



Title	Remarks on convergence of the Allen-Cahn equation
Author(s)	Tonegawa, Y.
Citation	Hokkaido University Preprint Series in Mathematics, 531, 1-18
Issue Date	2001-06
DOI	10.14943/83677
Doc URL	http://hdl.handle.net/2115/69281
Type	bulletin (article)
File Information	pre531.pdf



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Series #531. June 2001

HOKKAIDO UNIVERSITY
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REMARKS ON CONVERGENCE OF THE ALLEN-CAHN EQUATION

YOSHIHIRO TONEGAWA

ABSTRACT. We answer a question posed by Ilmanen on the integrality of varifolds which appear as the singular perturbation limit of the Allen-Cahn equation. We show that the density of the limit measure is integer multiple of the surface constant \mathcal{H}^{n-1} -a.e. for a.e. time. This shows that limit measures obtained via the Allen-Cahn equation and those via Brakke's construction share the same integrality property as well as being weak solutions for the mean curvature flow equation.

1. INTRODUCTION

The Allen-Cahn equation was proposed to describe the macroscopic motion of phase boundaries driven by surface tension [2]. It is

$$(1.1) \quad \varepsilon \frac{\partial u^\varepsilon}{\partial t} = \varepsilon \Delta u^\varepsilon - \varepsilon^{-1} W'(u^\varepsilon),$$

where W is a bistable potential with two wells of equal depth at ± 1 and the real-valued function u indicates the phase state at each point. Several authors studied the equation to the conclusion that the zero level set of u^ε approaches to a hypersurface with its normal velocity determined by the mean curvature as $\varepsilon \rightarrow 0$. The phase boundaries should have the thickness of order ε .

The formal derivation was given by Fife [14], Rubinstein, Sternberg and Keller [20], and others. The rigorous proof for radially symmetric case was given by Bronsard and Kohn [4]. With the assumption that the classical solution for the mean curvature flow exists, the general case was proved by de Mottoni and Schatzman [10], Chen [6], Chen and Elliott [8] and others. Evans, Soner and Souganidis [11] showed that the limit of the level set of the Allen-Cahn equation is contained in the viscosity solution for the mean curvature flow studied by Evans and Spruck [13] and Chen, Giga and Goto [9]. Ilmanen [17] showed with a technique from geometric measure theory that the limit is a mean curvature flow in the sense of Brakke [3]. Subsequently, Soner [22] gave proofs that more general initial data may be admitted in Ilmanen's work. There are numerous articles related to the general

subject of various Allen-Cahn type equations with modifications and those coupled with other field variables such as temperature. We cite only the most relevant articles and refer the reader to, for example, Soner's paper [22] for more complete references.

The purpose of this paper is to answer one question posed by Ilmanen [17, Section 13.2]. We show that the $(n - 1)$ -dimensional density of the limit measure μ_t of the Allen-Cahn equation is an integral multiple of the surface constant $\sigma = \int_{-1}^1 \sqrt{W(s)/2} ds$ for a.e. $t > 0$ and \mathcal{H}^{n-1} a.e. x . The more heuristic interpretation is that there is no fractional interface appearing as $\varepsilon \rightarrow 0$, and the interface profiles for a.e. points are close to integer multiples of the 1-D travelling wave profile at worst. Higher multiplicities can occur in fact, indicated in the existence results by Bronsard and Stoth [5]. Note that weak varifold solutions for the mean curvature flow constructed by Brakke [3] have such integrality property for a.e. $t > 0$. Accordingly, we conclude that the solutions obtained as the limit of the Allen-Cahn equation have all the measure-theoretic properties of Brakke's solutions. As the bi-products, all of the results on the weak varifold mean curvature flow due to Brakke hold for the limit of the Allen-Cahn equation, such as his clearing-out lemma, perpendicularity of the mean curvature, etc.

Another interest of this paper is our remark that the results due to Ilmanen, where the domain was \mathbb{R}^n , may be localized to a bounded domain. This is due to a local estimate of the so-called discrepancy measure, which in turn yields the local monotonicity formula for the properly scaled energy identity.

The proof of the stated results are appropriate parabolic modifications of the corresponding elliptic results due to Hutchinson and the author [16, Section 5]. There, we showed that any finite energy equilibria converge to a varifold with locally constant mean curvature and integer density.

In Section 2, we state our assumptions and main results. In Section 3, we discuss the derivation of the local monotonicity formula and in the last Section 4 show the integrality of the limit measure. Even though many parts of the proof in Section 4 are similar to those in [16, Section 5], we present the detail for the reader's convenience.

2. ASSUMPTIONS AND MAIN RESULTS

2.1. **Assumptions.** Throughout this paper, we assume

- A:** The function $W : \mathbb{R} \rightarrow [0, \infty)$ is C^3 and $W(\pm 1) = 0$. For some $\gamma \in (-1, 1)$, $W' < 0$ on $(\gamma, 1)$ and $W' > 0$ on $(-1, \gamma)$. For some $\alpha \in (0, 1)$ and $\kappa > 0$, $W''(x) \geq \kappa$ for all $|x| \geq \alpha$.

B: $U \subset \mathbb{R}^n$ is a bounded open set with Lipschitz boundary ∂U and $T \leq \infty$. A sequence of functions $\{u^i\}_{i=1}^\infty$, with $u_{tx_j}^i, u_{x_j x_k x_l}^i \in C(U \times (0, T))$, $1 \leq j, k, l \leq n$, satisfies

$$(2.1) \quad \varepsilon_i u_t^i = \varepsilon_i \Delta u^i - \varepsilon_i^{-1} W'(u^i)$$

on $U \times (0, T)$. Here, $\lim_{i \rightarrow \infty} \varepsilon_i = 0$, and we assume there exist c_0 and E_0 such that $\sup_{U \times (0, T)} |u^i| \leq c_0$ and

$$(2.2) \quad \int_{U \times \{t\}} \frac{\varepsilon_i |\nabla u^i|^2}{2} + \frac{W(u^i)}{\varepsilon_i} \leq E_0$$

for all $t \in (0, T)$ and i . Moreover,

$$(2.3) \quad \int_{U \times (0, T)} \varepsilon_i |u_t^i|^2 \leq E_0$$

for all i .

Assumption B is satisfied, for example, when we consider the following initial value problem

$$\begin{cases} \varepsilon u_t = \varepsilon \Delta u - \varepsilon^{-1} W'(u) & \text{on } U \times (0, \infty), \\ u(x, 0) = \phi_\varepsilon(x) & \text{on } U \\ \frac{\partial u}{\partial n} = 0 & \text{on } \partial U \times (0, \infty), \end{cases}$$

where the initial data have the sup norm and energy bounded uniformly with respect to ε as $\varepsilon \rightarrow 0$. Since the equation is a gradient flow of the energy in (2.2), assumptions (2.2) and (2.3) are satisfied with E_0 being the bound of the energy for the initial data. The sup norm bound of u follows from the standard maximum principle. The boundary Neumann condition may be also replaced by Dirichlet data $u = \phi_\varepsilon$ on $\partial U \times [0, \infty)$, where we also obtain (2.2) and (2.3). Our results are local in nature, so we take above assumptions as our starting point in this paper.

