \geq R + 2 \). Put \( w = \Phi f_{R+3} \) for \( x \in \Omega_{R+3} \) and \( = 0 \) for \( x \notin \Omega \). Then \( w \) satisfies

\[
\begin{aligned}
-\Delta w &= f_0 \quad \text{in} \quad B_{R+3}, \\
curl w \times \nu &= 0 \quad \text{on} \quad \partial B_{R+3}, \\
\nu \cdot w &= 0 \quad \text{on} \quad \partial B_{R+3}
\end{aligned}
\]

On the other hand, from \( R(0)f_0 = 0 \) for \( |x| \geq R + 2 \), we also have

\[
\begin{aligned}
-\Delta R_0(0)f_0 &= f_0 \quad \text{in} \quad B_{R+3}, \\
curl (R_0(0)f_0) \times \nu &= 0 \quad \text{on} \quad \partial B_{R+3}, \\
\nu \cdot (R_0(0)f_0) &= 0 \quad \text{on} \quad \partial B_{R+3}
\end{aligned}
\]

Hence we obtain \( w = R_0(0)f_0 \) in \( \Omega_{R+3} \). Therefore

\[
0 = A(0)f = R_0(0)f_0 + \varphi(\Phi f_{R+3} - R_0(0)f_0) = R_0(0)f_0.
\]

This implies \( f_0 = 0 \) in \( \Omega \).

**Proof of Lemma 2.2.** Let \( M = \| (I + S(\lambda))^{-1} \| \), where \( \| \cdot \| \) denotes the operator norm. From the fact that \( S(\lambda) \) is continuous in \( \Sigma_\varepsilon \cup \{0\} \), there is some \( \delta_0 > 0 \) such that \( \| S(\lambda) - S(0) \| < 1/2M \) for any \( \lambda \in \Sigma_\varepsilon(\delta_0) \). Hence, for \( \lambda \in \Sigma_\varepsilon(\delta_0) \),

\[
(I + S(\lambda))^{-1} = \sum_{j=1}^{\infty} [(I + S(0))^{-1}(S(0) - S(\lambda))]^j (I + S(0))^{-1}. \tag{2.5}
\]

Since \( S(\lambda) \) is holomorphic in \( \lambda \in \Sigma_\varepsilon \), by analytic Fredholm's alternative theorem (see e.g., Dunford and Schwartz [4, p. 592, Lemma 13]) we obtain \( (I + S(\lambda))^{-1} \) for any \( \lambda \in \Sigma_\varepsilon \) as a meromorphic function and we see that the set \( \Lambda \) of poles is discrete in \( \Sigma_\varepsilon \). The expansion of \( (I + S(\lambda))^{-1} \) follows from that of the expansion of \( R_0(\lambda) \), Lemma 2.3 and (2.5).

With help of above results, we prove Theorem 2.1.

**Proof of Theorem 2.1.** Define \( R(\lambda) \) by

\[
R(\lambda) = A(\lambda)(I + S(\lambda))^{-1}. \tag{2.6}
\]

Then the assertions are immediately derived from the expansion of \( R_0(\lambda) \), Lemma 2.2 and (2.6).
In the rest of this paper, we shall state the strategy of the proof of Theorem 1.1. Let \(0 < \epsilon < \epsilon_1 < \pi/2\) and let \(\gamma\) be a contour as follows: \(\gamma = \gamma_1 \cup \gamma_2\), where
\[
\gamma_1 = \{\lambda \in \mathbb{C} | 0 < |\lambda| \leq \delta_0/2, |\arg \lambda| = \pi - \epsilon_1\}, \\
\gamma_2 = \{\lambda \in \mathbb{C} | |\lambda| > \delta_0/2, |\arg \lambda| = \pi - \epsilon_1\}.
\]
According to Theorem 2.1, the semigroup \(e^{-tB}\) is represented as
\[
e^{-tB} = \frac{1}{2\pi i} \int_{\eta_1} \epsilon^M R(\lambda) d\lambda + \frac{1}{2\pi i} \int_{\eta_2} \epsilon^M (\lambda + B)^{-1} d\lambda,
\]
in \(L^2_0(\Omega) \cap L^{2}_{R+2}(\Omega)\). To prove Theorem 1.1, we introduce the following well known lemma concerning the gamma function \(\Gamma(\sigma)\).

**Lemma 2.6.** For \(\sigma > 0\) and \(t > 0\), it holds that
\[
\left| \frac{1}{2\pi i} \int_{\eta_1} \epsilon^M \lambda^{\sigma-1} d\lambda - \frac{\sin \sigma \pi}{\pi} \Gamma(\sigma) t^{-\sigma} \right| \leq Ce^{-\alpha t}.
\]

Finally combining Theorem 2.1 and Lemma 2.6, we have the local energy decay property of the semigroup \(e^{-tB}\), Theorem 1.1.

