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Title	Construction of canonical systems of basic invariants for finite reflection groups
Author(s)	辻栄, 周平
Degree Grantor	北海道大学
Degree Name	博士(理学)
Dissertation Number	甲第11536号
Issue Date	2014-09-25
DOI	https://doi.org/10.14943/doctoral.k11536
Doc URL	https://hdl.handle.net/2115/57128
Type	doctoral thesis
File Information	Shuhei_Tsujie.pdf



Construction of canonical systems of basic invariants for finite reflection groups

(有限鏡映群の標準不変式系の構成)

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September 2014

Preface

For a polytope P whose symmetry group is a reflection group W , a canonical system of basic invariants for W plays an important role to determine if the space of all P -harmonic functions coincides with the space of all W -harmonic functions. The main purpose of this thesis is to describe explicit formulas for a canonical system of basic invariants for a finite irreducible reflection group.

This thesis is mainly based on [17] and [18]. The paper [18] is a joint-work with Norihiro Nakashima and describes formulas for canonical systems of finite Euclidean reflection groups. The paper [17] is a joint-work with Norihiro Nakashima and Hiroaki Terao and proves the existence of canonical systems for unitary reflection groups. These materials are included in the thesis with a kind permission of those coworkers.

ACKNOWLEDGMENTS

There are many people whom I must acknowledge. I would like to show my greatest appreciation to Professor Katsunori Iwasaki who gave me a lot of advices to write this thesis. Dr. Norihiro Nakashima invited me to study the theme of this thesis and to work together. I owe a very important debt to him. I would also like to express my sincere gratitude to Professor Hiroaki Terao whose advices polished this thesis. I also thank Professor Mutsumi Saito and Professor Hiroshi Yamashita for their willingness to read the manuscript. Thanks to a longstanding support of Professor Iku Nakamura, I have been able to continue to study. I cannot express enough my feelings of appreciation to Professor Iku Nakamura. Also to my colleagues, my friends and my parents, I feel deep thankfulness.

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Chapter 1

Introduction

In this chapter we give the definition of a canonical system for a finite reflection group. Throughout this paper, $\mathbb{K}$ denotes the real number field $\mathbb{R}$ or the complex number field $\mathbb{C}$ and V an n -dimensional vector space over $\mathbb{K}$. Lehrer and Taylor [15] describe the theory of unitary reflection groups in detail.

1.1 Finite reflection groups

In this section, we recall the definition of a reflection and the classification of finite reflection groups.

Definition 1.1. A linear transformation $s \in \mathrm{GL}(V)$ is a *reflection* (or a *pseudo reflection*) if $\dim_{\mathbb{K}} \mathrm{Im}(1 - s) = 1$ and the order of s is finite. For a reflection s , the hyperplane $\mathrm{Ker}(1 - s)$ is called the *reflecting hyperplane* of s . A finite subgroup $W \subseteq \mathrm{GL}(V)$ is a *finite reflection group* if W is generated by reflections. When $\mathbb{K} = \mathbb{R}$ a reflection group is sometimes called a *Euclidean reflection group* and when $\mathbb{K} = \mathbb{C}$ a reflection group is called a *unitary reflection group* or a *complex reflection group*.

Let $W \subseteq \mathrm{GL}(V)$ be a finite reflection group. There exists a W -invariant inner product $\langle \cdot, \cdot \rangle$, that is, there exists a bilinear form $\langle \cdot, \cdot \rangle : V \times V \rightarrow \mathbb{K}$ satisfying the following:

- (1) $\overline{\langle u, v \rangle} = \langle v, u \rangle$,
- (2) $\langle u_1 + u_2, v \rangle = \langle u_1, v \rangle + \langle u_2, v \rangle$,
- (3) $\langle au, v \rangle = a\langle u, v \rangle$,

- (4) $\langle v, v \rangle \in \mathbb{R}$ and $\langle v, v \rangle \geq 0$,
- (5) $\langle v, v \rangle = 0$ if and only if $v = 0$,
- (6) $\langle wu, wv \rangle = \langle u, v \rangle$

for all $u, u_1, u_2, v \in V, a \in \mathbb{K}$ and $w \in W$, where $\bar{a} = a$ when $\mathbb{K} = \mathbb{R}$ or $\bar{a}$ denotes the complex conjugate of a when $\mathbb{K} = \mathbb{C}$.

Let $s \in W$ be a reflection and H the reflecting hyperplane of s . The orthogonal complement $H^\perp$ has dimension 1.

Definition 1.2. A generator α of $H^\perp$ is called a *root* of the reflection s .

Let α be a root of s . For any $u \in H$,

$$0 = \langle u, \alpha \rangle = \langle su, s\alpha \rangle = \langle u, s\alpha \rangle.$$

Therefore $s\alpha \in H^\perp = \mathbb{K}\alpha$. Hence α is an eigenvector of s . Assume that $s\alpha = \zeta\alpha$ for some $\zeta \in \mathbb{K}, \zeta \neq 1$. An arbitrary vector $v \in V$ has a unique decomposition

$$v = u + a\alpha,$$

where $u \in H$ and $a \in \mathbb{K}$. Since $\langle u, \alpha \rangle = 0$, we have $a = \frac{\langle v, \alpha \rangle}{\langle \alpha, \alpha \rangle}$. Therefore

$$sv = su + as\alpha = u + \zeta a\alpha = v - (1 - \zeta) \frac{\langle v, \alpha \rangle}{\langle \alpha, \alpha \rangle} \alpha. \quad (1.1)$$

Proposition 1.3. Let s_1, s_2 be reflections with roots α_1, α_2 respectively. Then s_1 and s_2 commute if and only if $\mathbb{K}\alpha_1 = \mathbb{K}\alpha_2$ or $\langle \alpha_1, \alpha_2 \rangle = 0$.

Proof. From (1.1), we have

$$\begin{aligned} s_2 s_1 v &= v - (1 - \zeta_1) \frac{\langle v, \alpha_1 \rangle}{\langle \alpha_1, \alpha_1 \rangle} \alpha_1 - (1 - \zeta_2) \frac{\langle v, \alpha_2 \rangle}{\langle \alpha_2, \alpha_2 \rangle} \alpha_2 \\ &\quad + (1 - \zeta_1)(1 - \zeta_2) \frac{\langle v, \alpha_1 \rangle \langle \alpha_1, \alpha_2 \rangle}{\langle \alpha_1, \alpha_1 \rangle \langle \alpha_2, \alpha_2 \rangle} \alpha_2, \end{aligned}$$

where $s_i \alpha_i = \zeta_i \alpha_i$ ($i = 1, 2$). By symmetry a similar expression holds for $s_1 s_2 v$. Therefore

$$\begin{aligned} &s_1 \text{ and } s_2 \text{ commute} \\ &\Leftrightarrow \langle v, \alpha_1 \rangle \langle \alpha_1, \alpha_2 \rangle \alpha_2 = \langle v, \alpha_2 \rangle \langle \alpha_2, \alpha_1 \rangle \alpha_1 \text{ for any } v \in V \\ &\Leftrightarrow \mathbb{K}\alpha_1 = \mathbb{K}\alpha_2 \text{ or } \langle \alpha_1, \alpha_2 \rangle = 0. \end{aligned}$$

□

Proposition 1.4. *Let s be a reflection with root α and $U \subseteq V$ a subspace. Then U is s -stable, that is, $sU = U$ if and only if $\alpha \in U$ or $\alpha \in U^\perp$.*

Proof. Assume that $sU = U$. Then $sU^\perp = U^\perp$. Write

$$\alpha = u + v \quad (u \in U, v \in U^\perp),$$

then

$$su + sv = s\alpha = \zeta\alpha = \zeta u + \zeta v.$$

Since $sU = U$ and $sU^\perp = U^\perp$, we have $su = \zeta u$ and $sv = \zeta v$. By definition $\dim_{\mathbb{K}} \text{Im}(1 - s) = 1$, one of u and v must be 0 since $\zeta \neq 1$. Hence $\alpha \in U$ or $\alpha \in U^\perp$.

Conversely, assume that $\alpha \in U^\perp$. Then the reflecting hyperplane of s contains U . Therefore U is s -stable. If $\alpha \in U$ then $U^\perp$ is s -stable so is U . $\square$

Proposition 1.5. *Let $U \subseteq V$ be a W -stable subspace and $W' \subseteq W$ the subgroup generated by reflections with roots in U . Then W' is a normal subgroup of W .*

Proof. Let $s \in W'$ with root $\alpha \in U$. For any $w \in W$ we have

$$s(w^{-1}v) = w^{-1}v - (1 - \zeta) \frac{\langle w^{-1}v, \alpha_1 \rangle}{\langle \alpha_1, \alpha_1 \rangle} \alpha_1.$$

Therefore

$$(ws w^{-1})v = v - (1 - \zeta) \frac{\langle v, w\alpha_1 \rangle}{\langle w\alpha_1, w\alpha_1 \rangle} w\alpha_1.$$

Thus $ws w^{-1}$ is a reflection with root $w\alpha$. Since U is W -stable, we have $w\alpha \in U$. By definition of W' we can conclude that $ws w^{-1} \in W'$. Hence W' is a normal subgroup of W . $\square$

Definition 1.6. Let $W \subseteq \text{GL}(V)$ be a finite reflection group. We say that W is *essential* if $V^W := \{v \in V \mid wv = v \text{ for all } w \in W\} = 0$ and W is *reducible* if $W = W_1 \times W_2$ for some non-trivial reflection subgroups $W_1, W_2 \subseteq W$. When W is not reducible, we say that W is *irreducible*.

Proposition 1.7. *The $\mathbb{K}[W]$ -module V is irreducible if and only if W is essential and irreducible.*

Proof. By Maschke's theorem V has the orthogonal decomposition

$$V = V^W \perp V_1 \perp \cdots \perp V_k,$$

where V_i ($1 \leq i \leq k$) are non-trivial irreducible submodules. Assume that the $\mathbb{K}[W]$ -module V is reducible. We may assume that W is essential and $k \geq 2$. Let $W_i \subseteq W$ be the subgroup generated by reflections with roots in V_i . Then the following three conditions hold:

- When $i \neq j$, elements $w \in W_i$ and $w' \in W_j$ commute by Proposition 1.3.
- $W = W_1 \cdots W_k$ by Proposition 1.4.
- W_i is a normal subgroup of W by Proposition 1.5.

