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A GENERALIZED CONSERVATION PROPERTY FOR THE HEAT SEMIGROUP ON WEIGHTED MANIFOLDS

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ABSTRACT. In this text we study a generalized conservation property for the heat semi-group generated by a Schrödinger operator with nonnegative potential on a weighted manifold. We establish Khasminskii's criterion for the generalized conservation property and discuss several applications.

1. Introduction

There are several ways to introduce Brownian motion on (weighted) Riemannian manifolds. One approach is through Markovian semigroups induced by self-adjoint realizations of the Laplacian. More precisely, if Δ_D is the self-adjoint realization of the Laplacian with generalized Dirichlet boundary conditions, it follows from standard theory on regular Dirichlet forms that there exists a unique Markov process $(B_t)_{t>0}$ on the manifold M with life-time ζ such that the operator (or rather the semigroup it generates) and the process correspond through the Feynman-Kac formula

$$e^{t\Delta_D} f(x) = \mathbb{E}_x \left[f(B_t) \mathbb{1}_{\{t < \zeta\}} \right], \quad x \in M, t > 0.$$

Here, \mathbb{E}_x denotes the expectation with respect to the process started at $x \in M$; we refer to [6] for details. The so-constructed process $(B_t)_{t>0}$ is called the *minimal Brownian motion* on M. If the underlying manifold is a bounded open subset of Euclidean space, minimal Brownian motion is Euclidean Brownian motion stopped upon hitting the boundary and the life-time is given by its first exit time from the domain.

One fundamental question about minimal Brownian motion is about its *stochastic completeness*, i.e., whether its life-time is infinite. It follows from the Feynman-Kac formula that an infinite life-time is equivalent to

$$\mathbb{P}_x(B_t \in M) = e^{t\Delta_D} 1(x) = 1, \quad x \in M, t > 0.$$

Due to the second equality involving the semigroup, in this case we also say that $(e^{t\Delta_D})_{t>0}$ is conservative (the semigroup solution to the heat equation preserves the total amount of heat in the system). Of course, on bounded open subsets of Euclidean space Brownian motion will eventually exit the domain so that it is always stochastically incomplete. Since bounded open domains in Euclidean space are not geodesically complete, one may wonder whether stochastic completeness is related to geodesic completeness but in [1] a geodesically complete but stochastically incomplete manifold is constructed. It is a manifold with large negative sectional curvature, which forces Brownian motion to exit the manifold in finite time.

This example brought up the need to investigate the interplay between the geometry of the manifold and stochastic completeness. Here we mention the pioneering works [7, 15, 30] that culminated in [8] with the insight that on a geodesically complete manifold stochastic completeness is related to the volume growth of balls. More precisely, geodesically complete manifolds whose volume of balls does not grow too fast are stochastically complete, see also [3, 9, 29] for related material. Since the discussed construction of Brownian motion through the Feynman-Kac formula uses the abstract machinery of Dirichlet forms, it does not come as a surprise that an optimal volume growth criterion for stochastic completeness was later also obtained for diffusion processes induced by strongly local regular Dirichlet forms on more general state spaces than manifolds, see [28], and for jump processes on discrete spaces, see [5, 16, 17].

All proofs for the optimal volume growth test for stochastic completeness have in common that they are based on an analytic criterion of Khasminskii [15]. It says that stochastic completeness holds if and only if all bounded smooth solutions to the initial value problem for the heat equation

$$\begin{cases} \partial_t u = \Delta u \\ u_0 = 0 \end{cases}$$

equal zero.

From the PDE viewpoint it is also natural to study this uniqueness property of the heat equation with the Laplacian replaced by the Schrödinger operator $H = \Delta - V$. Moreover, if V is nonnegative, the self-adjoint realization $H_D = \Delta_D - V$ with generalized Dirichlet boundary conditions generates a Markovian semigroup $(e^{tH_D})_{t>0}$ and hence corresponds to a Markov process through the Feynman-Kac formula. Locally this process behaves like Brownian motion, but certain paths are stopped earlier as the nonnegative potential drains heat from inside the system.

One may wonder whether in this case also conservativeness of the semigroup generated by H_D is related to uniqueness of bounded smooth solutions to the heat equation with respect to H. While the latter property may or may not be satisfied, if $V \neq 0$, the semigroup $(e^{tH_D})_{t>0}$ is never conservative. This follows from the observation that $(t,x) \mapsto e^{tH_D}1(x)$ is always a solution to the heat equation $\partial_t u = Hu$ while constant functions do not solve this equation when $V \neq 0$. However, it was recently observed in [20] for discrete Schrödinger operators with nonnegative potentials (such operators are induced by infinite weighted graphs) that uniqueness of bounded solutions to the heat equation is equivalent to a generalized conservation property. On manifolds the generalized conservation property takes the form

$$e^{tH_D}1(x) + \int_0^t e^{sH_D}V(x)ds = 1, \quad x \in M, t > 0.$$

Roughly speaking, the additional quantity $\int_0^t e^{sH_D}V(x)ds$ corresponds to the probability that the associated process is stopped up to time t due to the presence of the potential. Hence, the generalized conservation property says that heat is only lost inside the manifold due to the presence of the potential and not at "infinity".

It is the main goal of this paper to extend Khasminskii's criterion for the generalized conservation property to Schrödinger operators on manifolds. This is achieved in Theorem 3.3 and Theorem 3.4. Besides the criterion involving uniqueness of bounded solutions to the heat equation we also give a version for uniqueness of bounded solutions to the eigenvalue equation. Moreover, we discuss several applications.

We show that on stochastically complete manifolds the generalized conservation property holds for all nonnegative potentials. Since this result is perturbative in nature, we would like to stress that the generalized conservation property is not obtained by mere perturbation theory. More precisely, there exists a stochastically incomplete manifold and a potential such that H_D satisfies the generalized conservation property, see the discussion in Subsection 6.2 and Subsection 6.3.

As a second application we prove that the generalized conservation property for H_D is equivalent to the conservation property of $(1+V)^{-1}\Delta_D$ considered on the L^2 -space with respect to the changed measure $(1+V)\mathrm{vol}_g$, see Theorem 3.5. In terms of associated processes the latter operator corresponds to a diffusion process on the manifold obtained from a time change of minimal Brownian motion. This observation is new, in particular it is not included in the aforementioned [20] for discrete spaces. Since geometric criteria for conservativeness of general diffusions are rather well-understood, see [28], it opens the way for geometric criteria for the generalized conservation property. In Subsection 6.2 we pursue this strategy to characterize the generalized conservation property through volume growth criteria on model manifolds. Similar results on discrete spaces for weakly spherically symmetric graphs are contained in [21]. Moreover, in Subsection 6.3 we use the volume growth test for stochastic completeness from [28] to show that on every complete manifold there is a potential such that the semigroup generated by H_D is conservative in the generalized sense.

Minimal Brownian motion is defined with respect to the Laplacian with generalized Dirichlet boundary conditions. Other self-adjoint realizations of the Laplacian that generate Markovian semigroups can lead to other instances of Brownian motion according to the corresponding boundary conditions. However, it is known that if minimal Brownian motion is stochastically complete, there are no self-adjoint realizations of the Laplacian that generate Markovian semigroups other than Δ_D and hence Brownian motion is unique, see e.g. [11, 14, 22] for this result in various situations and generality. Analytically uniqueness of Brownian motion corresponds to the identity of the Sobolev spaces $W_0^1(M) = W^1(M)$ on the underlying manifold M. In Theorem 6.1 we extend the observation that stochastic completeness implies $W_0^1(M) = W^1(M)$ to the Schrödinger operator case, i.e., we prove that if $(e^{tH_D})_{t>0}$ satisfies the generalized conservation property, then $W_0^1(M,1+V) = W^1(M,1+V)$, where the latter denote weighted Sobolev spaces on the manifold, see Subsection 2.2 below.

Concerning our presentation of the subject we aim at two different audiences, namely people working on PDEs on manifolds and people acquainted with Dirichlet forms and stochastics. In order to reach both, compromises are necessary at several places. We finish this introduction by trying to explain the compromises and discuss where the strengths and the limits of our methods lay.

The most prominent class of spaces for global analysis are certainly smooth Riemannian manifolds. Therefore, we choose to focus on them, consider only smooth nonnegative potentials and formulate the extension of Khasminskii's criterion and applications in the smooth category. On a technical level this is possible because we can apply parabolic and elliptic local regularity theory, which we explain in detail.

As should be clear from the preceding discussion, the concept of the generalized conservation property also makes sense for other Markovian semigroups and an extension of Khasminskii's criterion is certainly of interest for Markovian semigroups associated with regular Dirichlet forms. The methods that we use in this text are strong and abstract enough to treat this case. We comment at the corresponding places on necessary changes and believe that it should be no problem for experts on Dirichlet forms to fill the gaps. However, since there is no local parabolic and elliptic regularity theory for general Dirichlet forms, smooth strong solutions need to be replaced by weak solutions in the local form domain. As mentioned above, for operators on discrete spaces Khasminskii's criterion for the generalized conservation property is contained in [20] and on a very abstract level similar results (only the elliptic but not the parabolic part) can be found in [26]. In contrast to these two texts we would like to point out that we work with parabolic maximum principles instead of elliptic maximum principles.

We mentioned at various places in the introduction that the generalized conservation property can be understood in terms of associated Markov processes. However, in order to keep the text reasonably short and accessible, our definitions, methods and proofs are purely analytical. We hint on the stochastic relevance of certain formulas and theorems but leave details to the reader.

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2. Preliminaries

In this section we introduce the notation and the objects that are used throughout the text. We basically follow [10], to which we refer the reader for formal definitions. For a background on Dirichlet form theory see [6, 24]. All functions in this text are real-valued.

2.1. Distributions and Schrödinger operators. Let $M = (M, g, \mu)$ be a smooth connected weighted Riemannian manifold without boundary. We assume that the measure μ has a smooth and strictly positive density Ψ on M against the Riemannian measure vol_{g} .

For $1 \leq p < \infty$ we denote by $L^p(M, \mu)$ the Lebesgue space of *p*-integrable functions with norm $\|\cdot\|_p$. If p=2, it is a Hilbert space with inner product

$$\langle f, g \rangle_{\mu} = \int_{M} f g d\mu.$$

Since μ is assumed to have a smooth and strictly positive density with respect to vol_g , the space of essentially bounded functions is independent of the particular choice of μ and we denote it by $L^{\infty}(M)$ and the corresponding norm by $\|\cdot\|_{\infty}$. The same holds true for the local Lebesgue spaces; for $1 \leq p \leq \infty$ we denote them by $L^p_{\operatorname{loc}}(M)$. Similarly, we write $L^0(M)$ for the space of all real-valued μ -a.e. defined measurable functions and $L^+(M)$ for the cone of all $[0,\infty]$ -valued μ -a.e. defined measurable functions. Note that functions in $L^+(M)$ may take the value ∞ on a set of positive measure. For two functions $f,g\in L^0(M)$ we let $f \wedge g = \min\{f,g\}$ and $f \vee g = \max\{f,g\}$, where the maximum and minimum are taken pointwise μ -a.e. Moreover, we write $f_+ = f \vee 0$ and $f_- = (-f) \vee 0$ for the positive and negative part of f, respectively.

The space of continuous functions on M is denoted by C(M) and equipped with the topology of uniform convergence on compact sets. We write $C_b(M)$ for the subspace of bounded continuous functions. Moreover, $C^{\infty}(M)$ is the space of smooth functions on M and and $C_c^{\infty}(M)$ is the space of smooth functions of compact support.

The space of test functions $\mathcal{D}(M) = C_c^{\infty}(M)$ is equipped with the usual locally convex topology, cf. [10, Chapter 4.1]. Its continuous dual, the space of distributions, is denoted by $\mathcal{D}'(M)$ and we write $\langle \cdot, \cdot \rangle$ for the dual pairing between $\mathcal{D}'(M)$ and $\mathcal{D}(M)$. A sequence of distributions (u_n) converges to a distribution u if $\langle u_n, \varphi \rangle \to \langle u, \varphi \rangle$ for each $\varphi \in \mathcal{D}(M)$. We identify functions $f \in L^1_{loc}(M)$ with the distribution

$$\mathcal{D}(M) \to \mathbb{R}, \ \varphi \mapsto \int_M f \varphi d\mathrm{vol}_g.$$

The so-obtained map $L^1_{loc}(M) \to \mathcal{D}'(M)$ is injective and continuous. For later it is important to note that we use the measure vol_g and not the measure μ for this identification. In particular, for $u \in L^2(M, \mu)$ (when viewed as distribution) and $\varphi \in \mathcal{D}(M)$ we have

$$\langle u, \Psi \varphi \rangle = \langle u, \varphi \rangle_u$$

where we recall that Ψ is the smooth density of μ against vol_q .

By $\Delta = \Delta_{\mu}$ we denote the weighted Laplacian of (M, g, μ) acting on $\mathcal{D}'(M)$; namely,

$$\Delta u = \frac{1}{\Psi} \operatorname{div}(\Psi \nabla u).$$

Here, ∇ and div are the distributional versions of the gradient and the divergence operator, respectively. The Laplacian leaves $\mathcal{D}(M)$ invariant and satisfies

$$\langle \Delta u, \Psi \varphi \rangle = \langle u, \Psi \Delta \varphi \rangle, \quad u \in \mathcal{D}'(M), \varphi \in \mathcal{D}(M).$$

This identity and our choice of the inclusion $L^1_{loc}(M) \hookrightarrow \mathcal{D}'(M)$ imply that the restriction of Δ to $\mathcal{D}(M)$ is a symmetric operator on $L^2(M,\mu)$.

To a smooth function $V: M \to \mathbb{R}$ and a strictly positive smooth function $\rho: M \to (0, \infty)$ we associate the *Schrödinger operator* $\mathcal{L}_{\rho,V}: \mathcal{D}'(M) \to \mathcal{D}'(M)$ via

$$\mathcal{L}_{\rho,V} = \rho^{-1}\Delta - \rho^{-1}V.$$

Its restriction to $\mathcal{D}(M)$ is a symmetric operator on $L^2(M, \rho\mu)$. The function V is called the *potential* and the function ρ is called the *density* of $\mathcal{L}_{\rho,V}$. Even though not strictly necessary, below we always assume the following.

Standing assumption. The potential V is nonnegative.

At various places we discuss which additional challenges a potential without a fixed sign poses and how these difficulties could possibly be overcome.