**References**


BLOW-UP OF SOLUTIONS OF QUASILINEAR PARABOLIC EQUATIONS WITH LOCALIZED REACTIONS

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Let $R > 0$ and

$$B = \{ x \in \mathbb{R}^N \mid |x| < R \}.$$  

We shall consider the initial boundary value problem for the quasilinear parabolic equation with both a nonlocal source (localized reaction) $bu^q(x_0,t)$ and a local source $au^p$, 

$$u_t = \Delta u^m + au^p + bu^q(x_0,t), \quad (x,t) \in B \times (0,T),$$

$$u(x,t) = 0, \quad (x,t) \in \partial B \times (0,T),$$

$$u(x,0) = u_0(x), \quad x \in B,$$

where $u_t = \partial u / \partial t$, $\Delta$ is the $N$-dimensional Laplacian, $p, q \geq 1, a, b > 0$, $x_0 \in B$ and $u_0(x) \geq 0$ in $B$. We assume that $u_0(x) = u_0(r) \in C(B) \ (r = |x|)$ is a radially symmetric function in $x \in B$ and a non-increasing function in $r \geq 0$, and $u_0(R) = 0$.

We shall only consider non-negative weak solutions $u = u(x,t)$.

Under these conditions, a non-negative weak solution of (2)-(4) exists locally in time (See [4] and [10] for $m = 1$ and [12] for $m \geq 1$). When $m = 1$, non-negative solutions of (2)-(4) are unique (See [3] and [10]). When $m > 1$, we do not know whether or not non-negative solutions of (2)-(4) are unique (But, when $b = 0$, the uniqueness of solutions can be proved [1]).

Moreover, we see that the solution $u(x,t)$ blows up in finite time for large initial data (see [3], [10] ($m = 1$) and [12] ($m > 1$) for $a = 0$ and see e.g. [7] for $b = 0$).
Namely, for some $T \in (0, \infty)$,

$$
\lim_{t \uparrow T} \|u(\cdot, t)\|_{L^\infty(B)} = \infty.
$$

We say this time $T$ the blow-up time.

We are interested in the shape of the blow-up set $S$ of a blow-up solution of (2)-(4):

$$
S = \{ x \in \bar{B} \mid \text{there exists a sequence } (x_m, t_m) \in B \times (0, T) \text{ satisfying } x_m \to x, t_m \uparrow T \text{ and } u(x_m, t_m) \to \infty \text{ as } m \to \infty \}.
$$

Each $x$ in $S$ is called "a blow-up point" of $u$.

When $a = 0$, we see that the blow-up solution of (2)-(4) blows up in whole domain $B$ (See [2, 3, 10] for $m = 1$ and [12] for $m > 1$). Namely, $S = \bar{B}$.

We call this phenomena "total blow-up".

On the other hand, when $b = 0$, it is well known that if $u(x, t)$ is non-decreasing in $t \geq 0$ (When $m = 1$, this assumption is not required), the blow-up solution goes to infinity only at the origin (see [13] [5] [6] for $m = 1$ and [8] for $m > 1$). Namely, $S = \{0\}$.

We call this blow-up phenomena "single point blow-up".

So, we consider the initial boundary value problem (2)-(4) with $a, b > 0$. Then, we are interested in the problem whether total blow-up or single point blow-up occurs according to the relations of the values of $p$ and $q$.

On this problem, when $m = 1$ Okada-Fukuda [9] obtain the interesting results: When $x_0 = 0$,

(1) Let $p > q+1$. Let $\Phi(x)$ be an eigenfunction corresponding to the first eigenvalue of $-\Delta$ with zero Dirichlet condition. If for some $\mu > 0$

$$
\Delta u_0 + u_0^p + u^q(x_0) \geq \mu \Phi
$$

then the blow-up solution of (2)-(4) blows up only at the origin, namely, $S = \{0\}$;

(II) Let $p \leq q+1$. then the blow-up solution blows up in whole domain $B$, namely, $S = B$;

When $x_0 \neq 0$,
(I) Let $p > q + 1$. If (9) holds then the blow-up solution of (2)-(4) blows up only at the origin, namely, $S = \{0\}$;

(II) Let $p < q$. Let $|x_0| < r_1 < R$ and $0 < \varepsilon_0 < 1$. If

\begin{equation}
\frac{\partial u}{\partial t} \geq 0 \quad \text{in } B \times (0, T)
\end{equation}

and

\begin{equation}
u_0(r_1) \geq \varepsilon_0 u_0(0) \quad \text{and } u_0(0) \text{ is large enough,}
\end{equation}

then the solution of (2)-(4) blows up in whole domain $B$, namely, $S = \bar{B}$.

Thus, when $m = 1$, in the case $x_0 = 0$, they showed that $p = q + 1$ is the cut off "straight line" between the cases where single point blow-up occurs and single point blow-up does not occurs. But, in the case $x_0 \neq 0$, they can not see clearly which blow-up phenomena occurs or not, especially, when $p - 1 \leq q \leq p$.

