<table>
<thead>
<tr>
<th>Title</th>
<th>ON THE POINTWISE DECAY ESTIMATE FOR THE WAVE EQUATION WITH COMPACTLY SUPPORTED FORCING TERM</th>
</tr>
</thead>
<tbody>
<tr>
<td>Author(s)</td>
<td>Kubo, Hideo</td>
</tr>
<tr>
<td>Citation</td>
<td>Hokkaido University Preprint Series in Mathematics, 1042, 1-14</td>
</tr>
<tr>
<td>Issue Date</td>
<td>2013-10-18</td>
</tr>
<tr>
<td>DOI</td>
<td>10.14943/84186</td>
</tr>
<tr>
<td>Doc URL</td>
<td><a href="http://hdl.handle.net/2115/69846">http://hdl.handle.net/2115/69846</a></td>
</tr>
<tr>
<td>Type</td>
<td>bulletin (article)</td>
</tr>
<tr>
<td>File Information</td>
<td>pre1042.pdf</td>
</tr>
</tbody>
</table>

Hokkaido University Collection of Scholarly and Academic Papers : HUSCAP
ON THE POINTWISE DECAY ESTIMATE FOR THE WAVE EQUATION WITH COMPactly SUPPORTED FORCING TERM

HIDEO KUBO

Dedicated to Professor Gustavo Ponce on the occasion of his 60th birthday

Abstract. In this paper we derive a new type of pointwise decay estimates for solutions to the Cauchy problem for the wave equation in 2D, in the sense that one can diminish the weight in the time variable for the forcing term if it is compactly supported in the spatial variables. As an application of the estimate, we also establish an improved decay estimate for the solution to the exterior problem in 2D.

Keywords. Wave equation, Pointwise decay estimate, Exterior problem

1. Introduction

In this paper we derive a new type of pointwise decay estimates for solutions to the following Cauchy problem for the wave equation:

\begin{equation}
(\partial_t^2 - \Delta)v = g(t, x), \quad (t, x) \in (0, T) \times \mathbb{R}^2,
\end{equation}

\begin{equation}
v(0, x) = v_0(x), \quad (\partial_t v)(0, x) = v_1(x), \quad x \in \mathbb{R}^2,
\end{equation}

where \( u = u(t, x) \) is an unknown function, \( \Delta = \partial_1^2 + \partial_2^2, \) \( \partial_t = \partial_0 = \partial/\partial t, \) and \( \partial_j = \partial/\partial x_j \) \( (j = 1, 2). \) In addition, we assume that \( v_0 \) and \( v_1 \) are smooth functions on \( \mathbb{R}^2, \) and that \( g \) is a smooth function on \([0, T) \times \mathbb{R}^2. \) As is well known, different kind if pointwise estimates has been used for treating nonlinear wave equations. This approach goes back to the seminal work of John [5].

On the other hand, the point of the present study is to understand how we can feel influence coming from such an assumption on the forcing term \( g(t) \) that for each fixed \( t \in [0, T), \) its support is contained in a ball with a fixed radius centered at the origin. This question is closely related to the exterior problem (see the section 4 below for details). But our pointwise estimate (1.3) itself is of interest, because it tells us that if the forcing term is compactly supported in the spatial variables, then one can diminish the weight in the time variable for the forcing term, compared with the standard pointwise decay estimate (2.4) below (see also Remark 1 in the below of Proposition 3.2).

1991 Mathematics Subject Classification. 35L15, 35L20.
Theorem 1.1. Let $a > 0$ and $1 < \nu < 3/2$. If $\text{supp}g(t, \cdot) \subset \{x \in \mathbb{R}^2 \mid |x| \leq a\}$ for any $t \in [0, T)$, then we have
\[
\langle t + |x| \rangle^{1/2} \min\{\langle x \rangle, \langle t - |x| \rangle\})^{\nu-1} |v(t, x)| \leq C \sup_{y \in \mathbb{R}^2} (y)^{\nu-1/2} \left( \sum_{|\alpha| \leq 1} |\partial_x^2 v_0(y)| + |v_1(y)| \right) + C \sup_{(s, y) \in [0, t] \times \mathbb{R}^2} \langle s \rangle^{\nu-1/2} |g(s, y)|,
\]
where $C$ is a constant, and $\langle x \rangle = \sqrt{1 + |x|^2}$.

This paper is organized as follows. In the next section we collect basic notations and recall known pointwise estimates for the problem (1.1)-(1.2). In the section 3 we give a proof of Theorem 1.1 in a slightly generalized form. The section 4 is devoted to establish an improved decay estimate for the exterior problem as an application of Theorem 1.1.

2. Preliminaries

2.1. Notation. Let us start with some standard notation.

- We put $\langle y \rangle := \sqrt{1 + |y|^2}$ for $y \in \mathbb{R}^d$ with $d \in \mathbb{N}$.
- Let $A = A(y)$ and $B = B(y)$ be two positive functions of some variable $y$, such as $y = (t, x)$ or $y = x$, on suitable domains. We write $A \leq B$ if there exists a positive constant $C$ such that $A(y) \leq CB(y)$ for all $y$ in the intersection of the domains of $A$ and $B$.
- The norm $\| \cdot \|_{L^\infty}$ without any other index stands for $\| \cdot \|_{L^\infty(\mathbb{R}^2)}$.
- For a time-space depending function $u$ satisfying $u(t, \cdot) \in X$ for $0 \leq t < T$ with a Banach space $X$, we put $\|u\|_{L^\infty_T X} := \sup_{0 \leq t < T} \|u(t, \cdot)\|_X$. For the brevity of the description, we sometimes use the expression $\|h(s, y)\|_{L^\infty_T L^\infty}$ with dummy variables $(s, y)$ for a function $h$ on $[0, t] \times \mathbb{R}^2$, which means $\sup_{0 \leq s < t} \|h(s, \cdot)\|_{L^\infty}$.
- $B_r$ stands for an open ball with radius $r$ centered at the origin of $\mathbb{R}^2$.