Hence $W = W_1 \times \cdots \times W_k$. Thus W is a reducible reflection group. Conversely, we may assume that W is essential and reducible. Then W has a decomposition $W = W_1 \times W_2$, where W_1 and W_2 are non-trivial reflection subgroups. Let $V_1 \subseteq V$ be the subgroup spanned by roots of reflections in W_1 . The subspace V_1 is W_1 -stable by Proposition 1.4. Since an element in W_1 and one in W_2 commute, the subspaces V_1 and V_2 are orthogonal by Proposition 1.3. Hence V_1 is contained in the reflecting hyperplanes of reflections in W_2 . Therefore V_1 is also W_2 -stable. Hence V_1 is a non-trivial W -stable subspace. Thus the $\mathbb{K}[W]$ -module V is reducible. $\square$

Irreducible finite Euclidean reflection groups were classified by Coxeter [3] [4] in terms of Coxeter-Dynkin diagrams. They consist of four infinite families $A_n, B_n, D_n, I_2(m)$, and six exceptional groups $E_6, E_7, E_8, F_4, H_3, H_4$.

Shepherd and Todd [22] classified irreducible finite unitary reflection groups into 37 cases, three infinite families (symmetric, imprimitive, cyclic) and 34 exceptional groups (denoted by $G_4, \dots, G_{37}$). The three infinite families are described by an infinite family $G(m, p, n)$ depending on three positive integer parameters with p dividing m .

Proposition 1.8 (Bourbaki [1]). *Let V be an Euclidean space and $W \subseteq \mathrm{O}(V)$ a finite Euclidean reflection group. If V is an irreducible $\mathbb{R}[W]$ -module then $\mathrm{End}_W(V) = \mathbb{R}$. Hence V is absolutely irreducible, that is, $V \otimes_{\mathbb{R}} \mathbb{C}$ is also irreducible as a $\mathbb{C}[W]$ -module.*

Proposition 1.8 provides that each irreducible finite Euclidean reflection group can be regarded as an irreducible finite unitary group. The correspondence is listed below:

Infinite family		Exceptional group	
A_n	$G(1, 1, n + 1)$	E_6	G_{35}
B_n	$G(2, 1, n)$	E_7	G_{36}
D_n	$G(2, 2, n)$	E_8	G_{37}
$I_2(m)$	$G(m, m, 2)$	F_4	G_{28}
		H_3	G_{23}
		H_4	G_{30}

1.2 Chevalley's Theorem

Let S be the symmetric algebra $S(V^*)$ of the dual space V^* . For any basis $x = (x_1, \dots, x_n)$ for V^* , we may regard S as the ring of polynomial functions $\mathbb{K}[x]$ of V^* . A finite reflection group W acts on S in a usual manner:

$$wf := f \circ w^{-1}$$

for all $w \in W$ and $f \in S$. Let S^W be the ring of W invariants and S_+^W its irrelevant ideal, that is, the ideal generated by homogeneous invariants of positive degrees. The following classical theorem is due to Chevalley [2].

Theorem 1.9 (Chevalley [2]). *The following assertions hold:*

- (1) *Let $\{f_1, \dots, f_m\}$ be a minimal system of homogeneous generators of S_+^W . Then $m = n$ and $f_1, \dots, f_n$ are algebraically independent.*
- (2) *There exist algebraically independent homogeneous invariants $f_1, \dots, f_n$ of positive degrees such that*

$$S^W = \mathbb{K}[f_1, \dots, f_n].$$

- (3) *The multiset of the degrees $\{\deg f_1, \dots, \deg f_n\}$ is independent of a choice of generators for S_+^W .*

Definition 1.10. The set of generators $\{f_1, \dots, f_n\}$ in Theorem 1.9 is called a *system of basic invariants* (or a *basic invariants* shortly) for W . The multiset $\{\deg f_1, \dots, \deg f_n\}$ is called the *degrees* of W .

Assume that V is reducible as a $\mathbb{K}[W]$ -module. Write $V = V_1 \oplus V_2$, where V_i is a non-trivial $\mathbb{K}[W]$ -module. From the proof of Proposition 1.7, we have $W = W_1 \times W_2$, where each W_i is a reflection group on V_i (allowed to be the unit group when $V_i \subseteq V^W$). Then

$$S^W = S(V_1^*)^{W_1} \otimes_{\mathbb{K}} S(V_2^*)^{W_2}.$$

Hence without loss of generality we may assume that V is an irreducible $\mathbb{K}[W]$ -module to determine a system of basic invariants for W . Many researchers determined systems of basic invariants explicitly (Coxeter [2], Lee [14], Lehner and Taylor [15], Mehta [16], Saito, Yano and Sekiguchi [19], Sekiguchi and Yano [20, 21]). Determining systems of basic invariants is not difficult for infinite families $A_n, B_n, D_n, I_2(m)$ and $G(m, p, n)$ but determining ones for exceptional groups needs further considerations.

1.3 Definition of canonical systems

For $v \in V$ we define a $\mathbb{K}$ -linear map $D_v: S \rightarrow S$ to be the directional derivative in direction v ,

$$D_v f := \lim_{t \rightarrow 0} \frac{1}{t} (f \circ T_{tv} - f),$$

where $T_v(u) := u + v$. The operator D_v is a derivation of S , that is, D_v satisfies

$$D_v(fg) = (D_v f)g + f(D_v g) \tag{1.2}$$

for all $f, g \in S$. Note that

$$D_v L = L(v) \tag{1.3}$$

for all $L \in V^* \subseteq S$.

Definition 1.11. We denote by $\mathcal{D}_S$ the commutative algebra which is generated by directional derivatives D_v ($v \in V$) regarding the product as map composition. An element of $\mathcal{D}_S$ is called a *differential operator*.

The linear map $D: V \rightarrow \mathcal{D}_S$ can be extended to a $\mathbb{K}$ -algebra isomorphism defined by the linear extension of

$$\begin{aligned} D: S(V) &\rightarrow \mathcal{D}_S \\ v_1 \otimes \cdots \otimes v_k &\mapsto D_{v_1} \cdots D_{v_k}. \end{aligned} \quad (1.4)$$

A finite reflection group W acts on $\mathcal{D}_S$ as

$$wD_p := D_{wp},$$

where $w \in W$ and $p \in S(V)$ so that (1.4) becomes a $\mathbb{K}[W]$ -algebra isomorphism.

Proposition 1.12. *Let $p \in S(V)$, $f \in S = S(V^*)$, $w \in W$. Then*

$$w(D_p f) = D_{wp}(wf).$$

Proof. Without loss of generality we may assume that p is homogeneous. By induction on the degree of p it suffices to show that $w(D_v f) = D_{wv}(wf)$ for all $p = v \in V$. We have

$$\begin{aligned} w(D_v f) &= \lim_{t \rightarrow 0} \frac{1}{t} (f \circ T_{tv} \circ w^{-1} - f \circ w^{-1}) \\ &= \lim_{t \rightarrow 0} \frac{1}{t} (f \circ w^{-1} \circ T_{twv} - f \circ w^{-1}) \\ &= D_{wv}(wf). \end{aligned}$$

Hence $w(D_v f) = D_{wv}(wf)$. □

Define a map $\iota: V \rightarrow V^*$ by

$$\iota(v) := \langle \cdot, v \rangle,$$

where $\langle \cdot, \cdot \rangle$ is the W -invariant inner product on V .

Proposition 1.13. *The map ι is a W -invariant (anti)isomorphism, that is, ι satisfying the following:*

- (1) $\iota(v_1 + v_2) = \iota(v_1) + \iota(v_2)$,
- (2) $\iota(av) = \bar{a}\iota(v)$,
- (3) ι is bijective,

$$(4) \quad \iota(wv) = w\iota(v)$$

for all $v, v_1, v_2 \in V, a \in \mathbb{K}$ and $w \in W$.

Proof. (1) For any $u, v_1, v_2 \in V$,

$$\begin{aligned} \iota(v_1 + v_2)(u) &= \langle u, v_1 + v_2 \rangle = \overline{\langle v_1 + v_2, u \rangle}_V = \overline{\langle v_1, u \rangle}_V + \overline{\langle v_2, u \rangle}_V \\ &= \langle v_1, u \rangle + \langle v_2, u \rangle = \iota(v_1)(u) + \iota(v_2)(u). \end{aligned}$$

Therefore $\iota(v_1 + v_2) = \iota(v_1) + \iota(v_2)$.

(2) For any $u, v \in V$ and $a \in \mathbb{K}$,

$$\begin{aligned} \iota(av)(u) &= \langle u, av \rangle = \overline{\langle av, u \rangle}_V = \overline{a\langle v, u \rangle}_V \\ &= \overline{a}\langle u, v \rangle = \overline{a}\iota(v)(u). \end{aligned}$$

Hence $\iota(av) = \overline{a}\iota(v)$.

(3) By (1) and (2) the subset $\text{Im } \iota \subseteq V^*$ is a subspace of V^* . Hence it suffices to verify that ι is injective. Assume that $\iota(v) = 0$. Then $\langle v, v \rangle = \iota(v)(v) = 0$, so that $v = 0$. Thus ι is injective.

(4) For any $u, v \in V$ and $w \in W$ we have

$$\iota(wv)(u) = \langle u, wv \rangle = \langle w^{-1}u, v \rangle = \iota(v)(w^{-1}u) = w\iota(v)(u).$$

Hence $\iota(wv) = w\iota(v)$. □

The map ι can be extended to a W -invariant (anti)isomorphism defined by the linear extension of

$$\begin{aligned} S(V^*) &\rightarrow S(V) \\ L_1 \otimes \cdots \otimes L_k &\mapsto \iota^{-1}(L_1) \otimes \cdots \otimes \iota^{-1}(L_k) \end{aligned}$$

Definition 1.14. We define a W -invariant (anti)isomorphism $*$: $S \rightarrow \mathcal{D}_S$ by

$$f^* := D_{\iota^{-1}(f)},$$

where $f \in S = S(V^*)$.