With this setting, for $t \in [0, T)$, define the Radon measures by

$$(2.4) \quad \mu_t^i(\phi) = \int_U \phi(x) \varepsilon_i \frac{|\nabla u^i(x, t)|^2}{2} dx$$

for $\phi \in C_c(U)$.

We also recall the notion of rectifiability for Radon measure.

Definition. ([17, 1.7]) We call a Radon measure μ $(n-1)$ -rectifiable if either of the following equivalent conditions is met:

(a) $\mu = \mathcal{H}^{n-1} \llcorner X \llcorner \theta$, where X is an $(n-1)$ -rectifiable \mathcal{H}^{n-1} -measurable set and $\theta \in L_{loc}^1(\mathcal{H}^{n-1} \llcorner X, (0, \infty))$.

(b) The measure-theoretic approximate tangent plane $T_x \mu$ exists μ -a.e. (see also [1, 3, 21]).

In [17], Ilmanen proved, among other things (with $U = \mathbb{R}^n$),

Theorem 2.1. ([17]) *There is a subsequence of $\{\varepsilon_i\}$ and Radon measures μ_t on U for all $t \in [0, \infty)$ such that*

(i) $\mu_t^i \rightarrow \mu_t$ for all $t > 0$ as Radon measures on U .

(ii) For a.e. $t > 0$, μ_t is $(n-1)$ -rectifiable.

(iii) μ_t satisfies the mean curvature flow equation in the sense of Brakke, namely, for any $\phi \in C_c^2(U)$, $\phi \geq 0$,

$$(2.5) \quad \bar{D}_t \int \phi d\mu_t \leq \int -\phi |H|^2 + \nabla \phi \cdot (T_x \mu_t)^\perp \cdot H d\mu_t$$

for each $t \in [0, \infty)$. Here, \bar{D}_t is the upper derivative, and H is the generalized mean curvature vector of μ_t . The right-hand side is understood to be $-\infty$ whenever μ_t is not $(n-1)$ -rectifiable, the first variation of μ_t is not absolutely continuous with respect to μ_t , or $|H|^2$ is not μ_t integrable. $T_x \mu$ denotes the weak tangent space (and the corresponding projection) of μ_t , and $(T_x \mu)^\perp$ denotes the normal subspace of $T_x \mu$ (and the corresponding projection).

Note that the first variation is defined usually for varifolds ([1, 3, 21]), while it is understood here that one may define the unique varifold from a given rectifiable Radon measure and the first variation is defined through this identification. In these regards, we follow Ilmanen's notations in [17].

Define the $(n-1)$ -dimensional density $\theta(x)$ by

$$\theta(x) = \lim_{r \rightarrow 0} \frac{1}{\omega_{n-1} r^{n-1}} \mu_t(B_r(x))$$

whenever the limit exists. Here, ω_{n-1} is the volume of the unit ball in \mathbb{R}^{n-1} . What we prove is the following:

Theorem 2.2. *For a.e. $t > 0$ and μ_t a.e. $x \in U$, $\theta(x) = N\sigma$ for some positive $N \in \mathbb{N}$, where $\sigma = \int_{-1}^1 \sqrt{W(s)}/2 ds$.*

Thus, for a.e. $t > 0$, $\mu_t = \mathcal{H}^{n-1} \llcorner X_t \llcorner \sigma N(x, t)$, where X_t is an $(n-1)$ -rectifiable set and $N(x, t)$ is integer-valued \mathcal{H}^{n-1} -measurable function. Due to the perpendicularity of the mean curvature vector for integral varifolds [3], we conclude that $H(x, t) \perp T_x \mu_t$ holds for a.e. $t > 0$ and μ_t a.e. $x \in U$. Hence, the mean curvature equation (2.5) is satisfied in the following form as well:

$$(2.5)' \quad \bar{D}_t \int \phi d\mu_t \leq \int -\phi |H|^2 + \nabla \phi \cdot H d\mu_t.$$

We note that if $N(x, t) = 1$ for a.e. $t > 0$ and \mathcal{H}^{n-1} -a.e. on X_t , then Brakke's partial regularity results apply to the measure μ_t and one may obtain the smoothness of the flow for a.e. sense.

3. LOCAL MONOTONICITY FORMULA

In this section we assume that the function $u : U \rightarrow \mathbb{R}$ satisfies assumption **B** with u^i and ε_i there replaced by u and ε respectively. We assume $\tilde{U} \subset\subset U$ and $0 < \tilde{t} < T$.

Here, we show the local monotonicity formula in Proposition 3.3, which is the local version of [17, Section 4.1]. The key point for the extension is the local upper bound of the discrepancy function for all sufficiently small ε (Lemma 3.2).

For any $(y, s) \in \tilde{U} \times (\tilde{t}, T)$ and $(x, t) \in U \times (0, T)$ with $t < s$, denote

$$\rho = \rho_{y,s}(x, t) = \frac{1}{(4\pi(s-t))^{(n-1)/2}} e^{-|x-y|^2/4(s-t)}.$$

For $\phi \in C_c^2(U, \mathbb{R}^+)$, the computation (see [17, Section 3.2]) shows

Lemma 3.1.

$$(3.1) \quad \begin{aligned} \frac{d}{dt} \int \phi d\mu_t^\varepsilon &= \int -\varepsilon\phi \left(-\Delta u + \frac{W'(u)}{\varepsilon^2} - \frac{\nu \cdot \nabla\phi}{\phi} \right)^2 \\ &\quad + \left(\frac{(\nu \cdot \nabla\phi)^2}{\phi} + \phi_{x_i x_i} - \nu_i \nu_j \phi_{x_i x_j} + \phi_t \right) d\mu_t^\varepsilon \\ &\quad + \left(-\nu_i \nu_j \phi_{x_i x_j} + \frac{(\nu \cdot \nabla\phi)^2}{\phi} \right) d\xi_t^\varepsilon. \end{aligned}$$

Here, $\nu = \frac{\nabla u}{|\nabla u|}$ (where it is understood that $\nu = 0$ on $|\nabla u| = 0$) and $d\xi_t^\varepsilon = \left(\frac{\varepsilon|\nabla u|^2}{2} - \frac{W(u)}{\varepsilon} \right) dx$. The summation of the indices is also customary. To localize the monotonicity formula, we fix \hat{U} with $\tilde{U} \subset\subset \hat{U} \subset\subset U$ and $\varphi \in C_c^\infty(U)$ such that $\varphi \equiv 1$ on \hat{U} . Insert $\phi = \varphi\rho$ in (3.1). Direct calculations show that (see [17])

$$\begin{aligned} \frac{(\nabla\rho \cdot \nu)^2}{\rho} + \rho_{x_i x_i} - \nu_i \nu_j \rho_{x_i x_j} + \rho_t &\equiv 0, \\ -\nu_i \nu_j \rho_{x_i x_j} + \frac{(\nu \cdot \nabla\rho)^2}{\rho} &= \frac{\rho}{2(s-t)}. \end{aligned}$$

Thus, dropping the first term, (3.1) with this choice gives

$$\frac{d}{dt} \int \varphi \rho_{y,s} d\mu_t^\varepsilon \leq c(\varphi) E_0 \sup_{x \in U \setminus \hat{U}} |\rho_{y,s}(x, t)| + \int \frac{\varphi \rho_{y,s}}{2(s-t)} d\xi_t^\varepsilon.$$

The first term arises from the differentiations of φ in (3.1). It is exponentially small when $s \approx t$. To control the second term, we need

Lemma 3.2. *There exist constants c_2 and ε_2 which depend only on c_0 , $\text{dist}(\tilde{U} \times (\tilde{t}, T), \partial_0(U \times (0, T)))$ and W such that*

$$(3.2) \quad \sup_{\tilde{U} \times (\tilde{t}, T)} \left(\frac{\varepsilon |\nabla u|^2}{2} - \frac{W(u)}{\varepsilon} \right) \leq c_2$$

for all $\varepsilon < \varepsilon_2$.