A distribution $u \in \mathcal{D}'((0,\infty) \times M)$ is called a (weak) solution to the heat equation (with respect to $\mathcal{L}_{o,V}$) if

$$\partial_t u = \mathcal{L}_{\rho,V} u$$

holds in the sense of $\mathcal{D}'((0,\infty)\times M)$. Due to local regularity theory, see Appendix A, every weak solution to the heat equation automatically belongs to $C^{\infty}((0,\infty)\times M)$. We usually write the time variable as a lower index, i.e., we let $u_t = u(t,\cdot)$ if u is a function depending on time and space. We say that a solution to the heat equation $u \in C^{\infty}((0,\infty)\times M)$ has initial value $f \in C(M)$ if it continuously extends to $[0,\infty)\times M$ (in which case we write $u \in C([0,\infty)\times M)$) and satisfies $u_0 = f$. Note that this is equivalent to the local uniform convergence $u_t \to f$, as $t \to 0+$.

2.2. Sobolev spaces and self-adjoint realizations. We define the first order weighted Sobolev space $W^1(M, \rho) = W^1_{\mu}(M, \rho)$ with respect to the density ρ by

$$W^{1}(M,\rho) = \{ f \in L^{2}(M,\rho\mu) \mid \nabla f \in \vec{L}^{2}(M,\mu) \}$$

and equip it with the norm

$$||f||_{W_1} = \left(\int_M |\nabla f|^2 d\mu + \int_M f^2 \rho d\mu\right)^{1/2}.$$

The closure of $C_c^{\infty}(M)$ in this space is denoted by $W_0^1(M,\rho) = W_{0,\mu}^1(M,\rho)$. If $\rho = 1$, we simply write $W^1(M)$ and $W_0^1(M)$ for $W^1(M,1)$ respectively $W_0^1(M,1)$.

In this paper we are concerned with properties of the self-adjoint realization of $\mathcal{L}_{\rho,V}$ that has generalized Dirichlet boundary conditions, which we introduce next. We let

$$D(Q_{\rho,V}) = W_0^1(M, V + \rho)$$

the domain of the quadratic form $Q_{\rho,V}:D(Q_{\rho,V})\times D(Q_{\rho,V})\to\mathbb{R}$ on which it acts by

$$Q_{\rho,V}(f,g) = \int_{M} \langle \nabla f, \nabla g \rangle d\mu + \int_{M} fgV d\mu.$$

It is a Dirichlet form on $L^2(M, \rho\mu)$, i.e., it is a nonnegative closed quadratic form and for any normal contraction C (a 1-Lipschitz function $C: \mathbb{R} \to \mathbb{R}$ with C(0) = 0) and all $f \in D(Q_{\rho,V})$ we have $C \circ f \in D(Q_{\rho,V})$ and $Q_{\rho,V}(C \circ f) \leq Q_{\rho,V}(f)$. Here and in what

follows we drop one argument when evaluation the diagonal of bilinear forms. This means that we use the convention $Q_{\rho,V}(f) = Q_{\rho,V}(f,f)$ for $f \in D(Q_{\rho,V})$.

It follows from the distributional definition of $\mathcal{L}_{\rho,V}$ that for all $f \in D(Q_{\rho,V})$ with $\mathcal{L}_{\rho,V}f \in L^2(M,\rho\mu)$ and $\varphi \in \mathcal{D}(M)$ we have

$$Q_{\rho,V}(f,\varphi) = \langle -\Delta f + V f, \Psi \varphi \rangle = \langle -\mathcal{L}_{\rho,V} f, \varphi \rangle_{\rho\mu}.$$

We denote by $L_{\rho,V}$ the nonpositive self-adjoint operator on $L^2(M,\rho\mu)$ that is associated with the closed form $Q_{\rho,V}$. By the above integration by parts formula it is a restriction of $\mathcal{L}_{\rho,V}$ to the domain

$$D(L_{\rho,V}) = \{ f \in D(Q_{\rho,V}) \mid \mathcal{L}_{\rho,V} f \in L^2(M,\rho\mu) \},$$

i.e., it acts by

$$L_{\rho,V}f = \mathcal{L}_{\rho,V}f, \quad f \in D(L_{\rho,V}).$$

Remark. The operator $L_{\rho,V}$ can be thought of having generalized Dirichlet boundary conditions or Dirichlet boundary conditions "at infinity". If V = 0 and $\rho = 1$, then $L_{1,0}$ is a self-adjoint realization of the weighted Laplacian. In our text it is important to allow nonvanishing potentials as well as some flexibility on the measure.

Since $Q_{\rho,V}$ is a Dirichlet form, the associated semigroup $T_t^{\rho,V} = e^{tL_{\rho,V}}$, t > 0, and resolvent $G_{\alpha}^{\rho,V} = (\alpha - L_{\rho,V})^{-1}$, $\alpha > 0$, are Markovian, i.e., for each $e \in L^2(M, \rho\mu)$ with $0 \le e \le 1$ they satisfy

$$0 \le T_t^{\rho,V} e \le 1$$
 and $0 \le \alpha G_{\alpha}^{\rho,V} e \le 1$.

Let $T: L^2(M, \rho\mu) \to L^2(M, \rho\mu)$ be a positivity preserving linear operator, i.e., an operator for which $f \geq 0$ implies $Tf \geq 0$. Then T can be extended to an operator $\tilde{T}: L^+(M) \to L^+(M)$ by letting

$$\tilde{T}f = \lim_{n \to \infty} Tf_n,$$

where (f_n) is an increasing sequence of nonnegative functions in $L^2(M, \rho\mu)$ with $f_n \to f$ μ -a.e. It is proven in [18] that this is well defined and a linear operator on the cone $L^+(M)$. In particular, if we let

$$dom(T) = \{ f \in L^0(M) \mid \tilde{T}|f| < \infty \,\mu\text{-a.e.} \},$$

then $\tilde{T}: \mathrm{dom}(T) \to L^0(m)$ defined by $\tilde{T}f := \tilde{T}f_+ - \tilde{T}f_-$ is a linear operator that extends T. In what follows we shall abuse notation and write T for the given operator and its extension to $\mathrm{dom}(T)$. We write dom for the domain of this extension because we reserve the capital D for the L^2 -domain of an unbounded operator or quadratic form.

The semigroup $(T_t^{\rho,V})$ and the resolvent $(G_{\alpha}^{\rho,V})$ are positivity preserving. It follows from their Markovian property that $L^{\infty}(M) \subseteq \text{dom}(T_t^{\rho,V}) \cap \text{dom}(G_{\alpha}^{\rho,V})$ and that $T_t^{\rho,V} 1 \le 1$ and $\alpha G_{\alpha}^{\rho,V} 1 \le 1$. Therefore, they act as contractions on the space $L^{\infty}(M)$. These extensions are weak-*-continuous on $L^{\infty}(M)$ in the parameters t respectively α . Since the semigroup and the resolvent are self-adjoint on $L^2(M,\rho\mu)$ and Markovian, by duality they can be extended to strongly continuous semigroups on $L^1(M,\rho\mu)$.

We recall the following basic definition concerning the extension to $L^{\infty}(M)$.

Definition 2.1 (Conservativeness and stochastic completeness). The Dirichlet form $Q_{\rho,V}$ is called *conservative* if $T_t^{\rho,V}1=1$ for all t>0. The weighted manifold (M,g,μ) is called *stochastically complete* if the Dirichlet form $Q_{1,0}$ on $L^2(M,\mu)$ is conservative.

3. A Generalized Conservation Property - Definition and Characterizations

It is a well known fact in Dirichlet form theory that Dirichlet forms with nonvanishing killing, in our case a nonvanishing potential V, cannot be conservative. In this section, we introduce a generalized conservation criterion invoking the potential. It is inspired by the corresponding definition for infinite weighted graphs that was given in [20]. We prove that Khasminskii's criterion [15] for stochastic completeness (conservativeness for the form with vanishing potential), which characterizes stochastic completeness in terms of unique solvability of the heat equation in L^{∞} , remains valid for the generalized conservation property with the Laplacian replaced by the Schrödinger operator. This can be seen as the main result of our paper.

In what follows we let $\hat{V} = V/\rho$. For t > 0 we define $H_t^{\rho,V} \in L^+(M)$ by

$$H_t^{\rho,V} = T_t^{\rho,V} 1 + \int_0^t T_s^{\rho,V} \hat{V} ds.$$

Here, $\int_0^t T_s^{\rho,V} \hat{V} ds$ is the $L^+(M)$ -extension of the positivity preserving operator

$$A_t: L^2(M, \rho\mu) \to L^2(M, \rho\mu), f \mapsto \int_0^t T_s^{\rho, V} f ds,$$

applied to the nonnegative function \hat{V} . Moreover, for $\alpha > 0$ we define $N_{\alpha}^{\rho,V} \in L^{+}(M)$ by

$$N_{\alpha}^{\rho,V} = \alpha G_{\alpha}^{\rho,V} 1 + G_{\alpha}^{\rho,V} \hat{V}.$$

The following theorem is the main technical insight of this paper. It discusses properties of the functions $H_t^{\rho,V}$ and $N_{\alpha}^{\rho,V}$. In particular, it shows that $\hat{V} \in \text{dom}(G_{\alpha}^{\rho,V})$ and $\hat{V} \in \text{dom}(A_t)$ so that the functions $N_{\alpha}^{\rho,V}$ and $H_t^{\rho,V}$ are finite. We postpone its proof to Section 5.

Theorem 3.1. (a) For each t > 0 we have $H_t^{\rho,V} \in C^{\infty}(M)$. The function $H^{\rho,V}: (0,\infty) \times M \to \mathbb{R}, (t,x) \mapsto H_t^{\rho,V}(x)$ satisfies $0 \leq H^{\rho,V} \leq 1$ and belongs to $C^{\infty}((0,\infty) \times M) \cap C([0,\infty) \times M)$. It solves the equation

$$\begin{cases} (\partial_t - \mathcal{L}_{\rho,V})H^{\rho,V} = V/\rho \ on \ (0,\infty) \times M, \\ H_0^{\rho,V} = 1. \end{cases}$$

Furthermore, $1 - H^{\rho,V}$ is the largest function $u \in C^{\infty}((0,\infty) \times M) \cap C([0,\infty) \times M)$ which satisfies $u \leq 1$ and

$$\begin{cases} (\partial_t - \mathcal{L}_{\rho,V})u \le 0 \text{ on } (0,\infty) \times M, \\ u_0 = 0. \end{cases}$$

(b) For each $\alpha > 0$ the function $N_{\alpha}^{\rho,V}$ belongs to $C^{\infty}(M)$, satisfies $0 \leq N_{\alpha}^{\rho,V} \leq 1$ and solves $(\alpha - \mathcal{L}_{\rho,V})N_{\alpha}^{\rho,V} = \alpha 1 + V/\rho$.

Furthermore, $1 - N_{\alpha}^{\rho,V}$ is the largest function $g \in C^{\infty}(M)$ which satisfies $g \leq 1$ and $(\alpha - \mathcal{L}_{\rho,V})g < 0$.

(c) For every $\alpha > 0$ and $x \in M$ we have

$$\int_0^\infty \alpha e^{-t\alpha} H_t^{\rho,V}(x) dt = N_\alpha^{\rho,V}(x).$$

(d) The following dichotomy holds. Either $H_t^{\rho,V}(x) = 1 = N_{\alpha}^{\rho,V}(x)$ for all $\alpha, t > 0$ and all $x \in M$ or $H_t^{\rho,V}(x) < 1$ and $N_{\alpha}^{\rho,V}(x) < 1$ for all $\alpha, t > 0$ and all $x \in M$.

Remark. As is standard, (a) and (b) mean that $H_t^{\rho,V}$ respectively $N_{\alpha}^{\rho,V}$ have smooth versions. In what follows we always work with those versions. Only assertion (d) uses that M is assumed to be connected.

With these properties of $H^{\rho,V}$ and $N_{\alpha}^{\rho,V}$ at hand, we can now introduce the generalized conservation property, the main concept of this paper.

Definition 3.2 (Conservativeness in the generalized sense). The Dirichlet form $Q_{\rho,V}$ (respectively the semigroup $(T_t^{\rho,V})_{t>0}$) is called *conservative in the generalized sense* if $H_t^{\rho,V}=1$ for all t>0.

Remark. For V=0 conservativeness and conservativeness in the generalized sense of $T_t^{\rho,V}$ coincide. The quantity $H_t^{\rho,V}$ has an interpretation in terms of the heat flow. If we study semigroup solutions to the heat equation (with respect to $\mathcal{L}_{\rho,V}$) with initial value 1, which corresponds to a uniform initial heat distribution, then $T_t^{\rho,V}$ 1 is the density of the total amount of heat in the system at time t. It can decrease over time for two reasons. Either heat is transported to the boundary of M (which can be thought of laying at infinity) or heat is lost inside of M due to the presence of a potential, which drains heat from the system. The amount of heat lost by the latter effect can (heuristically) be computed as

$$\int_0^t T_s^{\rho,V} \hat{V} ds,$$

cf. the discussion in [19, Section 8], which treats the same phenomenon for Dirichlet forms on graphs. Hence, the amount of heat transported to the boundary at infinity is $1 - H_t^{\rho,V}$, so that $H_t^{\rho,V} = 1$ for all t > 0 if and only if no heat is transported to the boundary at infinity. This generalized conservation property was first introduced in [20] for Dirichlet forms on graphs. Due to the previously described interpretation for $H_t^{\rho,V} = 1$, Dirichlet forms which are conservative in the generalized sense are called stochastically complete at infinity in [20]. In our terminology stochastic completeness is a property of the weighted manifold as a geometric object viz. the conservativeness of its canonical Dirichlet form. In contrast, we think of conservativeness (in the generalized sense) as a property of abstract

Markovian semigroups, where V and ρ appear as an additional non-geometric input. This is why we do not use the term stochastic completeness at infinity.

The main results of this paper are the following characterizations of the generalized conservation criterion. As mentioned above, they are extensions of the classical characterization of stochastic completeness by Khasminskii [15], which treats the case $\rho = \Psi = 1$ and V = 0.

Theorem 3.3. The following assertions are equivalent.

- (i) The function $1 H^{\rho,V}$ is nontrivial.
- (ii) For some/any $\alpha > 0$ the function $1 N_{\alpha}^{\rho,V}$ is nontrivial.
- (iii) For some/any $\alpha > 0$ there exists a nontrivial bounded $g \in C^{\infty}(M)$ with

$$(\alpha - \mathcal{L}_{\rho,V})g = 0.$$

(iv) For some/any $\alpha > 0$ there exists a nontrivial nonnegative bounded $g \in C^{\infty}(M)$ with

$$(\alpha - \mathcal{L}_{\rho,V})g \leq 0.$$

(v) There exists a nontrivial $u \in C^{\infty}((0,\infty) \times M) \cap C_b([0,\infty) \times M)$ that satisfies

$$\begin{cases} (\partial_t - \mathcal{L}_{\rho,V})u = 0 \ on \ (0,\infty) \times M, \\ u_0 = 0. \end{cases}$$

(vi) There exists a nontrivial nonnegative $u \in C^{\infty}((0,\infty) \times M) \cap C_b([0,\infty) \times M)$ that satisfies

$$\begin{cases} (\partial_t - \mathcal{L}_{\rho,V})u \le 0 \ on \ (0,\infty) \times M, \\ u_0 = 0. \end{cases}$$

Proof. In this proof we write G_{α} for $G_{\alpha}^{\rho,V}$, T_t for $T_t^{\rho,V}$, H_t for $H_t^{\rho,V}$ and N_{α} for $N_{\alpha}^{\rho,V}$ to shorten notation.

