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Hot-water drilling at Glaciar Perito Moreno, Southern Patagonia Icefield

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Abstract

Glaciar Perito Moreno is one of the major freshwater calving glaciers in the Southern Patagonia Icefield. Its fast-flowing characteristic is probably due to high water pressure at the glacier bed, however, subglacial conditions have never been observed in Patagonia until our recent undertaking. To investigate the role of subglacial water pressure in the calving glacier dynamics, we performed hot-water drilling at Glaciar Perito Moreno from February to March 2010. This study represents the first attempt ever at hot-water glacier drilling in Patagonia. Two boreholes were drilled to the bed at 4.7 km upglacier from the terminus, where the ice was revealed to be 515 ± 5 m thick and the bed located at about 330 m below the proglacial lake level. The water levels in the boreholes were >100 m above the lake level, which indicates that more than 90% of the ice overburden pressure was balanced out by the subglacial water pressure. Water in the boreholes had drained away before the drilling reached the bed, suggesting the existence of an englacial drainage system. These results provide crucial information for understanding the hydraulic and hydrological conditions of calving glaciers. In order to drill a 500 m deep glacier, an existing hot-water drilling system was adapted by increasing the number of high-pressure hot-water machines. The drilling operation at Glaciar Perito Moreno confirmed the system's capacity to drill a 500-m-deep borehole at a rate of 50 m h^{-1} with fuel consumption rates of 15.71 l h^{-1} for diesel and 3.91 l h^{-1} for petrol.

Key words: calving glacier, hot water drilling, subglacial water pressure, borehole, Patagonia

1. Introduction

The close examination of physical conditions beneath a glacier (*e.g.*, water pressure, drainage system, unconsolidated sediment layer, bedrock roughness) is important for understanding the role of basal processes in glacier motion. Subglacial conditions determine the speed of ice sliding over a bedrock as well as the deformation of a subglacial sediment layer, causing substantial changes in glacier flow speed. These basal ice flow processes are particularly important in outlet glaciers in Patagonia Icefields since most of them terminate in lakes or the ocean (Warren and Aniya, 1999; Rignot *et al.*, 2003; Rivera *et al.*, 2007). Calving glaciers flow faster than land terminating glaciers, particularly because the basal flow processes are enhanced by high water pressure generated by the

proglacial water body. Since a large amount of ice is discharged from the fast-flowing calving glaciers in Patagonia (Naruse *et al.*, 1992; Skvarca *et al.*, 1995; Warren *et al.*, 1995a; Warren *et al.*, 1995b; Rott *et al.*, 1998), the dynamics of these glaciers plays a key role in the recent ice mass loss of the Patagonia Icefields (Aniya *et al.*, 1997; Aniya, 1999; Rignot *et al.*, 2003; Rivera *et al.*, 2007). Nevertheless, detailed studies on glacier dynamics are very scarce and subglacial measurements have never been carried out in Patagonia.

Glaciar Perito Moreno is a fast-flowing freshwater calving glacier in Patagonia. The glacier extends over 30 km to the northeast from the Southern Patagonia Icefield and covers an area of 258 km^2 (Aniya *et al.*, 1997). The glacier front currently terminates in Brazo Rico and Canal de los Témpanos (185 m a.s.l.) (Stuefer *et al.*, 2007), forming a narrow water channel between the glacier snout and Península Magallanes. (Fig. 1a).