Let $e_1, \dots, e_n$ be an orthonormal basis for V and $x_1, \dots, x_n$ its dual basis. Then we have

$$x_i^* = D_{e_i} = \frac{\partial}{\partial x_i}.$$

For convenience we put $\partial_i := \frac{\partial}{\partial x_i}$. For a multi-index $\mathbf{i} = (i_1, \dots, i_n) \in \mathbb{N}_0 := \mathbb{Z}_{\geq 0}^n$ we write

$$x^{\mathbf{i}} := x_1^{i_1} \cdots x_n^{i_n}.$$

For a polynomial $f = \sum_{\mathbf{i}} a_{\mathbf{i}} x^{\mathbf{i}} \in S$ we have

$$f^* = \sum_{\mathbf{i}} \bar{a}_{\mathbf{i}} \partial^{\mathbf{i}},$$

where $\partial := (\partial_1, \dots, \partial_n)$.

Proposition 1.15. *For $f \in S$*

$$f^* x_i - x_i f^* = (\partial_i f)^*.$$

as operators on S .

Proof. We may assume that f is a monomial. Since the operators x_i and ∂_j commute when $i \neq j$ it suffices to show that

$$\partial_i^m x_i - x_i \partial_i^m = m \partial_i^{m-1}$$

by induction on m .

Let $m = 1$ then for any $f \in S$

$$\partial_i x_i f = f + x_i \partial_i f.$$

Hence $\partial_i x_i - x_i \partial_i = 1$ as operators on S .

For $m \geq 2$

$$\begin{aligned} \partial_i^m x_i &= \partial_i (\partial_i^{m-1} x_i) \\ &= \partial_i (x_i \partial_i^{m-1} + (m-1) \partial_i^{m-2}) \\ &= (x_i \partial_i + 1) \partial_i^{m-1} + (m-1) \partial_i^{m-1} \\ &= x_i \partial_i^m + m \partial_i^{m-1} \end{aligned}$$

as operators on S . Therefore $\partial_i^m x_i - x_i \partial_i^m = m \partial_i^{m-1}$.

□

Definition 1.16. Define a map $(\cdot, \cdot): S \times S \rightarrow S$ by

$$(f, g) := f^*g \quad (f, g \in S)$$

and define a map $(\cdot, \cdot)_0: S \times S \rightarrow \mathbb{K}$ by

$$(f, g)_0 := (f, g)(0) = (f^*g)(0) \quad (f, g \in S).$$

Proposition 1.17. *The map $(\cdot, \cdot)$ is a W -invariant sesquilinear map, that is, the following hold:*

- (1) $(f_1 + f_2, g) = (f_1, g) + (f_2, g)$ and $(f, g_1 + g_2) = (f, g_1) + (f, g_2)$,
- (2) $(af, g) = \bar{a}(f, g)$ and $(f, ag) = a(f, g)$,
- (3) $w(f, g) = (wf, wg)$

for all $f, f_1, f_2, g, g_1, g_2 \in S, a \in \mathbb{K}, w \in W$.

The operator f^* is the adjoint operator of the multiplication-by- f map with respect to $(\cdot, \cdot)_0$:

$$(4) \quad (fg, h) = (g, f^*h)$$

for all $f, g, h \in S$.

Moreover, if $f, g \in S$ are homogeneous and have the same degree then

$$(5) \quad (f, g) = (f, g)_0.$$

Proof. (1) and (2) follow immediately from the linearity of differential operators and the (anti)linearity of the map $*$. To verify (3) we take $f, g \in S$ and $w \in W$. By Proposition 1.12 we have

$$w(f, g) = w(D_{\iota^{-1}(f)}g) = D_{w\iota^{-1}(f)}(wg) = D_{\iota^{-1}(wf)}(wg) = (wf, wg).$$

$$(4) \quad \text{We have } (fg, h) = (fg)^*h = g^*(f^*h) = (g, f^*h).$$

(5) If $f, g \in S$ are homogeneous and have the same degree then (f, g) is a constant. Hence $(f, g) = (f, g)_0$. $\square$

Proposition 1.18. *The map $(\cdot, \cdot)_0$ is a W -invariant inner product on S , that is, $(\cdot, \cdot)_0$ satisfies the following:*

$$(1) \quad \overline{(f, g)_0} = (g, f)_0,$$

$$(2) \quad (f_1 + f_2, g)_0 = (f_1, g)_0 + (f_2, g)_0,$$

$$(3) \quad (af, g)_0 = \bar{a}(f, g)_0,$$

$$(4) \quad (f, f)_0 \in \mathbb{R} \text{ and } (f, f)_0 \geq 0,$$

$$(5) \quad (f, f)_0 = 0 \text{ if and only if } f = 0,$$

$$(6) \quad (wf, wg)_0 = (f, g)_0$$

for all $f, f_1, f_2, g \in S, a \in \mathbb{K}, w \in W$.

The operator f^* is the adjoint operator of the multiplication-by- f map with respect to $(\cdot, \cdot)_0$:

$$(7) \quad (fg, h)_0 = (g, f^*h)_0 \text{ and } (g, fh)_0 = (f^*g, h)_0.$$

for all $f, g, h \in S$.

Proof. (1) We may assume that $f, g \in S$ are homogeneous. If $\deg f \neq \deg g$ then $(f, g)_0 = 0 = (g, f)_0$. Assume that $k := \deg f = \deg g$ and write

$$f = \sum_{|\mathbf{i}|=k} a_{\mathbf{i}} x^{\mathbf{i}}, g = \sum_{|\mathbf{i}|=k} b_{\mathbf{i}} x^{\mathbf{i}},$$

where $|\mathbf{i}| := i_1 + \cdots + i_n$. Then we have

$$(f, g)_0 = \left(\sum_{|\mathbf{i}|=k} \bar{a}_{\mathbf{i}} \partial^{\mathbf{i}} \right) \left(\sum_{|\mathbf{i}|=k} b_{\mathbf{i}} x^{\mathbf{i}} \right) = \sum_{|\mathbf{i}|=k} \mathbf{i}! \bar{a}_{\mathbf{i}} b_{\mathbf{i}}, \quad (1.5)$$

where $\mathbf{i}! := i_1 \cdots i_n$. By symmetry a similar expression holds for $(g, f)_0$. Hence $\overline{(f, g)_0} = (g, f)_0$.

(2)(3) These conditions follow immediately from Proposition 1.17.

(4)(5) By expression (1.5) we have

$$(f, f)_0 = \sum_{|\mathbf{i}|=\deg f} \mathbf{i}! |a_{\mathbf{i}}|^2.$$

Hence (4) and (5) hold.

(6) We may assume that $f, g \in S$ are homogeneous. If $\deg f \neq \deg g$ then $(wf, wg)_0 = 0 = (f, g)_0$. Hence we may assume that $\deg f = \deg g$. Then

$(f, g)_0 = (f, g)$ is a constant. Therefore $(wf, wg)_0 = (wf, wg) = w(f, g) = (f, g)_0$.

(7) The first equality $(fg, h)_0 = (g, f^*h)_0$ follows immediately from Proposition 1.17(4). We shall prove the second equality. We may assume that f, g, h are all homogeneous and $\deg g = \deg f + \deg h$ since $(g, fh)_0 = 0 = (f^*g, h)$ if $\deg g \neq \deg f + \deg h$. By Proposition 1.17(4)(5) we have

$$(g, fh)_0 = \overline{(fh, g)}_0 = \overline{(h, f^*g)}_0 = (f^*g, h)_0.$$

□

Definition 1.19. A system of basic invariants $\{f_1, \dots, f_n\}$ is said to be a *canonical system of basic invariants* (or *canonical invariants* shortly) if

$$(f_i, f_j) = 0 \quad (i \neq j). \quad (1.6)$$

A canonical system of basic invariants $\{f_1, \dots, f_n\}$ is normalized if

$$(f_i, f_i) = 1$$

for all $i \in \{1, \dots, n\}$.

This notion was introduced by Flatto [5, 6] and by Flatto and Wiener[7] for the first time, but in a quite different manner. Later Iwasaki [8] formulated it as in Definition 1.6, introducing the terminology "canonical system". When $\mathbb{K} = \mathbb{R}$, according to [5, 6, 7] it was also proven that the existence and the uniqueness (up to equivalence) of canonical systems, where two systems $\{f_1, \dots, f_n\}$ and $\{g_1, \dots, g_n\}$ are equivalent if there exists $A \in \text{GL}_n(\mathbb{K})$ such that

$$[f_1 \dots f_n] = [g_1 \dots g_n]A.$$

Canonical systems are determined explicitly by Iwasaki [8] for types A_n, B_n, D_n and $I_2(m)$ and by Iwasaki, Kenma and Matsumoto [13] for types H_3, H_4 and F_4 .

1.4 Steinberg's Theorem

To state Steinberg's theorem we introduce the notion of a W -harmonic polynomial.

Definition 1.20. We call $D_p \in \mathcal{D}_S$ a W -invariant differential operator if $wD_p = D_p$ for all $w \in W$.

Definition 1.21. A polynomial $f \in S$ is W -harmonic if $D_p f = 0$ for all W -invariant differential operator D_p without a constant term. The space of W -harmonic polynomials is denoted by $\mathcal{H}_W$.

Let $I := SS_+^W$, where S_+^W is the irrelevant ideal of S^W . Making use of the sesquilinear map $(\cdot, \cdot)$ we may express

$$\mathcal{H}_W = \{f \in S \mid (g, f) = 0 \text{ for all } g \in I\}. \quad (1.7)$$

Let $\mathcal{A}_W$ be the set of the reflecting hyperplanes of all reflections in W . For any $H \in \mathcal{A}_W$ we define a subgroup $W_H \subseteq W$ by the pointwise stabilizer of H , that is,

$$W_H := \{w \in W \mid wv = v \text{ for all } v \in H\}.$$

For a root α of H (a generator of 1-dimensional subspace $H^\perp$) we have

$$w\alpha = \zeta_w \alpha \quad (w \in W_H)$$

for some $\zeta_w \in \mathbb{K}^\times$ and this is independent of a choice of a root α . The finiteness of W implies that ζ_w is a root of unity. Hence we have a group inclusion

$$\begin{aligned} W_H &\rightarrow \boldsymbol{\mu}(\mathbb{K}), \\ w &\mapsto \zeta_w \end{aligned}$$

where $\boldsymbol{\mu}(\mathbb{K})$ denotes the group of roots of unity in $\mathbb{K}$. Therefore W_H is a cyclic group. Define e_H to be the order of W_H .