(i) \Leftrightarrow (ii): We use the identity

$$\int_0^\infty e^{-t\alpha} H_t \, dt = G_\alpha 1 + \frac{1}{\alpha} G_\alpha \hat{V}.$$

It shows that H=1 implies $N_{\alpha}=1$ for any $\alpha>0$. Hence, the nontriviality of $1-N_{\alpha}$ for one $\alpha>0$ shows the nontriviality of 1-H.

For the other implication note that by Theorem 3.1 the function H is smooth and satisfies $H \leq 1$. This implies that if $H \neq 1$, then there exist 0 < s < t and $\Omega \subseteq M$ open such that $H \leq C < 1$ on $(s,t) \times \Omega$. By the previous equation we obtain that $N_{\alpha} < 1$ on Ω for any $\alpha > 0$. Thus, the nontriviality of 1 - H implies that for any $\alpha > 0$ the function $1 - N_{\alpha}$ is nontrivial.

- $(i) \Rightarrow (v)$ and $(i) \Rightarrow (vi)$: By Theorem 3.1 the function 1 H has the desired properties.
- (v) \Rightarrow (i): Let $u \in C^{\infty}((0,\infty) \times M) \cap C_b([0,\infty) \times M)$ nontrivial with

$$\begin{cases} (\partial_t - \mathcal{L}_{\rho,V})u = 0 & \text{on } (0,\infty) \times M, \\ u_0 = 0. \end{cases}$$

Without loss of generality we can assume $|u| \le 1$. Theorem 3.1 (a) applied to u and -u yields $u \le 1 - H$ and $-u \le 1 - H$ so that $|u| \le 1 - H$. Since u is nontrivial, this implies that 1 - H is nontrivial.

(vi) \Rightarrow (i): Let $u \in C^{\infty}((0,\infty) \times M) \cap C_b([0,\infty) \times M)$ nontrivial and nonnegative with

$$\begin{cases} (\partial_t - \mathcal{L}_{\rho,V})u \le 0 & \text{on } (0,\infty) \times M, \\ u_0 = 0. \end{cases}$$

Without loss of generality we can assume $u \le 1$. Theorem 3.1 (a) shows $u \le 1 - H$. Since u is nonnegative and nontrivial, this implies that 1 - H is nontrivial.

(ii) \Leftrightarrow (iii) \Leftrightarrow (iv): This can be proven along the same lines as the other implications using Theorem 3.1 (b) instead of Theorem 3.1 (a).

For the sake of completeness we also mention the following characterization of the generalized conservation property. It is just the negation of the previous theorem. Recall that $\hat{V} = V/\rho$.

Theorem 3.4. The following assertions are equivalent.

(i) The Dirichlet form $Q_{\rho,V}$ on $L^2(M,\rho\mu)$ is conservative in the generalized sense, i.e., for all t>0 we have

$$1 = T_t^{\rho, V} 1 + \int_0^t T_s^{\rho, V} \hat{V} \, ds.$$

(ii) For all $\alpha > 0$ we have

$$1 = \alpha G_{\alpha}^{\rho,V} 1 + G_{\alpha}^{\rho,V} \hat{V}.$$

- (iii) For one/any $\alpha > 0$ any bounded $g \in C^{\infty}(M)$ with $(\alpha \mathcal{L}_{\rho,V})g = 0$ satisfies g = 0.
- (iv) For one/any $\alpha > 0$ any nonnegative bounded $g \in C^{\infty}(M)$ with $(\alpha \mathcal{L}_{\rho,V})g \leq 0$ satisfies g = 0.
- (v) Any solution $u \in C^{\infty}((0,\infty) \times M) \cap C_b([0,\infty) \times M)$ to the equation

$$\begin{cases} (\partial_t - \mathcal{L}_{\rho,V})u = 0 \text{ on } (0,\infty) \times M, \\ u_0 = 0, \end{cases}$$

satisfies u = 0.

(vi) Any nonnegative $u \in C^{\infty}((0,\infty) \times M) \cap C_b([0,\infty) \times M)$ that satisfies the differential inequality

$$\begin{cases} (\partial_t - \mathcal{L}_{\rho,V})u \le 0 \ on \ (0,\infty) \times M, \\ u_0 = 0, \end{cases}$$

satisfies u = 0.

Remark. (1) Theorem 3.3 can be seen as a generalization of [20, Theorem 1] on graphs, which does not include our assertion (ii), to the manifold case. An abstract version of the equivalence of (ii), (iii) and (iv) in Theorem 3.4 is given by [26, Theorem 4.68], which treats all Dirichlet forms. There however only weak solutions are considered and the equivalence of (i), (v) and (vi) is missing. In contrast to the proofs in

- [20, 26], which use elliptic maximum principles, our proof relies on a parabolic maximum principle.
- (2) In this text we chose to work in the smooth category because the input data (M, g, μ) and ρ, V are assumed to be smooth. If they were not, we could not use elliptic and parabolic regularity theory as we do here. However, the previous theorem would still hold true with essentially the same proof but with C^{∞} -solutions replaced by weak solutions in the local form domain.

As a consequence to the previous characterizations we obtain that conservativeness with vanishing potential implies conservativeness in the generalized sense for all nonnegative potentials. Moreover, conservativeness in the generalized sense is the same as conservativeness of a Dirichlet form with changed measure. In terms of associated stochastic processes this corresponds to a time change.

- **Theorem 3.5.** (a) If $Q_{\rho,0}$ is conservative, then $Q_{\rho,V}$ is conservative in the generalized sense. In particular, if (M, g, μ) is stochastically complete, then $Q_{1,V}$ is conservative in the generalized sense.
- (b) The Dirichlet form $Q_{\rho,V}$ on $L^2(M,\rho\mu)$ is conservative in the generalized sense if and only if the Dirichlet form $Q_{\rho+V,0}$ on $L^2(M,(\rho+V)\mu)$ is conservative.

Proof. (a): Let $\alpha > 0$ and let $u \in C^{\infty}(M)$ nonnegative and bounded with

$$(\alpha - \rho^{-1}\Delta + \rho^{-1}V)u = (\alpha - \mathcal{L}_{\rho,V})u \le 0.$$

According to Theorem 3.4 it suffices to prove u = 0. Since $\rho^{-1}V$ and u are nonnegative, the assumptions on u imply $(\alpha - \mathcal{L}_{\rho,0})u = (\alpha - \rho^{-1}\Delta)u \leq 0$. The conservativeness of $Q_{\rho,0}$ yields u = 0 by Theorem 3.4.

(b): Let $u \in C^{\infty}(M)$ be a solution to the equation $(1 - \mathcal{L}_{\rho,V})u = 0$. By definition of $\mathcal{L}_{\rho,V}$ and since $\rho > 0$, this is equivalent to $\rho u + Vu = \Delta u$. This in turn holds if and only if $\mathcal{L}_{\rho+V,0}u = (\rho+V)^{-1}\Delta u = u$. Therefore, $(1-\mathcal{L}_{\rho,V})u = 0$ has a nontrivial bounded solution in $C^{\infty}(M)$ if and only if $(1-\mathcal{L}_{\rho+V,0})u = 0$ has a nontrivial bounded solution in $C^{\infty}(M)$. With this at hand, the claim follows from Theorem 3.4.

Remark. For graphs assertion (a) is contained in [20]. Assertion (b) seems to be a new observation. Since conservativeness of Dirichlet forms is quite well-understood, it opens the way to studying the generalized conservation property. In Subsection 6.2 we use this strategy to provide a characterization of the generalized conservation property on model manifolds in terms of volume growth. In Subsection 6.3 we employ known volume growth criteria for the conservativeness of $Q_{\rho+V,0}$ to obtain that on any complete manifold there is a potential such that $Q_{\rho+V,0}$ is consevative in the generalized sense.

4. Maximum principles

In this section we discuss a parabolic and an elliptic maximum principle for the operator $\mathcal{L}_{\rho,V}$. Both are used in the proof of the main results. The proofs that we give apply to more general situations and so they may be of independent interest.

We let $\widetilde{Q}_{\rho,V}$ the Dirichlet form on $L^2(M,\rho\mu)$ with domain $D(\widetilde{Q}_{\rho,V}) = W^1(M,\rho+V)$, on which it acts by

$$\widetilde{Q}_{\rho,V}(f,g) = \int_{M} \langle \nabla f, \nabla g \rangle d\mu + \int_{M} V f g d\mu.$$

With this notation we have $||f||_{W^1}^2 = \widetilde{Q}_{\rho,V}(f) + ||f||_2^2$ for $f \in W^1(M, \rho + V)$. It follows from the definition of the distributional operator $\mathcal{L}_{\rho,V}$ that

$$\widetilde{Q}_{\rho,V}(f,\varphi) = \langle -\mathcal{L}_{\rho,V}f, \varphi \rangle_{\rho\mu}, \quad f \in D(\widetilde{Q}_{\rho,V}), \varphi \in C_c^{\infty}(M).$$

In particular, the associated self-adjoint operator is a restriction of $\mathcal{L}_{\rho,V}$. The following observation lies at the heart of all maximum principles in this section.

Lemma 4.1. The space $W_0^1(M, \rho + V)$ is an order ideal in $W^1(M, \rho + V)$, i.e., for $f \in W_0^1(M, \rho + V)$, $g \in W^1(M, \rho + V)$ the inequality $|g| \leq |f|$ implies $g \in W_0^1(M, \rho + V)$.

Proof. Let f, g as stated. Since $g_+, g_- \in W^1(M, \rho + V)$, $|f| \in W^1_0(M, \rho + V)$ (here we use that $\widetilde{Q}_{\rho,V}$ and $Q_{\rho,V}$ are Dirichlet forms and $x \mapsto x \vee 0$, $y \mapsto |y|$ are normal contractions) and $|g_+|, |g_-| \leq |f|$, it suffices to consider the case $0 \leq g \leq f$. By definition of $W^1_0(M, \rho + V)$ there exists a sequence (φ_n) in $C_c^{\infty}(M)$ with $||f - \varphi_n||_{W^1} \to 0$. Consider the functions

$$g_n := g \wedge |\varphi_n| = \frac{1}{2}(g + |\varphi_n| - |g - |\varphi_n||).$$

Since $0 \leq g \leq f$, the sequence (g_n) converges to g in $L^2(M, \rho\mu)$. Moreover, $\widetilde{Q}_{\rho,V}$ is a Dirichlet form and $\mathbb{R} \to \mathbb{R}, x \mapsto |x|$ is a normal contraction. Therefore,

$$\widetilde{Q}_{\rho,V}(g_n)^{1/2} = \frac{1}{2}\widetilde{Q}_{\rho,V}(g + |\varphi_n| - |g - |\varphi_n||)^{1/2}$$

$$\leq \frac{1}{2}\widetilde{Q}_{\rho,V}(g + |\varphi_n|)^{1/2} + \frac{1}{2}\widetilde{Q}_{\rho,V}(|g - |\varphi_n||)^{1/2}$$

$$\leq \widetilde{Q}_{\rho,V}(g)^{1/2} + \widetilde{Q}_{\rho,V}(\varphi_n)^{1/2}.$$

This implies that (g_n) is a bounded sequence in $W^1(M, \rho + V)$. By construction each g_n has compact support. It follows with the same arguments as in [10, Lemma 5.5] that functions in $W^1(M, \rho + V)$ with compact support belong to $W^1_0(M, \rho + V)$ (only the case $\rho = 1, V = 0$ is considered in [10] but the argument is more general). Hence (g_n) is a bounded sequence in the Hilbert space $(W^1_0(M, \rho + V), \|\cdot\|_{W^1})$. The Banach-Saks theorem implies that it has a subsequence (g_{n_k}) such that its sequence of Cesàro means $\tilde{g}_N = N^{-1} \sum_{k=1}^N g_{n_k}$ converges to some $h \in W^1_0(M, \rho + V)$ with respect to $\|\cdot\|_{W^1}$. In particular, $\tilde{g}_N \to h$ in $L^2(M, \rho\mu)$. However, since $g_n \to g$ in $L^2(M, \rho\mu)$, we also have $\tilde{g}_N \to g$ in $L^2(M, \rho\mu)$, such that $g = h \in W^1_0(M, \rho + V)$. This proves the claim.

Remark. The previous lemma says that the domain of the Dirichlet form $Q_{\rho,V}$ is an order ideal the domain of the Dirichlet form $\widetilde{Q}_{\rho,V}$. According to [25, Lemma 2.2] this is equivalent to $D(Q_{\rho,V}) \cap L^{\infty}(M)$ being an algebraic ideal in $D(\widetilde{Q}_{\rho,V}) \cap L^{\infty}(M)$. Form extensions of $Q_{\rho,V}$ with this property are called Silverstein extensions in the literature; hence $\widetilde{Q}_{\rho,V}$ is a Silverstein extension of $Q_{\rho,V}$.

We say that a function $f \in W^1(M, \rho + V)$ satisfies

$$f \ge 0 \mod W_0^1(M, \rho + V)$$

if there exists $g \in W_0^1(M, \rho + V)$ such that $f + g \ge 0$. For our purposes this is an adequate form of saying that f is nonnegative on 'the boundary' of M. The following lemma characterizes when this inequality holds. It can be proven along the same lines as [10, Lemma 5.12] but we give an alternative proof that is based on the fact that $W_0^1(M, \rho + V)$ is an order ideal in $W^1(M, \rho + V)$.

Lemma 4.2. A function $f \in W^1(M, \rho + V)$ satisfies $f \geq 0 \mod W_0^1(M, \rho + V)$ if and only if $f_- \in W_0^1(M, \rho + V)$.

Proof. It follows from the definition that $f_- \in W_0^1(M, \rho + V)$ implies

$$f \ge 0 \mod W_0^1(M, \rho + V).$$

Now assume that there exists some $g \in W_0^1(M, \rho + V)$ such that $f + g \ge 0$. We have $|g| \in W_0^1(M, \rho + V)$ and so we can assume $g \ge 0$. This implies $0 \le f_- \le g$. Since $f_- \in W^1(M, \rho + V)$, the claim follows from Lemma 4.1.

The following maximum principle is an extension of [10, Theorem 5.16] to the case when $V \neq 0$.

Theorem 4.3 (Parabolic maximum principle). Let $0 < T \le \infty$ and let $v : (0,T) \to W^1(M, \rho + V)$ be a path with the following properties.