Following Klainerman [10], we introduce the vector fields $\Gamma = (\Gamma_0, \ldots, \Gamma_3)$:
\[
\Gamma_0 = \partial_0 = \partial_t, \quad \Gamma_j = \partial_j \ (j = 1, 2), \quad \Gamma_3 = O_{12} = x_1 \partial_2 - x_2 \partial_1.
\]
We put $\partial = (\partial_0, \partial_1, \partial_2)$, and $\tilde{\Gamma} = (\nabla_x, O_{12})$. The standard multi-index notation will be used for these sets of vector fields, such as $\partial^\alpha = \partial_0^{\alpha_0} \partial_1^{\alpha_1} \partial_2^{\alpha_2}$ with $\alpha = (\alpha_0, \alpha_1, \alpha_2)$ and $\Gamma^\gamma = \Gamma_0^{\gamma_0} \cdots \Gamma_3^{\gamma_3}$ with $\gamma = (\gamma_0, \ldots, \gamma_3)$.

For simplicity, we set
\[
|\varphi(t, x)|_m = \sum_{|\alpha| \leq m} |\Gamma^\alpha \varphi(t, x)|
\]
for a real-valued smooth function $\varphi(t, x)$ and a non-negative integer $m$.

Denoting $[A, B] := AB - BA$, we have
\[
[\Gamma_i, \partial_i^2 - \Delta] = 0, \quad i = 0, 1, 2, 3,
\]
and also for $i, j = 0, 1, 2, 3$, we have $[\Gamma_i, \Gamma_j] = \sum_{k=0}^3 c_{ij}^k \Gamma_k$ with suitable constants $c_{ij}^k$. 

2.2. Decay estimates for the Cauchy problem. In this subsection we recall known decay estimates for the solution of the Cauchy problem (1.1)-(1.2). We denote by $S_0[\vec{v}_0, g](t, x)$ the solution to this problem with $\vec{v}_0 = (v_0, v_1) \in (C^\infty(\mathbb{R}^2))^2$ decaying rapidly at spatial infinity. Let $K_0[\vec{v}_0](t, x)$ and $L_0[g](t, x)$ be the solutions with $g = 0$ and $\vec{v}_0 = (0, 0)$, respectively.

The following decay estimate for solutions of the homogeneous wave equation follows from Proposition 2.1 with $\kappa = \nu - (1/2) > 0$ in [15]. Indeed, one can reduce the estimate to the case $m = 0$, thanks to (2.2).

**Lemma 2.1.** Let $1 < \nu < 3/2$ and $m$ be a non-negative integer. For $\vec{v}_0 = (v_0, v_1) \in (C^\infty(\mathbb{R}^2))^2$ we have

$$\langle t + |x| \rangle^{1/2} \langle t - |x| \rangle^{\nu-1} |K_0[\vec{v}_0](t, x)|_m,$$

(2.3)

$$\lesssim B_{\nu+(1/2), m}[\vec{v}_0] := \sum_{|\gamma| \leq k+1} \|\langle \cdot \rangle^{\nu+(1/2)} \Gamma^\gamma v_0\|_{L^\infty} + \sum_{|\gamma| \leq k} \|\langle \cdot \rangle^{\nu+(1/2)} \Gamma^\gamma v_1\|_{L^\infty}$$

for $(t, x) \in [0, T) \times \mathbb{R}^2$.

The following lemma is concerned with the inhomogeneous wave equation. For the proof, see [13, Lemma 3.4], also Di Flaviano [1].

**Lemma 2.2.** Let $1 < \nu < 3/2$, $\kappa > 1$, and $m$ is a non-negative integer. If $g$ is a smooth function on $[0, T) \times \mathbb{R}^2$, then we have

$$\langle t + |x| \rangle^{1/2} \langle t - |x| \rangle^{\nu-1} |L_0[g](t, x)|_m,$$

(2.4)

$$\lesssim \sum_{|\beta| \leq m} \|\langle y \rangle^{1/2} (s + |y|)^\nu (\min\{\langle |y| \rangle, \langle s - |y| \rangle\})^\kappa \Gamma^\beta g(s, y)\|_{L^\infty L^\infty}$$

for $(t, x) \in [0, T) \times \mathbb{R}^2$.

3. Proof of Theorem 1.1

In this section we shall prove the following pointwise decay estimate which is involved with the generalized derivatives $\Gamma$’s. This kind of generalization of Theorem 1.1 would be useful, when we wish to study the nonlinear wave equations.

**Theorem 3.1.** Let $a > 0$, $1 < \nu < 3/2$ and $m$ be a non-negative integer. If $\text{supp} g(t, \cdot) \subset B_a$ for any $t \in [0, T)$, then we have

$$\langle t + |x| \rangle^{1/2} (\min\{\langle |x| \rangle, \langle t - |x| \rangle\})^{\nu-1} |S_0[\vec{v}_0, g](t, x)|_m,$$

(3.1)

$$\lesssim B_{\nu+(1/2), m}[\vec{v}_0] + \sum_{|\alpha| \leq m} \|\langle s \rangle^{\nu-(1/2)} \partial^\alpha g(s, y)\|_{L^\infty L^\infty}.$$
Proposition 3.2. Under the same assumptions of Theorem 3.1, we have

\[ \langle t + |x| \rangle^{1/2} (\min\{\langle |x| \rangle, \langle t - |x| \rangle\})^{\nu - 1} |L_0[g](t, x)|_m \]
\[ \lesssim \sum_{|\alpha| \leq m} \| \langle s \rangle^{\nu - (1/2)} \partial^{\beta} g(s, y) \|_{L_\infty L_\infty} . \] (3.2)