We define a polynomial $\Delta \in S$ by

$$\Delta := \prod_{H \in \mathcal{A}_W} L_H^{e_H-1},$$

where $L_H \in V^*$ satisfying $\text{Ker } L_H = H$.

Definition 1.22. A polynomial $f \in S$ is skew if $wf = (\det w)f$ for all $w \in W$.

Proposition 1.23 (Steinberg [23]). *The polynomial Δ is skew, and every skew polynomial is divisible by Δ .*

The skew polynomial Δ is quite important to study W -harmonic polynomials. Steinberg also proved the significant theorem below.

Theorem 1.24 (Steinberg [23]). *The following hold:*

- (1) $f \in I$ if and only if $(f, \Delta) = 0$,
- (2) $\mathcal{H}_W = \mathcal{D}_S \Delta$.

By Theorem 1.24 we have an orthogonal decomposition

$$S = I \oplus \mathcal{H}_W \tag{1.8}$$

Theorem 1.25 (Chevalley [2]). *The space S/I affords the regular representation of W .*

From (1.8) and Theorem 1.25 we can deduce

Proposition 1.26. *The space $\mathcal{H}_W$ of W -harmonic polynomials affords the regular representation of W .*

Chapter 2

Background

In this chapter we introduce the mean value property for polytopes and its relation with the canonical system of basic invariants for a finite reflection group.

2.1 The mean value property for a polytope

Let V be an n -dimensional Euclidean space. An n -dimensional *convex polytope* is the convex hull of a finite set of points in V whose affine hull is the entire space V . An n -dimensional *polytope* P is a finite union of n -dimensional convex polytopes. For each $k \in \{0, 1, \dots, n\}$, the k -*skeleton* of P is the union of all k -dimensional faces of P , which is denoted by $P(k)$.

For a polytope P the *symmetry group* $\Gamma(P)$ of P is defined by

$$\Gamma(P) := \{\sigma \in \text{GL}(V) \mid \sigma P = P\}.$$

Definition 2.1. Let $P \subseteq V$ be an n -dimensional polytope and $k = 0, \dots, n$. A continuous function $f: V \rightarrow \mathbb{R}$ is said to be $P(k)$ -*harmonic* if it satisfies the mean value property:

$$f(x) = \frac{1}{|P(k)|} \int_{P(k)} f(x + ry) d\mu_k(y)$$

for any $x \in V$ and $r > 0$, where μ_k is the k -dimensional Euclidean measure and $|P(k)| := \mu_k(P(k))$ is the k -dimensional volume of $P(k)$. The space of all $P(k)$ -harmonic functions is denoted by $\mathcal{H}_{P(k)}$.

Theorem 2.2 (Iwasaki [9]). *Let $P \subseteq V$ be an n -dimensional polytope and $k = 0, \dots, n$. Then the following assertions hold:*

- (1) $\mathcal{H}_{P(k)}$ is a finite-dimensional linear space of polynomials,
- (2) A basis of $\mathcal{H}_{P(k)}$ can be taken from homogeneous polynomials,
- (3) $\mathcal{H}_{P(k)}$ admits a structure of $\mathcal{D}_S$ -module, where $S = S(V^*)$.

Let $G \subseteq \mathrm{GL}(V)$ be a finite group. A polynomial $f \in S$ is said to be G -harmonic if

$$(g, f) = g(\partial)f = 0$$

holds for any $g \in S_+^G$. Let $\mathcal{H}_G$ denote the space of all G -harmonic polynomials. Iwasaki [9] showed that

$$\mathcal{H}_{\Gamma(P)} \subseteq \mathcal{H}_{P(k)}. \quad (2.1)$$

The inclusion (2.1) yields a problem to find sufficient conditions for the equality $\mathcal{H}_{\Gamma(P)} = \mathcal{H}_{P(k)}$.

2.2 Relation with a canonical system

Iwasaki [11, Theorem 1.1] stated a method to decide if the inclusion (2.1) is actually an equality when P admits a finite reflection group W as its symmetry group.

Theorem 2.3 (Iwasaki [11]). *Let $P \subseteq V$ be an n -dimensional polytope and assume that $W := \Gamma(P)$ is a finite reflection group. Let $\{f_1, \dots, f_n\}$ be a canonical system of basic invariants for W . Assume that the degrees of W are strictly increasing:*

$$d_1 < d_2 < \dots < d_n. \quad (2.2)$$

Then for every integer $k = 0, \dots, n$, the equality

$$\mathcal{H}_W = \mathcal{H}_{P(k)} \quad (2.3)$$

is equivalent to the condition

$$\int_{P(k)} f_i(x) d\mu_k(x) \neq 0 \quad (i = 1, \dots, n). \quad (2.4)$$

The symmetry group of a regular convex polytope is a finite irreducible reflection group satisfying the condition (2.2). The equality (2.3) is proven for regular convex polytopes except for measure polytopes (n -dimensional cubes) by verifying the condition (2.4)[10, 13]. Iwasaki [12] verified (2.3) for measure polytopes by using another method, hence for all regular convex polytopes. The symmetry group of a regular convex polytope is an irreducible reflection group of type A_n, B_n, F_4, H_3, H_4 or $I_2(m)$. For polytopes admitting reflection groups of the other types as their symmetry group, for example Gosset 4_{21} polytope (admitting a reflection group of type E_8), the problem to verify (2.3) is still open.

Chapter 3

Existence of a canonical system

This chapter is based on a joint-work with Nakashima and Terao [17]. Let V be an n -dimensional vector space over $\mathbb{K}$ ($\mathbb{K} = \mathbb{R}$ or $\mathbb{C}$) and W an essential irreducible finite reflection group of V . Existence of a canonical system was proven by Flatto [5, 6] and by Flatto and Wiener[7] for $\mathbb{K} = \mathbb{R}$. In this chapter we shall prove the existence including the case $\mathbb{K} = \mathbb{C}$.

3.1 Preliminaries

Let $e_1, \dots, e_n$ be an orthonormal basis for V with respect to the W -invariant inner product $\langle \cdot, \cdot \rangle$ on V , $x_1, \dots, x_n$ the dual basis and $\partial_1, \dots, \partial_n$ the corresponding derivations. For $S = S(V^*)$ we define the module of regular 1-forms Ω_S^1 as

$$\Omega_S^1 := S \otimes_{\mathbb{K}} V^*$$

equipped with the differential map $d: S \rightarrow \Omega_S^1$ defined by

$$df := \sum_{i=1}^n \partial_i f \otimes x_i = \sum_{i=1}^n (\partial_i f) dx_i.$$

Define

$$f\omega = f \sum_{i=1}^n g_i dx_i := \sum_{i=1}^n (fg_i) dx_i$$

for all $f \in S$ and $\omega = \sum_{i=1}^n g_i dx_i \in \Omega_S^1$. Thus Ω_S^1 has a structure of a graded S -module. The differential map d satisfies

$$d(fg) = f(dg) + g(df) \quad (3.1)$$

for all $f, g \in S$ since

$$d(fg) = \sum_{i=1}^n \partial_i(fg) dx_i = \sum_{i=1}^n (f \partial_i g + g \partial_i f) dx_i = f(dg) + g(df).$$

The reflection group W acts on Ω_S^1 as

$$w\omega := \sum_{i=1}^n w g_i \otimes w x_i,$$

where $w \in W$ and $\omega = \sum_{i=1}^n g_i \otimes x_i$. Because of (3.1) and

$$d(wx_i) = 1 \otimes w x_i = w(1 \otimes x_i) = w(dx_i),$$

the differential map d is a $\mathbb{K}[W]$ -homomorphism.

Define a $\mathbb{K}[W]$ -homomorphism $\varepsilon: \Omega_S^1 \rightarrow S$ by

$$\varepsilon \left(\sum_{i=1}^n f_i dx_i \right) := \sum_{i=1}^n x_i f_i.$$

Then the composition $\varepsilon \circ d$ is the Euler operator:

$$\varepsilon(df) = \sum_{i=1}^n x_i \partial_i f.$$

One can verify that for a homogeneous polynomial $f \in S$

$$\varepsilon(df) = (\deg f) f.$$

We define a subspace Ω_W as below to show the existence of a canonical system.

Definition 3.1. Define

$$\Omega_W := (\mathcal{H}_W \otimes_{\mathbb{K}} V^*)^W,$$

$$\mathcal{F}_W := \bigoplus_{k=1}^{\infty} \{ f \in S_k^W \mid (g, f) = 0 \text{ for all } g \in S_{\ell}^W \text{ with } 0 < \ell < k \},$$

where S_k^W denotes the space generated by homogeneous invariants of degree k and $(\cdot, \cdot)$ is the sesquilinear map defined by Definition 1.16.

3.2 Main theorems

Our purpose in this chapter is to prove the theorems:

Theorem 3.2. *We have $\dim_{\mathbb{K}} \Omega_W = \dim_{\mathbb{K}} \mathcal{F}_W = n$. The restrictions $d|_{\mathcal{F}_W} : \mathcal{F}_W \rightarrow \Omega_W$ and $\varepsilon|_{\Omega_W} : \Omega_W \rightarrow \mathcal{F}_W$ are isomorphisms.*

Theorem 3.3. *Any orthogonal homogeneous basis for the vector space $\mathcal{F}_W$ is a canonical system of basic invariants for the reflection group W , and vice versa. In particular there exists a unique canonical system up to equivalence.*

First we shall prove the following lemma:

Lemma 3.4. *The following hold:*

- (1) $d(\mathcal{F}_W) \subseteq \Omega_W$ and the restriction $d|_{\mathcal{F}_W}$ is an injection,
- (2) $\varepsilon(\Omega_W) \subseteq \mathcal{F}_W$.

Proof. (1) Let $f \in \mathcal{F}_W$ and $g \in I$. To prove $df \in \Omega_W$ it suffices to show that $(g, \partial_i f) = 0$ for all $i \in \{1, \dots, n\}$. We may assume that f and g are homogeneous. If $\deg g \geq \deg f$ then $(g, \partial_i f) = 0$. Suppose $\deg g < \deg f$. Then $(g, \partial_i f) = \partial_i g^* f = 0$ since $f \in \mathcal{F}_W$ and $d(\Omega) \subseteq \mathcal{F}_W$.