So, the main purpose of this paper is to solve these problems completely in the case $x_0 \neq 0$ and to extend these results to the case $m \geq 1$. We summarize our results as follows:

**Theorem 1.** Assume $a, b > 0$ and $p, q > m \geq 1$.

(I) Assume $p > q$. If $u(x, t)$ is non-decreasing in $t \geq 0$ for each $x \in B$ then the blow-up solution of (2)-(4) blows up only at the origin, that is, $S = \{0\}$;

(II) Assume $p < q$.

(i) If (11) holds then the solution of (2)-(4) blows up in whole domain $B$, that is, $S = \bar{B}$.

(ii) There exists a solution of (2)-(4) such that it blows up only at the origin, that is, $S = \{0\}$.

**Remark 2.** When $m = 1$, in (I) of Theorem 1 we do not need the assumption that $u(x, t)$ is non-decreasing in $t \geq 0$ for each $x \in B$.

**Remark 3.** There exists a solution $u(x, t)$ of (2)-(4) such that it is non-decreasing in $t \geq 0$ for each $x \in B$, if the inequality

\begin{equation}
\Delta u_0^m + u_0^p + u_0^2(x_0) \geq 0 \quad \text{in } B
\end{equation}
holds in the next sense: For any bounded domain $D \subset B$ with smooth boundary $\partial D$, and nonnegative $\varphi(x) \in C^2(D)$ which vanishes on the boundary $\partial D$,

\[
\int_D \left\{ u_0^m \Delta \varphi + u_0^p \varphi + u_0^q(x_0) \varphi \right\} dx - \int_{\partial D} u_0 \partial_n \varphi dS \geq 0
\]

where $n$ denotes the outer unit normal to the boundary.

Namely, in the case where $m = 1$ and $x_0 \neq 0$, we see that $p = q$ is the cut off "straight line" between the cases where single point blow-up occurs and single point blow-up does not occur. This result seems to be very interesting, since the cut off "straight lines" are different between the cases $x_0 \neq 0$ and $x_0 = 0$, when $m = 1$.

**Remark 4.** We can not get any result in the case where $p = q$.

**Remark 5.** If $p, q < m$ then the solution of (2)-(4) exists globally in time [12].

Thus, we completely solve the open problem when $x_0 \neq 0$ in Okada-Fukuda [9], except for the case $p = q$. We note that even if $m = 1$ (semilinear case), the results of the existence of single point blow-up solutions where $p < q$ are new. It seems to be interesting that the problem has both a single point blow-up solution and a total blow-up solution by only choosing initial data $u_0$ as in (II), since the other problems do not have such phenomena.

Our methods which are based on the maximum principle, are essentially due to Fujita-Chen [6] for the proof of (I) of Theorem 1 and due to Okada-Fukuda [9] for the proof of (i) of (I) in Theorem 1. But, we can not apply their methods directly, since our equation is degenerate at $u = 0$ and some of our results are refinements of their results.

Finally, we mention the existence, uniqueness and (total) blow-up of local solutions of (2)-(4) more in detail.

The existence of local solutions of (2)-(4) was shown by Cannon-Yin [4] when $m = 1$. Souplet [10] extended their results to more general form which contain various nonlocal problems. But, in quasilinear case $m > 1$ there are few papers studying these problems and we show the existence of local solutions of (2)-(4) in the quasilinear case in [12].

The uniqueness of local solutions was studied by Chadam-Pierce-Yin [3] and Souplet [10] (for more general equations) when $m = 1$. When $m > 1$ and $b = 0$, the
uniqueness of local solutions was studied by Aronson-Crandall-Peletier [1]. When $m > 1$ and $b > 0$, however, there are few papers studying the uniqueness of solutions and we cannot show it. So, our discussions are derived without using the uniqueness of local solutions of (2) when $m > 1$.

The existence of blow-up solutions of (2)-(4) was also shown in [3] and [10] in the case $m = 1$. It was shown in [3] that if initial data $u_0(x)$ is large enough in the neighborhood of fixed $x_0$, then the solution of (2)-(4) blows up in finite time. The results from [3] was extended in [10] to moving $x_0 = x_0(t)$. We note that in [10] the assumptions that initial data $u_0(x)$ is large enough in the neighborhood of $x_0$ is not required. In [12] we also obtain the blow-up results which are the extensions of [10] to $m > 1$.

Further, when $m = 1$ and $a = 0$, it was also shown in [3] (see also [11]) that the blow-up solution of (2)-(4) blows up in whole domain $B$. In [12] we extend the results from [3] and [11] to quasilinear case $m > 1$.

References


Initial Behavior of Solutions of Diffusion Equations and Symmetries of Domains

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1 Introduction

This is based on the author's recent work with R. Magnanini. We study the relation between the initial behavior of solutions of diffusion equations and symmetries of domains. We deal with the porous medium equation and the heat equation.