Remark 1. Let us compare (3.2) with (2.4). It is clear that (2.4) implies

\[ \langle t + |x| \rangle^{1/2} (\min\{\langle |x| \rangle, \langle t - |x| \rangle\})^{\nu - 1} |L_0[g](t, x)|_m \]
\[ \lesssim \sum_{|\alpha| \leq m} \| \langle y \rangle^{1/2 + \kappa} \langle s \rangle^\nu \Gamma^{\beta} g(s, y) \|_{L_\infty L_\infty} . \] (3.3)

In particular, if \text{supp} g(s, \cdot) \subset B_a, then the right hand side is evaluated by

\[ \sum_{|\alpha| \leq m} \| \langle s \rangle^{\nu - (1/2)} \partial^{\beta} g(s, y) \|_{L_\infty L_\infty} . \]

Therefore, (3.2) is actually different from (2.4) in the sense that one can diminish the weight on the forcing term with respect to the time variable as long as the forcing term is compactly supported in the spatial variable.

Proof of Proposition 3.2. It follows from (2.2) and the uniqueness for the classical solution that

\[ Z^\alpha L_0[g] = L_0[Z^\alpha g] + K_0[(\phi_\alpha, \psi_\alpha)], \quad |\alpha| \leq m, \] (3.4)

where we put \phi_\alpha(x) = (Z^\alpha L_0[g])(0, x), \psi_\alpha(x) = (\partial_t Z^\alpha L_0[g])(0, x). From the equation (1.1) we get

\[ \phi_\alpha(x) = \sum_{|\beta| \leq |\alpha| - 2} C_{\beta}(Z^\beta g)(0, x), \quad \psi_\alpha(x) = \sum_{|\beta| \leq |\alpha| - 1} C'_{\beta}(Z^\beta g)(0, x) \]

with suitable constants \( C_\beta, C'_\beta \). Therefore, by (2.3) with \( 1 < \nu < 3/2 \), we get

\[ \langle t + |x| \rangle^{1/2} (t - |x|)^{\nu - 1} |K_0[(\phi_\alpha, \psi_\alpha)](t, x)| \lesssim \sum_{|\alpha| \leq m - 1} \| \langle \cdot \rangle^{\nu - (1/2)} (Z^\alpha g)(0) \|_{L_\infty} \]
\[ \lesssim \sum_{|\alpha| \leq m} \| \langle s \rangle^{\nu - (1/2)} \partial^{\beta} g(s, y) \|_{L_\infty L_\infty} , \]

because of the assumption on \( g \). Hence, from (3.4) we see that it is enough to show

\[ \langle t + |x| \rangle^{1/2} (\min\{\langle r \rangle, \langle t - r \rangle\})^{\nu - 1} |L_0[g](t, x)| \lesssim \| \langle s \rangle^{\nu - (1/2)} g(s, y) \|_{L_\infty L_\infty} . \] (3.5)
Let $\chi_A$ be the characteristic function for a set $A$. Then, following the opening of the section 4 in [11], we get

$$|L_0[g](t, x)| \lesssim \|s\| L^{\nu} L^\infty \times \left( \int_0^t ds \int_{|s-r|}^{t-s} \chi_{[0, a]}(\lambda) \langle s \rangle^{-(\nu-1/2)} K_1(\lambda, r, t-s) d\lambda \right)$$

$$+ \int_{(t-r)^+}^{(t-r)} ds \int_0^{t-s} \chi_{[0, a]}(\lambda) \langle s \rangle^{-(\nu-1/2)} K_2(\lambda, r, t-s) d\lambda \right)$$

(3.6)

with $r = |x|$. Here we denoted

$$K_1(\lambda, r, t) = \frac{2}{\sqrt{\pi}} \int_{|\lambda-r|}^{t} \frac{\rho h(\lambda, \rho, r)}{\sqrt{t^2 - \rho^2}} d\rho, \ |t - r| < \lambda < t + r,$$

$$K_2(\lambda, r, t) = \frac{2}{\sqrt{\pi}} \int_{|\lambda-r|}^{\lambda+r} \frac{\rho h(\lambda, \rho, r)}{\sqrt{t^2 - \rho^2}} d\rho, \ 0 < \lambda < t - r$$

with $h(\lambda, \rho, r) = (\rho^2 - (\lambda - r)^2)^{-1/2}((\lambda + r)^2 - \rho^2)^{-1/2}$, and they are estimated as follows:

$$K_1(\lambda, r, t-s) \leq \frac{\sqrt[3]{\lambda}}{\sqrt{\lambda - s + r + t\sqrt{\lambda + s + r + t}}},$$

for $0 \leq s \leq t, \ |t - s - r| < \lambda < t - s + r$, and

$$K_2(\lambda, r, t-s) \leq \frac{\sqrt[3]{\lambda}}{\sqrt{t - r - \lambda - s\sqrt{t + r + \lambda - s}}}$$

for $0 \leq s \leq t, \ 0 < \lambda < t - s - r$. Indeed, these estimates follow from the proofs of (4.18) and (4.22) in [11], because $\sqrt{\lambda}$ is simply evaluated by $\sqrt{\alpha}$ when $\alpha \geq \beta$, which is equivalent to $s \geq 0$, in their proofs (notice that $K_1(\lambda, s, r, t)$ and $K_2(\lambda, s, r, t)$ in [11] are actually equal to $K_1(\lambda, r, t-s)$ and $K_2(\lambda, r, t-s)$). Thus we have

$$|L_0[g](t, x)| \lesssim (I_1(t, r) + I_2(t, r)) \|s\| L^{\nu} L^\infty,$$

where we put

$$I_1(t, r) = \int_0^t ds \int_{|s-r|}^{t-s} \frac{\chi_{[0, a]}(\lambda) \langle s \rangle^{-(\nu-1/2)}}{\sqrt{\lambda - s + r + t\sqrt{\lambda + s + r + t}}} d\lambda,$$