The proof is a straightforward modification of the elliptic case discussed in [16, Proposition 3.3] (see also the remark after [16, Lemma 3.6]), so we omit the proof. Then, (3.1) and (3.2) combined with $\int_{\mathbb{R}^n} \rho \, dx = (4\pi(s-t))^{1/2}$ give

$$\frac{d}{dt} \int \varphi \rho_{y,s} \, d\mu_t^\varepsilon \leq c(\varphi) E_0 \sup_{x \in U \setminus \tilde{U}} |\rho_{y,s}(x, t)| + c_2 \pi^{1/2} / \sqrt{2(s-t)}.$$

By integrating above over t and choosing an appropriate constant, we obtain

Proposition 3.3. *There exist constants c_3 and ε_3 depending only on φ , c_0 , \tilde{t} , T , E_0 and W such that, for $0 < \tilde{t} < t_1 < t_2 < s < T$ and $y \in \tilde{U}$,*

$$(3.3) \quad \int \varphi \rho_{y,s} \, d\mu_{t_2}^\varepsilon \leq \int \varphi \rho_{y,s} \, d\mu_{t_1}^\varepsilon + c_3(\sqrt{s-t_1} - \sqrt{s-t_2})$$

for all $\varepsilon < \varepsilon_3$.

Note that the last term may be made as small as we like by choosing $s-t_1$ small. Once we have (3.3), we may localize Ilmanen's argument in [17] which shows the rectifiability of the limit measure and the Brakke's flow equation under the assumption A and B on a bounded domain. This requires a careful re-evaluation of his proof, but we only point out that no part of Ilmanen's argument requires global properties and the estimates there go through with minor modifications coming from the small error term in (3.3). Since our main objective in this paper is the proof of the integrality, we leave the detail to the reader.

4. THE PROOF OF INTEGRALITY

Here, we prove that the limit measure has the integral density property for a.e. points for a.e. time. The proof is similar to the time-independent case, even though one needs to control the time derivative term. This is achieved, roughly speaking, by analyzing the measure at generic times when there is no sudden jump of mass. Also, one does not

have a uniform density ratio lower bound on the support of the limit measure, which is different from the corresponding time-independent situation discussed in [16].

The first proposition shows that there is little energy away from the interface, uniformly in ε . Since we have the discrepancy measure estimate (3.2), the control of the second term in the energy is sufficient to control the first term in the energy.

Proposition 4.1. *Assume that Assumptions **A** and **B** are true with u^i , ε_i and $U \times (0, T)$ replaced by u , ε and $B_3(0) \times (0, 2)$ respectively and suppose $s > 0$ is given. Then there exist positive constants b and ε_4 depending only on c_0 , E_0 , W and s such that*

$$\int_{(B_1(0) \times \{t\}) \cap \{|u| \geq 1-b\}} \frac{W(u)}{\varepsilon} \leq s$$

for all $t \in (1, 2)$ whenever $\varepsilon \leq \varepsilon_4$.

To prove this, we need the following two lemmas.

Lemma 4.2. *There exists a constant c_4 depending only on κ such that if $(x_0, t_0) \in B_1(0) \times (1, 2)$, $0 < \varepsilon < 1$ and $u(x_0, t_0) < 1 - \varepsilon^\beta$ ($u(x_0, t_0) > -1 + \varepsilon^\beta$), where β satisfies $1 \leq \tilde{r} \equiv c_4 \beta |\ln \varepsilon| \leq \varepsilon^{-1}$, then*

$$\inf_{B_{\varepsilon \tilde{r}}(x_0) \times (t_0 - \varepsilon^2 \tilde{r}^2, t_0)} u < \alpha \quad (\text{resp.} \quad \sup_{B_{\varepsilon \tilde{r}}(x_0) \times (t_0 - \varepsilon^2 \tilde{r}^2, t_0)} u > -\alpha).$$

Proof. Rescale the domain by $x \mapsto \frac{x-x_0}{\varepsilon}$ and $t \mapsto \frac{t-t_0}{\varepsilon^2}$. For the comparison argument, we need a function $\psi \geq 1$ with the following properties:

$$\begin{cases} \psi_t = \Delta \psi - \frac{\kappa}{4} \psi & \text{on } \mathbb{R}^n \times (-\infty, 0), \\ \psi(x, t) \geq e^{(\kappa|x|+|t|)/c_4} & \text{on } \mathbb{R}^n \times (-\infty, 0) \setminus B_1^{n+1}(0, 0), \\ \psi(0, 0) = 1 \end{cases}$$

for some $c_4 = c(\kappa)$. Such function is obtained by first defining $\tilde{\psi}$ on \mathbb{R}^n as the entire radial solution of $\Delta \tilde{\psi} = \frac{\kappa}{8} \tilde{\psi}$, $\tilde{\psi}(0) = 1$, which grows exponentially as $|x| \rightarrow \infty$, and then by defining $\psi(x, t) = \tilde{\psi}(x) e^{-\frac{\kappa t}{8}}$. Fix such ψ and c_4 . Let $\tilde{r} = c_4 \beta |\ln \varepsilon|$. Note $1 - \varepsilon^\beta e^{\tilde{r}/c_4} = 0$. For a contradiction, assume that $u(0, 0) < 1 - \varepsilon^\beta$ and $\inf_{B_{\tilde{r}}(0, 0) \times (-\tilde{r}^2, 0)} u > \alpha$. Define $\phi = 1 - \varepsilon^\beta \psi$. Then ϕ satisfies $\phi_t = \Delta \phi + \frac{\kappa}{4} (1 - \phi)$, $\phi < 1 - \varepsilon^\beta e^{\tilde{r}/c_4} < \alpha < u$ on $\partial_0(B_{\tilde{r}}(0, 0) \times (-\tilde{r}^2, 0))$ and $\phi(0, 0) > u(0, 0)$. Thus $u - \phi$ achieves a negative minimum away from the parabolic boundary. There, $(u - \phi)_t - \Delta(u - \phi) \leq 0$ and thus with the equation,

$$0 \geq -W'(u) + \frac{\kappa}{4}(\phi - 1) \geq -W'(\phi) + \frac{\kappa}{4}(\phi - 1) \geq \frac{\kappa}{2} \varepsilon^\beta \psi - \frac{\kappa}{4} \varepsilon^\beta \psi > 0,$$

which is a contradiction. This proves the desired estimate after rescaling back. The supremum estimate is similar. \square

For $t \in (1, 2)$ and $0 < r < 1$, define

$$Z_{r,t} = \{x \in B_1(0) \mid \inf_{B_r(x) \times (t-r^2, t)} |u| < \alpha\}.$$

Lemma 4.3. *There exist constants c_5 and ε_5 depending only on c_0 , E_0 and W such that if $\varepsilon \leq r \leq 1$ then*

$$\mathcal{L}^n(Z_{r,t}) \leq c_5 r$$

provided $0 < \varepsilon < \varepsilon_5$ and $t \in (1, 2)$.