- $\partial_t v$ exists as a strong limit in $L^2(M, \rho \mu)$,
- $v(t)_{-} \to 0$ in $L^{2}(M, \rho\mu)$, as $t \to 0+$,
- for every 0 < t < T, $v(t) \ge 0 \mod W_0^1(M, \rho + V)$,
- for every 0 < s < T, $(\partial_t v)(s) \ge \mathcal{L}_{\rho,V}(v(s))$ in the sense of $\mathcal{D}'(M)$.

Then $v \geq 0$ on $(0,T) \times M$.

Proof. According to Lemma 4.2 the 'boundary condition' $v \geq 0 \mod W_0^1(M, \rho + V)$ implies $v_- \in W_0^1(M, \rho + V)$. Thus, (for every fixed time) we can choose a sequence of nonnegative functions in $C_c^{\infty}(M)$ with $\varphi_n \to v_-$ with respect to $\|\cdot\|_{W^1}$ (this can be proven along the same lines as [10, Lemma 5.4]). Recall that $\mu = \Psi \operatorname{vol}_g$, $\langle \cdot, \cdot \rangle_{\rho\mu}$ denotes the inner product of $L^2(M, \rho\mu)$ and $\langle \cdot, \cdot \rangle$ denotes the dual pairing of $\mathcal{D}'(M)$. Using the distributional Definition of $\mathcal{L}_{\rho,V}$ and $\partial_t v \geq \mathcal{L}_{\rho,V} v$, we obtain

$$\begin{split} \langle \partial_t v, v_- \rangle_{\rho\mu} &= \lim_{n \to \infty} \langle \partial_t v, \varphi_n \rangle_{\rho\mu} \\ &= \lim_{n \to \infty} \langle \partial_t v, \rho \Psi \varphi_n \rangle \\ &\geq \lim_{n \to \infty} \langle \mathcal{L}_{\rho, V} v, \rho \Psi \varphi_n \rangle \\ &= -\lim_{n \to \infty} \widetilde{Q}_{\rho, V}(v, \varphi_n) \\ &= -\widetilde{Q}_{\rho, V}(v, v_-). \end{split}$$

Since $\widetilde{Q}_{\rho,V}$ is a Dirichlet form, we have $v_+ \in D(\widetilde{Q}_{\rho,V})$ and $\widetilde{Q}_{\rho,V}(v_+,v_-) \leq 0$. Therefore, the above amounts to

$$\langle \partial_t v, v_- \rangle_{\rho\mu} \ge \widetilde{Q}_{\rho,V}(v_-) \ge 0.$$

We shall see below that $\partial_t \|v_-\|_2^2 = -2 \langle \partial_t v, v_- \rangle_{\rho\mu}$, which implies $\partial_t \|v_-\|_2^2 \leq 0$. Hence, the function $t \mapsto \|v(t)_-\|_2^2$ is decreasing in time. Since we assumed $v(t)_- \to 0$ in $L^2(M, \rho\mu)$, as $t \to 0+$, we obtain $v_- = 0$ on (0, T) and we arrive at the conclusion $v \geq 0$.

It remains to prove $\partial_t ||v_-||_2^2 = -2 \langle \partial_t v, v_- \rangle_{\rho\mu}$. To this end, consider the C^1 -function

$$\varphi : \mathbb{R} \to \mathbb{R}, \varphi(x) = \begin{cases} x^2 & \text{if } x \leq 0, \\ 0 & \text{else.} \end{cases}$$

Its derivative satisfies

$$\varphi'(x) = \begin{cases} 2x & \text{if } x \le 0, \\ 0 & \text{else.} \end{cases}$$

An elementary computation shows that for any $x, y \in \mathbb{R}$ we have

$$\varphi(y) = \varphi(x) + \varphi'(x)(y - x) + R(x, y)$$

with a remainder R that satisfies $|R(x,y)| \leq (x-y)^2$. We obtain

$$\begin{split} \int_{M} & ((v(s+h)_{-})^{2} - (v(s)_{-})^{2})\rho d\mu = \int_{M} \left(\varphi(v(s+h)) - \varphi(v(s))\right)\rho d\mu \\ & = \int_{M} \varphi'(v(s))(v(s+h) - v(s))\rho d\mu + \int_{M} R(v(s+h), v(s))\rho d\mu \\ & = -2\int_{M} v(s)_{-}(v(s+h) - v(s))\rho d\mu + \int_{M} R(v(s+h), v(s))\rho d\mu. \end{split}$$

Since $\partial_t v$ exists in $L^2(M,\mu)$ as a strong limit, we also have

$$\begin{split} \frac{1}{h} \left| \int_{M} R(v(s+h), v(s)) \rho d\mu \right| &\leq \frac{1}{h} \int_{M} (v(s+h) - v(s))^{2} \rho d\mu \\ &= h \left\| \frac{v(s+h) - v(s)}{h} \right\|_{2}^{2} \to 0, \text{ as } h \to 0, \end{split}$$

and

$$\frac{1}{h} \int_{\mathcal{M}} v(s)_{-}(v(s+h) - v(s))\rho d\mu \to \langle (\partial_{t}v)(s), v(s)_{-} \rangle_{\rho\mu}, \text{ as } h \to 0.$$

Combining these considerations shows $\partial_t ||v_-||_2^2 = -2 \langle \partial_t v, v_- \rangle_{\rho\mu}$ and finishes the proof. \square

Remark. The previous lemma only relies on the fact that we work on a weighted manifold at one place. We use the identity $-\langle \mathcal{L}_{\rho,V}u, \rho\Psi\varphi\rangle = \widetilde{Q}_{\rho,V}(u,\varphi)$ for $u \in D(\widetilde{Q}_{\rho,V})$ and $\varphi \in C_c^{\infty}(M)$. Suppose that \mathcal{E} and $\widetilde{\mathcal{E}}$ are Dirichlet forms (on an arbitrary L^2 -space) such that $\widetilde{\mathcal{E}}$ extends \mathcal{E} and $D(\widetilde{\mathcal{E}})$ is an order ideal of $D(\mathcal{E})$ (in this case $\widetilde{\mathcal{E}}$ is called Silverstein extension of \mathcal{E} , cf. the previous remark). Our proof of Lemma 4.2 also works for the pair

 \mathcal{E} and $\widetilde{\mathcal{E}}$, i.e., for $u \in D(\widetilde{\mathcal{E}})$ the inequality $u \geq 0 \mod D(\mathcal{E})$ is equivalent to $u_- \in D(\mathcal{E})$. If, furthermore, one takes the inequality

$$\langle \partial_t u, \varphi \rangle \ge -\widetilde{\mathcal{E}}(u, \varphi)$$

for all nonnegative φ in a suitable core of $D(\mathcal{E})$ as a replacement for the distributional inequality $\partial_t u \geq \mathcal{L}_{\rho,V} u$, then one can prove a parabolic maximum principle for the pair of forms \mathcal{E} and $\widetilde{\mathcal{E}}$ along the same lines as above. In this sense our proof of the lemma is not only an extension of [10, Theorem 5.16] to the case when $V \neq 0$, but to general Dirichlet forms.

Theorem 4.4 (Elliptic maximum principle). Let $f \in W^1(M, \rho + V)$ with

$$f \ge 0 \mod W_0^1(M, \rho + V).$$

If for some $\alpha > 0$ it satisfies $(\alpha - \mathcal{L}_{o,V}) f \geq 0$, then $f \geq 0$.

Proof. Lemma 4.2 implies $f_- \in W_0^1(M, \rho + V)$. As we have seen in the proof of Lemma 4.3, we can therefore choose a sequence (φ_n) of nonnegative functions in $C_c^{\infty}(M)$ that converges to f_- in $W_0^1(M, \rho + V)$. Using the definition of $\mathcal{L}_{\rho,V}$ we obtain

$$\begin{split} \widetilde{Q}_{\rho,V}(f,f_{-}) &= \lim_{n \to \infty} \widetilde{Q}_{\rho,V}(f,\varphi_{n}) = -\lim_{n \to \infty} \langle \mathcal{L}_{\rho,V}f, \Psi \rho \varphi_{n} \rangle \\ &\geq -\alpha \lim_{n \to \infty} \langle f, \Psi \rho \varphi_{n} \rangle = -\alpha \langle f, f_{-} \rangle_{\rho\mu} = \alpha \|f_{-}\|_{2}^{2}. \end{split}$$

Since $\widetilde{Q}_{\rho,V}$ is a Dirichlet form, we also have $\widetilde{Q}_{\rho,V}(f_+,f_-) \leq 0$ and therefore $\widetilde{Q}_{\rho,V}(f,f_-) \leq 0$. Combined with the previous computation this shows $f_- = 0$.

Remark. This maximum principle also holds true for a Dirichlet form and a Silverstein extension, cf. the remark after the proof of Theorem 4.3.

5. Proof of the properties of $N_{\alpha}^{\rho,V}$ and $H_{t}^{\rho,V}$

This section is devoted to proving Theorem 3.1. For the proof we need several auxiliary lemmas. Let $\Omega \subseteq M$ an open subset. We denote by (T_t^{Ω}) the $L^2(\Omega, \rho\mu)$ -semigroup of the Dirichlet form

$$Q_{\rho,V}^{\Omega}(f,g) = \int_{\Omega} \langle \nabla f, \nabla g \rangle \, d\mu + \int_{\Omega} V f g d\mu$$

with domain $D(Q_{\rho,V}^{\Omega}) = W_0^1(\Omega, \rho + V)$. We extend it to $f \in L^2(M, \rho\mu)$ by letting

$$T_t^{\Omega} f := \begin{cases} T_t^{\Omega} f|_{\Omega} & \text{on } \Omega, \\ 0 & \text{on } M \setminus \Omega. \end{cases}$$

Similarly, we write (G^{Ω}_{α}) for the $L^2(\Omega,\rho\mu)$ -resolvent of $Q^{\Omega}_{\rho,V}$ and extend it to $L^2(M,\rho\mu)$

Lemma 5.1 (Duhamel's principle). Let $\Omega \subseteq M$ be an open relatively compact subset and let $f \in C^{\infty}(M)$. Let $u \in C^{\infty}((0,\infty) \times M) \cap C([0,\infty) \times M)$ nonnegative. If $\partial_t u - \mathcal{L}_{\rho,V} u \geq f$ on $(0,\infty) \times \Omega$, then

$$u_t \ge T_t^{\Omega} u_0 + \int_0^t T_s^{\Omega} f ds.$$

Proof. We prove that the restriction of the function

$$t \mapsto v_t := u_t - \left(T_t^{\Omega} u_0 + \int_0^t T_s^{\Omega} f \, ds \right)$$

to $L^2(\Omega, \rho\mu)$ satisfies all the assumptions of Theorem 4.3 (when applied on the weighted manifold (Ω, g, μ)). The nonnegativity of u and the vanishing of $T_t^{\Omega}u_0$ and $T_t^{\Omega}f$ outside of Ω then imply the claim.

Since Ω is relatively compact and $u \in C^{\infty}((0,\infty) \times M) \cap C([0,\infty) \times M)$ the following holds true:

- $\partial_t u$ exists as a strong limit in $L^2(\Omega, \rho \mu)$,
- $u(t,\cdot) \to u_0$ in $L^2(\Omega,\rho\mu)$, as $t \to 0+$,
- $u|_{\Omega} \in W^1(\Omega, \rho + V)$.

Moreover, u_0 and f are continuous on $\overline{\Omega}$ so that their restrictions to Ω belong to $L^2(\Omega, \rho\mu)$. The semigroup (T_t^{Ω}) is strongly continuous on $L^2(\Omega, \mu)$. Therefore,

$$T_t^{\Omega}u_0 + \int_0^t T_s^{\Omega}fds \to u_0 \text{ in } L^2(\Omega,\rho\mu), \text{ as } t \to 0+.$$

This shows $\lim_{t\to 0+} v(t) = 0$ in $L^2(\Omega, \rho\mu)$.

If we denote by $L_{\rho,V}^{\Omega}$ the self-adjoint operator associated with $Q_{\rho,V}^{\Omega}$, it follows from standard semigroup theory that $T_t^{\Omega}u_0 \in D(L_{\rho,V}^{\Omega})$ and $\int_0^t T_s^{\Omega}fds \in D(L_{\rho,V}^{\Omega})$. Since $u \geq 0$ and $D(L_{\rho,V}^{\Omega}) \subseteq D(Q_{\rho,V}^{\Omega}) = W_0^1(\Omega, \rho + V)$, this implies $v \geq 0 \mod W_0^1(\Omega, \rho + V)$. By semigroup theory we also have $L_{\rho,V}^{\Omega}T_t^{\Omega}u_0 = \partial_t(T_t^{\Omega}u_0)$ and

$$L_{\rho,V}^{\Omega} \int_{0}^{t} T_{s}^{\Omega} f ds = T_{t}^{\Omega} f - f = \partial_{t} \int_{0}^{t} T_{s}^{\Omega} f ds - f,$$

where the time derivatives exist as strong limits in $L^2(\Omega, \rho\mu)$. Therefore, $\partial_t v$ exists strongly in $L^2(\Omega, \rho\mu)$. Using that the operator $L^{\Omega}_{\rho,V}$ is a restriction of $\mathcal{L}_{\rho,V}$, these computations and the pointwise assumption $\partial_t u - \mathcal{L}_{\rho,V} u \geq f$ on Ω show

$$\partial_t v = \partial_t u - \partial_t T_t^{\Omega} u_0 - \partial_t \int_0^t T_s^{\Omega} f ds$$

$$\geq \mathcal{L}_{\rho, V} u + f - \mathcal{L}_{\rho, V} T_t^{\Omega} u_0 - \mathcal{L}_{\rho, V} \int_0^t T_s^{\Omega} f ds - f$$

$$= \mathcal{L}_{\rho, V} v$$

in the sense of $\mathcal{D}'(\Omega)$. Thus, we confirmed that v satisfies all the assumptions of Theorem 4.3 and we arrive at $v \geq 0$.

The following lemma is an extension of part of [10, Theorem 7.13] to integrals of semi-groups and the case with $V \neq 0$.

Lemma 5.2. Let $e, f \in C_c^{\infty}(M)$ and let $u:(0,\infty) \to L^2(M,\rho\mu)$ given by

$$u(t) = T_t^{\rho,V} e + \int_0^t T_s^{\rho,V} f ds.$$

For each t > 0 we have $u(t) \in C^{\infty}(M)$. Moreover, the function $\tilde{u} : (0, \infty) \times M \to \mathbb{R}$, $(t, x) \mapsto u(t)(x)$ belongs to $C^{\infty}((0, \infty) \times M) \cap C([0, \infty) \times M)$ and satisfies

$$\begin{cases} (\partial_t - \mathcal{L}_{\rho,V})\tilde{u} = f, \\ \tilde{u}_0 = e. \end{cases}$$

Proof. In this proof we write T_t for $T_t^{\rho,V}$ to shorten notation.