(3.7)

$$I_2(t, r) = \int_{(t-r)^+}^{(t-r)} ds \int_0^{t-s} \frac{\chi_{[0, a]}(\lambda) \langle s \rangle^{-(\nu-1/2)}}{\sqrt{t - r - \lambda - s\sqrt{t + r + \lambda - s}}} d\lambda.$$  

(3.8)

Therefore, in order to prove (3.5), we have only to show

$$I_1(t, r) \lesssim \langle t + r \rangle^{\nu-1/2} \langle t - r \rangle^{-(\nu-1)},$$

(3.9)

$$I_2(t, r) \lesssim \langle t + r \rangle^{-1/2} (\min \{ \langle r \rangle, \langle t - r \rangle \})^{-(\nu-1)}.$$ 

(3.10)
First we estimate \( I_1(r, t) \). Since \( I_1 \equiv 0 \) if \( r - t \geq a \), we may assume \( t - r \geq -a \). Notice that if \( \lambda \geq |(t - r) - s| \) and \( \lambda \leq a \), then \( \langle s \rangle \) is equivalent to \( \langle t - r \rangle \) and \( \lambda - s + r + t \geq 2r \). Therefore from (3.7) we have

\[
I_1(t, r) \lesssim \frac{t - r}{\sqrt{2\lambda}} \int_0^t ds \int_{t-s-r}^{t-r} \frac{1}{\sqrt{\lambda + s + r - t}} \chi_{[0, a]}(\lambda) d\lambda. \tag{3.11}
\]

To proceed further, we divide the argument into four cases.

1. \(|t - r| \leq a\) and \(0 < r \leq a\): It follows that

\[
I_1(t, r) \lesssim \frac{1}{\sqrt{r}} \int_0^t ds \int_{t-s-r}^{t-r} \frac{1}{\sqrt{\lambda + s + r - t}} d\lambda \lesssim t.
\]

Since \( t \leq |t - r| + r \leq 2a \) in this case, the above estimate yields (3.9).

2. \(|t - r| \leq a\) and \(r \geq a\): We change the order of the integration to obtain

\[
\sqrt{r}I_1(t, r) \lesssim \int_0^{(t-r)_+} d\lambda \int_{-\lambda-t-r}^{\lambda+t-r} \frac{1}{\sqrt{\lambda + s + r - t}} ds
\]

\[
+ \int_{(t-r)_+}^a d\lambda \int_{-\lambda-t-r}^{\lambda+t-r} \frac{1}{\sqrt{\lambda + s + r - t}} ds \lesssim 1.
\]

Since \( 4r \geq 2r + a + (t - r) = r + t + a \) in this case, this estimate implies (3.9).

3. \( t - r \geq a\) and \(0 < r \leq a\): It follows from (3.11) that

\[
\langle t - r \rangle^{\nu - 1/2} I_1(t, r) \lesssim \frac{1}{\sqrt{r}} \int_0^r d\lambda \int_{-\lambda-t-r}^{\lambda+t-r} \frac{1}{\sqrt{\lambda + s + r - t}} ds
\]

\[
+ \frac{1}{\sqrt{r}} \int_r^a d\lambda \int_{-\lambda-t-r}^{\lambda+t-r} \frac{1}{\sqrt{\lambda + s + r - t}} ds \lesssim 1.
\]

Since \( t \geq r + a \geq 2r \) in this case, \( \langle t - r \rangle \) is equivalent to \( \langle t + r \rangle \), so that the above estimate yields (3.9).

4. \( t - r \geq a\) and \(r \geq a\): From (3.11) we have

\[
\langle t - r \rangle^{\nu - 1/2} \langle r \rangle^{1/2} I_1(t, r) \lesssim \int_0^a d\lambda \int_{-\lambda-t-r}^{\lambda+t-r} \frac{1}{\sqrt{\lambda + s + r - t}} ds \lesssim 1,
\]

which yields (3.9). Indeed, if \( t \geq 2r \), then \( \langle t - r \rangle \) is equivalent to \( \langle t + r \rangle \). On the other hand, if \( t \leq 2r \), then \( \langle r \rangle \) is equivalent to \( \langle t + r \rangle \). Therefore, the above estimate is enough to conclude that the desired one holds.

Next we estimate \( I_2(r, t) \). We may assume \( t - r > 0 \), and we divide the argument into three cases.

1. \(0 < t - r \leq 4a\) and \(0 < r \leq a\): It follows (3.8) that

\[
I_2(t, r) \lesssim \int_0^{t-r} ds \int_0^{t-s-r} \frac{1}{\sqrt{t-r-\lambda-s} \sqrt{\lambda}} d\lambda \lesssim a\pi.
\]

Thus we get (3.10).
2. $0 < t - r \leq 4a$ and $r \geq a$: Changing the order of the integration, we get

$$ I_2(t, r) \lesssim \int_0^{t-r} d\lambda \int_0^{-\lambda+t-r} \frac{1}{\sqrt{t-r-\lambda-s}\sqrt{t+r+\lambda-s}} ds. $$

Since $t + r + \lambda - s \geq 2r + 2\lambda \geq 2r$ for $\lambda \geq 0$ and $s \leq -\lambda + t - r$, we obtain

$$ I_2(t, r) \lesssim \frac{(t-r)^{3/2}}{\sqrt{2r}} \lesssim \frac{1}{\sqrt{r}}, $$

which implies (3.10).