Proof. Let $\varphi \in C_c^\infty(B_3(0))$ be as in Proposition 3.3 with $\varphi \equiv 1$ on $\tilde{U} = B_2(0)$, $\tilde{t} = 1$, $T = 2$ and let c_3 and ε_2 be the constants for the monotonicity formula under these conditions. We claim that there exist some constants c_6 and c_7 such that

$$(4.1) \quad \int_{B_{c_6 r}(x_0) \times \{t_0 - 2r^2\}} \frac{\varepsilon |\nabla u|^2}{2} + \frac{W}{\varepsilon} \geq c_7 r^{n-1}$$

whenever $x_0 \in Z_{r,t_0}$ and $\varepsilon \leq \varepsilon_3$. To see this, let $(x_1, t_1) \in B_r(x_0) \times (t_0 - r^2, t_0)$ with $|u(x_1, t_1)| < \alpha$. The change of variables $x \mapsto \frac{x-x_1}{\varepsilon}$, $t \mapsto \frac{t-t_1}{\varepsilon^2}$ with $\tilde{u}(x, t) = u(\varepsilon x + x_1, \varepsilon^2 t + t_1)$ shows

$$(4.2) \quad \int \varphi \rho_{x_1, t_1 + \varepsilon^2}(\cdot, t_1) \frac{W(u)}{\varepsilon} \geq \int_{B_{\varepsilon^{-1}}(0)} \rho_{0,1}(\cdot, 0) W(\tilde{u}).$$

Since $|\tilde{u}|_{C^1} \leq c(W)$ in this scale, $|\tilde{u}(0, 0)| < \alpha$ implies $W(\tilde{u}) \geq c(W) > 0$ on some neighborhood determined by W and c_0 . Thus (4.2) is bounded from below by some definite constant, say, c_8 . By (3.3),

$$\int \varphi \rho_{x_1, t_1 + \varepsilon^2} d\mu_{t_1}^\varepsilon \leq \int \varphi \rho_{x_1, t_1 + \varepsilon^2} d\mu_{t_0 - 2r^2}^\varepsilon + c_3 \sqrt{t_1 + \varepsilon^2 - t_0 + 2r^2}$$

when $\varepsilon < \varepsilon_3$. Since $|t_0 - t_1| \leq r^2$, by restricting r depending on c_3 and c_8 , we have

$$\frac{c_8}{2} \leq \int \varphi \rho_{x_1, t_1 + \varepsilon^2} d\mu_{t_0 - 2r^2}^\varepsilon.$$

Then, choosing an appropriate c_6 depending only on c_8 and E_0 , we have

$$\frac{c_8}{4} \leq \int_{B_{c_6 r}(x)} \rho_{x_1, t_1 + \varepsilon^2} d\mu_{t_0 - 2r^2}^\varepsilon.$$

On $B_{c_6 r}(x)$, $\rho_{x_1, t_1 + \varepsilon^2}(\cdot, t_0 - 2r^2) \leq c(c_6) r^{n-1}$. Thus we obtain (4.1) with an appropriate choice of c_7 . Once this is done, the Besicovitch covering theorem immediately yields the lemma. \square

Proof of Proposition 4.1. With these two lemmas, the proof proceeds similarly to that of [16, Proposition 5.1].

First assume that $1 - b > \alpha$ and $c_4 |\ln b| \geq 1$, and choose an integer $J = J(\varepsilon, b) \geq 1$ such that $\varepsilon^{1/2^{J+1}} \in (b, \sqrt{b}]$. We also assume that $\varepsilon \leq \varepsilon_5$ and $c_4 |\ln \varepsilon| \leq \varepsilon^{-1}$. Fix $t \in (1, 2)$. For $j = 1, \dots, J$, define

$$A_j = \{x \in B_1(0) \mid 1 - \varepsilon^{1/2^{j+1}} \leq |u(x, t)| \leq 1 - \varepsilon^{1/2^j}\}.$$

Then Lemma 4.2 with $\beta = 1/2^j$ shows that

$$A_j \subset Z_{c_4 2^{-j} \varepsilon |\ln \varepsilon|, t},$$

and Lemma 4.3 shows

$$\mathcal{L}^n(A_j) \leq c_5 c_4 2^{-j} \varepsilon |\ln \varepsilon| \quad \text{for } j = 1, \dots, J.$$

On A_j , using $|u| \geq 1 - \varepsilon^{1/2^{j+1}}$,

$$\frac{W(u)}{\varepsilon} \leq \max_{u \in [\alpha, 1]} W''(u) \cdot \varepsilon^{-1} (\varepsilon^{1/2^{j+1}})^2 / 2 \leq c_9(W) \varepsilon^{2^{-j}-1}.$$

Let $Y = B_1(0) \cap \{1 - b \leq |u| \leq 1 - \sqrt{\varepsilon}\} \subset \bigcup_{j=1}^J A_j$. Since $\varepsilon^{1/2^{J+1}} < \sqrt{b}$ it now follows with $c_{10} = c_9 c_5 c_4$ (depending only on E_0 and W) that

$$\begin{aligned} \int_Y \frac{W(u)}{\varepsilon} &\leq \sum_{j=1}^J \int_{A_j} \frac{W(u)}{\varepsilon} \leq c_{10} |\ln \varepsilon| \sum_{j=1}^J 2^{-j} \varepsilon^{2^{-j}} \\ &\leq c_{10} |\ln \varepsilon| \int_0^{J+1} 2^{-t} \varepsilon^{2^{-t}} = c_{10} (\varepsilon^{2^{-(J+1)}} - \varepsilon) / \ln 2 \leq c_{10} \sqrt{b} / \ln 2. \end{aligned}$$

We restrict b so that the last term is less than $\frac{\varepsilon}{2}$.

To estimate the integral on $\{1 - \sqrt{\varepsilon} \leq |u|\}$ let

$$A_0 = \left\{ x \in B_1(0) \mid 1 - \sqrt{\varepsilon} \leq |u(x)| \leq 1 - \varepsilon^{2/3} \right\}$$

and similarly estimate

$$\int_{A_0} \frac{W(u)}{\varepsilon} \leq c_{10} \frac{2}{3} \varepsilon |\ln \varepsilon|.$$

Finally for $\{|u| \geq 1 - \varepsilon^{2/3}\}$, using $|u| \leq 1 + \varepsilon$ (which can be proved by the parabolic maximum principle),

$$\int_{B_1(0) \cap \{1 - \varepsilon^{2/3} \leq |u|\}} \frac{W(u)}{\varepsilon} \leq c_{11}(c_0, W) \varepsilon.$$

Restricting ε again, we obtain the stated inequality. \square

In the following, define

$$e_\varepsilon = \frac{\varepsilon|\nabla u|^2}{2} + \frac{W(u)}{\varepsilon}, \quad \xi_\varepsilon = \frac{\varepsilon|\nabla u|^2}{2} - \frac{W(u)}{\varepsilon}.$$

Also define $P : \mathbb{R}^n \rightarrow \mathbb{R}^{n-1}$ by $P(x) = (x_1, \dots, x_{n-1})$, and $P^\perp : \mathbb{R}^n \rightarrow \mathbb{R}$ by $P^\perp(x) = x_n$, where $x = (x_1, \dots, x_n)$. Also define $\nu = (\nu_1, \dots, \nu_n) = \frac{\nabla u}{|\nabla u|}$ whenever $|\nabla u| \neq 0$ and $\nu = 0$ when $|\nabla u| = 0$.