Suppose that $df = 0$ for a polynomial in $\mathcal{F}_W$. Then f is a constant. Since every non-zero homogeneous polynomial in $\mathcal{F}_W$ has positive degree, we can conclude that $f = 0$ and $d|_{\mathcal{F}_W}$ is injective.

(2) Let $f \in \varepsilon(\Omega_W)$ and $g \in S_+^W$ with $\deg g < \deg f$. We may assume that both of f and g are homogeneous. The polynomial $(g, f) = g^* f$ is a non-constant invariant since f, g are invariants with $\deg g < \deg f$. Hence $g^* f \in I$. We shall prove that $g^* f \in \mathcal{H}_W$. Since $f \in \varepsilon(\Omega_W)$ we may write $f = \sum_{i=1}^n x_i f_i$ for some $f_i \in \mathcal{H}_W$. By Proposition 1.15 and Theorem 1.24 we have

$$g^* f = \sum_{i=1}^n g^* x_i f_i = \sum_{i=1}^n (x_i (g^* f_i) + (\partial_i g)^* f_i) = \sum_{i=1}^n (\partial_i g)^* f_i.$$

Hence $g^* f \in \mathcal{H}_W$. Therefore $g^* f \in I \cap \mathcal{H}_W = 0$. Thus $(g, f) = g^* f = 0$ and $f \in \mathcal{F}_W$. Hence $\varepsilon(\Omega_W) \subseteq \mathcal{F}_W$. □

Recall the orthogonal decomposition (1.8) $S = I \oplus \mathcal{H}_W$. Let π the projection map from S to $\mathcal{H}_W$ with respect to the decomposition $S = I \oplus \mathcal{H}_W$. Define a $\mathbb{K}[W]$ -endomorphism $\tilde{\pi}$ on $\Omega_S^1 = S \otimes_{\mathbb{K}} V^*$ by

$$\tilde{\pi}\left(\sum_{i=1}^n f_i dx_i\right) := \sum_{i=1}^n \pi(f_i) dx_i.$$

Then we have

$$\text{Ker } \tilde{\pi} = I \otimes_{\mathbb{K}} V^* \text{ and } \text{Im } \tilde{\pi} = \mathcal{H}_W \otimes V^*.$$

For a system of basic invariants $\{h_1, \dots, h_n\}$ we put

$$dh_i = \eta_i + \omega_i,$$

where $\eta_i \in (I \otimes_{\mathbb{K}} V^*)^W$ and $\omega_i \in \Omega_W = (\mathcal{H}_W \otimes_{\mathbb{K}} V^*)^W$

For each $i \in \{1, \dots, n\}$ we define

$$g_i := \varepsilon(\eta_i) \in S^W, \quad f_i := \varepsilon(\omega_i) = (\varepsilon \circ \tilde{\pi})(dh_i) \in \mathcal{F}_W,$$

where $f_i \in \mathcal{F}_W$ follows from Lemma 3.4(2). Then we have

$$(\deg h_i)h_i = \varepsilon(h_i) = g_i + f_i.$$

Lemma 3.5. *The subset $\{f_1, \dots, f_n\} \subseteq \mathcal{F}_W$ is a system of basic invariants.*

Proof. We may write $\eta_i = \sum_{j=1}^n g_{ij} dx_j$. For every $i, j \in \{1, \dots, n\}$ the polynomial $g_{ij} \in I$. We may assume that $\{h_1, \dots, h_\ell\}$ is a subset of the system $\{h_1, \dots, h_n\}$ consisting of invariants h_j with $\deg h_j < \deg h_i$. Then there exist polynomials $g_{ijk} \in S$ such that

$$g_{ij} = \sum_{k=1}^{\ell} g_{ijk} h_k.$$

Then we have

$$g_i = \varepsilon(\eta_i) = \sum_{j=1}^n x_j g_{ij} = \sum_{j=1}^n \sum_{k=1}^{\ell} x_j g_{ijk} h_k.$$

Since g_i is invariant we have

$$g_i = \text{Av}(g_i) = \sum_{j=1}^n \sum_{k=1}^{\ell} \text{Av}(x_j g_{ijk}) h_k,$$

where Av is the averaging operator defined by

$$\text{Av} := \frac{1}{|W|} \sum_{w \in W} w,$$

where $|W|$ denotes the order of W . The invariants $\text{Av}(x_j g_{ijk})$ are polynomials in $\{h_1, \dots, h_{\ell}\}$ so is g_i . By induction on $\deg h_i$ all of $\{h_1, \dots, h_n\}$ are polynomials in $\{f_1, \dots, f_n\}$. Hence $\{f_1, \dots, f_n\}$ is a generating system of S_+^W . By Theorem 1.9 we can conclude that $\{f_1, \dots, f_n\}$ is a system of basic invariants. $\square$

We now prove Theorems 3.2 and 3.3.

Proof of Theorem 3.2. By Lemma 3.5 the space $\mathcal{F}_W$ contains a system of basic invariants. Hence $\dim_{\mathbb{K}} \mathcal{F}_W \geq n$. Lemma 3.4(1) implies $\dim_{\mathbb{K}} \mathcal{F}_W \leq \dim_{\mathbb{K}} \Omega_W$. We shall show that $\dim_{\mathbb{K}} \Omega_W = n$. There exists a natural isomorphism

$$\Omega_W = (\mathcal{H}_W \otimes_{\mathbb{K}} V^*)^W \simeq \text{Hom}_{\mathbb{K}[W]}(V, \mathcal{H}_W). \quad (3.2)$$

The dimension of $\text{Hom}_{\mathbb{K}[W]}(V, \mathcal{H}_W)$ coincides with the multiplicity of V in $\mathcal{H}_W$ since V is (absolutely) irreducible by Proposition 1.8. From Proposition 1.26 the space of W -harmonic polynomials $\mathcal{H}_W$ affords the regular representation of W . Therefore the multiplicity of V in $\mathcal{H}_W$ is $\dim_{\mathbb{K}} V = n$, so $\dim_{\mathbb{K}} \Omega_W = n$. Thus the estimate $n \leq \dim_{\mathbb{K}} \mathcal{F}_W \leq \dim_{\mathbb{K}} \Omega_W = n$ forces $\dim_{\mathbb{K}} \mathcal{F}_W = \dim_{\mathbb{K}} \Omega_W = n$. Hence the restriction $d|_{\mathcal{F}_W}: \mathcal{F}_W \rightarrow \Omega_W$ becomes an isomorphism, since it is injective by Lemma 3.4(1). From Lemma 3.4(2), we have $\varepsilon(\Omega_W) \subseteq \mathcal{F}_W$. To show that $\varepsilon|_{\Omega_W}: \Omega_W \rightarrow \mathcal{F}_W$ is an isomorphism, note that there is a commutative diagram

$$\begin{array}{ccc} \mathcal{F}_W & & \\ d|_{\mathcal{F}_W} \downarrow \wr & \searrow \text{Euler op.} & \\ \Omega_W & \xrightarrow{\varepsilon|_{\Omega_W}} & \mathcal{F}_W \end{array}$$

Since $d|_{\mathcal{F}_W}$ and the Euler operator in the diagram are isomorphic, so is $\varepsilon|_{\Omega_W}$. $\square$

Proof of Theorem 3.3. By Lemma 3.5, the vector space $\mathcal{F}_W$ contains a system $\{f_1, \dots, f_n\}$ of basic invariants for the reflection group W . This system becomes a homogeneous linear basis for $\mathcal{F}_W$, since $\dim_{\mathbb{K}} \mathcal{F}_W = n$ by Theorem 3.2 and algebraic independence implies linear independence. Therefore any homogeneous linear basis for $\mathcal{F}_W$ gives a system of basic invariants for W .

Take an orthogonal homogeneous basis $\mathcal{B}$ for $\mathcal{F}_W$. Then $\mathcal{B}$ is a system of basic invariants satisfying the condition (1.6). Therefore $\mathcal{B}$ is a canonical system of basic invariants. In particular, a canonical system exists.

Conversely, let $\mathcal{B}$ be a canonical system. The condition (1.6) implies $\mathcal{B} \subseteq \mathcal{F}_W$. Hence $\mathcal{B}$ is an orthogonal homogeneous basis for the vector space $\mathcal{F}_W$. In particular, there exists a unique canonical system up to equivalence. $\square$

Corollary 3.6. *Let π be the projection onto $\mathcal{H}_W$ with respect to the decomposition $S = I \oplus \mathcal{H}_W$ and $\tilde{\pi} := \pi \otimes 1_{V^*}$. For an arbitrary system $\{h_1, \dots, h_n\}$ of basic invariants, the orthogonalization of the system*

$$\{(\varepsilon \circ \tilde{\pi})(dh_i) \mid 1 \leq i \leq n\}$$

yields a canonical system of basic invariants.

Chapter 4

Explicit formulas for canonical systems

This chapter is based on a joint-work with Nakashima [18]. Let V be an n -dimensional vector space over $\mathbb{K}$ ($\mathbb{K} = \mathbb{R}$ or $\mathbb{C}$) and W an essential irreducible finite reflection group of V . By Corollary 3.6 a canonical system may be expressed by making use of an arbitrary system of basic invariants, but this formula is not explicit because of abstractness of the projection π . In this chapter we shall create a computable map which refines Corollary 3.6.