3. $t - r \geq 4a$: It follows from (3.8) that

$$ I_2(t, r) \lesssim \langle t + r \rangle^{-1/2} (\min \{ \langle r \rangle, \langle t - r \rangle \})^{-(\nu - 1)}. $$

Since $-\lambda + 2^{-1}(t - r) \geq 4^{-1}(t - r)$ for $\lambda \leq a$ and $t - r \geq 4a$, we have

$$ \langle t - r \rangle^{\nu - (1/2)} I_2(t, r) \lesssim \int_0^{a} d\lambda \int_0^{-\lambda+t-r} \frac{1}{\sqrt{t-r-\lambda-s}\sqrt{t+r+\lambda-s}} ds. $$

When $t \leq 2r$ and $r \geq a$, we have only show

$$ I_2(t, r) \lesssim r^{-1/2} \langle t - r \rangle^{-(\nu - 1)}. $$

Since $t + r + \lambda - s \geq 2r + 2\lambda \geq 2r$ for $s \leq -\lambda + t - r$ and $\lambda \geq 0$, we have

$$ \langle t - r \rangle^{\nu - (1/2)} I_2(t, r) \lesssim \int_0^{a} d\lambda \int_0^{-\lambda+t-r} \frac{1}{\sqrt{t-r-\lambda-s}\sqrt{t+r+\lambda-s}} ds $$

$$ \lesssim r^{-1/2} \langle t - r \rangle^{1/2}, $$

which implies (3.14). When $t \geq 2r$ and $r \geq a$, we have only show

$$ I_2(t, r) \lesssim r^{-(\nu - 1)} \langle t - r \rangle^{-1/2}. $$

For simplicity, we put $\theta = \nu - 1$. Since $1 < \nu < 3/2$, we have $0 < \theta < 1/2$. It follows that

$$ \langle t - r \rangle^{\nu - (1/2)} I_2(t, r) \lesssim \frac{1}{(2r)^{\theta}} \int_0^{a} J(t, r, \lambda) d\lambda, $$

where we set

$$ J(t, r, \lambda) = \int_{-\lambda+2^{-1}(t-r)}^{-\lambda+t-r} \frac{1}{\sqrt{t-r-\lambda-s}(t+r+\lambda-s)^{(1/2)-\theta}} ds. $$
For \( \lambda \geq 0 \) we have
\[
J(t, r, \lambda) \lesssim \int_{-\lambda+2^{-1}(t-r)}^{t-r} (t-r-\lambda-s)^{-1+\theta} ds \lesssim (t-r)^{\theta}.
\]
Thus we get (3.15). When \( 0 < r \leq a \), we have only show
\[
(3.17) \quad I_{2,1}(t, r) \lesssim (t-r)^{-1/2}.
\]
By (3.16) we have
\[
(t-r)^{-\nu-(1/2)} I_{2,1}(t, r) \lesssim \int_{0}^{\infty} \frac{1}{(2\lambda)^{\theta}} J(t, r, \lambda) d\lambda \lesssim (t-r)^{\theta},
\]
which yields (3.17). From (3.14), (3.15), and (3.17), we obtain (3.13).

Next we consider \( I_{2,2} \). Since \( t-r-\lambda-s \geq (t-r)/2 \) and \( t+r+\lambda-s \geq (t+r)/2 \) for \( s \leq -\lambda+2^{-1}(t-r) \) and \( \lambda \geq 0 \), we get
\[
I_{2,2}(t, r) \lesssim \frac{1}{\sqrt{t+r} \sqrt{r-t}} \int_{0}^{\infty} d\lambda \int_{0}^{(2-1)(t-r)} \langle s \rangle^{-\nu-(1/2)} ds \\
\lesssim \frac{(t-r)^{-\nu+(3/2)}}{\sqrt{t+r} \sqrt{r-t}} \lesssim (t+r)^{-1/2} (t-r)^{-(\nu+1)}.
\]
Combining this estimate with (3.14), (3.15), and (3.17), we obtain (3.13).

Thus the proof of (3.2) is complete. \( \square \)

4. ON THE EXTERIOR PROBLEM FOR THE WAVE EQUATION

As an application of Theorem 3.1, we examine the pointwise decay estimate for the exterior problem in this section.

Let \( \Omega \) be an unbounded domain in \( \mathbb{R}^2 \) with compact and smooth boundary \( \partial \Omega \). We put \( \mathcal{O} := \mathbb{R}^2 \setminus \Omega \), which is called an obstacle and is assumed to be non-empty. Throughout this section we shall assume \( 0 \in \mathcal{O} \) so that we have \( |x| \geq c_0 \) for \( x \in \Omega \) with some positive constant \( c_0 \). We shall also assume that \( \overline{\mathcal{O}} \subset B_1 \). Thus a function \( v = v(x) \) on \( \Omega \) vanishing for \( |x| \leq 1 \) can be naturally regarded as a function on \( \mathbb{R}^2 \).