By standard semigroup theory the function u is continuous and continuously differentiable (strongly in $L^2(M,\rho\mu)$). Let u' denote its derivative. Lemma C.2 yields the existence of $\tilde{u} \in L^1_{loc}((0,\infty) \times M)$ with $\partial_t \tilde{u} \in L^1_{loc}((0,\infty) \times M)$ such that $\tilde{u}_t = u(t)$ for λ -a.e. t > 0 and $(\partial_t \tilde{u})_s = u'(s)$ for λ -a.e. s > 0. Moreover, since the generator of $T_t^{\rho,V}$ is a restriction of $\mathcal{L}_{\rho,V}$, we have $u' - \mathcal{L}_{\rho,V}u = f$ in $L^2(M,\rho\mu)$. Together with the properties of \tilde{u} this implies $(\partial_t - \mathcal{L}_{\rho,V})\tilde{u} = f$ in the sense of distributions. We infer from Lemma A.2 that $\tilde{u} \in C^{\infty}((0,\infty) \times M)$ (or more precisely it has a smooth version, which we consider from now on). The continuity of u and the smoothness of \tilde{u} imply $u(t) = \tilde{u}_t$ in $L^2(M,\rho\mu)$ for all t > 0.

It remains to prove the result on the initial value of \tilde{u} . Recall that $L_{\rho,V}$ is the selfadjoint operator associated with $Q_{\rho,V}$ (the generator of $(T_t^{\rho,V})$). Let μ_e, μ_f the spectral measures of $L_{\rho,V}$ at e, f, respectively. Let $m \in \mathbb{N}_0$ arbitrary. Since $e, f \in C_c^{\infty}(M)$, we have $e, f \in D(L_{\rho,V}^m)$ and the spectral calculus of $L_{\rho,V}$ shows $T_t e, \int_0^t T_s f ds \in D(L_{\rho,V}^m)$,

$$||L_{\rho,V}^m(T_t e - e)||_2^2 = \int_{-\infty}^0 \lambda^{2m} (e^{\lambda t} - 1)^2 d\mu_e$$

and

$$\left\| L_{\rho,V}^m \int_0^t T_s f ds \right\|_2^2 = \int_{-\infty}^0 \lambda^{2(m-1)} (e^{\lambda t} - 1)^2 d\mu_f.$$

For any t > 0 and the functions

$$f_t: (-\infty, 0] \to \mathbb{R}, f_t(\lambda) = \lambda^{2(m-1)} (e^{\lambda t} - 1)^2$$

satisfy $|f_t(\lambda)| \leq t^2 |\lambda|^{2m}$, $\lambda \leq 0$, and since $e, f \in D(L^m_{\rho,V})$, the function $\lambda \mapsto |\lambda|^{2m}$ is μ_e and μ_f integrable. Hence, it follows from Lebesgue's dominated convergence theorem that

$$\lim_{t \to 0+} \|L_{\rho,V}^m(T_t e - e)\|_2^2 = \lim_{t \to 0+} \left\| L_{\rho,V}^m \int_0^t T_s f ds \right\|_2^2 = 0.$$

The operator $L_{\rho,V}$ is a restriction of $\mathcal{L}_{\rho,V}$ so that these computations show $\|\mathcal{L}_{\rho,V}^m(\tilde{u}_t-e)\|_2 \to 0$, as $t \to 0+$, for every $m \in \mathbb{N}_0$. The local Sobolev embedding theorem, see Lemma A.1, implies that this convergence also holds locally uniformly. In particular, we obtain $\tilde{u}_0 = e$ and we arrive at the desired claim.

In the following lemma we denote by A_t the positivity preserving operator

$$A_t: L^2(M, \rho\mu) \to L^2(M, \rho\mu), \quad A_t f = \int_0^t T_s^{\rho, V} f ds,$$

and its extension to $L^+(M)$.

Lemma 5.3. Let $f \in L^+(M)$ such that $A_t f \in L^{\infty}(M)$ for all t > 0. Then the map $(0, \infty) \to L^{\infty}(M)$, $t \mapsto A_t f$ is weak-*-continuous.

Proof. We denote by (\cdot,\cdot) the dual pairing between $L^{\infty}(M)$ and $L^{1}(M,\rho\mu)$. For given $g \in L^{1}(M,\rho\mu)$ and $t_{0}, \varepsilon > 0$ we choose $\tilde{f} \in L^{2}(M,\rho\mu) \cap L^{\infty}(M)$ with $0 \leq \tilde{f} \leq f$ such that

$$0 \le (A_{t_0+1}f - A_{t_0+1}\tilde{f}, |g|) < \varepsilon.$$

Such an \tilde{f} exists by the definition of the extension of A_t to $L^+(M)$ and the assumption $A_t f \in L^{\infty}(M)$ for all t > 0. Since the semigroup $(T_t^{\rho,V})$ is positivity preserving, for $h \in L^+(M)$ the map $(0,\infty) \to L^+(M), t \mapsto A_t h$ is monotone increasing in the sense of the order on $L^+(M)$. Using that A_t is linear on $\text{dom}(A_t)$, this monotonicity implies for $0 < t < t_0 + 1$ that

 $|(A_t f - A_t \tilde{f}, |g|)| = |(A_t (f - \tilde{f}), |g|)| \le |(A_{t_0+1} (f - \tilde{f}), |g|)| = (A_{t_0+1} f - A_{t_0+1} \tilde{f}, |g|) < \varepsilon.$ For $0 < t < t_0 + 1$ we obtain

$$|(A_t f - A_{t_0} f, g)| \le (|A_t \tilde{f} - A_{t_0} \tilde{f}|, |g|) + 2\varepsilon = \left| \int_{t_0}^t (T_s^{\rho, V} \tilde{f}, |g|) ds \right| + 2\varepsilon.$$

Since \tilde{f} was chosen in $L^{\infty}(M)$, the map $(0,\infty) \to L^{\infty}(M)$, $s \mapsto T_s^{\rho,V} \tilde{f}$ is weak-*-continuous. Hence, it follows from the above computation that for t sufficiently close to t_0 we have $|(A_t f - A_{t_0} f, g)| < 3\varepsilon$. Since ε was arbitrary, this finishes the proof.

With all these preparations at hand we can now proof Theorem 3.1. Recall that $H_t^{\rho,V}=T_t^{\rho,V}1+\int_0^t T_s^{\rho,V}\hat{V}ds$ and $N_\alpha^{\rho,V}=\alpha G_\alpha^{\rho,V}1+G_\alpha^{\rho,V}\hat{V}$ with $\hat{V}=V/\rho$.

Proof of Theorem 3.1. In this proof we write G_{α} for $G_{\alpha}^{\rho,V}$, T_t for $T_t^{\rho,V}$, H_t for $H_t^{\rho,V}$ and N_{α} for $N_{\alpha}^{\rho,V}$ to shorten notation.

(a): The bound $0 \le H$ is obvious as the involved operators are positivity preserving. Let $e, f \in C_c^{\infty}(M)$ with $0 \le e \le 1$ and $0 \le f \le \hat{V}$ and let $\Omega \subseteq M$ open and relatively compact. A function u as in the maximality statement satisfies $(\partial_t - \mathcal{L}_{\rho,V})(1-u) \ge \hat{V}$ and $(1-u)_0 = 1$. Thus, Duhamel's principle, Lemma 5.1, shows

$$1 - u_t \ge T_t^{\Omega} 1 + \int_0^t T_s^{\Omega} \hat{V} ds \ge T_t^{\Omega} e + \int_0^t T_s^{\Omega} f ds.$$

Letting $\Omega \nearrow M$ and using Lemma B.1 this implies

$$(\heartsuit) 1 - u_t \ge T_t e + \int_0^t T_s f ds.$$

Moreover, letting $e \nearrow 1$ and $f \nearrow \hat{V}$ we arrive at $1 - u_t \ge H_t$ for all t > 0. Since the extension of the semigroup $T_t^{\rho,V}$ to $L^{\infty}(M)$ is weak-*-continuous, this observation and Lemma 5.3 yield that $(0,\infty) \to L^{\infty}(M)$, $t \mapsto H_t$ is weak-*-continuous.

Lemma 5.2 implies that for each t > 0 we have

$$H_t^{e,f} := T_t e + \int_0^t T_s f ds \in C^{\infty}(M)$$

and that the function $H^{e,f}$ given by $(t,x) \mapsto H_t^{e,f}(x)$ satisfies $H^{e,f} \in C^{\infty}((0,\infty) \times M)$.

Let now $(e_n), (f_n)$ increasing sequences in $C_c^{\infty}(M)$ with $e_n \to 1$ pointwise and $f_n \to \hat{V}$ pointwise. Since $(T_t^{\rho,V})$ is positivity preserving and Inequality \heartsuit holds for all e_n, f_n , for each t > 0 we have

$$H_t^{e_n, f_n} \le H_t^{e_{n+1}, f_{n+1}} \le 1 - u_t \,\mu$$
-a.e.

The smoothness of H^{e_n,f_n} and 1-u implies that these inequalities hold for all $(t,x) \in (0,\infty) \times M$. In particular, the limit $h := \lim_{n \to \infty} H^{e_n,f_n}$ exists pointwise.

It follows from the definition of H that for each t > 0 we have $h_t = H_t$ μ -a.e. In particular, h is a measurable version of H on $(0, \infty) \times M$ and the bound $H^{e_n, f_n} \leq 1 - u$ yields $h \leq 1 - u$.

From the monotone convergence theorem and the bound $0 \leq h \leq 1$ we further obtain $H^{e_n,f_n} \to h$ in $L^1_{loc}((0,\infty) \times M)$. Since $L^1_{loc}((0,\infty) \times M)$ continuously embeds into $\mathcal{D}'((0,\infty) \times M)$ and since the distributional version of $\partial_t - \mathcal{L}_{\rho,V}$ is continuous with respect to \mathcal{D}' -convergence, this and Lemma 5.2 imply

$$(\partial_t - \mathcal{L}_{\rho,V})h = \lim_{n \to \infty} (\partial_t - \mathcal{L}_{\rho,V})H^{e_n,f_n} = \lim_{n \to \infty} f_n = \hat{V},$$

in $\mathcal{D}'((0,\infty)\times M)$. It follows from Lemma A.2 that h has a version $\tilde{h}\in C^{\infty}((0,\infty)\times M)$. From Fubini's theorem we infer that for λ -a.e. t>0 we have $h_t=\tilde{h}_t$ μ -a.e. This implies $\tilde{h}_t=H_t$ in $L^+(M)$ for λ -a.e. t>0. Since \tilde{h} is smooth and $t\mapsto H_t$ is weak-*-continuous on $L^{\infty}(M)$, we arrive at $\tilde{h}_t=H_t$ in $L^+(M)$ for all t>0, the claimed smoothness of H_t . The inequality $u_t\leq 1-H_t$ has been proven along the way.

It remains to show the result on the initial value of H. For this purpose it suffices to prove $\tilde{h} \in C([0,\infty) \times M)$ and $\tilde{h}_0 = 1$. Let $K \subseteq M$ compact and suppose e = 1 on K. Since for every t > 0 we have $H_t^{e,f} \leq H_t \leq 1$ pointwise μ -a.e. and $(t,x) \to H_t^{e,f}(x)$ is smooth, for every t > 0 we obtain the pointwise estimate

$$|1 - \tilde{h}_t| \le |1 - H_t^{e,f}|.$$

According to Lemma 5.2 we have $H_t^{e,f} \to e$ locally uniformly, as $t \to 0+$. This implies $\tilde{h}_t \to 0$ locally uniformly on K, as $t \to 0+$. Since K was arbitrary, this proves $\tilde{h} \in C([0,\infty) \times M)$ and $\tilde{h}_0 = 1$.

(b): Let $g \in C^{\infty}(M)$ with $g \leq 1$ and $(\alpha - \mathcal{L}_{\rho,V})g \leq 0$ be given. For $\Omega \subseteq M$ relatively compact and $e, f \in C_c^{\infty}(M)$ with $0 \leq e \leq 1$ and $0 \leq f \leq \hat{V}$ we let

$$h_{e,f}^{\Omega} = 1 - \alpha G_{\alpha}^{\Omega} e - G_{\alpha}^{\Omega} f - g|_{\Omega}.$$

Then $h_{e,f}^{\Omega} \in W^1(\Omega, \rho + V)$. Since $\alpha G_{\alpha}^{\Omega} e + G_{\alpha}^{\Omega} f \in W_0^1(\Omega, \rho + V)$ and $g \leq 1$, we have $h_{e,f}^{\Omega} \geq 0$ mod $W_0^1(\Omega, \rho + V)$. Moreover, the inequality $(\alpha - \mathcal{L}_{\rho,V})g \leq 0$ and that $\mathcal{L}_{\rho,V}$ is an extension of the generator of G_{α}^{Ω} yield

$$(\alpha - \mathcal{L}_{\rho,V})h_{e,f}^{\Omega} = \alpha + \hat{V} - \alpha e - f - (\alpha - \mathcal{L}_{\rho,V})g \ge 0 \text{ on } \Omega.$$

With this at hand, Theorem 4.4 shows $h_{e,f}^{\Omega} \geq 0$. Letting first $\Omega \nearrow M$ and using Lemma B.1 and letting $e \nearrow 1$, $f \nearrow \hat{V}$ afterwards shows $1 - N_{\alpha} - g \geq 0$. Let now g = 0. Since

the convergence of $h_{e,f}^{\Omega}$ is monotone decreasing and $h_{e,f}^{\Omega}$ is nonnegative, we also obtain $h_{e,f}^{\Omega} \to 1 - N_{\alpha}$ in $\mathcal{D}'(M)$. This implies in $\mathcal{D}'(M)$

$$(\alpha - \mathcal{L}_{\rho,V})(1 - N_{\alpha}) = \lim_{f \nearrow V} \lim_{e \nearrow 1} \lim_{\Omega \nearrow M} (\alpha - \mathcal{L}_{\rho,V}) h_{e,f}^{\Omega} = 0.$$

Lemma A.1 yields that $1 - N_{\alpha}$ and hence also N_{α} is smooth. This finishes the proof of (b). (c): For H and N_{α} we choose the smooth versions as in (a) and (b). The L^2 -resolvent (G_{α}) is the Laplace transform of (T_t) (in the Bochner sense), i.e., for all $\alpha > 0$ and $f \in L^2(M, \rho\mu)$ we have

$$\int_0^\infty e^{-t\alpha} T_t f dt = G_\alpha f.$$

Let now $e, f \in C_c(M)$ with $0 \le e \le 1$ and $0 \le f \le \hat{V}$, respectively, and let $H_t^{e,f} \in C^{\infty}(M)$ be as defined as in the proof of (a). Fubini's theorem yields

$$\int_0^\infty e^{-t\alpha} H_t^{e,f} dt = \int_0^\infty e^{-t\alpha} T_t e dt + \int_0^\infty \int_0^t e^{-t\alpha} T_s f ds dt = G_\alpha e + \frac{1}{\alpha} G_\alpha f,$$

where the identity holds in $L^2(M, \rho\mu)$. Since both side of the equation are smooth, it also holds pointwise everywhere on M. Letting $e \nearrow 1$ and $f \nearrow V$ we have that $H^{e,f} \nearrow H$ $\lambda \otimes \mu$ -a.e. (cf. proof of (a)) and $G_{\alpha}e + \frac{1}{\alpha}G_{\alpha}f \nearrow \alpha^{-1}N_{\alpha}$ μ -a.e. With this at hand, for nonnegative $\varphi \in \mathcal{D}(M)$ we conclude with the help of the monotone convergence theorem and Fubini's theorem that

$$\langle \int_0^\infty e^{-t\alpha} H_t dt, \varphi \rangle = \frac{1}{\alpha} \langle N_\alpha, \varphi \rangle.$$

Since $\int_0^\infty e^{-t\alpha} H_t dt$ and N_α are continuous, we arrive at the desired identity.