The following is the slight modification of [16, Lemma 5.4] but we give the full detail for the reader's convenience. Here, the time variable is fixed.

Lemma 4.4. *Suppose*

- (1) $N \geq 1$ is an integer, Y is a subset of \mathbb{R}^n , $0 < R < \infty$, $1 < M < \infty$, $0 < a < \infty$, $0 < \varepsilon < 1$, $0 < \eta < 1$, $0 < E_0 < \infty$ and $-\infty \leq l_1 < l_2 \leq \infty$.
- (2) Y has no more than $N + 1$ elements, $P(y) = 0$ for all $y \in Y$, $Y \subset \{x \mid l_1 + a < x_n < l_2 - a\}$ and $|y - z| > 3a$ for any distinct $y, z \in Y$.
- (3) $(M + 1)$ diameter $Y < R$, and denote $\tilde{R} \equiv M$ diameter Y .
- (4) On $\{x \in \mathbb{R}^n \mid \text{dist}(x, Y) < R\}$, u satisfies (1.1) with $|u| \leq 2$ and $\xi_\varepsilon \leq \eta$.
- (5) For each $x = (x_1, \dots, x_n) \in Y$,

$$\int_0^R \frac{d\tau}{\tau^n} \int_{B_\tau(x) \cap \{y_n = l_j\}} |e_\varepsilon(y_n - x_n) - \varepsilon u_{x_n}(y - x) \cdot \nabla u| d\mathcal{H}^{n-1}y \leq \eta$$

for $j = 1, 2$.

- (6) For each $x \in Y$ and $a \leq r \leq R$,

$$\int_{B_r(x)} \varepsilon |u_t| |\nabla u| + |\xi_\varepsilon| + (1 - (\nu_n)^2) \varepsilon |\nabla u|^2 \leq \eta r^{n-1} \quad \text{and} \quad \int_{B_r(x)} \varepsilon |\nabla u|^2 \leq E_0 r^{n-1}.$$

Then the following hold:

- (A): There exists $l_3 \in (l_1, l_2)$ such that $|x_n - l_3| \geq a$ and

$$\int_0^{\tilde{R}} \frac{d\tau}{\tau^n} \int_{B_\tau(x) \cap \{y_n = l_3\}} |e_\varepsilon(y_n - x_n) - \varepsilon u_{x_n}(y - x) \cdot \nabla u| d\mathcal{H}^{n-1}y$$

$$\leq 3(N + 1)NM(\eta + E_0^{1/2}\eta^{1/2})$$

for each $x \in Y$.

- (B): Denote

$$Y_1 = Y \cap \{x \mid l_1 < x_n < l_3\}, \quad Y_2 = Y \cap \{x \mid l_3 < x_n < l_2\},$$

$$\mathcal{S}_0 = \{x \mid l_1 < x_n < l_2 \text{ and } \text{dist}(Y, x) < R\},$$

$$\mathcal{S}_1 = \{x \mid l_1 < x_n < l_3 \text{ and } \text{dist}(Y_1, x) < \tilde{R}\},$$

$$\mathcal{S}_2 = \{x \mid l_3 < x_n < l_2 \text{ and } \text{dist}(Y_2, x) < \tilde{R}\}.$$

Then Y_1 and Y_2 are non-empty and

$$\frac{1}{\tilde{R}^{n-1}} \left\{ \int_{S_1} e_\varepsilon + \int_{S_2} e_\varepsilon \right\} \leq \left(1 + \frac{1}{M} \right)^{n-1} \frac{1}{R^{n-1}} \int_{S_0} e_\varepsilon + c(n)\eta(R+1)$$

holds.

Proof. Note the condition on $\varepsilon|u_t||\nabla u|$ in (6) has the effect of keeping the time derivative term small, so that we may derive the desired results just as in the elliptic case.

Let $\zeta_2(y) : \mathbb{R}^n \rightarrow \mathbb{R}$ be a smooth approximation to the characteristic function of the set $\mathcal{S} \equiv \{y \in \mathbb{R}^n \mid l_1 < y_n < l_2\}$ which depends only on y_n . Let $x \in Y$ (and change the coordinates so that $x = 0$) and let $\zeta_1(y)$ be a smooth approximation of the characteristic function $\chi_{B_r(0)}$, where $0 < r < R$. Multiply the equation (1.1) by $(y \cdot \nabla u)\zeta_1(y)\zeta_2(y)$. After integration by parts twice and letting $\zeta_1 \rightarrow \chi_{B_r(0)}$, we obtain

$$\begin{aligned} & \frac{d}{dr} \left\{ \frac{1}{r^{n-1}} \int_{B_r} e_\varepsilon \zeta_2 \right\} + \frac{1}{r^n} \int_{B_r} (\xi_\varepsilon + \varepsilon u_t (y \cdot \nabla u)) \zeta_2 \\ & - \frac{\varepsilon}{r^{n+1}} \int_{\partial B_r} (y \cdot \nabla u)^2 \zeta_2 - \frac{1}{r^n} \int_{B_r} \{e_\varepsilon y_n - \varepsilon u_{x_n} (y \cdot \nabla u)\} \zeta_2' = 0. \end{aligned}$$

After integrating over $[r, R]$ and letting $\zeta_2 \rightarrow \chi_{\mathcal{S}}$, and then using (4), (5) and (6), we obtain

$$(4.3) \quad \frac{1}{R^{n-1}} \int_{B_R \cap \mathcal{S}} e_\varepsilon \geq \frac{1}{r^{n-1}} \int_{B_r \cap \mathcal{S}} e_\varepsilon - c(n)\eta(R+1)$$

where $c(n)$ depends only on the dimension n .