Given \( T > 0 \), we consider the mixed problem for the wave equation:
\[
(4.1) \quad (\partial_t^2 - \Delta_x) u = f(t, x), \quad (t, x) \in (0, T) \times \Omega,
\]
\[
(4.2) \quad u(t, x) = 0, \quad (t, x) \in (0, T) \times \partial \Omega,
\]
\[
(4.3) \quad u(0, x) = u_0(x), \quad \partial_t u(0, x) = u_1(x), \quad x \in \Omega.
\]
We assume \( u_0, u_1 \in C^\infty(\overline{\Omega}) \), namely, they are smooth functions on \( \overline{\Omega} \) vanishing outside some ball. On the other hand, \( f \in C^\infty([0, T) \times \overline{\Omega}) \) is assumed to satisfy \( f(t, \cdot) \in C^\infty(\overline{\Omega}) \) for any fixed \( t \in [0, T) \). In order to obtain a smooth solution to (4.1)-(4.3), we need the compatibility condition to infinite order, i.e., \( u_j(x) \) vanishes on \( \partial \Omega \) for any non-negative integer \( j \), where \( u_j(x) \) is determined by
\[
(4.4) \quad u_j(x) = \Delta u_{j-2}(x) + (\partial_t^{j-2} f)(0, x), \quad j \geq 2.
\]
We denote by $X(T)$ the set of all such data $\Xi = (u_0, u_1, f) = (\bar{u}_0, f)$. For $\Xi$ we denote by $S[\Xi](t, x)$ the solution of the mixed problem (4.1)-(4.3). Besides, we set $K[\bar{u}_0] = S[(\bar{u}_0, 0)]$ and $L[f] = S[(0, 0, f)]$.

Then we have the following decay estimates.

**Theorem 4.1.** Let $1 < \nu < 3/2$, $\kappa > 1$, and $k$ be a non-negative integer. Assume that $\mathcal{O}$ is star-shaped, and $\Xi = (\bar{u}_0, f) \in X(T)$. Then we have

$$
\langle t + |x| \rangle^{1/2} \left( \min \{ \langle x \rangle, \langle t - |x| \rangle \} \right)^{\nu - 1} |S[\Xi](t, x)|_k
$$

for $(t, x) \in [0, T) \times \overline{\Omega}$. Here we put

$$
W_{\nu, \kappa}(s, y) = \langle s + |y| \rangle^\nu \left( \min \{ \langle |y| \rangle, \langle s - |y| \rangle \} \right)^\kappa,
$$

$$
A_{\rho, k}[u_0, u_1] = \sum_{|\gamma| \leq k} \| \langle \cdot \rangle^\rho \tilde{\Gamma}_\gamma u_0 \|_{L^\infty_\Omega} + \sum_{|\gamma| \leq k} \| \langle \cdot \rangle^\rho \tilde{\Gamma}_\gamma u_1 \|_{L^\infty_\Omega}.
$$

Our proof of the theorem is based on the cut-off method used in Shibata and Tsutsumi [19], where the nonlinear problem was handled when the space dimension is greater than 3 (see also [2, 3], [4], [6], [8, 9], [12], [16], [17], [18], and the references cited therein). Because the decaying rate of the solution to the wave equation is weaker and weaker as the space dimension is lower and lower, in our previous works [7, 13, 14] which treat the two-dimensional case, we could not obtain such a decay estimate of the solution itself as above. But, thanks to (3.2), we succeed to derive the same decay estimate as in the boundaryless case. The estimate (4.5) will be used in the forthcoming papers concerning the nonlinear wave equation in the exterior domain.

### 4.1. Decomposition of solutions

For $a > 0$, we denote by $\psi_a$ a smooth radially symmetric function on $\mathbb{R}^2$ satisfying

$$
\begin{cases}
\psi_a(x) = 0, & |x| \leq a, \\
\psi_a(x) = 1, & |x| \geq a + 1.
\end{cases}
$$

Besides, for $a \geq 1$ we set

$$
\Omega_a = \Omega \cap B_a.
$$

Since $\overline{\mathcal{O}} \subset B_1$, we see that $\Omega_a \neq \emptyset$ for any $a \geq 1$. Then we have the following decomposition (for the proof, we refer to [19], [12, Lemma 3.1]).

**Lemma 4.2.** Fix $a \geq 1$. Let $\Xi = (u_0, u_1, f) \in X(T)$. Assume that

$$
supp f(t, \cdot) \subset \overline{\Omega}_{t+a} \quad \text{and} \quad supp u_0 \subset \overline{\Omega}_a, \ supp u_1 \subset \overline{\Omega}_a
$$

holds for any $t \in (0, T)$. Then we have

$$
S[\Xi](t, x) = \psi_a(x) S_0[\psi_{2a}\Xi](t, x) + \sum_{i=1}^4 S_i[\Xi](t, x),
$$

for $(t, x) \in [0, T) \times \overline{\Omega}$.
where
\begin{align}
\tag{4.9}
S_1[\Xi](t, x) &= (1 - \psi_{2a}(x))L[\psi_a, -\Delta]S_0[\psi_{2a}\Xi](t, x), \\
\tag{4.10}
S_2[\Xi](t, x) &= -L_0[\psi_{2a}, -\Delta]L[\psi_a, -\Delta]S_0[\psi_{2a}\Xi](t, x), \\
\tag{4.11}
S_3[\Xi](t, x) &= (1 - \psi_{3a}(x))S[(1 - \psi_{2a})\Xi](t, x), \\
\tag{4.12}
S_4[\Xi](t, x) &= -L_0[\psi_{3a}, -\Delta]S[(1 - \psi_{2a})\Xi](t, x).
\end{align}

4.2. Proof of Theorem 4.1. For $a > 1$, we denote by $X_a(T)$ the set of all $(u_0, u_1, f) \in X(T)$ satisfying
\begin{equation*}
u_0(x) = u_1(x) = f(t, x) \equiv 0 \text{ for } |x| \geq a \text{ and } t \in [0, T).\end{equation*}
It is useful to prepare the following lemma for the proof of Theorem 4.1.