4.1 Preliminaries

Recall the W -invariant sesquilinear map $(\cdot, \cdot): S \times S \rightarrow S$ defined by Definition 1.16. The restriction of $(\cdot, \cdot)$ to $\mathcal{F}_W \times \mathcal{F}_W$ is a inner product on $\mathcal{F}_W$ since for homogeneous polynomials $f, g \in \mathcal{F}_W$

$$(f, g) = \begin{cases} (f, g)_0 & \text{if } \deg f = \deg g \\ 0 & \text{if } \deg f \neq \deg g \end{cases}.$$

We introduce a sesquilinear map $(\cdot, \cdot): \Omega_W \times \Omega_W \rightarrow S$ defined by

$$\left(\sum_{i=1}^n f_i dx_i, \sum_{j=1}^n g_j dx_j \right) := \sum_{i=1}^n \sum_{j=1}^n (f_i, g_j)(x_i, x_j) = \sum_{i=1}^n (f_i, g_i), \quad (4.1)$$

where $(\cdot, \cdot)$ in the middle and the right hand is the sesquilinear map defined by Definition 1.16. By Theorem 3.2, any element in Ω_W is of the form

df ($f \in \mathcal{F}_W$). For any homogeneous polynomials $f, g \in \mathcal{F}_W$,

$$\begin{aligned} (df, dg) &= \left(\sum_{i=1}^n \partial_i f dx_i, \sum_{i=1}^n \partial_i g dx_i \right) = \sum_{i=1}^n (\partial_i f, \partial_i g) \\ &= \sum_{i=1}^n (x_i \partial_i f, g) = (\deg f)(f, g). \end{aligned}$$

Hence the sesquilinear map (4.1) actually determines an inner product on Ω_W . For homogeneous elements $\omega_1, \omega_2 \in \Omega_W$ satisfying $\deg \omega_1 \neq \deg \omega_2$, we have $(\omega_1, \omega_2) = 0$. Therefore

$$f \perp g \text{ if and only if } df \perp dg$$

for homogeneous polynomials $f, g \in \mathcal{F}_W$ and

$$\omega_1 \perp \omega_2 \text{ if and only if } \varepsilon(\omega_1) \perp \varepsilon(\omega_2) \quad (4.2)$$

for homogeneous elements $\omega_1, \omega_2 \in \Omega_W$.

Proposition 4.1. *Let $\{\omega_1, \dots, \omega_n\}$ be an orthogonal homogeneous basis for Ω_W . Then $\{\varepsilon(\omega_1), \dots, \varepsilon(\omega_n)\}$ is a canonical system of basic invariants.*

Proof. It follows from Theorem 3.2, Theorem 3.3 and (4.2). $\square$

4.2 Construction of canonical systems

We will construct a homogeneous basis for $\mathcal{F}_W$ from arbitrary basic invariants. The following map plays an important roll for the construction.

Definition 4.2. Define a linear map $\phi: S \rightarrow S$ by

$$\phi(f) = ((f, \Delta) \Delta).$$

Proposition 4.3. *The map ϕ has the following properties:*

- (1) ϕ is a $\mathbb{K}[W]$ -homomorphism,
- (2) ϕ is homogeneous and degree-preserving,
- (3) $\text{Ker } \phi = I$ and $\text{Im } \phi = \mathcal{H}_W$. In particular the restriction $\phi|_{\mathcal{H}_W}: \mathcal{H}_W \rightarrow \mathcal{H}_W$ is a $\mathbb{K}[W]$ -isomorphism.

(4) ϕ is a symmetric (Hermitian) transformation with respect to the inner product $(\cdot, \cdot)_0$, that is,

$$(\phi(f), g)_0 = (f, \phi(g))_0, \quad (f, g \in S).$$

In particular, $\phi: S \rightarrow S$ can be diagonalized by homogeneous polynomials.

Proof. (1) For any $f \in S$ and $w \in W$,

$$\begin{aligned} w\phi(f) &= w((f, \Delta), \Delta) \\ &= ((wf, (\det w)\Delta), (\det w)\Delta) \\ &= ((\det w)(wf, \Delta), (\det w)\Delta) \\ &= \overline{(\det w)}(\det w)((wf, \Delta), \Delta) \\ &= ((wf, \Delta), \Delta) \\ &= \phi(wf). \end{aligned}$$

(2) For any homogeneous polynomial $f \in S$,

$$\deg \phi(f) = \deg \Delta - \deg(f, \Delta) = \deg \Delta - (\deg \Delta - \deg f) = \deg f.$$

(3) By Theorem 1.24,

$$f \in \text{Ker } \phi \Leftrightarrow ((f, \Delta), \Delta) = 0 \Leftrightarrow (f, \Delta) \in I \cap \mathbb{K}[\partial]\Delta = 0 \Leftrightarrow f \in I.$$

By Theorem 1.24 again, we have $\text{Im } \phi \subseteq \mathcal{H}_W$. Since $\text{Ker } \phi = I$ we have $\dim_{\mathbb{K}} \text{Im } \phi = \dim_{\mathbb{K}} \mathcal{H}_W$. Then $\text{Im } \phi = \mathcal{H}_W$ and the restriction $\phi|_{\mathcal{H}_W}: \mathcal{H}_W \rightarrow \mathcal{H}_W$ is an isomorphism.

(4) We may assume that f, g are homogeneous polynomials having the same degree. Put $F := (f, \Delta)$ and $G := (g, \Delta)$. Then

$$(f, \phi(g))_0 = (f, (G, \Delta))_0 = (fG, \Delta)_0 = (G, (f, \Delta))_0 = (G, F)_0.$$

By symmetry

$$(\phi(f), g)_0 = \overline{(g, \phi(f))}_0 = \overline{(F, G)}_0 = (G, F)_0 = (f, \phi(g))_0.$$

Thus ϕ is a symmetric (Hermitian) transformation with respect to the inner product $(\cdot, \cdot)_0$. $\square$

Remark. In the proof of (2) and (4), we did not use any property of Δ other than homogeneity. Hence (2) and (4) are true for $\phi_h(f) := ((f, h), h)$ with any homogeneous polynomial $h \in S$.

The map ϕ induces a linear map $\tilde{\phi}: (\Omega_S^1)^W \rightarrow \Omega_W$ defined by

$$\tilde{\phi} \left(\sum_{i=1}^n f_i dx_i \right) := \sum_{i=1}^n \phi(f_i) dx_i.$$

By Proposition 4.3, we have

Proposition 4.4. *The following conditions hold:*

- (1) $\tilde{\phi}$ is homogeneous and degree-preserving,
- (2) $\text{Ker } \tilde{\phi} = (I \otimes_{\mathbb{K}} V^*)^W$ and $\text{Im } \tilde{\phi} = \Omega_W$. In particular the restriction $\tilde{\phi}|_{\Omega_W}: \Omega_W \rightarrow \Omega_W$ is an isomorphism.
- (3) $\tilde{\phi}$ is a symmetric (Hermitian) transformation with respect to the inner product $(\cdot, \cdot): \Omega_W \times \Omega_W \rightarrow \mathbb{K}$, that is,

$$(\tilde{\phi}(\omega_1), \omega_2) = (\omega_1, \tilde{\phi}(\omega_2)), \quad (\omega_1, \omega_2 \in \Omega_W).$$

In particular, $\tilde{\phi}|_{\Omega_W}: \Omega_W \rightarrow \Omega_W$ can be diagonalized by homogeneous elements.

Proof. (1) and (2) follow immediately by Proposition 4.3.

(3) Let $\omega_1, \omega_2 \in \Omega_W$ be homogeneous elements. If $\deg \omega_1 \neq \deg \omega_2$ then

$$(\tilde{\phi}(\omega_1), \omega_2) = 0 = (\omega_1, \tilde{\phi}(\omega_2)).$$

When $\deg \omega_1 = \deg \omega_2$,

$$\begin{aligned} (\tilde{\phi}(\omega_1), \omega_2) &= \left(\sum_{i=1}^n \phi(f_i) dx_i, \sum_{i=1}^n g_i dx_i \right) = \sum_{i=1}^n (\phi(f_i), g_i)_0 \\ &= \sum_{i=1}^n (f_i, \phi(g_i))_0 = \left(\sum_{i=1}^n f_i dx_i, \sum_{i=1}^n \phi(g_i) dx_i \right) \\ &= (\omega_1, \tilde{\phi}(\omega_2)). \end{aligned}$$

Thus $\tilde{\phi}$ is symmetric (Hermitian). □

Proposition 4.5. *There exists a canonical system $\{f_1, \dots, f_n\}$ such that $df_1, \dots, df_n$ are eigenvectors of $\tilde{\phi}$.*

Proof. Let $U_{d,\lambda}$ be the subspace of Ω_W consisting of homogeneous eigenvectors of $\tilde{\phi}$ with degree d and eigenvalue λ . By Proposition 4.4,

$$\Omega_W = \bigoplus_{d,\lambda} U_{d,\lambda},$$

where every λ is real since $\tilde{\phi}$ is symmetric (Hermitian). We assume that $U_{d_1,\lambda_1} \neq U_{d_2,\lambda_2}$. If $d_1 \neq d_2$, then U_{d_1,λ_1} is orthogonal to U_{d_2,λ_2} . When $\lambda_1 \neq \lambda_2$, let $\omega_1 \in U_{d_1,\lambda_1}$ and $\omega_2 \in U_{d_2,\lambda_2}$. By Proposition 4.4 (3), we have

$$\lambda_1(\omega_1, \omega_2) = \left(\tilde{\phi}(\omega_1), \omega_2 \right) = \left(\omega_1, \tilde{\phi}(\omega_2) \right) = \lambda_2(\omega_1, \omega_2).$$

Then $(\omega_1, \omega_2) = 0$. This means that U_{d_1,λ_1} is orthogonal to U_{d_2,λ_2} . Hence the subspaces $U_{d,\lambda}$ are orthogonal to each other.

The union of orthogonal bases for $U_{d,\lambda}$ is an orthogonal basis for Ω_W consisting of eigenvectors of $\tilde{\phi}$. Let $\{\omega_1, \dots, \omega_n\}$ be such an orthogonal basis for Ω_W . Then $\varepsilon(\omega_1), \dots, \varepsilon(\omega_n)$ is a required canonical system. $\square$

Theorem 4.6. *For an arbitrary system of basic invariants $\{h_1, \dots, h_n\}$, the system*

$$\{\tilde{\phi}(dh_1), \dots, \tilde{\phi}(dh_n)\}$$

is a basis for Ω_W . Therefore the orthogonalization of

$$\left\{ (\varepsilon \circ \tilde{\phi})(dh_i) = \sum_{j=1}^n x_j \phi(\partial_j h_i) \mid 1 \leq i \leq n \right\} \quad (4.3)$$

is a canonical system of basic invariants.