Next, choose $\tilde{y}, \tilde{z} \in Y$ such that $\tilde{z}_n - \tilde{y}_n \geq \text{diameter } Y/N$ and that there is no element of Y in $\{x \in \mathbb{R}^n \mid \tilde{y}_n < x_n < \tilde{z}_n\}$. Let $\tilde{l}_1 = \tilde{y}_n + \frac{\tilde{z}_n - \tilde{y}_n}{3}$ and $\tilde{l}_2 = \tilde{z}_n - \frac{\tilde{z}_n - \tilde{y}_n}{3}$. To choose an appropriate $l \in [\tilde{l}_1, \tilde{l}_2]$ which satisfies (A), we first observe, for $x \in Y$ and $y \in B_r(x)$,

$$\begin{aligned} I & \equiv |e_\varepsilon(y_n - x_n) - \varepsilon u_{x_n}(y - x) \cdot \nabla u| \\ & = |(-\xi_\varepsilon)(y_n - x_n) + \varepsilon |\nabla u|^2 ((y_n - x_n) - \nu_n(y - x) \cdot \nu)| \\ & \leq |\xi_\varepsilon| r + \varepsilon |\nabla u|^2 r \left(1 - (\nu_n)^2 + \sqrt{1 - (\nu_n)^2} \right). \end{aligned}$$

Using (6), we compute

$$\begin{aligned} \int_{\tilde{l}_1}^{\tilde{l}_2} dl \int_0^{\tilde{R}} \frac{d\tau}{\tau^n} \int_{B_\tau(x) \cap \{y_n=l\}} I d\mathcal{H}^{n-1}y & = \int_0^{\tilde{R}} \frac{d\tau}{\tau^n} \int_{B_\tau(x) \cap \{\tilde{l}_1 < y_n < \tilde{l}_2\}} I dy \\ & \leq \tilde{R}(\eta + E_0^{1/2}\eta^{1/2}). \end{aligned}$$

Thus, we may choose $l_3 \in [\tilde{l}_1, \tilde{l}_2]$ such that

$$\int_0^{\tilde{R}} \frac{d\tau}{\tau^n} \int_{B_\tau(x) \cap \{y_n=l_3\}} I d\mathcal{H}^{n-1}y \leq \frac{(N+1)\tilde{R}(\eta + E_0^{1/2}\eta^{1/2})}{\tilde{l}_2 - \tilde{l}_1}$$

for all $x \in Y$. Since $\tilde{l}_2 - \tilde{l}_1 \geq \text{diameter } Y/3N$, we have $\tilde{R}/(\tilde{l}_2 - \tilde{l}_1) \leq 3MN$, and we obtain (A).

Define \mathcal{S}_1 and \mathcal{S}_2 as in (B). For any $x \in Y$, we have $\mathcal{S}_1 \cup \mathcal{S}_2 \subset B_{(\tilde{R}+\text{diam } Y)}(x) \cap \mathcal{S}$, thus

$$\begin{aligned} & \frac{1}{\tilde{R}^{n-1}} \left\{ \int_{\mathcal{S}_1} e_\varepsilon + \int_{\mathcal{S}_2} e_\varepsilon \right\} \leq \frac{1}{\tilde{R}^{n-1}} \int_{B_{(\tilde{R}+\text{diam } Y)}(x) \cap \mathcal{S}} e_\varepsilon \\ & \leq \left(1 + \frac{1}{M}\right)^{n-1} \left\{ \frac{1}{R^{n-1}} \int_{B_R(x) \cap \mathcal{S}} e_\varepsilon + c(n)\eta(R+1) \right\}. \end{aligned}$$

We used (4.3) in the last inequality. Finally, noting that $B_R(x) \cap \mathcal{S} \subset \mathcal{S}_0$, we obtain (B). \square

Once we have the previous lemma, we obtain the following proposition by inductively using the lemma and separating each element of Y . Again, the time variable here is fixed:

Proposition 4.5. *Corresponding to each R, E_0, s and N such that $0 < R < \infty, 0 < E_0 < \infty, 0 < s < 1$ and N is a positive integer, there exists $\eta > 0$ with the following property:*

Assume the following:

- (1) $Y \subset \mathbb{R}^n$ has no more than $N+1$ elements, $P(y) = 0$ for all $y \in Y$, $a > 0, |y - z| > 3a$ for all $y, z \in Y$ and $\text{diameter } Y \leq \eta R$.
- (2) On $\{x \in \mathbb{R}^n \mid \text{dist}(x, Y) < R\}$, u satisfies (1.1) with $|u| \leq 2$ and $\xi_\varepsilon \leq \eta$.
- (3) For each $y \in Y$ and $a \leq r \leq R$,

$$\int_{B_r(y)} \varepsilon |u_t| |\nabla u| + |\xi_\varepsilon| + (1 - (\nu_n)^2) \varepsilon |\nabla u|^2 dy \leq \eta r^{n-1}, \quad \int_{B_r(y)} \varepsilon |\nabla u|^2 \leq E_0 r^{n-1}.$$

Then we have

$$\sum_{y \in Y} \frac{1}{a^{n-1}} \int_{B_a(y)} e_\varepsilon \leq s + \frac{1+s}{R^{n-1}} \int_{\{x \mid \text{dist}(Y, x) < R\}} e_\varepsilon.$$

The next proposition is almost identical to [16, Proposition 5.6], which deals with the “ ε -scale”. Note that we do not have to include any condition of the time derivative term.

Proposition 4.6. *Given $0 < s < 1$ and $0 < b < 1$, there exist $0 < \eta < 1$ and $1 < L < \infty$ (which also depend on W) with the following property:*

Assume $0 < \varepsilon < 1$ and u satisfies (1.1) and $\xi_\varepsilon \leq \eta$ on $B_1(0) \times (-1, 1)$, $|u(0, 0)| \leq 1 - b$, and

$$(4.4) \quad \int_{B_{4\varepsilon L}(0) \times \{0\}} (|\xi_\varepsilon| + (1 - (\nu_n)^2)\varepsilon|\nabla u|^2) \leq \eta(4\varepsilon L)^{n-1}.$$

Then, we have $P^{-1}(0) \cap \{x \in B_{3L\varepsilon}(0) \mid u(x, 0) = u(0, 0)\} = \{0\}$ and

$$(4.5) \quad \left| \frac{1}{\omega_{n-1}(L\varepsilon)^{n-1}} \int_{B_{L\varepsilon}(0) \times \{0\}} e_\varepsilon - 2\sigma \right| \leq s.$$

Proof. We rescale the domain by $x \mapsto x/\varepsilon$ and $t \mapsto t/\varepsilon^2$ for convenience. We still denote the rescaled function as u .

Let $q : \mathbb{R} \rightarrow (-1, 1)$ be the unique solution of the ODE

$$\begin{cases} q'(t) = \sqrt{2W(q(t))} & \text{for } t \in \mathbb{R}, \\ q(0) = u(0, 0). \end{cases}$$

We note that

$$\int_{-\infty}^{\infty} \frac{1}{2} |q'(t)|^2 dt = \int_{-\infty}^{\infty} \sqrt{\frac{W(q(t))}{2}} q'(t) dt = \int_{-1}^1 \sqrt{\frac{W(s)}{2}} ds = \sigma.$$

We also identify q on \mathbb{R}^n by $q(x_1, \dots, x_n) = q(x_n)$.

For given b and s , we fix a large enough $L > 1$ so that

$$(4.6) \quad \left| \frac{1}{\omega_{n-1}L^{n-1}} \int_{B_L(0)} \left(\frac{1}{2} |\nabla q|^2 + W(q) \right) - 2\sigma \right| \leq \frac{s}{2}$$

whenever $|q(0)| \leq 1 - b$. Next, using the pointwise assumption $\frac{1}{2} |\nabla u|^2 - W(u) \leq \eta$ on $B_{4L}(0) \times \{0\}$ and $|u(0, 0)| \leq 1 - b$, we restrict η so that $|u| \leq 1 - \tilde{b}$ on $B_{4L}(0) \times \{0\}$ for some $\tilde{b} = \tilde{b}(W, b, s) > 0$.