Concerning the porous medium equation, we consider the flow of a gas into a bounded porous container $\Omega$ with smooth boundary $\partial\Omega$. Initially $\Omega$ is empty and at all times the density of the gas is kept constant on $\partial\Omega$. Choose a number $R > 0$ sufficiently small to have that, for any point $x$ in $\Omega$ having distance $R$ from $\partial\Omega$, the closed ball $B$ with radius $R$ centered at $x$ intersects $\partial\Omega$ only at one point. We show that if the gas content of all such balls $B$ is constant at each given time, then $\Omega$ must be a ball.

Concerning the heat equation, we consider a convex and polygonal heat conductor $\Omega$ whose inscribed circle touches every side of $\partial\Omega$. Initially $\Omega$ has zero temperature and at all times the temperature is kept constant on $\partial\Omega$. The cold spot is the point at which the temperature attains its minimum at each given time. It is proved that, if the cold spot is stationary, then $\Omega$ must satisfy two geometric conditions. In particular, we show that these geometric conditions yield some symmetries provided $\Omega$ is either pentagonal or hexagonal.

First, we consider the porous medium equation. Let $\Omega$ be a bounded domain in $\mathbb{R}^N$, $N \geq 2$, with smooth boundary $\partial\Omega$. The physical situation can be modeled as the following initial-boundary value problem for the porous medium equation:

\begin{align*}
  u_t &= \Delta u^m & \text{in } \Omega \times (0, \infty), & (1.1) \\
  u &= 1 & \text{on } \partial\Omega \times (0, \infty), & (1.2) \\
  u &= 0 & \text{on } \Omega \times \{0\}, & (1.3)
\end{align*}
where $u = u(x, t)$ denotes the normalized density of the gas at a point $x \in \Omega$ and at a time $t > 0$, and $m > 1$ is a constant. Existence and uniqueness of the weak solution are guaranteed by the standard theory for the porous medium equation. Since the diffusivity $mu^{m-1}$ vanishes with $u$, an important feature of the solution is that the flow propagates disturbance from rest with finite speed. See [Ar]. Therefore, it is known that for any point $x \in \Omega$ there exists a time $T(x) > 0$ satisfying

$$
\begin{cases}
  u(x, t) = 0 & \text{for all } t \in [0, T(x)], \\
  u(x, t) > 0 & \text{for all } t \in (T(x), \infty).
\end{cases}
$$

(1.4)

For any point $x \in \overline{\Omega}$, define the function $d = d(x)$ by

$$
d(x) = \inf \{|x - y| : y \in \partial \Omega\}.
$$

(1.5)

This function $d(x)$ denotes the distance between $x$ and $\partial \Omega$. For each $\rho > 0$, set

$$
\Omega_\rho = \{x \in \Omega : d(x) < \rho\}.
$$

(1.6)

Since $\partial \Omega$ is smooth and compact, there exists a number $\delta > 0$ such that

$$
\forall x \in \Omega_\delta \exists y = y(x) \in \partial \Omega \text{ with } d(x) = |x - y(x)|; \\
\max_{1 \leq j \leq N-1} \kappa_j(y) < \frac{1}{\delta} \text{ for any } y \in \partial \Omega,
$$

(1.7)

(1.8)

where $\kappa_1(y), \ldots, \kappa_{N-1}(y)$ denote the principal curvatures of $\partial \Omega$ at $y \in \partial \Omega$ with respect to the interior normal direction to $\Omega$. Let us quote a theorem from C. Cortázar, M. Del Pino, and M. Elgueta [CDE] (see Theorem 1.1, p. 134).

**Theorem 1.1** ([CDE]) There exists a number $\varepsilon_0 > 0$ such that for any $x \in \Omega_{\varepsilon_0}$

$$
T(x) = d^2 \{T_0 - H(y(x))T_1d + o(d)\}, \quad d = d(x),
$$

(1.9)

where $T_0$, $T_1$ are positive constants depending only on $m$, and $H(y(x)) = \sum_{j=1}^{N-1} \kappa_j(y(x))$.

Combining this theorem with Aleksandrov’s sphere theorem (see Theorem 3.1) yield

**Corollary 1.2** Suppose that there exists a number $\rho > 0$ such that, for any pair of points $x, z \in \Omega_\rho$, $d(x) = d(z)$ implies $T(x) = T(z)$. Then $\Omega$ must be a ball.
One purpose of this talk is to report another sphere theorem. Take a number $R > 0$ with $0 < R < \delta$, where $\delta$ is the number given in (1.7) and (1.8). Set
\[ \Gamma_R = \{ x \in \Omega : d(x) = R \}. \] (1.10)
Then we have from (1.7)
\[ \overline{B_R(x)} \cap \partial \Omega = \{ y(x) \} \quad \text{for any } x \in \Gamma_R, \] (1.11)
where $B_R(x)$ denotes an open ball in $\mathbb{R}^N$ centered at $x$ and with radius $R$.