Lemma 4.3. Let $O$ be star-shaped. Let $a$, $b > 1$, $0 < \rho \leq 1$, $1 < \nu \leq 3/2$, $\kappa > 1$, and $m$ be a non-negative integer.
(i) Let $\chi$ be a smooth function on $\mathbb{R}^2$ satisfying $\text{supp } \chi \subset B_0$. If $\Xi = (\tilde{u}_0, f) \in X_a(T)$, then we have
\begin{align}
\tag{4.13}
\langle t \rangle^\rho |\chi S[\Xi](t, x)|_m & \lesssim A_{0, m+1}[\tilde{u}_0] + \sum_{|\beta| \leq m+1} \|\langle s \rangle^\rho \partial^\beta f(s, y)\|_{L^\infty_T L^\infty_x(\Omega_a)}
\end{align}
for $(t, x) \in [0, T) \times \Omega_a$.
(ii) Let $g$ be a smooth function on $[0, T) \times \mathbb{R}^2$ and satisfy $\text{supp } g(t, \cdot) \subset B_a \setminus B_1$ for any $t \in [0, T)$. Then we have
\begin{align}
\tag{4.14}
\langle t + |x| \rangle^{1/2} (\min\{\langle |x| \rangle, \langle t - |x| \rangle\})^{\nu - 1} |L_0[g](t, x)|_m & \lesssim \sum_{|\beta| \leq m} \|\langle s \rangle^{\nu - (1/2)} \partial^\beta g(s, y)\|_{L^\infty_T L^\infty_x(\Omega_a)}
\end{align}
for $(t, x) \in [0, T) \times \Omega_a$.
(iii) Let $\tilde{v}_0$ and $g$ be smooth functions on $\mathbb{R}^2$ and on $[0, T) \times \mathbb{R}^2$, respectively. If $\tilde{v}_0(x) = g(t, x) = 0$ for any $(t, x) \in [0, T) \times B_1$, then
\begin{align}
\tag{4.15}
\langle t \rangle^{\nu - (1/2)} |S_0[(\tilde{v}_0, g)](t, x)|_m & \lesssim A_{\nu + (1/2), m-1} [\tilde{v}_0] + \sum_{|\beta| \leq m} \|\langle y \rangle^{1/2} W_{\nu, \kappa}(s, y) \Gamma^\beta g(s, y)\|_{L^\infty_T L^\infty_y(\Omega)}
\end{align}
for $(t, x) \in [0, T) \times \Omega_a$.

Proof. One can find the proof of (4.13) in [13, Lemma 4.1]. Since $\text{supp } g(t, \cdot) \subset \overline{B_a \setminus B_1} \subset \Omega_a$, we get (4.14) from (3.2).
Finally we prove (4.15) by using (2.3) and (2.4) with (4.6). It follows that
\[
\langle t + |x| \rangle^{\nu-1} \langle t - |x| \rangle^{\nu} |S_0[\vec{v}_0, g](t, x)|_k
\]
\[
\lesssim B_{\nu+1/2,k}[\bar{v}_0] + \sum_{|\beta| \leq k} \|\langle y \rangle^{1/2} W_{\nu,\kappa}(s, y) \Gamma^\delta g(s, y)\|_{L^\infty L^\infty}
\]
for \((t, x) \in [0, T) \times \mathbb{R}^2\). Observe that \(\langle t - |x| \rangle\) is equivalent to \(\langle t \rangle\) when \(x \in \Omega_0^c\). Therefore we get (4.15). This completes the proof.

**Proof of Theorem 4.1.** According to Lemma 4.2 with \(a = 1\), we can write
\[
S[\Xi](t, x) = \psi_1(x) S_0[\psi_2 \Xi](t, x) + \sum_{i=1}^{4} S_i[\Xi](t, x)
\]
for \((t, x) \in [0, T) \times \Omega\), where \(\psi_a\) is defined by (4.7) and \(S_i[\Xi]\) for \(1 \leq i \leq 4\) are defined by (4.9)–(4.12) with \(a = 1\). It is easy to check that
\[
\langle t + |x| \rangle^{\nu-1} \langle t - |x| \rangle^{\nu} |S_0[\psi_2 \Xi](t, x)|_k
\]
\[
\lesssim B_{\nu+1/2,k}[\bar{v}_0] + \sum_{|\beta| \leq k} \|\langle y \rangle^{1/2} W_{\nu,\kappa}(s, y) \Gamma^\delta g(s, y)\|_{L^\infty L^\infty}
\]
for \((t, x) \in [0, T) \times \Omega, a \geq 1\) and any smooth function \(h\). Note that this identity implies
\[
S_i[\Xi] = 0, 0, [\psi_a, -\Delta] h \in X_{a+1}(T)
\]
because \(\text{supp} \nabla \psi_a \cup \text{supp} \Delta \psi_a \subset \overline{B_{a+1}} \setminus B_a\).

Let \(1/2 < \nu < 3/2\) and \(\kappa > 1\) in the following. Applying (2.3) and (2.4), we have
\[
\langle t + |x| \rangle^{\nu-1} \langle t - |x| \rangle^{\nu} |S_0[\psi_2 \Xi](t, x)|_k
\]
\[
\lesssim B_{\nu+1/2,k}[\bar{v}_0] + \sum_{|\beta| \leq k} \|\langle y \rangle^{1/2} W_{\nu,\kappa}(s, y) \Gamma^\delta f(s, y)\|_{L^\infty L^\infty}
\]
so that
\[
\langle t + |x| \rangle^{\nu-1} \langle t - |x| \rangle^{\nu} |S_0[\psi_2 \Xi](t, x)|_k
\]
\[
\lesssim A_{\nu+1/2,k}[\bar{u}_0] + \sum_{|\beta| \leq k} \|\langle y \rangle^{1/2} W_{\nu,\kappa}(s, y) \Gamma^\delta f(s, y)\|_{L^\infty L^\infty}
\]
(4.19)