Proof. We can take a canonical system $\{f_1, \dots, f_n\}$ satisfying that $df_1, \dots, df_n$ are eigenvectors of $\tilde{\phi}$ by Proposition 4.5. Let $\lambda_1, \dots, \lambda_n$ be the eigenvalues of $\tilde{\phi}$ corresponding to $df_1, \dots, df_n$. All of these are nonzero since $\tilde{\phi}|_{\Omega_W}$ is an isomorphism. Let $d_1 \leq \dots \leq d_n$ be the degrees of W . We may assume that $\deg f_i = \deg h_i = d_i$. Let r be the multiplicity of d_i . Then we may assume that $d_i = \dots = d_{i+r-1}$. We only need to verify that the linear

independence of $\{\tilde{\phi}(dh_i), \dots, \tilde{\phi}(dh_{i+r-1})\}$ since homogeneous elements having different degrees are orthogonal to each other.

For $j = 0, \dots, r-1$, we may write

$$h_{i+j} = \sum_{k=0}^{r-1} a_{jk} f_{i+k} + P_j(f_1, \dots, f_{i-1}), \quad (4.4)$$

where $P_j = P_j(f_1, \dots, f_{i-1})$ is a polynomial in $f_1, \dots, f_{i-1}$ and $a_{jk} \in \mathbb{K}$. Since $\{h_1, \dots, h_n\}$ is algebraically independent, we have $\det[a_{jk}] \neq 0$. The 1-form dP_j is in $\ker \tilde{\phi} = (I \otimes_{\mathbb{K}} V^*)^W$ since each term of P_j is a product of two or more invariants in $\{f_1, \dots, f_r\}$. Applying $\tilde{\phi} \circ d$ on the equality (4.4), we have

$$\tilde{\phi}(dh_{i+j}) = \sum_{k=0}^{r-1} a_{jk} \lambda_{i+k} df_{i+k}. \quad (4.5)$$

Therefore, $\tilde{\phi}(dh_i), \dots, \tilde{\phi}(dh_{i+r-1})$ are linearly independent since $\det[a_{jk}] \neq 0$. $\square$

Corollary 4.7. *Suppose that the degrees of W are all different. Then the system (4.3) is a canonical system of basic invariants.*

Chapter 5

Canonical systems for $G(m, p, n)$

For the infinite family of irreducible finite Euclidean reflection groups (of types A_n, B_n, D_n, I_2), Iwasaki [8] constructs explicit formulas for the canonical systems. In this chapter, we construct explicit formulas for canonical systems for unitary reflection groups $G(m, p, n)$ by making use of a similar method to Iwasaki's one.

5.1 Preliminaries

For positive integers m, n , let $\mu_m := \mu_m(\mathbb{C})$ be the cyclic group of m -th roots of unity and $\mathfrak{S}_n$ the symmetric group of degree n . The group $\mathfrak{S}_n$ acts on μ_m^n by changing coordinates. For a divisor p of m , define

$$A(m, p, n) := \{ \zeta = (\zeta_1, \zeta_2, \dots, \zeta_n) \in \mu_m^n \mid (\zeta_1 \zeta_2 \cdots \zeta_n)^{m/p} = 1 \}.$$

It is easy to show that $A(m, p, n)$ is a subgroup of μ_m^n and is stable under the action of $\mathfrak{S}_n$.

Definition 5.1. For positive integers m, n and a divisor p of m , we define a group $G(m, p, n)$ by the semidirect product of $A(m, p, n)$ and $\mathfrak{S}_n$:

$$G(m, p, n) := A(m, p, n) \rtimes \mathfrak{S}_n.$$

The group structure is given by

$$(\zeta, \sigma)(\zeta', \sigma') = (\zeta(\sigma\zeta'), \sigma\sigma').$$

For each permutation $\sigma \in \mathfrak{S}_n$, E_σ denotes the permutation matrix with respect to σ . Note that both of $\text{diag}(\zeta)$ and E_σ are unitary matrices for $\zeta \in \boldsymbol{\mu}_m^n$ and $\sigma \in \mathfrak{S}_n$. We define a map $\rho: G(m, p, n) \rightarrow U_n(\mathbb{C})$ by

$$\rho(\zeta, \sigma) := \text{diag}(\zeta)E_\sigma.$$

Proposition 5.2. *The map ρ is an injective group homomorphism.*

Proof. For any $(\zeta, \sigma), (\zeta', \sigma') \in G(m, p, n)$,

$$\begin{aligned} \rho((\zeta, \sigma)(\zeta', \sigma')) &= \rho(\zeta(\sigma\zeta'), \sigma\sigma') \\ &= \text{diag}(\zeta(\sigma\zeta'))E_{\sigma\sigma'} \\ &= \text{diag}(\zeta) \text{diag}(\sigma\zeta')E_\sigma E_{\sigma'} \\ &= \text{diag}(\zeta)E_\sigma \text{diag}(\zeta')E_{\sigma'} \\ &= \rho(\zeta, \sigma)\rho(\zeta', \sigma'). \end{aligned}$$

Hence ρ is a homomorphism. Assume that $\rho(\zeta, \sigma) = \text{diag}(\zeta)E_\sigma = I$. Then $\text{diag}(\zeta) = E_{\sigma^{-1}}$. Hence both of $\text{diag}(\zeta)$ and $E_{\sigma^{-1}}$ are equal to the identity matrix. Therefore (ζ, σ) is equal to the identity of $G(m, p, n)$. Thus the homomorphism ρ is injective. $\square$

Let $V := \mathbb{C}^n$ and $e_1, \dots, e_n$ the standard basis for V . Let $x = (x_1, \dots, x_n)$ be the dual basis of $e_1, \dots, e_n$ and S the ring of polynomial function $\mathbb{C}[x]$. From the previous proposition, we can regard the group $G(m, p, n)$ as a subgroup of $U(V) \cong U_n(\mathbb{C})$. The group $G(m, p, n)$ contains two kinds of reflections:

$$s_{i,\zeta} e_k = \begin{cases} \zeta e_i & (k = i) \\ e_k & (k \neq i) \end{cases} \text{ for } \zeta \in \boldsymbol{\mu}_{m/p}, 1 \leq i \leq n,$$

$$s_{i,j,\zeta} e_k = \begin{cases} \zeta e_j & (k = i) \\ \zeta^{-1} e_i & (k = j) \\ e_k & (k \neq i, j) \end{cases} \text{ for } \zeta \in \boldsymbol{\mu}_m, 1 \leq i < j \leq n.$$

All reflections of $G(m, p, n)$ are of types above and $G(m, p, n)$ are generated by those reflections (see for example [15]). Therefore the skew polynomial Δ for $G(m, p, n)$ is given by

$$\Delta = \prod_{i=1}^n x_i^{m/p-1} \prod_{\substack{1 \leq i < j \leq n \\ \zeta \in \boldsymbol{\mu}_m}} (x_i - \zeta x_j) = \prod_{i=1}^n x_i^{m/p-1} \prod_{1 \leq i < j \leq n} (x_i^m - x_j^m). \quad (5.1)$$

According to [15], a system of basic invariants for $G(m, p, n)$ is given by

$$\sum_{i=1}^n x_i^m, \quad \sum_{i=1}^n x_i^{2m}, \quad \dots, \quad \sum_{i=1}^n x_i^{(n-1)m}, \quad (x_1 \cdots x_n)^{m/p}. \quad (5.2)$$

Hence the degrees of $G(m, p, n)$ are

$$m, 2m, \dots, (n-1)m, n\frac{m}{p}. \quad (5.3)$$

When $p = 1$, replacing the invariant $(x_1 \cdots x_n)^m$ by $\sum_{i=1}^n x_i^{nm}$, we have another system of basic invariants for $G(m, 1, n)$:

$$\sum_{k=1}^n x_k^{im} \quad (1 \leq i \leq n). \quad (5.4)$$

5.2 Canonical systems for $G(m, 1, n)$

In this section we set $G := G(m, 1, n)$. Let $\{f_1, \dots, f_n\}$ be a canonical system for G . From (5.3), we may assume that $\deg f_i = im$. Since every f_i is homogeneous, we have

$$(\deg f_i) f_i = \sum_{j=1}^n x_j \partial_j f_i.$$

Hence it suffices to determine $\partial_1 f_i, \dots, \partial_n f_i$ to determine f_i . From the proof of Lemma 3.4(1), we have $\partial_j f_i \in \mathcal{H}_G$. By Steinberg's Theorem 1.24 (2) there exists a homogeneous polynomial $g_{ij} \in S$ such that

$$\partial_j f_i = g_{ij}^* \Delta \quad (1 \leq i, j \leq n). \quad (5.5)$$

From (5.1) the skew polynomial Δ for $G(m, 1, n)$ is given by

$$\Delta = \prod_{i=1}^n x_i^{m-1} \prod_{1 \leq i < j \leq n} (x_i^m - x_j^m).$$

Let

$$G_j := \text{Stab}_G(x_j) = \{w \in G \mid wx_j = x_j\}.$$

The subgroup G_j is a reflection group isomorphic to $G(m, 1, n-1)$. So the order of G_j is independent of j . The skew polynomial Δ_j for G_j is given by

$$\Delta_j = \prod_{\substack{1 \leq k \leq n \\ k \neq j}} x_k^{m-1} \prod_{\substack{1 \leq k < \ell \leq n \\ k, \ell \neq j}} (x_k^m - x_\ell^m).$$

Define the averaging operator Av_j and the skew operator Sk_j for G_j by

$$\begin{aligned} \text{Av}_j &:= \frac{1}{|G_j|} \sum_{w \in G_j} w, \\ \text{Sk}_j &:= \frac{1}{|G_j|} \sum_{w \in G_j} (\det w)^{-1} w, \end{aligned}$$

where $|G_j|$ is the order of G_j . Applying Av_j to (5.5), we have

$$\begin{aligned} \partial_j f_i &= \text{Av}_j(g_{ij}^* \Delta) \\ &= \frac{1}{|G_j|} \sum_{w \in G_j} (wg_{ij})^* w \Delta \\ &= \frac{1}{|G_j|} \sum_{w \in G_j} (wg_{ij})^* (\det w) \Delta \\ &= \frac{1}{|G_j|} \sum_{w \in G_j} ((\det w)^{-1} wg_{ij})^* \Delta \\ &= (\text{Sk}_j g_{ij})^* \Delta \quad (1 \leq i, j \leq n), \end{aligned} \tag{5.6}$$

where the fourth equality follows from the fact that $\det w$ is a root of unity. By Proposition 1.23, every skew polynomial $\text{Sk}_j g_{ij}$ is divisible by the skew polynomial Δ_j . Hence there exists a G_j -invariant homogeneous polynomial h_{ij} such that $\text{Sk}_j g_{ij} = h_{ij} \Delta_j$. From (5.6), we have

$$-1 + \deg f_i = -(\deg h_{ij} + \deg \Delta_j) + \deg \Delta.$$

Hence

$$\begin{aligned} \deg h_{ij} &= 1 - \deg f_i - \deg \Delta_j + \deg \Delta \\ &= 1 - im - (n-1)(m-1) - m \binom{n-1}{2} + n(m-1) + m \binom{n}{2} \\ &= (n-i)m. \end{aligned}$$