Our sphere theorem is the following.

**Theorem 1.3** Suppose that there exists a function $a : (0, \infty) \rightarrow (0, \infty)$ satisfying
\[ \int_{B_R(x)} u(z, t) \, dz = a(t) \quad \text{for any } x \in \Gamma_R \text{ and for any } t > 0. \] (1.12)
Then $\Omega$ must be a ball.

This theorem is shown by combining the following lemma with Aleksandrov's sphere theorem.

**Lemma 1.4** For any $x \in \Gamma_R$, as $t \rightarrow +0$
\[ t^{-\frac{N+1}{4}} \int_{B_R(x)} u(z, t) \, dz \rightarrow c(m, N) \left\{ \prod_{j=1}^{N-1} \left( \frac{1}{R} - \kappa_j(y(x)) \right) \right\}^{-\frac{1}{2}}, \] (1.13)
where $c(m, N)$ is a positive constant depending only on $m$ and $N$, and $y(x) \in \partial \Omega$ is a point given in (1.7).

Next, let us consider the heat equation. Let $\Omega$ be a bounded convex domain in $\mathbb{R}^N$. The physical situation can be modeled as the following initial-boundary value problem for the heat equation:
\[ u_t = \Delta u \quad \text{in} \quad \Omega \times (0, \infty), \] (1.14)
\[ u = 1 \quad \text{on} \quad \partial \Omega \times (0, \infty), \] (1.15)
\[ u = 0 \quad \text{on} \quad \Omega \times \{0\}, \] (1.16)
where $u = u(x, t)$ denotes the normalized temperature at a point $x \in \Omega$ and at a time $t > 0$. Since $\Omega$ is convex, a result of [BL] shows that $\log(1 - u(x, t))$ is concave in $x$, which, together with the analyticity of $u$ in $x$, implies that for each time $t > 0$ there exists a unique point $x(t) \in \Omega$ satisfying
\[ \{ x \in \Omega : \nabla u(x, t) = 0 \} = \{ x(t) \}. \] (1.17)
The point $x(t)$ is the unique cold spot for each time $t > 0$. Put $I = \{x \in \Omega : d(x) = \max_{y \in \Omega} d(y)\}$, where $d$ is the function defined by (1.5). Then, we have

$$\text{dist}(x(t), I) \to 0 \quad \text{as} \quad t \to +0,$$

since the function $-4t \log u(x, t)$ attains its maximum at $x = x(t)$ for each $t > 0$ and a result of Varadhan [V] shows that

$$-4t \log u(x, t) \to d(x)^2 \quad \text{as} \quad t \to +0 \quad \text{uniformly on} \quad \overline{\Omega}. \quad (1.19)$$

In conclusion, the cold spot $x(t)$ starts from $I$. Also, as $t \to \infty$, $x(t)$ tends to the point at which a positive first eigenfunction of $-\Delta$ with the homogeneous Dirichlet boundary condition attains its maximum. There was a conjecture of Klamkin concerning the behavior of the cold spot. For simplicity, let $\Omega$ contain the origin. The conjecture of Klamkin [KL] stated that if the origin is a stationary cold spot, that is, if $x(t) \equiv 0$, then $\Omega$ must be centro-symmetric with respect to the origin. This was denied by Gulliver-Willms [GW] and Kawohl [Ka]. A typical counterexample is an equilateral triangle in the plane. After that Chamberland-Siegel [CS] posed the following conjecture.

**Conjecture 1.5 (Chamberland-Siegel)** If the origin is a stationary cold spot in a bounded convex domain $\Omega$, then $\Omega$ is invariant under the action of an essential subgroup $G$ of orthogonal transformations.

A subgroup $G$ is said to be essential if, for every $x \neq 0$, there exists an element $g \in G$ such that $gx \neq x$. Of course, the condition that $\Omega$ is invariant under the action of an essential subgroup $G$ of orthogonal transformations is a sufficient condition for the origin being a stationary cold spot. Indeed, if $\Omega$ is invariant under the action of an essential subgroup $G$ of orthogonal transformations, then by the unique solvability of the initial-Dirichlet problem (1.14)-(1.16) the solution $u$ itself is invariant under the action of $G$. Namely, we have $u(x, t) = u(gx, t)$ ($x \in \Omega, \ t > 0, \ g \in G$). This, together with the assumption that $G$ is essential, implies that $\nabla u(0, t) = 0$ ($t > 0$), and then it follows from (1.17) that the origin is a stationary cold spot.

Our previous results to Conjecture 1.5 is

**Theorem 1.6 ([MS 4])** When $N = 2$, the following hold true.

1. If $\Omega$ is a triangle and the origin is a stationary cold spot, then $\Omega$ must be an equilateral triangle centered at the origin.