(d): We only prove the statement for N_{α} , the statement for H then follows with the help of assertion (c). For $\alpha > 0$ we consider the smooth function $u = 1 - N_{\alpha}$. We prove that u(x) = 0 for some $x \in M$ implies u = 0 on M. Since M is connected and the set of zeros $N = \{x \in M \mid u(x) = 0\}$ is closed, it suffices to show that N is also open.

According to (a) we have $(\alpha - \mathcal{L}_{\rho,V})u = 0$, or equivalently,

$$-\Delta u + (\alpha \rho + V)u = 0.$$

Let $x \in N$ and let $\varphi : U \to W$ be a chart with $x \in U \subseteq M$ and $W \subseteq \mathbb{R}^d$. The equation for u implies that in local coordinates the smooth function $\bar{u} = u \circ \varphi^{-1} : W \to \mathbb{R}$ satisfies

$$D\bar{u} := -\sum_{i,j} a_{ij} \partial_i \partial_j \bar{u} + \sum_i b_i \partial_i \bar{u} + c\bar{u} = 0,$$

where a_{ij} , b_i and c are smooth functions on W and ∂_i are the ordinary partial derivatives. Moreover, the 0-th order coefficient c is nonnegative and by shrinking U if necessary the coefficient matrix (a_{ij}) can be chosen to be uniformly elliptic. For such elliptic operators it is well-known that smooth functions $v: W \to [0, \infty)$ with Dv = 0 and v(x) = 0 for some $x \in W$ vanish identically on W, see e.g. [4, Theorem 6.4.4]. We conclude $\bar{u} = 0$ on W so that u = 0 on U. This shows that the set of zeros of u is open and finishes the proof. \square

Our proofs would also allow for real-valued potentials without a definite sign. However, in this case it seems to be technically hard to even define H and N_{α} . We shortly discuss this in the following remark.

Remark. Our proof of Theorem 3.1 shows that in principle we could drop the assumption that the smooth potential V is nonnegative and allow sufficiently small negative parts. More precisely, if the negative part V_- belongs to the extended Kato class of the operator L_{ρ,V_+} and satisfies $c_{\alpha}(V_-) < 1$ for some $\alpha > 0$ in the sense of [27], the form $Q_{\rho,V}$ is closed on the domain $W_0^1(M, \rho + V_+)$ and the associated semigroup and resolvent are positivity preserving and map $L^{\infty}(M)$ to $L^{\infty}(M)$. In this case, also the main technical lemmas, namely the maximum principles Lemma 4.3 and Lemma 4.4, hold true for paths in $W^1(M, \rho + V_+)$. In their proofs we only used that the form $Q_{\rho,V}$ satisfies the first Beurling-Deny criterion and not the second. However, it is harder to control the quantity $\int_0^t T_s^{\rho,V} \hat{V} ds$. If we let $H_t^{\Omega} = T_t^{\Omega} 1 + \int_0^t T_t^{\Omega} \hat{V} ds$ as in the proof above, Duhamel's principle (applied to 1 and $1 - H^{\Omega}$) guarantees that for any compact $\Omega \subseteq M$ and t > 0 we have

$$1 \ge T_t^{\Omega} 1 + \int_0^t T_t^{\Omega} \hat{V} ds \ge 0.$$

In contrast to situation for nonnegative potentials, this inequality and $T_t^{\rho,V}1 \in L^{\infty}(M)$ do not guarantee the finiteness of

$$\int_0^t T_t^{\rho,V} |\hat{V}| ds.$$

Hence, $H^{\rho,V}$ (and also $N_{\alpha}^{\rho,V}$) may not be well-defined. However, if V_{-} is small as above and additionally satisfies $V_{-} \in L^{q}(M,\rho\mu)$ for some $1 \leq q \leq \infty$, it follows from the considerations in [27] that $\int_{0}^{t} T_{t}^{\rho,V} V_{-} ds \in L^{q}(M,\rho\mu)$. In this situation, the statements of Theorem 3.1 remain true. Once the existence of $H^{\rho,V}$ is settled, the above inequalities show $0 \leq H^{\rho,V} \leq 1$ after letting $\Omega \nearrow M$ and using Lemma B.1. In particular, $H^{\rho,V}$ is bounded and the assertions of Theorem 3.3 and Theorem 3.4 can be proven with the help of Theorem 3.1. We leave the details to the reader. Since the extended Kato condition of [27] is technical and not easily verified on manifolds, see e.g. the recent in [13, 12], we chose to state our main results for nonnegative potentials only.

6. Applications

In this section we discuss several applications of the generalized conservation property. We show that the generalized conservation property implies Markov uniqueness. On model manifolds we provide a characterization of the generalized conservation property in terms of volume growth and we show that on complete manifolds there always exists a potential making the forms conservative in the generalized sense.

6.1. Markov uniqueness. It is well known that on a stochastically complete manifold we have $W^1(M) = W_0^1(M)$. In terms of associated stochastic processes this means that there is only one Brownian motion on M. It is also known from Dirichlet form theory that the conservativeness of $Q_{\rho,0}$ implies $W^1(M,\rho) = W_0^1(M,\rho)$ and that in the finite

measure case (i.e. when $\rho \in L^1(M,\mu)$) both properties (uniqueness of Brownian motion and $W^1(M,\rho) = W^1_0(M,\rho)$ are equivalent, see e.g. [22, 14]. The following theorem provides an extension to the case when V does not vanish.

Theorem 6.1. Of the following assertions (i) always implies (ii). If $\rho + V \in L^1(M, \mu)$, then they are equivalent.

- (i) $Q_{\rho,V}$ is conservative in the generalized sense. (ii) $W^1(M,\rho+V)=W^1_0(M,\rho+V)$.

Proof. (i) \Rightarrow (ii): We assume that $W^1(M, \rho + V) \neq W^1_0(M, \rho + V)$ and denote by $\widetilde{Q}_{\rho, V}$ the Dirichlet form with domain $W^1(M, \rho + V)$ that was introduced in Section 4. Since essentially bounded functions are dense in the domains of Dirichlet forms, see e.g. [6, Theorem 1.4.2, there exists an essentially bounded $h \in W^1(M, \rho + V) \setminus W_0^1(M, \rho + V)$ with $||h||_{\infty} \leq 1$. Let h_0 be the Hilbert space projection of h in $(W^1(M, \rho + V), ||\cdot||_{W^1})$ onto the closed subspace $W_0^1(M, \rho + V)$. We prove that $h_r := h - h_0$ is essentially bounded and satisfies $(1 - \mathcal{L}_{\rho,V})h_r = 0$. It then follows from Lemma A.1 that h_r is smooth. By Theorem 3.3 (iii) the form $Q_{\rho,V}$ is not conservative in the generalized sense, a contradiction.

Since h_0 is the orthogonal projection onto $W_0^1(M, \rho+V)$, h_r is orthogonal to all $\varphi \in \mathcal{D}(M)$ with respect to the inner product induced by $\|\cdot\|_{W^1}$ on $W^1(M, \rho + V)$. Hence, for all $\varphi \in \mathcal{D}(M)$ we obtain

$$\int_{M} \langle \nabla h_r, \nabla \varphi \rangle \, d\mu + \int_{M} h_r \varphi V d\mu + \int_{M} h_r \varphi \rho d\mu = 0.$$

By definition of $\mathcal{L}_{\rho,V}$ this is nothing more than saying $(1 - \mathcal{L}_{\rho,V})h_r = 0$ in the sense of distributions.

It remains to prove the boundedness of h_r . By the projection theorem in Hilbert spaces it satisfies

$$||h_r||_{W^1} = ||h - h_0||_{W^1} = \inf\{||h - \psi||_{W^1} \mid \psi \in W_0^1(M, \rho + V)\}.$$

Let ψ_n a sequence in $W_0^1(M, \rho + V)$ converging to h_0 . We prove that

$$\varphi_n := h - ((h - \psi_n) \wedge 1) \vee (-1)$$

belongs to $W_0^1(M, \rho + V)$ and converges to h_0 . From this the claimed boundedness of $h_r = h - h_0$ follows.

Since $\|\cdot\|_{W^1}^2$ with domain $W^1(M, \rho + V)$ is a Dirichlet form, the functions φ_n belong to $W^1(M, \rho + V)$. Moreover, using $||h||_{\infty} \le 1$ shows $|\varphi_n| \le |\psi_n|$. Since $\psi_n \in W^1_0(M, \rho + V)$ and $W_0^1(M, \rho + V)$ is an order ideal in $W^1(M, \rho + V)$, see Lemma 4.1, we obtain $\varphi_n \in W_0^1(M, \rho + V)$. Using again that $\|\cdot\|_{W^1}^2$ is a Dirichlet form we arrive at

$$||h - \psi_n||_{W^1}^2 \ge ||((h - \psi_n) \land 1) \lor (-1)||_{W^1}^2 = ||h - \varphi_n||_{W^1}^2 = ||h_0 - \varphi_n||^2 + ||h - h_0||_{W^1}^2.$$

This shows $\varphi_n \to h_0$ and finishes the proof of (i) \Rightarrow (ii).

Now assume $\rho + V \in L^1(M,\mu)$. (ii) \Rightarrow (i): Due to $\rho + V \in L^1(M,\mu)$ we have $1 \in$ $W^1(M, \rho+V) = W_0^1(M, \rho+V)$. This implies that the Dirichlet form $Q_{\rho+V,0}$ on $L^2(M, \rho+V)$ is recurrent, see [6, Theorem 1.6.3]. Moreover, it is well known that recurrence implies conservativeness, see e.g. [6, Theorem 1.6.5 and Theorem 1.6.6], i.e., $Q_{\rho+V,0}$ is conservative. According to Theorem 3.5 this shows that $Q_{\rho,V}$ is conservative in the generalized sense. \square

- **Remark.** (1) An abstract version of this theorem for general Dirichlet forms is [26, Corollary 4.58]. The above proof is basically the one in [26] adapted to our situation.
 - (2) It follows with arguments involving domination of quadratic forms that the equality $W^1(M,\rho) = W^1_0(M,\rho)$ always implies $W^1(M,\rho+V) = W^1_0(M,\rho+V)$ for nonnegative V, see [23]. In particular, if $Q_{\rho,0}$ is conservative we have $W^1(M,\rho+V) = W^1_0(M,\rho+V)$. However, we would like to point out that our theorem still strengthens the known criteria for $W^1(M,\rho+V) = W^1_0(M,\rho+V)$ since there are manifolds and weights for which $T_t^{\rho,0}$ is not conservative but $T_t^{\rho,V}$ is conservative in the generalized sense, see Corollary 6.4 below.
- 6.2. **Model manifolds.** In this subsection we characterize the generalized conservation criterion for model manifolds.

Let $E = (0, \infty) \times \mathbb{S}^{n-1} \cup \{0\}$ be equipped with the topology making the coordinate map $\mathbb{R}^n \to E, x \mapsto (|x|, |x|^{-1}x)$ if $x \neq 0$ and $0 \mapsto 0$ a homeomorphism. A Riemannian manifold (M, g) is called *n*-dimensional model manifold (of infinite radius) if M = E and for each $(r, \theta) \in (0, \infty) \times \mathbb{S}^{n-1}$ on the tangent space $T_{(r,\theta)}M = T_r(0, \infty) \oplus T_{\theta}\mathbb{S}^{n-1}$ the metric takes the form

$$g = (dr)^2 + \sigma(r)^2 (d\theta)^2,$$

where $\sigma:(0,\infty)\to(0,\infty)$ is smooth and $(dr)^2,(d\theta)^2$ denote the standard metrics on $T_r(0,\infty)$ respectively $T_\theta\mathbb{S}^{n-1}$. In this case, the function σ is called the *scaling function* of the model.

Let (M,g) be a model manifold and let d be the induced geodesic distance on M. We call a function $f: M \to \mathbb{R}$ radially symmetric if f(x) = f(y) for all $x, y \in M$ with d(x,0) = d(y,0). In this case there exists a function $\tilde{f}: [0,\infty) \to \mathbb{R}$ such that $f(x) = \tilde{f}(r)$ whenever d(x,0) = r. In what follows we abuse notation and simply write f(r) instead of $\tilde{f}(r)$.

For simplicity we also assume $\mu = \operatorname{vol}_g$, i.e., $\Psi = 1$. If f is smooth and radially symmetric, so is $\Delta f = \operatorname{div}(\nabla f)$ and for r > 0 it takes the form

$$\Delta f(r) = f''(r) + (n-1)\frac{\sigma'(r)}{\sigma(r)}f'(r),$$

see e.g. [10]. If, moreover, ρ and V are radially symmetric, so is $\mathcal{L}_{\rho,V}f$ and for r>0 it is given by

$$\mathcal{L}_{\rho,V}f(r) = \rho(r)^{-1}f''(r) + \rho(r)^{-1}(n-1)\frac{\sigma'(r)}{\sigma(r)}f'(r) - \rho(r)^{-1}V(r)f(r).$$

From now on we assume that ρ is radially symmetric. For $r \geq 0$ we denote by $v_{\rho}(r) = \int_{B_r(0)} \rho dvol_g$ the volume of the d-ball of radius r around 0 with respect to the measure ρvol_g . It can be computed as

$$v(r) = \int_0^r \int_{\mathbb{S}^{n-1}} \rho(\xi) \sigma^{n-1}(\xi) d\xi d\theta = \omega_n \int_0^r \rho(\xi) \sigma^{n-1}(\xi) d\xi,$$

where ω_n is the surface area of \mathbb{S}^{n-1} (the volume of the unit sphere in \mathbb{R}^n), see e.g. [10]. The quantity $s(r) = \omega_n \sigma^{n-1}(r)$ is the surface area of the sphere of radius r in the manifold (M, g). We obtain the following characterization of the generalized conservation property on model manifolds.