From (5.4), each h_{ij} is a polynomial of the G_j -invariants

$$\sum_{\substack{1 \leq k \leq n \\ k \neq j}} x_k^{\ell m} \quad (1 \leq \ell \leq n-1).$$

For any positive integer ℓ , we have $\sum_{k=1}^n x_k^{\ell m} \in I$. Hence

$$h_{ij} \equiv c_{ij} x_j^{(n-i)m} \pmod{I}$$

for some constant $c_{ij} \in \mathbb{C}^\times$. By Steinberg's Theorem 1.24(1), the equality (5.6) yields

$$\partial_j f_i = (\text{Sk}_j g_{ij})^* \Delta = (h_{ij} \Delta_j)^* \Delta = \left(c_{ij} x_j^{(n-i)m} \Delta_j \right)^* \Delta.$$

Finally we need to determine the coefficients c_{ij} . Without loss of generality we may assume that $c_{i1} = 1$. For $j \geq 2$, let $s_j := s_{1,j,1}$. Then

$$s_j \Delta_j = (-1)^{\#\{k \mid 1 < k < j\}} \Delta_1 = (-1)^{j-2} \Delta_1.$$

Therefore

$$\begin{aligned} \partial_1 f_i &= s_j (\partial_j f_i) = \left(c_{ij} x_1^{(n-i)m} (-1)^{j-2} \Delta_1 \right)^* (-\Delta) \\ &= (-1)^{j-1} \overline{c_{ij}} \left(x_1^{(n-i)m} \Delta_1 \right)^* \Delta = (-1)^{j-1} \overline{c_{ij}} \partial_1 f_i. \end{aligned}$$

Hence $(-1)^{j-1} \overline{c_{ij}} = 1$, namely, $c_{ij} = (-1)^{j-1}$. We have concluded the following theorem.

Theorem 5.3. *Polynomials*

$$f_i = \sum_{j=1}^n (-1)^{j-1} x_j \left(x_j^{(n-i)m} \Delta_j \right)^* \Delta \quad (1 \leq i \leq n)$$

form a canonical system of basic invariants for $G(m, 1, n)$, where the skew polynomials Δ, Δ_j are defined by

$$\begin{aligned} \Delta &= \prod_{k=1}^n x_k^{m-1} \prod_{1 \leq k < \ell \leq n} (x_k^m - x_\ell^m), \\ \Delta_j &= \prod_{\substack{1 \leq k \leq n \\ k \neq j}} x_k^{m-1} \prod_{\substack{1 \leq k < \ell \leq n \\ k, \ell \neq j}} (x_k^m - x_\ell^m) \quad (1 \leq j \leq n). \end{aligned}$$

Corollary 5.4. *Let $W = G(1, 1, n)$. Then W is a (non-essential) finite Euclidean reflection group of type A_{n-1} . A system of canonical invariants for W is given by*

$$f_i = \sum_{j=1}^n (-1)^{j-1} x_j (x_j^{n-i} \Delta_j)^* \Delta \quad (1 \leq i \leq n),$$

where the skew polynomials Δ, Δ_j are defined by

$$\begin{aligned} \Delta &= \prod_{1 \leq k < \ell \leq n} (x_k - x_\ell), \\ \Delta_j &= \prod_{\substack{1 \leq k < \ell \leq n \\ k, \ell \neq j}} (x_k - x_\ell) \quad (1 \leq j \leq n). \end{aligned}$$

Corollary 5.5. *Let $W = G(2, 1, n)$. Then W is an irreducible finite Euclidean reflection group of type B_n . A system of canonical invariants for W is given by*

$$f_i = \sum_{j=1}^n (-1)^{j-1} x_j \left(x_j^{2(n-i)} \Delta_j \right)^* \Delta \quad (1 \leq i \leq n),$$

where the skew polynomials Δ, Δ_j are defined by

$$\begin{aligned} \Delta &= \prod_{k=1}^n x_k \prod_{1 \leq k < \ell \leq n} (x_k^2 - x_\ell^2), \\ \Delta_j &= \prod_{\substack{1 \leq k \leq n \\ k \neq j}} x_k \prod_{\substack{1 \leq k < \ell \leq n \\ k, \ell \neq j}} (x_k^2 - x_\ell^2) \quad (1 \leq j \leq n). \end{aligned}$$

5.3 Canonical systems for $G(m, p, n)$ with $p > 1$

Let m, n be positive integers and $p \geq 2$ a divisor of m . Throughout this section we set $G := G(m, p, n)$. Let $f_1, \dots, f_n$ be a canonical system for $G(m, 1, n)$ given by Theorem 5.3. We shall prove the following theorem.

Theorem 5.6. *The polynomials*

$$f_1, \dots, f_{n-1}, (x_1 \cdots x_n)^{m/p}$$

form a canonical system of basic invariants for $G = G(m, p, n)$.

Proof. We only need to verify that $f_1, \dots, f_{n-1}, (x_1 \cdots x_n)^{m/p}$ form an orthogonal basis for $\mathcal{F}_G$ by Theorem 3.3. Set

$$g_i := \sum_{j=1}^n x_j^{im} \quad (1 \leq i \leq n).$$

From (5.2) the polynomials $g_1, \dots, g_{n-1}, (x_1 \cdots x_n)^{m/p}$ form a system of basic invariants for G and from (5.4) the polynomials $g_1, \dots, g_n$ form a system of basic invariants for $G(m, 1, n)$. It is immediate that $g_i^*(x_1 \cdots x_n)^{m/p} = 0$ for $i \in \{1, \dots, n-1\}$ since $p > 1$. Hence $(x_1 \cdots x_n)^{m/p} \in \mathcal{F}_G$.

To show $f_i \in \mathcal{F}_G$ ($1 \leq i \leq n-1$) we need to verify that

$$g_j^* f_i = 0 \quad (j < i) \quad \text{and} \quad (\partial_1 \cdots \partial_n)^{m/p} f_i = 0 \quad (1 \leq i \leq n-1).$$

The former follows immediately since the system $f_1, \dots, f_n$ is canonical for $G(m, 1, n)$ and the polynomials $g_1, \dots, g_n$ form a system of basic invariants for $G(m, 1, n)$. To prove that the latter condition holds we have only to verify

$$\partial_1 \cdots \partial_n f_i = 0 \quad (1 \leq i \leq n-1). \quad (5.7)$$

Let ζ be a primitive m -th root of unity. Since f_i is a $G(m, 1, n)$ -invariant, we have

$$s_{j,\zeta}(\partial_1 \cdots \partial_n f_i) = \zeta \partial_1 \cdots \partial_n f_i \quad (1 \leq j \leq n).$$

Hence the polynomial $\partial_1 \cdots \partial_n f_i$ is a skew polynomial for the cyclic reflection group $\langle s_{j,\zeta} \rangle$ of order m . From Proposition 1.23 the polynomial $\partial_1 \cdots \partial_n f_i$ is divisible by the skew polynomial x_j^{m-1} for every $j \in \{1, \dots, n\}$. Therefore $\partial_1 \cdots \partial_n f_i$ is divisible by $(x_1 \cdots x_n)^{m-1}$. For $1 \leq i \leq n-1$, we have $\deg \partial_1 \cdots \partial_n f_i = im - n < n(m-1) = \deg(x_1 \cdots x_n)^{m-1}$. Thus (5.7) holds. Hence $f_i \in \mathcal{F}_G$ for $i \in \{1, \dots, n-1\}$.

Finally we show the orthogonality of $f_1, \dots, f_{n-1}, (x_1 \cdots x_n)^{m/p}$. The conditions $f_i^* f_j = 0$ ($1 \leq i, j \leq n-1, i \neq j$) follow from the orthogonality of the system $f_1, \dots, f_n$. The conditions $(\partial_1 \cdots \partial_n)^{m/p} f_i = 0$ ($1 \leq i \leq n-1$) are proved above. For $i \in \{1, \dots, n-1\}$, if $\deg f_i < \deg(x_1 \cdots x_n)^{m/p}$ then $f_i^*(x_1 \cdots x_n)^{m/p} = 0$ since f_i is a polynomial in $g_1, \dots, g_i$. If $\deg f_i = \deg(x_1 \cdots x_n)^{m/p}$ then $f_i^*(x_1 \cdots x_n)^{m/p} = (\partial_1 \cdots \partial_n)^{m/p} f_i = 0$. If $\deg f_i > \deg(x_1 \cdots x_n)^{m/p}$ then the condition $f_i^*(x_1 \cdots x_n)^{m/p} = 0$ is trivial. Thus the orthogonality of the system $f_1, \dots, f_{n-1}, (x_1 \cdots x_n)^{m/p}$ has been proved. $\square$

Corollary 5.7. *Let $W = G(2, 2, n)$. Then W is an irreducible finite Euclidean reflection group of type D_n . A system of canonical invariants for W is given by*

$$f_i = \sum_{j=1}^n (-1)^{j-1} x_j \left(x_j^{2(n-i)} \Delta_j \right)^* \Delta \quad (1 \leq i \leq n-1),$$

$$f_n = (x_1 \cdots x_n)^{m/p}$$

where the skew polynomials Δ, Δ_j are defined by

$$\Delta = \prod_{k=1}^n x_k \prod_{1 \leq k < \ell \leq n} (x_k^2 - x_\ell^2),$$

$$\Delta_j = \prod_{\substack{1 \leq k \leq n \\ k \neq j}} x_k \prod_{\substack{1 \leq k < \ell \leq n \\ k, \ell \neq j}} (x_k^2 - x_\ell^2) \quad (1 \leq j \leq n).$$

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