Define a function $z(x, t) : B_{4L}(0) \times (-1, 1) \rightarrow \mathbb{R}$ by setting

$$z(x, t) = q^{-1}(u(x, t)),$$

where $q^{-1} : (-1, 1) \rightarrow \mathbb{R}$ is the inverse function of q . Since $|u| \leq 1 - \tilde{b}$, z is well-defined and $q'(z(x, t)) \geq \min_{|u| \leq 1 - \tilde{b}} \sqrt{2W(u)}$ for $x \in B_{4L}(0)$. Moreover, since we may use the equation (1.1) to estimate $\|u\|_{C^2(B_{3L}(0) \times \{0\})}$, $\|z\|_{C^2(B_{3L}(0) \times \{0\})}$ is uniformly bounded depending only on W , b and s by the lower bound of q' . Thus, with

$$\begin{aligned} \frac{1}{2} |\nabla u|^2 - W(u) &= \frac{1}{2} (q'(z))^2 (|\nabla z|^2 - 1), \\ |\nabla u|^2 (1 - (\nu_n)^2) &= (q'(z))^2 (|\nabla z|^2 - (z_{x_n})^2) \end{aligned}$$

and the inequality (4.4), we may obtain (with either + or -)

$$\|z(x) \pm x_n\|_{C^1(B_{3L}(0) \times \{0\})} \leq c(b, s, W)\eta^{1/(n+1)}.$$

This shows that $u(x)$ is C^1 close to $q(x_n)$ on $B_{3L}(0) \times \{0\}$. Combined with (4.6), by choosing η sufficiently small, we obtain (4.5). Also, $u_{x_n} = q'(z)z_{x_n} \neq 0$ on $B_{3L}(0) \times \{0\}$ implies the first assertion. \square

Proof of integrality. By the argument in [17, Section 9.3, 9.5], for any $t = t_0 > 0$ with $\bar{D}_t \mu_t(\phi) > -\infty$, where $\phi \in C_c^2(U; \mathbb{R}^+)$ is a fixed function, we can choose a sequence $\{t_i\}_{i=1}^\infty$ such that (after choosing a suitable subsequence of $\{u^i\}_{i=1}^\infty$ and translating t_0 to 0)

- (1) $t_i > 0$, $\lim_{i \rightarrow \infty} t_i = 0$,
- (2) $\limsup_{i \rightarrow \infty} \int \varepsilon_i \phi |u_t^i|^2 \Big|_{t=t_i} < \infty$,
- (3) $\lim_{i \rightarrow \infty} \int \phi |\xi^i| \Big|_{t=t_i} = 0$, where $\xi^i = \frac{\varepsilon_i |\nabla u^i|^2}{2} - \frac{W(u^i)}{\varepsilon_i} \Big|_{t=t_i}$,
- (4) $\int_{B_r(x)} d\mu_{t_i}^i \leq E_0 r^{n-1}$ for all $x \in \text{supp} \phi$ and $0 < r < \text{dist}(\text{supp} \phi, \partial U)/2$,
- (5) $\mu_{t_i}^i \rightarrow \mu_0$ as Radon measure in U ,
- (6) $\mathcal{H}^{n-1}(\text{supp} \mu_0 \cap \{\phi > 0\}) < \infty$,
- (7) $\frac{\varepsilon_i |\nabla u^i|^2}{2} - \frac{W(u^i)}{\varepsilon_i} \Big|_{t=t_i} \leq c_2$ on $\{\phi > 0\}$ (by Lemma 3.2).

Note that (4) follows from the monotonicity formula (see [17, Section 5.1(2)]). Under these conditions, Ilmanen [17] proved the rectifiability of the limit μ_0 as well as the Brakke's inequality of varifold mean curvature flow equation (2.5) for μ_t . As a result, the convergence of $\mu_{t_i}^i$ to μ_0 is also in the sense of varifold ([17, Section 9]). Here we show that $\sigma^{-1} \mu_0$ is also integral. This is achieved by showing that the $(n-1)$ -dimensional density of $\sigma^{-1} \mu_0$ is integer-valued for \mathcal{H}^{n-1} -a.e. for $t = 0$, which is a generic time.

For any $q \in \mathbb{N}$, define

$$A_{i,q} = \left\{ x \in \text{supp} \phi \mid \int_{B_r(x)} \varepsilon_i |u_t^i| |\nabla u^i| \phi \Big|_{t=t_i} \leq q \int_{B_r(x)} \phi d\mu_{t_i}^i \right.$$

for all $0 < r < \text{dist}(\text{supp} \phi, \partial U)/2$.

Since

$$\begin{aligned} & \limsup_{i \rightarrow \infty} \int \varepsilon_i |u_t^i| |\nabla u^i| \phi \\ & \leq \limsup_{i \rightarrow \infty} \left(\int \varepsilon_i |u_t^i|^2 \phi \right)^{1/2} \left(\int \varepsilon_i |\nabla u^i|^2 \phi \right)^{1/2} \leq c_{11} < \infty, \end{aligned}$$

the Besicovitch covering theorem shows that

$$\int_{A_{i,q}^c} \phi d\mu_{t_i}^i \leq q^{-1} c(n) c_{11}$$

for all large i . Here, we denote the complement of a set X by X^c . Let A_q be the set of points $x \in \text{supp}\phi$ such that there are $x_i \in A_{i,q}$ for infinitely many i with $x = \lim_{i \rightarrow \infty} x_i$. By the definition, A_q is closed. Define $A = \cup_{q=1}^{\infty} A_q$. We want to see that $\int_{A^c} \phi d\mu_0 = 0$. If not true, then, we would have $\int_{A_q^c} \phi d\mu_0 > 0$ for any $q > 0$. Let $\tilde{\phi} \in C_c(A_q^c)$ be such that $0 \leq \tilde{\phi} \leq 1$ and $\int_{A_q^c} \phi \tilde{\phi} d\mu_0 > \frac{1}{2} \int_{A_q^c} \phi d\mu_0$. Since $\text{supp}\tilde{\phi}$ is compact, we may choose (by the definition of A_q) $N(q) \in \mathbb{N}$ such that $\text{supp}\tilde{\phi} \subset A_{i,q}^c$ for all $i \geq N(q)$. Hence,

$$\frac{1}{2} \int_{A_q^c} \phi d\mu_0 \leq \limsup_{i \rightarrow \infty} \int_{A_{i,q}^c} \phi \tilde{\phi} d\mu_{t_i}^i \leq q^{-1} c(n) c_{11}.$$

We then have, for any $q \in \mathbb{N}$, $\int_{A^c} \phi d\mu_0 \leq q^{-1} c(n) c_{11}$, so $\int_{A^c} \phi d\mu_0 = 0$.