2. If $\Omega$ is a convex quadrangle and the origin is a stationary cold spot, then $\Omega$ must be a parallelogram centered at the origin.
If \( \Omega \) is a non-convex quadrangle, then there is no stationary critical point of \( u \) in \( \Omega \). In particular, there is no stationary cold spot.

In (1) of Theorem 1.6, \( G \) is the cyclic group generated by the rotation of the angle \( \frac{2\pi}{3} \), and in (2) \( G = \{ I, -I \} \) where \( I \) is the identity mapping. The proof is based on two ingredients; one is the balance law around stationary critical points of the heat flow (see Theorem 3.2 (ii)) and the other is making use of the asymptotic behavior as \( t \to +0 \) of solutions of the heat equation due to Varadhan [V].

Another purpose of this talk is to report the following results.

**Theorem 1.7** Let \( N = 2 \) and suppose that \( \Omega \) is a convex polygon whose inscribed circle touches every side of \( \partial \Omega \). Then the following hold true.

1. If \( \Omega \) is a pentagon and the origin is a stationary cold spot, then \( \Omega \) must be a regular pentagon centered at the origin.

2. If \( \Omega \) is a hexagon and the origin is a stationary cold spot, then \( \Omega \) is invariant under the action of the rotation of one of angles \( \frac{\pi}{3}, \pi, \frac{2\pi}{3} \).

This theorem is shown by the following general result.

**Theorem 1.8** Let \( N = 2 \) and let \( \Omega \) be a convex \( m \)-polygon with \( m \geq 5 \). Suppose that the origin is a stationary cold spot and the sphere \( \partial B_R(0) \) touches every side of \( \partial \Omega \), say \( \partial \Omega \cap \partial B_R(0) = \{ p_1, \ldots, p_m \} \). Let \( q_1, \ldots, q_k \) (\( 1 \leq k \leq m \)) be the nearest \( k \) corners of \( \partial \Omega \) to the origin. Then the following hold.

\[
\sum_{j=1}^{m} p_j = 0 \quad \text{and} \quad \sum_{j=1}^{k} q_j = 0. \tag{1.20}
\]

The first equation of (1.20) follows directly from Theorem 3.2 (ii), and the second equation of (1.20) is new.

### 2 Outlines of proofs

**Proof of Lemma 1.4 (an outline)**: In [CDE], for sufficiently short time interval \((0, t_0)\) a subsolution and a supersolution for problem (1.1)-(1.3) were constructed. We use these to know that there exist a number \( \xi_0 > 0 \) and a nonnegative function \( F = F(\xi) (\xi \geq 0) \) satisfying \( F(0) = 1 \) and \( F(\xi) = 0 \) for \( \xi \geq \xi_0 \) such that for sufficiently small \( t > 0 \) an approximate formula

\[
u(x,t) \sim F\left(\frac{d(x)}{\sqrt{t}}\right) \tag{2.1}
\]
holds true, roughly speaking. For any \( x_0 \in \Gamma_R \) and for any \( t \in (0, t_0) \) we have from the coarea formula

\[
\int_{B_R(x_0)} F \left( \frac{d(x)}{\sqrt{t}} \right) \, dx = \int_0^{2R} F \left( \frac{s}{\sqrt{t}} \right) \left\{ \int_{\Gamma_s \cap B_R(x_0)} dS_x \right\} \, ds, \tag{2.2}
\]

where \( \Gamma_s \) is given as in (1.10) and \( dS_x \) denotes the area element of \( \Gamma_s \). We calculate

\[
\lim_{s \to 0} s^{-\frac{N-1}{2}} \int_{\Gamma_s \cap B_R(x_0)} dS_x = 2^{N-1} \omega_{N-1} \left\{ \prod_{j=1}^{N-1} \left( \frac{1}{R} - \kappa_j(y(x_0)) \right) \right\}^{-\frac{1}{2}}, \tag{2.3}
\]

where \( \omega_{N-1} \) denotes the volume of unit ball in \( \mathbb{R}^{N-1} \). Hence

\[
\int_{B_R(x_0)} F \left( \frac{d(x)}{\sqrt{t}} \right) \, dx = \int_0^{2R} F \left( \frac{s}{\sqrt{t}} \right) s^{-\frac{N-1}{2}} \int_{\Gamma_s \cap B_R(x_0)} dS_x \, ds
\]

\[
= t^{\frac{N+1}{4}} \int_0^{\frac{2R}{\sqrt{t}}} F(\xi) \xi^{-\frac{N+1}{2}} \left\{ (\sqrt{t} \xi)^{-\frac{N-1}{2}} \int_{\Gamma_{\sqrt{t} \xi} \cap B_R(x_0)} dS_x \right\} d\xi.
\]

Therefore, with the aid of the Lebesgue's dominated convergence theorem, from (2.3) we see that as \( t \to +0 \)

\[
t^{-\frac{N+1}{4}} \int_{B_R(x_0)} F \left( \frac{d(x)}{\sqrt{t}} \right) \, dx \to c(m, N) \left\{ \prod_{j=1}^{N-1} \left( \frac{1}{R} - \kappa_j(y(x_0)) \right) \right\}^{-\frac{1}{2}},
\]

where \( c(m, N) \) is a positive constant depending only on \( m \) and \( N \). This, together with (2.1), gives the formula (1.13).