Next we estimate \(S_1[\Xi]\) and \(S_3[\Xi]\). Using (4.13) and then (4.17), we get
\[
\langle t \rangle^{\nu-1/2} |S_1[\Xi](t, x)|_k
\]
\[
\lesssim \sum_{|\beta| \leq k+1} \|\langle s \rangle^{\nu-1/2} \partial^\beta (\psi_1, -\Delta) S_0[\psi_2 \Xi](s, y)\|_{L^\infty L^\infty(\Omega)}
\]
\[
\lesssim \sum_{|\beta| \leq k+2} \|\langle s \rangle^{\nu-1/2} \partial^\beta S_0[\psi_2 \Xi](s, y)\|_{L^\infty L^\infty(\Omega)}
\]
Since \((\psi_2 \Xi)(t, x) = 0\) if \(|x| \leq 2\), we can use (4.15) to obtain
\[
\langle t \rangle^{\nu-1/2} |S_1[\Xi](t, x)|_k
\]
\[
\lesssim A_{\nu+(1/2), k+2}[\psi_2 \tilde{u}_0] + \sum_{|\beta| \leq k+2} \|y|^{1/2} W_{\nu, \kappa}(s, y) \Gamma^\beta f(s, y)\|_{L^\infty L^\infty_t}
\]
for \((t, x) \in [0, T) \times \Omega\).

Because \((1 - \psi_2) \Xi \in X_3(T)\) for \(\Xi \in X(T)\), it follows from (4.11) and (4.13) that
\[
\langle t \rangle^{\nu-1/2} |S_3[\Xi](t, x)|_k
\]
\[
\lesssim A_{0, k+1}[\tilde{u}_0] + \sum_{|\beta| \leq k+1} \|\langle s \rangle^{\nu-1/2} s^\beta f(s, y)|_{L^\infty L^\infty_t(\Omega_3)}
\]
for \((t, x) \in [0, T) \times \Omega\).

By using the trivial inequality \(\langle s \rangle^{\nu-1/2} \lesssim |y|^{1/2} W_{\nu, \kappa}(s, y)\) in \([0, T) \times \Omega_3\), from (4.20) and (4.21) we see that
\[
\langle t \rangle^{\nu-1/2} \left( |S_1[\Xi](t, x)|_k + |S_3[\Xi](t, x)|_k \right)
\]
\[
\lesssim A_{\nu+(1/2), k+2}[\tilde{u}_0] + \sum_{|\beta| \leq k+2} \|y|^{1/2} W_{\nu, \kappa}(s, y) \Gamma^\beta f(s, y)\|_{L^\infty L^\infty_t}.
\]

Moreover, noting that \(S_1[\Xi]\) and \(S_3[\Xi]\) are supported on \(\bar{\Omega}_4\), we can replace the weight on the left hand side as follows:
\[
\langle t + |x| \rangle^{1/2} \langle t - |x| \rangle^{\nu-1} \left( |S_1[\Xi](t, x)|_k + |S_3[\Xi](t, x)|_k \right)
\]
\[
\lesssim A_{\nu+(1/2), k+2}[\tilde{u}_0] + \sum_{|\beta| \leq k+2} \|y|^{1/2} W_{\nu, \kappa}(s, y) \Gamma^\beta f(s, y)\|_{L^\infty L^\infty_t}.
\]

Finally we consider \(S_2[\Xi]\) and \(S_4[\Xi]\). Setting \(g_j[\Xi] = (\partial_x^2 - \Delta) S_j[\Xi]\) for \(j = 2, 4\), and recalling (4.10), (4.12), and the definition of \(L_0\), we have
\[
g_2[\Xi] = -[\psi_2, -\Delta] L \left[ [\psi_1, -\Delta] S_0[\psi_2 \Xi] \right],
\]
\[
g_4[\Xi] = -[\psi_3, -\Delta] S \left[ (1 - \psi_2) \Xi \right].
\]

Having in mind (4.17) we can say that \(g_2\) and \(g_4\) have the same structures as \(S_1\) and \(S_3\), but they contain one more derivative. Therefore, arguing similarly to the derivation of (4.22), we arrive at
\[
\langle t \rangle^{\nu-1/2} \left( |g_2[\Xi](t, x)|_k + |g_4[\Xi](t, x)|_k \right)
\]
\[
\lesssim A_{\nu+(1/2), k+3}[\tilde{u}_0] + \sum_{|\beta| \leq k+3} \|y|^{1/2} W_{\nu, \kappa}(s, y) \Gamma^\beta f(s, y)\|_{L^\infty L^\infty_t}.
\]
Since \( S_j[\Xi] = L_0[g_j] \) for \( j = 2, 4 \), and \( g_2, g_4 \) are supported on \( B_4 \setminus B_2 \), we are in a position to apply (4.14) and we get

\[
\langle t + |x| \rangle^{1/2} \left( \min \{ |(t - |x|)| \} \right)^{\nu - 1} \left( |S_2[\Xi](t, x)| + |S_4[\Xi](t, x)| \right)
\]

\[
\lesssim A_{\nu+(1/2),k+3}[\bar{u}_0] + \sum_{|\beta| \leq k+3} \| y^{1/2} W_{\nu,k}(s, y) \Gamma^{\beta} f(s, y) \|_{L^\infty_t L^\infty_y}.
\]

Now (4.5) follows from (4.19), (4.23) and (4.25). This completes the proof. \( \square \)

**Acknowledgments**

The author is partially supported by Grant-in-Aid for Science Research (B) (No. 24340024), JSPS.

**References**


Department of Mathematics, Faculty of Science, Hokkaido University, Sapporo 060-0810, Japan

E-mail address: kubo@math.sci.hokudai.ac.jp