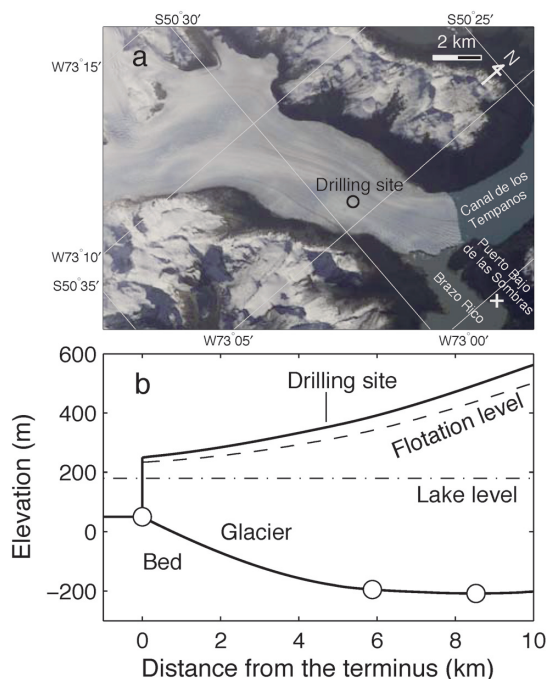


Figure 1. (a) Satellite image of Glaciar Perito Moreno with the drilling site indicated by (○). Drilling equipment was transported by a helicopter from the site indicated by (+). The image was taken on 27 March 2002 (image courtesy of the Image Science & Analysis Laboratory, NASA Johnson Space Center). (b) Longitudinal cross section of Glaciar Perito Moreno along the central flowline. The bed profile is drawn by interpolation of observational data points (○) (Stuefer *et al.*, 2007). The lake water level and ice flotation level are indicated by the dot-dashed and dotted lines.

Unlike the other glaciers in Patagonia, no significant retreat is being observed in Glaciar Perito Moreno (Aniya and Skvarca, 1992; Skvarca and Naruse, 1997; Stuefer, 1999; Stuefer *et al.*, 2007). Its front position has oscillated within several hundred meters since the early 20th century (Skvarca and Naruse, 1997). The glacier flows at a rate of $400\text{--}800\text{ m a}^{-1}$ in the region extending several kilometers from the calving front (Rott *et al.*, 1998; Michel and Rignot, 1999; Floricioiu *et al.*, 2008; Ciappa *et al.*, 2010). According to seismic soundings performed by Stuefer *et al.* (2007), the glacier bed elevation is $150\text{--}400\text{ m}$ below the lake level within the reach of 10 km from the terminus (Fig. 1b). The glacier bed is thus expected to be at high water pressure under the influence of the proglacial lakes. A substantial part of ice overburden pressure is balanced out by the subglacial water pressure, which is a preferable condition for the basal ice flow processes (e.g., Bindshadler, 1983). Annual flow speed variations are relatively small (Stuefer *et al.*, 2007), whereas a clear seasonal flow speed change has been observed by a recent study using satellite data (Ciappa *et al.*, 2010). Naruse *et al.* (1995) reported diurnal flow speed variations at a few hundred meters from the side

margins.

In the 2008/2009 austral summer season, we carried out high-frequency ice flow measurements on Glaciar Perito Moreno and found clear diurnal flow speed variations in the central region of the glacier at about 5 km from the terminus (Sugiyama *et al.*, 2009). The flow speed was closely correlated to air temperature, suggesting that meltwater production is controlling the basal ice flow by swiftly changing subglacial water pressure. The flow speed was very sensitive to the meltwater input, probably because the relationship between the water pressure and flow speed is highly nonlinear when the pressure rises close to the overburden pressure (Bindshadler, 1983; Truffer and Iken, 1998; Sugiyama and Gudmundsson, 2004). To test this hypothesis, we drilled Glaciar Perito Moreno using a hot-water drilling technique to measure subglacial water pressure. This was the first attempt in Patagonia to drill through a glacier for the purpose of conducting subglacial observations. The aim of this paper is to describe the hot-water drilling system used for this project and report the drilling field campaign carried out in early 2010.