**Proof of Theorem 1.8 (an outline):** We introduce a subsolution \( u^- = u^-(x, t) \) and a supersolution \( u^+ = u^+(x, t) \) for problem (1.14)-(1.16). Denote by \( \nu_1, \ldots, \nu_m \) the interior normal unit vectors to \( \partial \Omega \) at the points \( p_1, \ldots, p_m \), respectively. Define the function \( f = f(\xi) \) by

\[
f(\xi) = \frac{1}{\sqrt{\pi}} \int_\xi^\infty e^{-\frac{1}{2} s^2} \, ds \quad \text{for all } \xi \in \mathbb{R}. \tag{2.4}
\]

Hence \( u^- \) and \( u^+ \) are given by

\[
u^-(x, t) = \max_{1 \leq j \leq m} f \left( \frac{(x - p_j) \cdot \nu_j}{\sqrt{t}} \right), \tag{2.5}
\]

\[
u^+(x, t) = \sum_{j=1}^m f \left( \frac{(x - p_j) \cdot \nu_j}{\sqrt{t}} \right). \tag{2.6}
\]
Then it follows from the comparison principle that
\[ u^- \leq u \leq u^+ \text{ in } \Omega \times (0, \infty). \] (2.7)
Let \( R^* = |q_1| (= |q_2| = \cdots = |q_k|) \). Then \( R^* > R \). By using the fact that \( \Omega \) is a convex polygon, with a reflection argument we can extend the solution \( u \) to a solution \( u^* = u^*(x, t) \) of the heat equation in a larger domain \( \Omega^* \times (0, \infty) \supseteq \Omega \times (0, \infty) \), where \( B_{R^*}(0) \subset \Omega^* \). Since the origin is a stationary cold spot, we see that the origin is a stationary critical point of \( u^* \). Therefore, by using Theorem 3.2 (ii), we get
\[ \int_{B_{R^*}(0)} xu^*(x, t) \, dx = 0 \text{ for any } t > 0. \] (2.8)
Letting \( t \to +0 \) yields
\[ 2 \int_{B_{R^*}(0) \setminus \Omega} x \, dx = 0, \] (2.9)
which implies the first equation of (1.20).

Denote by \( \mathcal{R} \) the region obtained by reflecting \( B_{R^*}(0) \setminus \overline{\Omega} \) with respect to each side of \( \partial \Omega \), and put \( E = (B_{R^*}(0) \cap \Omega) \setminus \mathcal{R} \). Note that \( \mathcal{R} \subset \Omega \) and \( E \subset \Omega \). Denote by \( x^* \) the reflection of the point \( x \) with respect to each side of \( \partial \Omega \). Then \( u^*(x, t) \equiv 2 - u^*(x^*, t) \) because of (1.15). Therefore it follows from (2.9) that for any \( t > 0 \)
\[ 0 = \int_{B_{R^*}(0)} xu^*(x, t) \, dx = \int_{E} xu(x, t) \, dx + \int_{\mathcal{R}} (x - x^*)u(x, t) \, dx. \] (2.10)
Then, with the help of (2.7), we investigate the limit
\[ \lim_{t \to +0} \frac{1}{t} \left\{ \text{the right-hand side of (2.10)} \right\}, \]
and by using the first equation of (1.20), we see that the second equation of (1.20) holds true.

3 Appendices and Remarks

1. We quote Aleksandrov's sphere theorem from [Alek].

**Theorem 3.1 (Aleksandrov)** Let \( N \geq 3 \), and let \( \Phi = \Phi(\kappa_1, \cdots, \kappa_{N-1}) \) be a \( C^1 \) function defined for \( \kappa_1 \geq \cdots \geq \kappa_{N-1} \) and satisfying \( \frac{\partial \Phi}{\partial \kappa_i} > 0 \) \((i = 1, \cdots, N - 1)\). Suppose that we have a closed \( C^2 \) hypersurface \( S \) embedded in \( \mathbb{R}^N \). If on \( S \) the function \( \Phi \) of its principal curvatures \( \kappa_1, \cdots, \kappa_{N-1} \) is constant, then \( S \) must be a sphere.
2. We quote the balance law of the temperature around stationary zeros and stationary critical points of the heat flow from [MS 3].