Theorem 6.2. Let (M, g) be a model manifold with radially symmetric ρ and V and let $\mu = \operatorname{vol}_q$. The following assertions are equivalent.

- (i) The Dirichlet form $Q_{\rho,V}$ on $L^2(M, \rho \text{vol}_g)$ is conservative in the generalized sense.
- (ii) There exists a > 0 such that

$$\int_{a}^{\infty} \frac{v_{\rho+V}(r)}{s(r)} dr = \int_{a}^{\infty} \frac{v_{\rho}(r)}{s(r)} dr + \int_{a}^{\infty} \frac{\int_{0}^{r} s(\xi)V(\xi)d\xi}{s(r)} dr = \infty.$$

Remark. (1) Weakly spherically symmetric graphs are discrete analogues of model manifolds. A version of the theorem for weakly spherically symmetric graphs is contained in [21].

(2) Since $Q_{\rho,V}$ on $L^2(M,\rho \text{vol}_g)$ is conservative in the generalized sense if and only if $Q_{\rho+V,0}$ on $L^2(M,(\rho+V)\text{vol}_g)$ is conservative, the theorem is an extension of the well known characterization of stochastic completeness of model manifolds (the case $\rho=1,V=0$) in terms of their volume growth, see e.g. [9, Proposition 3.2]. More precisely, it treats the case when the measure used in the integrals in the definition of the form $Q_{\rho+V,0}$ (in this case vol_g) and the measure of the underlying L^2 -space (in this case $(\rho+V)\text{vol}_g$) are different.

Before proving the theorem we note the following elementary lemma on radially symmetric smooth solutions to the eigenvalue equation. We include a proof for the convenience of the reader.

Lemma 6.3. Let (M,g) be a model manifold with radially symmetric ρ and V and let $\mu = \operatorname{vol}_g$. Moreover, let $f: M \to [0,\infty)$ be a smooth radially symmetric solution to the equation $(1 - \mathcal{L}_{\rho,V})f = 0$. For all $r > r' \ge 0$ it satisfies the identity

$$f(r) = f(r') + \int_{r'}^{r} \frac{1}{s(\eta)} \int_{0}^{\eta} s(\xi)(\rho(\xi) + V(\xi)) f(\xi) d\xi d\eta.$$

In particular, the function $[0,\infty) \to [0,\infty), r \mapsto f(r)$ is monotone increasing.

Proof. We use the discussed formulas for $\mathcal{L}_{\rho,V}f$ for radially symmetric functions and the identity $(n-1)\sigma'/\sigma = s'/s$ to obtain that f satisfies

$$f'' + \frac{s'}{s}f' = (\rho + V)f.$$

Multiplying this by s, integrating it from 0 to $\eta > 0$ and using $s(0+) = \omega_n \sigma^{n-1}(0+) = 0$ yields

$$(sf')(\eta) = \int_0^{\eta} s(\xi)(\rho(\xi) + V(\xi))f(\xi)d\xi.$$

Dividing by s and integrating from r' to r yields

$$f(r) = f(r') + \int_{r'}^{r} \frac{1}{s(\eta)} \int_{0}^{\eta} s(\xi)(\rho(\xi) + V(\xi)) f(\xi) d\xi d\eta.$$

The "In particular"-part follows from the fact that all integrands are nonnegative. \Box

Proof of Theorem 6.2. (i) \Rightarrow (ii): We assume

$$\int_{1}^{\infty} \frac{v_{\rho+V}(r)}{s(r)} dr < \infty$$

and use [14, Theorem 7.5] to show that the Dirichlet form $Q_{\rho+V,0}$ on $L^2(M,(\rho+V)\text{vol}_g)$ is not conservative. According to Theorem 3.5 this implies that $Q_{\rho,V}$ is not conservative in the generalized sense. Strictly speaking [14, Theorem 7.5] can only be applied to the form $Q_{1,0}$, i.e., the case when $\rho+V=1$. However, the theory developed in [14] treats arbitrary Dirichlet forms and [14, Theorem 7.5] is an application of this more general framework to manifolds. It also works when $\rho+V\neq 1$.

According to [14, Theorem 7.5] it suffices to prove the existence of a function $f \in L^1(M, (\rho+V)\operatorname{vol}_g) \cap L^2(M, (\rho+V)\operatorname{vol}_g)$ with $|\nabla f| \in L^2(M, \operatorname{vol}_g)$ and $\mathcal{L}_{\rho+V,0}f \in L^1(M, (\rho+V)\operatorname{vol}_g) \cap L^2(M, (\rho+V)\operatorname{vol}_g)$ such that

$$\int_{M} \mathcal{L}_{\rho+V,0} f(V+\rho) d\text{vol}_{g} = \int_{M} \Delta f d\text{vol}_{g} \neq 0.$$

We consider the radially symmetric function g on $M \setminus B_{1/2}(0)$ given by

$$g(r) = \int_{r}^{\infty} \frac{1}{s(\xi)} d\xi, \quad r > \frac{1}{2}.$$

Fubini's theorem and our volume growth condition imply $g \in L^1(M \setminus B_{1/2}(0), (\rho + V) \operatorname{vol}_g)$. Since g is monotone decreasing with $g(r) \to 0$, as $r \to \infty$, it also belongs to $L^2(M \setminus B_{1/2}(0), (\rho + V) \operatorname{vol}_g)$. In particular, g is finite and smooth and satisfies

$$\Delta g(r) = g''(r) - \frac{s'(r)}{s(r)}g'(r) = 0, \quad r > \frac{1}{2}.$$

Moreover, since M is a model manifold, we have $|\nabla g|(r) = |g'(r)|$ so that

$$\int_{M\setminus B_1(0)} |\nabla g|^2 d\mathrm{vol}_g = \int_1^\infty s(r) \frac{1}{s(r)^2} dr = g(1) < \infty.$$

Let now f be a smooth radially symmetric function on M such that f = g on $M \setminus B_{1/2}(0)$. The desired integrability properties of f directly follow from properties of g and so it remains to prove the statement on Δf . Using the identities $\Delta f = s^{-1}(sf')'$ and $\Delta f(r) = 0$ for r > 1 we compute

$$\int_{M} \Delta f d\text{vol}_{g} = \int_{0}^{\infty} s(r) \Delta f(r) dr = \int_{0}^{1} s(r) \Delta f(r) dr = f'(1) s(1) - f'(0+) s(0+) = -1.$$

This proves (ii).

(ii) \Rightarrow (i): We consider the function $f=1-N_1^{\rho,V}=1-G_1^{\rho,V}1-G_1^{\rho,V}(V/\rho)$. According to Theorem 3.1 it is smooth, satisfies $0 \leq f \leq 1$ and $(1-\mathcal{L}_{\rho,V})f=0$. Moreover, since V, ρ and the constant function 1 are radially symmetric, it follows from routine arguments that f is radially symmetric (use that the form $Q_{\rho,V}$ is invariant with respect to rotations in the \mathbb{S}^{n-1} -variable and that this invariance yields an invariance for the resolvent; for the operator theoretic details see e.g. [21, Appendix A]). Assume now that (i) does not hold. By Theorem 3.1 (d) this implies f(x) > 0 for all $x \in M$ and hence f(r) > 0 for all $r \geq 0$. According to Lemma 6.3 $[0, \infty) \to (0, \infty), r \mapsto f(r)$ is monotone increasing. Hence, the integral formula of Lemma 6.3 implies

$$f(r) \ge f(0) + f(0) \int_0^r \frac{1}{s(\eta)} \int_0^{\eta} s(\xi)(\rho(\xi) + V(\xi)) d\xi d\eta = f(0) + f(0) \int_0^r \frac{v_{\rho+V}(\eta)}{s(\eta)} d\eta.$$

With (ii) this shows $f(r) \to \infty$, as $r \to \infty$, a contradiction to the boundedness of f. \square

Corollary 6.4. Let (M, g) be a model manifold with radially symmetric ρ and let $\mu = \operatorname{vol}_g$. There exists a radially symmetric V such that $Q_{\rho,V}$ is conservative in the generalized sense.

Proof. Choose a smooth function $f:[0,\infty)\to[0,\infty)$ such that f=0 on a neighborhood of 0 and

$$\int_{1}^{\infty} \frac{\int_{0}^{r} s(\xi) f(\xi) d\xi}{s(r)} dr = \infty.$$

Since the metric d is smooth off the diagonal, the function $V: M \to [0, \infty)$ defined by V(x) = f(d(0, x)) is smooth and radially symmetric. With this choice of V it follows from Theorem 6.2 that $Q_{\rho,V}$ is conservative in the generalized sense.

6.3. Large potentials on complete manifolds. In this subsection we show that on every complete weighted manifold (M, g, μ) and for every smooth $\rho: M \to (0, \infty)$ we can choose a smooth potential $V \geq 0$ such that $Q_{\rho,V}$ is conservative in the genralized sense. Our proof is based on a volume growth criterion for stochastic completeness for strongly local regular Dirichlet forms from [28]. We refer to this reference for the terminology used in this subsection.

We write $W^1_{\text{loc}}(M)$ for the local first order Sobolev space, i.e., $f \in W^1_{\text{loc}}(M)$ iff for every relatively compact open $\Omega \subseteq M$ there exists $\varphi \in W^1_0(M, \rho)$ (or equivalently $\varphi \in W^1(M, \rho)$) with $f = \varphi$ on Ω . Since ρ is assumed to be smooth (and hence bounded and strictly positive on a neighborhood of every relatively compact open set), it follows that this definition is indeed independent of ρ .

The quadratic form $Q_{\rho,0}$ is a strongly local regular Dirichlet form on $L^2(M,\rho\mu)$ and its local domain is given by $W^1_{\text{loc}}(M)$. If we denote by $\Gamma(f) = |\nabla f|^2 \mu$ the energy measure of a function $f \in W^1_{\text{loc}}(M)$, then for $f \in D(Q_{\rho,0}) = W^1_0(M,\rho)$ we have

$$Q_{\rho,0}(f) = \int_M d\Gamma(f).$$

The intrinsic metric associated with $Q_{\rho,0}$ on $L^2(M,\rho\mu)$ is defined by

$$d_{\rho}(x,y) = \sup\{|f(x) - f(y)| \mid f \in W^{1}_{loc}(M) \cap C(M) \text{ with } d\Gamma(f) \leq \rho d\mu\}$$

= \sup\{|f(x) - f(y)| \| | f \in W^{1}_{loc}(M) \cap C(M) \text{ with } |\nabla f|^{2} \le \rho\}.

Rademacher's theorem implies that for $\rho = 1$ the metric d_1 is the geodesic distance on (M, g) and that for general ρ the function d_{ρ} is a metric, which induces the original topology on M.

We fix some $o \in M$ and let $B_r^{\rho} = \{x \in M \mid d_{\rho}(x, o) \leq r\}$. Moreover, we denote the volume of B_r^{ρ} with respet to $\rho \mu$ by

$$\nu_{\rho}(r) = (\rho\mu)(B_r^{\rho}) = \int_{B_r^{\rho}} \rho d\mu.$$

We recall [28, Theorem 4], which in our situation takes the following form.

Lemma 6.5 (Sturm's volume growth test for conservativeness). Suppose that open balls with respect to d_{ρ} are relatively compact. Then

$$\int_{1}^{\infty} \frac{r}{\max\{\log \nu_{\rho}(r), 1\}} dr = \infty$$

implies that $Q_{\rho,0}$ is conservative.

Remark. In [28, Theorem 4] the denominator in the volume growth test reads $\log \nu_{\rho}(r)$ instead of $\max\{\log \nu_{\rho}(r), 1\}$. This is not correct. It is possible to construct stochastically incomplete model manifolds with $\nu_1(r) \simeq e^{(r-1)^2}$ around r=1, see [9]. In this case we have $\int_1^{\infty} \frac{r}{\log \nu_1(r)} dr = \infty$. However, the proof of [28, Theorem 4] yields the statement of the previous lemma.

Theorem 6.6. If the weighted manifold (M, g, μ) is complete, for every smooth $\rho : M \to (0, \infty)$ there exists a smooth potential $V \geq 0$ such that $Q_{\rho,V}$ is conservative in the generalized sense.

Proof. According to Theorem 3.5 it suffices to show that there exists $V \ge 0$ such that the form $Q_{\rho+V,0}$ on $L^2(M,(\rho+V)\mu)$ is conservative. We employ Sturm's volume growth test for conservativeness to verify the existence of such a potential.

We fix $o \in M$. In this proof we denote by d the geodesic distance induced by g and by B_r the closed r ball around o with respect to d.

Let $f: \mathbb{R} \to [0, \infty)$ be smooth, strictly increasing and convex with f(0) = 0. Since the geodesic distance d is Lipschitz with Lipschitz constant equal to 1, Rademacher's theorem implies $\nabla d(o, \cdot) \in \vec{L}^{\infty}(M)$ with $|\nabla d(o, \cdot)| \leq 1$. Therefore, the function

$$\psi: M \to [0, \infty), \psi(x) = f(d(o, x))$$

satisfies $|\nabla \psi(x)|^2 \leq f'(d(o,x))^2$ for almost every $x \in M$. We choose a smooth potential $V: M \to [0,\infty)$ such that $2+f'(d(o,x))^2 \geq V(x) \geq 1+f'(d(o,x))^2$. Note that on compact subsets of M such a function V exists by the Stone-Weierstraß theorem and on the whole of M it can be constructed with the help of smooth partitions of unity.

Since $V \geq 1$, we have $d_{\rho+V} \geq d_1 = d$, so that $d_{\rho+V}$ -balls are included in d-balls. By the Hopf-Rinow theorem the completeness of (M, g, μ) implies that d-balls are relatively compact. Hence, $d_{\rho+V}$ -balls are also relatively compact. Thus, it only remains to verify the volume growth condition of Sturm's test for stochastic completeness.