2. Hot-water Drilling System

The hot-water drilling system was prepared by adapting an existing system developed at the Institute of Low Temperature Science, Hokkaido University (Sugiyama *et al.*, 2008; Tsutaki and Sugiyama, 2009). The original system was designed for drilling as deep as 200 m , thus it was necessary to increase the drilling capacity to drill through Glaciar Perito Moreno with expected thickness of $450\text{--}550\text{ m}$ at our study site. We installed an additional high-pressure hot-water machine (Kärcher HDS1000BE) and constructed piping to bring together hot water from two machines (Fig. 2a). The length of the drilling hose was extended to 550 m . An electrically powered winch system (Fig. 2b) was developed to lower down and lift up the hose in a borehole, as the hose is too heavy to handle by man power alone during deep drilling. The winch was controlled by hand using a handle connected to a gear system as observed in Figure 2b. Electric power from a generator was used only to wind up the hose after the completion of drilling. The winch was equipped with a brake system (lower right in Fig. 2b) designed and constructed at the workshop of the Institute of Low Temperature Science. This brake keeps the hose tightly wound around the winch drum, so that the necessary friction was generated at the interface between hose and drum.

The hot water machines draw water with petrol-driven pumps from a water basin or supraglacial water source. The water is warmed up with a heater which uses diesel as fuel. Hot water flowed through 12.7 mm inner diameter high pressure hoses (Bridges-

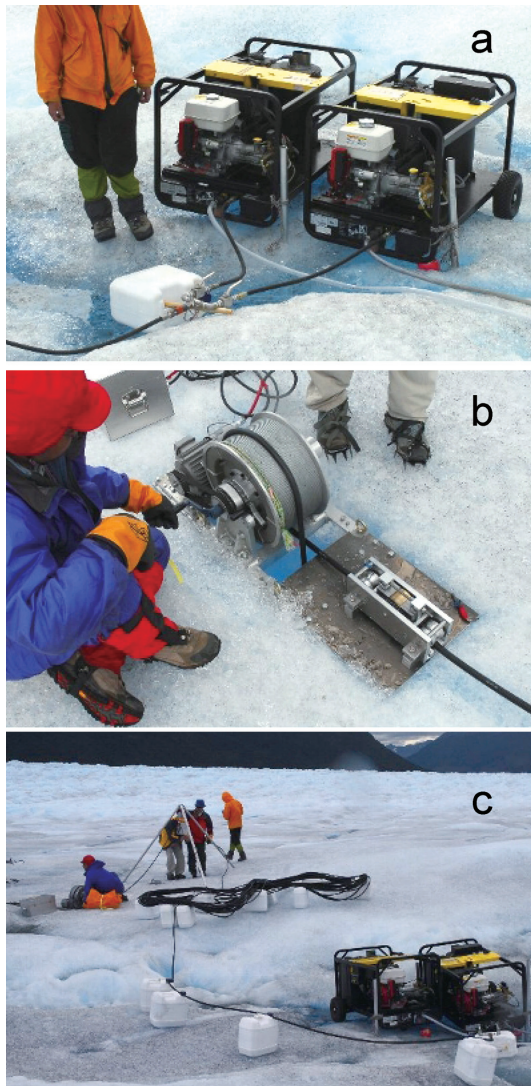


Figure 2. Photographs showing hot-water drilling on Glaciar Perito Moreno. (a) High-pressure hot-water machines. The machines discharge hot water through the black hoses, which are combined into one by means of the piping. (b) Winch system with a brake in the lower right. (c) The hot-water drilling system set up on the glacier. The bore-hole is at the middle left.

tone WAR08, outer diameter is 19.8 mm) before it emitted a narrow water jet from a 3.0 mm diameter nozzle (Katorigumi Inc. K-18). The nozzle was mounted on a 3-m-long metal pipe, which provided a load to straighten the hanging hoses for drilling a vertical borehole. For drilling of shallow boreholes, a tripod and pulley system was used instead of the winch. The weight of all the drilling equipment was approximately 600 kg, excluding fuel.