**Theorem 3.2 (Balance law)** Let $G$ be a domain in $\mathbb{R}^N (N \geq 2)$. Fix a point $x_0 \in G$, and set $d_* = \text{dist}(x_0, \partial G)$. Suppose that $v = v(x, t)$ satisfies the heat equation in $G \times (0, \infty)$. Then the following hold:

(i) $v(x_0, t) = 0 \ (t > 0)$ if and only if

$$\int_{\partial B_r(x_0)} v(x, t) \, dS_x = 0 \quad ((r, t) \in (0, d_*) \times (0, \infty)), \tag{3.1}$$

where $dS_x$ denotes the area element of the sphere $\partial B_r(x_0)$.

(ii) $\nabla v(x_0, t) = 0 \ (t > 0)$ if and only if

$$\int_{\partial B_r(x_0)} (x - x_0)v(x, t) \, dS_x = 0 \quad ((r, t) \in (0, d_*) \times (0, \infty)). \tag{3.2}$$

(ii) was proved in [MS 1], and (i) was stated in [MS 2]. In [MS 3], another proof of (i) and a shorter proof of (ii) were given.

3. For the heat equation, the sphere theorem corresponding to Theorem 1.3 is the following.

**Theorem 3.3 ([MS 3])** Let $\Omega$ be a bounded domain in $\mathbb{R}^N (N \geq 2)$ satisfying the exterior sphere condition and suppose that $D$ is a domain satisfying the interior cone condition, and such that $\overline{D} \subset \Omega$. Assume that the boundary $\partial D$ is a stationary isothermic surface of the solution $u$ of problem (1.14)-(1.16), that is,

$$u(x, t) = a(t) \quad ((x, t) \in \partial D \times (0, \infty)) \tag{3.3}$$

for some function $a : (0, \infty) \to (0, \infty)$. Then $\Omega$ must be a ball.

The proof in [MS 3] is different from that of Theorem 1.3. The outline is as follows. The asymptotic behavior (1.19), together with assumption (3.3), implies that

$$\partial D = \{ x \in \Omega : \, d(x) = R \} \quad (= \Gamma_R) \tag{3.4}$$

for some $R > 0$. Then Theorem 3.2 (i) yields that

$$\int_{\partial B_R(x)} u(z, t) \, dS_z = b(t) \quad \text{for any } x \in \Gamma_R \text{ and for any } t > 0 \tag{3.5}$$

for some function $b : (0, \infty) \to (0, \infty)$ (see [MS 3] for details).
For the unique solution \( u \) of the initial-Dirichlet problem (1.14)-(1.16), define the function \( W = W(x,s) \) by

\[
W(x,s) = s \int_0^\infty u(x,t) e^{-st} \, dt \quad ((x,s) \in \overline{\Omega} \times (0,\infty)). \tag{3.6}
\]

Then, \( W \) satisfies the following.

\[
\Delta W - s \, W = 0 \quad \text{in} \quad \Omega \quad \text{and} \quad W = 1 \quad \text{on} \quad \partial \Omega. \tag{3.7}
\]

By a result of Varadhan [V], we have

\[
- \frac{1}{\sqrt{s}} \log W(x,s) \to d(x) \quad \text{as} \quad s \to \infty \quad \text{uniformly on} \quad \overline{\Omega}. \tag{3.8}
\]

In [V], Varadhan first showed (3.8) and then, by using it, he showed (1.19). Roughly speaking, (3.8) means that for sufficiently large \( s > 0 \) we may have an approximate formula

\[
W(x,s) \sim e^{-\sqrt{s}d(x)}. \]

This formula, together with Laplace's method, yields

**Theorem 3.4** ([MS 3]) Let \( \Omega \) be a bounded domain in \( \mathbb{R}^N \) with piecewise \( C^2 \) boundary \( \partial \Omega \). Assume that, for an open ball \( B_r(x_0) \subset \Omega \), the set \( \partial \Omega \cap \partial B_r(x_0) \) consists of a finite number of points \( p_1, \ldots, p_K \), and \( \kappa_j(p_k) < \frac{1}{r} \) \( (j = 1, \ldots, N-1) \) for any \( k = 1, \ldots, K \). Then, for any continuous function \( \varphi \) on \( \mathbb{R}^N \), the following formula holds:

\[
\lim_{s \to \infty} s^{-\frac{N-1}{4}} \int_{\partial B_r(x_0)} \varphi(x) \, W(x,s) \, dS_x = (2\pi)^{\frac{N-1}{2}} \sum_{k=1}^{K} \varphi(p_k) \left\{ \prod_{j=1}^{N-1} \left[ \frac{1}{r} - \kappa_j(p_k) \right] \right\}^{-\frac{1}{2}}.
\tag{3.9}
\]

By setting \( r = R \), \( x_0 = x \in \Gamma_R \), \( K = 1 \), and \( \varphi \equiv 1 \), we use Theorem 3.4. Hence, in view of (3.5) and (3.6), we use Aleksandrov's sphere theorem to obtain the conclusion of Theorem 3.3. Remark that we can not use the function \( W \) to prove Theorem 1.3.

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