Next, since μ_0 is rectifiable, μ_0 -a.e. point x (which we translate to the origin subsequently) has a weak tangent plane. Namely, let V be the rectifiable varifold with $\|V\| = \mu_0$. Then, at such point (after rotation), $\lim_{i \rightarrow \infty} (\Phi_{r_i})_{\#} V = \theta v(P)$, where $r_i \rightarrow 0$, $(\Phi_{r_i})_{\#}$ is the usual push-forward with $\Phi_{r_i}(x) = \frac{x}{r_i}$, $v(P)$ corresponds to the varifold associated with the $(n-1)$ -dimensional plane $P = \{x_n = 0\}$, and θ is the density at the point. For μ_0 a.e., we may also assume that the point is in A_q for some $q \in \mathbb{N}$ and thus there exists a sequence $x_i \in A_{i,q}$ with $0 = \lim_{i \rightarrow \infty} x_i$. Let V^i be the varifold associated with $\mu_{t_i}^i$. After choosing a subsequence, we may assume that $(\Phi_{r_i})_{\#} V^i$ converge to $\theta v(P)$, $\lim_{i \rightarrow \infty} \frac{x_i}{r_i} = 0$ and $\lim_{i \rightarrow \infty} \frac{t_i}{r_i^2} = 0$. Rescale the coordinates by $\tilde{x} = \frac{x}{r_i}$, $\tilde{t} = \frac{t}{r_i^2}$ and $\tilde{\varepsilon}_i = \frac{\varepsilon_i}{r_i}$ (and subsequently drop $\tilde{\cdot}$). We preserve the form of the equation (1.1) under the scaling, and by the definition of $A_{i,q}$ and (4), we have

$$(4.7) \quad \int_{B_3(0)} \varepsilon_i |u_t^i| |\nabla u^i| \Big|_{t=t_i} \leq r_i q \rightarrow 0$$

as $i \rightarrow \infty$. The condition (7) is, under the scaling,

$$(4.8) \quad \frac{\varepsilon_i |\nabla u^i|^2}{2} - \frac{W(u^i)}{\varepsilon_i} \Big|_{t=t_i} \leq c_2 r_i \rightarrow 0$$

on $\{\phi > 0\}$ as $i \rightarrow \infty$. Since $(\Phi_{r_i})_{\#} V^i$ converges to $\theta v(P)$ in the varifold sense, we also have

$$(4.9) \quad \lim_{i \rightarrow \infty} \int_{B_3(0)} (1 - (\nu_n)^2) \varepsilon_i |\nabla u^i|^2 \Big|_{t=t_i} = 0.$$

Suppose N is the smallest positive integer greater than $\sigma^{-1}\theta$. Fix an arbitrary small $s > 0$. Use Proposition 4.1 to choose $b > 0$, and then

with (4.8) we have

$$(4.10) \quad \int_{B_3(0) \cap \{|u^i| \geq 1-b\}} \left(\frac{\varepsilon_i |\nabla u^i|^2}{2} + \frac{W(u^i)}{\varepsilon_i} \right) \Big|_{t=t_i} \leq s$$

for all sufficiently large i . With these choices of s , b and $R = 1$, we choose η and L via Proposition 4.5 and 4.6 (the smaller η should be chosen). For all large i , we define

$$\begin{aligned} G_i &= B_2(0) \times \{t_i\} \cap \{|u^i| \leq 1-b\} \cap \{x \mid \\ &\int_{B_r(x)} \varepsilon_i |u_t^i| |\nabla u^i| + |\xi^i| + (1 - \nu_n^2) \varepsilon_i |\nabla u^i|^2 \Big|_{t=t_i} \\ &\leq \eta E_0^{-1} \mu_{t_i}^i(B_r(x)) \text{ if } 4\varepsilon_i L \leq r \leq 1 \}. \end{aligned}$$

By repeating the argument leading to (4.3), one may prove that there exist constants c_{12} and c_{13} depending only on n , \tilde{U} and W such that

$$(4.11) \quad \frac{1}{r^{n-1}} \mu_{t_i}^i(B_r(x)) \geq c_{12} \text{ for all } \varepsilon_i \leq r \leq c_{13} \text{ and } x \in G_i.$$

By the Besicovitch covering theorem, one shows that

$$(4.12) \quad \begin{aligned} &\mu_{t_i}^i(B_2(0) \cap \{|u| \leq 1-b\} \setminus G_i) \\ &\leq c(n) \eta^{-1} E_0 \int_{B_3(0)} \varepsilon_i |u_t^i| |\nabla u^i| + |\xi^i| + (1 - \nu_n^2) \varepsilon_i |\nabla u^i|^2 \Big|_{t=t_i}, \end{aligned}$$

which goes to 0 as $i \rightarrow \infty$ by (3), (4.7) and (4.9). Also $\text{dist}(P, G_i) \rightarrow 0$ as $i \rightarrow \infty$, since $\mu_{t_i}^i \rightarrow \theta \|v(T)\|$ and by (4.11).

For any $x \in B_1^{n-1}(0) := (\mathbb{R}^{n-1} \times \{0\}) \cap B_1(0)$ and $|l| \leq 1-b$, we let $Y = P^{-1}(x) \cap G_i \cap \{u^i = l\}$ and apply Proposition 4.5, where we set $a = L\varepsilon_i$. By Proposition 4.6, each element of Y is separated by at least $3L\varepsilon_i$, and all the assumptions are satisfied for sufficiently large i . We prove that Y does not contain more than $N-1$ elements for any $x \in B_1^{n-1}(0)$ as follows. Since

$$\sup_{x \in B_1^{n-1}(0)} \frac{1}{\omega_{n-1}} \int_{B_1(x)} \left(\frac{\varepsilon_i |\nabla u^i|^2}{2} + \frac{W(u^i)}{\varepsilon_i} \right) \leq 2\theta + s$$

for large i , Y having more than $N-1$ elements would imply, by Proposition 4.5, that

$$2\sigma N \leq (N+1)s + (1+s)(2\theta + s).$$

This would be a contradiction to $\theta\sigma^{-1} < N$ for sufficiently small s depending only on N .

Finally, since $|\xi^i| \rightarrow 0$ as $i \rightarrow \infty$, we have $\left| \frac{\varepsilon_i |\nabla u^i|^2}{2} - |\nabla u^i| \sqrt{W(u^i)/2\varepsilon_i} \right| \rightarrow 0$ in L^1_{loc} . As the result and by (4.10) and (4.12), for $t = t_i$,

$$\omega_{n-1}\theta = \lim_{i \rightarrow \infty} \int_{B_1(0)} \frac{\varepsilon_i |\nabla u^i|^2}{2} \leq \lim_{i \rightarrow \infty} \int_{B_1(0) \cap \{|u^i| \leq 1-b\} \cap G_i} |\nabla u^i| \sqrt{W(u^i)/2} + s.$$

By the co-area formula, $\lim_{i \rightarrow \infty} \|P_{\#} V^i\| = \theta v(P)$ and the above discussion then implies

$$\begin{aligned} \omega_{n-1}\theta &\leq \lim_{i \rightarrow \infty} \int_{-1+b}^{1-b} \|P_{\#}(v(\{u^i = t\} \cap G_i))\| (B_1^{n-1}(0)) \sqrt{W(t)/2} dt + s \\ &\leq \omega_{n-1}(N-1) \int_{-1+b}^{1-b} \sqrt{W(t)/2} dt + s \leq \omega_{n-1}(N-1)\sigma + s. \end{aligned}$$

Since s is arbitrary, we have $\theta = (N-1)\sigma$. □

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