The drilling system was tested before the campaign at the Institute of Low Temperature Science using a water basin filled with water from a tap. The temperature of the water jet was measured with a temperature logger (HIOKI 3633) following a method described in Tsutaki and Sugiyama (2009). The system generated hot water at about 65°C at a rate of 1600

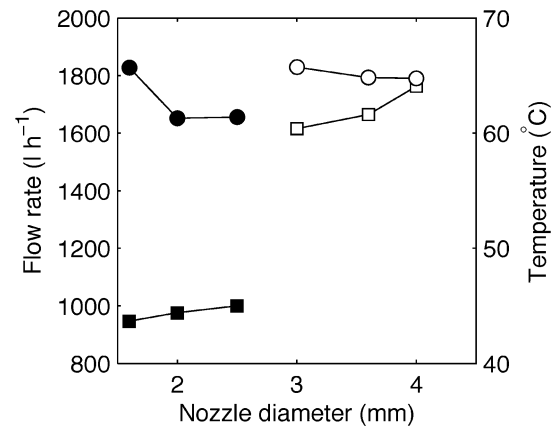


Figure 3. Flow rate (○) and water jet temperature (□) of the hot-water drilling system obtained using water jet nozzles with different diameters. The closed circles and squares (●, ■) are flow rate and temperature reported for the old system, which uses one hot-water machine (Tsutaki and Sugiyama, 2009).

l h^{-1} and a pressure of 10 MPa (Fig. 3). The water temperature and the flow rate show that the new system generates approximately 80% more power (heat in a unit time) than the original system (Fig. 3) (Tsutaki and Sugiyama, 2009).

3. Overview of Field Campaign

The field campaign began on 24 February 2010. It was ascertained that the location of the drilling site fulfilled the requisite conditions such as: availability of water, relatively flat surface for drilling and helicopter operations, proximity to the 2008/09 GPS measurement sites, and ice thickness not greater than the hose length. After a reconnaissance visit on 24 February, the drilling site was chosen at $\text{S}50^{\circ} 29' 27.2''$, $\text{W}73^{\circ} 5' 39.5''$ (Fig. 1a). The site was 4.7 km from the terminus and several hundred meters off the central flowline. The ice thickness was estimated as 450–550 m, based on the seismic data (Stuefer *et al.*, 2007). Water was available in a nearby supraglacial pond. The drilling equipment and fuel (400 l of diesel for the heaters and 150 l of petrol for the pumps and generator) were transported on 25 February by a helicopter of the Gendarmeria Nacional from Puerto Bajo de las Sombras located at 7.5 km east of the drilling site (Fig. 1a). The system was set up immediately upon arrival at the site, and drilling began on 26 February. As the drilling site was a two-hour walk from our camp, the daily activity on the glacier was limited to 1000–1900 h. Drilling operations continued until March 5 and the equipment was evacuated by helicopter from the glacier on the following day.

4. Drilling

Drilling did not progress efficiently until 28 February because one of the pumps needed to be repaired and the winch system had to be tested. The first borehole (BH1) reached the glacier bed on 2 March after the consumption of 235 l of diesel and 90 l of petrol. The total duration of the hot-water system operation was 21 hours, including time spent for testing the devices. The total fuel consumption rates were 11.21 h^{-1} for diesel and 4.31 h^{-1} for petrol. The diesel consumption rate was lower than the normal value of the system because one of the two hot water machines was out of order during the first half of the drilling. The second borehole (BH2) was drilled approximately 5 m downglacier from BH1. Drilling began on 4 March and completed the next day after 10.5 hours of operation. The diesel and petrol consumption rates were 15.7 and 3.91 h^{-1} , respectively.

Figure 4 shows drilling depth as a function of drilling duration. The depth was known from the hose length plus its extension due to the own weight. The extension was calculated from the extension rate ($7.1 \times 10^{-5} \text{ N}^{-1}$) and hose weight (0.25 kg m^{-1}) reported by the manufacturer (Bridgestone Co.). The drilling rate for BH1 was not uniform because we began drilling by hand with the tripod and pulley system and then the system was replaced by the winch at the depth of 197 m. Hand drilling is generally more efficient unless the hose in a borehole is too heavy to handle. The winch system was used for the entire part of BH2 to avoid an interruption due to the exchange of the systems. Drilling rates from the surface to the bed were 48 and 50 m h^{-1} for BH1 and BH2, respectively. The drilling speed and fuel consumption rates are summarized in Table 1.