With the properties of ψ at hand, it follows from the definition of $d_{\rho+V}$ that

$$d_{\rho+V}(x,o) \ge |\psi(x) - \psi(o)| = f(d(o,x)).$$

Hence, for $r \geq 1$ we have the inclusion

$$B_r^{\rho+V} \subseteq B_{f^{-1}(r)},$$

which leads to

$$\nu_{\rho+V}(r) \leq \int_{B_{f^{-1}(r)}} (\rho+V) d\mu \leq \int_{B_{f^{-1}(r)}} (2+\rho) d\mu + f'(f^{-1}(r))^2 \mu(B_{f^{-1}(r)}).$$

For the last inequality we used $V(x) \leq 2 + f'(d(x, o))^2$ and the convexity of f. Using this and substituting $s = f^{-1}(r)$ we obtain

$$\begin{split} \int_{1}^{\infty} \frac{r}{\max\{\log \nu_{\rho+V}(r), 1\}} dr &\geq \int_{1}^{\infty} \frac{r}{\max\{\log((2+\rho)\mu(B_{f^{-1}(r)})) + f'(f^{-1}(r))^{2}\mu(B_{f^{-1}(r)})), 1\}} dr \\ &= \int_{f^{-1}(1)}^{\infty} \frac{f(s)f'(s)}{\max\{\log((2+\rho)\mu(B_{s})) + f'(s)^{2}\mu(B_{s})), 1\}} ds. \end{split}$$

It is now a simple exercise to construct a function f with the required properties such that the latter integral diverges. For example, one can choose f such that $f(r) = e^{g(r)}$ for some sufficiently large smooth convex function g. Now the claim follows from Sturm's volume growth criterion.

Remark. For graphs it is known that one can always add a large enough potential to force the corresponding form to be conservative in the generalized sense, see [20].

We believe (but do not have a proof) that our theorem also holds for manifolds that are not complete. In this case, it should be possible to find V such that $d_{\rho+V}$ has relatively compact balls. With this at hand, one can then argue as in the proof above.

Corollary 6.7. There exists a complete but stochastically incomplete Riemannian manifold (i.e. $Q_{1,0}$ is not conservative) and a potential V such that $Q_{1,V}$ is conservative in the generalized sense.

Proof. This follows from the existence of a complete but stochastically incomplete Riemannian manifold and our previous theorem. \Box

APPENDIX A. LOCAL REGULARITY THEORY

In this appendix we collect local regularity results for the operator $\mathcal{L}_{\rho,V}$. They are consequences of the well-known local elliptic and local parabolic regularity theory in Euclidean spaces. In order to obtain versions on weighted manifolds, one just needs to localize the operators accordingly. For the case when V = 0 and $\rho = 1$, this can be found e.g. in [10, Chapters 6 and 7]. Since we assume $V \geq 0$, the proofs given there can be carried trough

verbatim in our situation (otherwise some slight modifications would be needed). In other words, for the reader who is well-acquainted with local regularity theory the following lemmas are simple exercises, while other readers may find the proofs in [10].

The following Sobolev embedding theorem is a version of [10, Theorem 7.1].

Lemma A.1. Let $f \in L^2_{loc}(M)$. If for each $m \geq 0$ we have $(\mathcal{L}_{\rho,V})^m f \in L^2_{loc}(M)$, then $f \in C^{\infty}(M)$. Moreover, if (f_n) is a sequence in $L^2_{loc}(M)$ such that for each $m \geq 0$ also $(\mathcal{L}_{\rho,V})^m f_n \in L^2_{loc}(M)$ and $(\mathcal{L}_{\rho,V})^m f_n \to (\mathcal{L}_{\rho,V})^m f$ in $L^2_{loc}(M)$, then $f_n \to f$ locally uniformly.

The following hypoellipticity statement is a version of [10, Theorem 7.4].

Lemma A.2. Let $f \in C^{\infty}(M)$ and let $u \in \mathcal{D}'((0,T) \times M)$ satisfy

$$\partial_t u - \mathcal{L}_{o,V} u = f.$$

Then $u \in C^{\infty}((0,T) \times M)$.

APPENDIX B. CONVERGENCE OF SEMIGROUPS

Let $\Omega \subseteq M$ an open subset. We let (T_t^{Ω}) denote the $L^2(\Omega, \rho\mu)$ semigroup of the Dirichlet form

$$Q_{\rho,V}^{\Omega}(f,g) = \int_{\Omega} \langle \nabla f, \nabla g \rangle \, d\mu + \int_{\Omega} V f g d\mu$$

with domain $D(Q_{\rho,V}^{\Omega}) = W_0^1(\Omega, \rho + V)$. We extend it to $f \in L^2(M, \rho\mu)$ by letting

$$T_t^{\Omega} f := \begin{cases} T_t^{\Omega} f|_{\Omega} & \text{on } \Omega \\ 0 & \text{on } M \setminus \Omega. \end{cases}$$

Similarly, we denote by (G_{α}^{Ω}) the resolvent of $Q_{\rho,V}^{\Omega}$ extended by 0 outside of Ω .

Lemma B.1. Let (Ω_n) an ascending sequence of open subsets of M with $\bigcup_n \Omega_n = M$. Then, for every t > 0 and $\alpha > 0$ we have $T_t^{\Omega_n} \to T_t^{\rho,V}$ and $G_{\alpha}^{\Omega_n} \to G_{\alpha}^{\rho,V}$ strongly in $L^2(M)$, as $n \to \infty$.

Proof. We prove that $Q_{\rho,V}^{\Omega_n}$ converges to $Q_{\rho,V}$ in the generalized Mosco sense, see. [2, 8 Appendix] for a definition. The desired statement then follows from [2, Theorem 8.3].

We denote by $\pi_n: L^2(M, \rho\mu) \to L^2(\Omega_n, \rho\mu)$ the restriction $f \mapsto f|_{\Omega_n}$. Its adjoint $E_n := \pi_n^*$ extends a function in $L^2(\Omega_n, \rho\mu)$ to M by letting it equal to 0 outside of Ω_n . For verifying generalized Moso convergence, we need to prove the following statements.

(a) For $f_n \in L^2(\Omega_n, \rho\mu)$, $f \in L^2(M, \rho\mu)$ with $E_n f_n \to f$ weakly in $L^2(M, \rho\mu)$ the inequality

$$Q_{\rho,V}(f) \le \liminf_{n \to \infty} Q_{\rho,V}^{\Omega_n}(f_n)$$

holds (with the convention $Q_{\rho,V}(g) = \infty$ if $f \notin D(Q_{\rho,V})$). (b) For every $f \in D(Q_{\rho,V})$ there exist $f_n \in D(Q_{\rho,V}^{\Omega_n})$ with $E_n f_n \to f$ strongly in $L^2(M,\rho\mu)$ and

$$\limsup_{n \to \infty} Q_{\rho,V}^{\Omega_n}(f_n) \le Q_{\rho,V}(f).$$

The closedness of $Q_{\rho,V}$ implies that it is lower semicontinuous with respect to weak convergence. Hence, $E_n f_n \to f$ weakly in $L^2(M, \rho \mu)$ yields

$$Q_{\rho,V}(f) \le \liminf_{n \to \infty} Q_{\rho,V}(E_n f_n).$$

It follows from the definition of $Q_{\rho,V}^{\Omega_n}$ that $Q_{\rho,V}(E_nf_n) = Q_{\rho,V}^{\Omega_n}(f_n)$. This proves (a). For proving (b) we use that $C_c^{\infty}(M)$ is dense in $D(Q_{\rho,V})$ with respect to the form norm. For given $f \in D(Q_{\rho,V})$ let (f_n) a sequence in $C_c^{\infty}(M)$ that converges to f with respect to $\|\cdot\|_{W^1}$. From this sequence we can build up a sequence (g_n) with supp $g_n\subseteq\Omega_n$ and $g_n\to f$ with respect to $\|\cdot\|_{W^1}$ as follows. For $n \in \mathbb{N}$ we define

$$k_n := \max\{k \le n \mid \text{supp } f_k \subseteq \Omega_n\}$$

and set $g_n := f_{k_n}$. By construction we have supp $g_n \subseteq \Omega_n$. The sequence (k_n) is increasing and since the (f_n) have compact support, it diverges. We obtain $g_n \to f$ with respect to $\|\cdot\|_{W^1}$. These considerations imply $\pi_n g_n \in D(Q_{\rho,V}^{\Omega_n})$ and

$$\limsup_{n \to \infty} Q_{\rho,V}^{\Omega_n}(\pi_n g_n) = \limsup_{n \to \infty} Q_{\rho,V}(g_n) = Q_{\rho,V}(f).$$

This finishes the proof.

APPENDIX C. TWO LEMMAS ON MEASURABLE CHOICES

The following lemmas are certainly well known to experts. Since we could not find proper references, we include their proofs for the convenience of the reader. Let $0 < T \le \infty$. By λ we denote the Lebesgue measure on (0,T). Let $u:(0,T)\to L^2(M,\mu)$. A measurable function $\tilde{u} \in L^1_{loc}((0,T) \times M, \lambda \otimes \mu)$ such that $u(t) = \tilde{u}_t$ in $L^2(M,\mu)$ for λ -a.e. $t \in (0,T)$ is called a locally integrable version of u. Note that by Fubini's theorem this is well-defined, i.e., it is independent of the choice of the representative of \tilde{u} .

Recall that in this paper $\langle \cdot, \cdot \rangle_{\mu}$ denotes the $L^2(M, \mu)$ -inner product and that $\langle \cdot, \cdot \rangle$ denotes the dual pairing between test functions and distributions.

Lemma C.1. Let $0 < T \le \infty$ and let $u:(0,T) \to L^2(M,\mu)$ continuous. Then there exists a locally integrable version of u.

Proof. Since the Borel- σ -algebra of M is countably generated, $L^2(M,\mu)$ is separable. Let $(f_k)_{k\geq 1}$ be a countable orthonormal basis for $L^2(M,\mu)$. Moreover, let $I_n\subseteq (0,T)$ increasing compact intervals with $\bigcup_n I_n = (0,T)$. For $k,n \in \mathbb{N}$ the maps

$$g_{n,k}:(0,T)\times M\to\mathbb{R},\ (x,t)\mapsto \langle u(t),f_k\rangle_\mu 1_{I_n}(t)f_k(x)$$

are clearly measurable. We consider

$$u_{n,l} := \sum_{k=1}^{l} g_{n,k}.$$

Parseval's inequality in $L^2(M,\mu)$ and the strong continuity of u imply

$$\int_{0}^{T} \int_{M} |u_{n,l}|^{2} d\mu d\lambda \leq \int_{0}^{T} 1_{I_{n}}(t) \|\tilde{u}(t)\|_{2}^{2} d\lambda(t) < \infty,$$

uniformly. Hence, for each $n \in \mathbb{N}$ the limit $u_n := \lim_{l \to \infty} u_{n,l}$ exists in $L^2((0,T) \times M, \lambda \otimes \mu)$. For $n \geq m$ the functions u_n and u_m only differ on $I_n \setminus I_m$; indeed we have $u_m = u_n 1_{I_m \times M}$. Hence, the limit $\tilde{u} = \lim_{n \to \infty} u_n$ exists in $L^1_{\text{loc}}((0,T) \times M, \lambda \otimes \mu)$ and satisfies $\tilde{u}1_{I_n \times M} = u_n$. Parseval's identity and the properties of \tilde{u} yield

$$\begin{split} \int_{0}^{T} \|\tilde{u}_{t} - u(t)\|_{2}^{2} d\lambda(t) &= \lim_{n \to \infty} \int_{I_{n}} \|\tilde{u}_{t} - u(t)\|_{2}^{2} d\lambda(t) \\ &= \lim_{n \to \infty} \int_{I_{n}} \|u_{n}(t, \cdot) - \tilde{u}(t)\|_{2}^{2} d\lambda(t) \\ &= \lim_{n \to \infty} \lim_{l \to \infty} \int_{I_{n}} \|(u_{n,l})_{t} - u(t)\|_{2}^{2} d\lambda(t) \\ &= \lim_{n \to \infty} \lim_{l \to \infty} \int_{I_{n}} \sum_{k=l+1}^{\infty} |\langle u(t), f_{k} \rangle_{\mu}|^{2} d\lambda(t). \end{split}$$

The strong continuity of u yields

$$\sup_{t \in I_n} \sum_{k=l+1}^{\infty} |\langle u(t), f_k \rangle_{\mu}|^2 \le \sup_{t \in I_n} ||u(t)||_2^2 < \infty, \text{ for all } l \in \mathbb{N}.$$

Hence, Lebesgue's theorem yields

$$\lim_{l \to \infty} \int_{I_n} \sum_{k-l+1}^{\infty} |\langle \tilde{u}(t), f_k \rangle_{\mu}|^2 d\lambda(t) = 0,$$

and the assertion $\tilde{u}_t = u(t)$ in $L^2(M, \mu)$ for λ -a.e. $t \in (0, T)$ is proven.

We say that $u:(0,T) \to L^2(M,\mu)$ is continuously differentiable if for all 0 < s < T the limit

$$u'(s) = \lim_{h \to 0} \frac{1}{h} (u(s+h) - u(s))$$

exists in $L^2(M,\mu)$ and $u':(0,T)\to L^2(M,\mu)$ is continuous. In the following lemma ∂_t denotes the distributional time derivative on $\mathcal{D}'((0,\infty)\times M)$.

Lemma C.2. Let $0 < T \le \infty$ and let $u : (0,T) \to L^2(M,\mu)$ be continuously differentiable. Then there exists a locally integrable version \tilde{u} of u such that $\partial_t \tilde{u} \in L^1_{loc}((0,T) \times M, \lambda \otimes \mu)$ is a locally integrable version of u'.

Proof. According to the previous lemma u and u' have locally integrable versions \tilde{u} and v, respectively. Hence, it suffices to prove $v = \partial_t \tilde{u}$. For $\varphi \in \mathcal{D}((0, \infty) \times M)$ we compute

$$\begin{split} \langle \tilde{u}, \partial_t \varphi \rangle &= \int_0^\infty \int_M \tilde{u}_s(x) (\partial_t \varphi)_s(x) d\mu(x) d\lambda(s) \\ &= \lim_{h \to 0} h^{-1} \int_0^\infty \int_M \tilde{u}_s(x) (\varphi_{s+h}(x) - \varphi_s(x)) d\mu(x) d\lambda(s) \\ &= \lim_{h \to 0} h^{-1} \int_0^\infty \int_M (\tilde{u}_{s-h}(x) - \tilde{u}_s(x)) \varphi_s(x) d\mu(x) d\lambda(s) \\ &= \lim_{h \to 0} h^{-1} \int_0^\infty \langle u(s-h) - u(s), \varphi_s \rangle_\mu d\lambda(s) \\ &= - \int_0^\infty \langle u'(s), \varphi_s \rangle_\mu d\lambda(s). \end{split}$$

For the second to last equality we used that \tilde{u} is a locally integrable version of u. Moreover, for the last equality we used a standard result for differentiating under the integral sign using that u is continuously differentiable and φ has compact support in $(0,T) \times M$. Since v is a locally integrable version of u', we further obtain

$$\int_0^\infty \langle u'(s), \varphi_s \rangle_\mu \, d\lambda(s) = \int_0^\infty \langle v, \varphi_s \rangle_\mu \, d\lambda(s) = \langle v, \varphi \rangle \,.$$

This proves $\partial_t \tilde{u} = v$, as by definition $\langle \partial_t \tilde{u}, \varphi \rangle = -\langle \tilde{u}, \partial_t \varphi \rangle$.

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