In order to detect the glacier bed during drilling, the weight of the drilling hose hanging in the borehole was measured every 5 to 20 m (Fig. 5). A rope was twisted around the hose to hang it under a hook of a spring scale. Sudden increases in the load were observed at hose lengths of 344 m in BH1 and 375 m in BH2. These clear changes occurred because of water drainage from the borehole as described later in this section. At hose lengths between 506–512 m (BH1) and 504–512 m (BH2), the load suddenly dropped and decreased progressively as we continued the drilling. Detailed measurements in BH1 showed that the change could be reproduced by lowering and lifting the hose at this depth (Fig. 5 inset). These were clear indications that the drilling nozzle hit the bed. The load decreased because the nozzle came into contact with the bed and the hose leaned on the borehole wall. Based on these observations, we conclude that the ice thickness at the drilling site was 504–512 m plus stretching of the hose ($7 \pm 0.5 \text{ m}$) and ambiguities in the hose

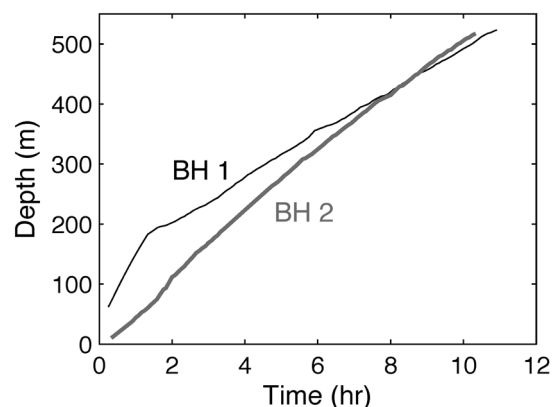


Figure 4. Drilling depth v.s. duration for the drilling of BH1 (black) and BH2 (bold gray).

Table 1. Depth of the boreholes, drilling speed and fuel consumption rates of the hot water system.

Borehole	Depth m	Drilling speed m h^{-1}	Fuel consumption rate	
			Diesel (l h^{-1})	Petrol (l h^{-1})
BH1	516 ± 4	48	11.2	4.3
BH2	515 ± 5	50	15.7	3.9

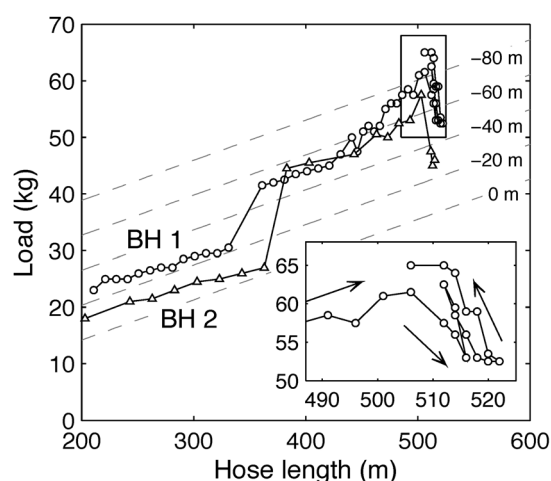


Figure 5. Weight of the drilling hose measured during the drilling of BH1 (○) and BH2 (△). The dashed lines are weight of the hose estimated for the indicated water levels (relative to the surface). The inset shows details near the bed in BH1.

length (± 0.5), which equals to $515 \pm 5 \text{ m}$. This result is consistent with the seismic data (Stuefer *et al.*, 2007), although detailed comparison is not possible as the seismic measurements were performed several hundred meters upglacier from our drilling site.

Boreholes are usually filled with water during hot-water drilling. The water often drains away when a borehole reaches the bed, but drainage can also occur beforehand, within the glacier. These drainage events provide important information on subglacial and englacial hydrological connections. Water in BH1 first drained at 176 m from the surface.

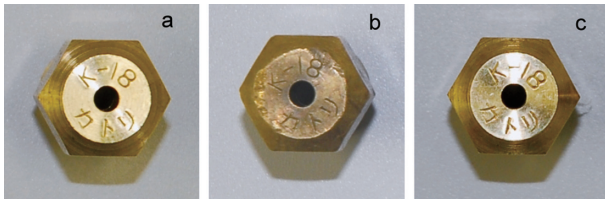


Figure 6. Drilling nozzles (a) before the drilling and (b) after the drilling of BH1 and (c) BH2.

The sudden increase in the hose weight at the depth 344 m (Fig. 5) implies that water drained again and buoyancy force acting on the hose decreased. Judging from the weight of the hose hanging in the borehole estimated for different water levels (dashed lines in Fig. 5), the level dropped from 20 to 50 m below the ice surface at the second drainage. In BH2, drainage occurred at 375 m depth, as did the increase in weight (Fig. 5). The change in the weight by 17.5 kg implies that the water level dropped approximately 60 m. These observations suggest the existence of an englacial drainage system in Glaciar Perito Moreno. According to our visual observation of the water level in the boreholes, the drainage rate was in the range of 10^{-2} – 10^{-1} m³ min⁻¹. This rate was relatively lower than those of subglacial and englacial drainage that we encountered in the Alps.

The inspection of the hot-water jet nozzles after the drilling provided a clue to glacier bed conditions. The surface of the brass nozzle often became heavily scratched or scraped when it hit bedrock (Sugiyama *et al.*, 2008). However, the nozzle used for BH1 had only small scratch marks and the one used in BH2 bore no evidence of contact with rocks (Figure 6). Therefore, it is likely that the glacier is underlain by an unconsolidated layer composed of sediment and gravels at the drilling site. The difference in the damage to the nozzles used in the two boreholes may be due to the fact that we moved the drill up and down at the bottom of BH1, whereas we stopped the drilling in BH2 as soon as reached the bed.

After drilling was completed, water-pressure sensors (Geokon 4500S and HOBO U20) were installed in the two boreholes to measure the respective water levels. The measurements showed that the water levels in BH1 and BH2 correlated with one another. They fluctuated in a diurnal manner within a level between 425–460 m from the bed, which corresponded to more than 90% of the ice flotation level at the site. The pressure variations were correlated to surface flow speed and air temperature, implying that our hypothesis was correct. Detailed analyses of the water level variations together with ice flow speed and air temperature data will be presented elsewhere.

5. Conclusion

A hot-water drilling technique was employed to

drill through Glaciar Perito Moreno, a freshwater calving glacier in the Southern Patagonia Icefield, for subglacial observations. We drilled two boreholes to the glacier bed at 4.7 km from the terminus. The drilling revealed the ice thickness at the drilling site to be 515 ± 5 m. The completion of the drilling to the bed was clearly detected by changes in the weight of the hose hanging in the boreholes. Water in the boreholes drained before the drilling reached the bed, indicating the existence of an englacial drainage system. According to inspections of hot water nozzles after the drilling, the glacier is probably underlain by unconsolidated sediments and gravels. The water level in boreholes after the drilling was more than 90% of the ice flotation level, which strongly suggests that ice flow of Glaciar Perito Moreno is influenced by a high subglacial water pressure and its variations.

In order to drill a glacier to a depth of more than 500 m, two high-pressure hot-water machines were assembled together and a winch system was newly constructed. The drilling speed from the surface to the bed was 50 m h⁻¹ when the system was running properly. The rates of fuel consumption were 15.71 hr⁻¹ for diesel and 3.91 hr⁻¹ for petrol.

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